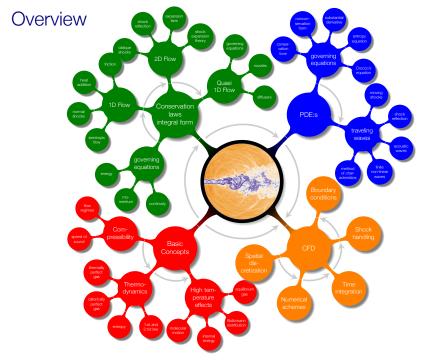
Compressible Flow - TME085 Lecture 10

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Chapter 7 Unsteady Wave Motion





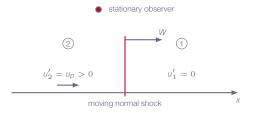
Addressed Learning Outcomes

- 3 Describe typical engineering flow situations in which compressibility effects are more or less predominant (e.g. Mach number regimes for steady-state flows)
- 8 Derive (marked) and apply (all) of the presented mathematical formulae for classical gas dynamics j unsteady waves and discontinuities in 1D
- 9 Solve engineering problems involving the above-mentioned phenomena (8a-8k)
- 12 Explain the main principles behind a modern Finite Volume CFD code and such concepts as explicit/implicit time stepping, CFL number, conservation, handling of compression shocks, and boundary conditions

what happens when a moving shock approaches a wall?

Chapter 7.2 Moving Normal Shock Waves

Moving Normal Shock Waves - Governing Equations



For stationary normal shocks we have:

$$\rho_1 u_1 = \rho_2 u_2$$

$$\rho_1 u_1^2 + \rho_1 = \rho_2 u_2^2 + \rho_2$$

$$h_1 + \frac{1}{2} u_1^2 = h_2 + \frac{1}{2} u_2^2$$

With $(u_1 = W)$ and $(u_2 = W - u_D)$ we get:

$$\rho_1 W = \rho_2 (W - u_p)$$

$$\rho_1 W^2 + \rho_1 = \rho_2 (W - u_p)^2 + \rho_2$$

$$h_1 + \frac{1}{2} W^2 = h_2 + \frac{1}{2} (W - u_p)^2$$

From the continuity equation we get:

$$u_{p} = W\left(1 - \frac{\rho_{1}}{\rho_{2}}\right) > 0$$

After some derivation we obtain:

$$u_{p} = \frac{a_{1}}{\gamma} \left(\frac{\rho_{2}}{\rho_{1}} - 1 \right) \left[\frac{\frac{2\gamma}{\gamma + 1}}{\frac{\rho_{2}}{\rho_{1}} + \frac{\gamma - 1}{\gamma + 1}} \right]^{1/2}$$

May also show that

$$\frac{\rho_2}{\rho_1} = \frac{1 + \frac{\gamma + 1}{\gamma - 1} \left(\frac{\rho_2}{\rho_1}\right)}{\frac{\gamma + 1}{\gamma - 1} + \frac{\rho_2}{\rho_1}}$$

and

$$\frac{T_2}{T_1} = \frac{\rho_2}{\rho_1} \left[\frac{\frac{\gamma+1}{\gamma-1} + \frac{\rho_2}{\rho_1}}{1 + \frac{\gamma+1}{\gamma-1} \left(\frac{\rho_2}{\rho_1}\right)} \right]$$

Induced Mach number:

$$M_p = \frac{u_p}{a_2} = \frac{u_p}{a_1} \frac{a_1}{a_2} = \frac{u_p}{a_1} \sqrt{\frac{T_1}{T_2}}$$

inserting u_p/a_1 and T_1/T_2 from relations on previous slides we get:

$$M_{\rho} = \frac{1}{\gamma} \left(\frac{\rho_2}{\rho_1} - 1 \right) \left[\frac{\frac{2\gamma}{\gamma + 1}}{\frac{\gamma - 1}{\gamma + 1} + \frac{\rho_2}{\rho_1}} \right]^{1/2} \left[\frac{1 + \left(\frac{\gamma + 1}{\gamma - 1} \right) \left(\frac{\rho_2}{\rho_1} \right)}{\left(\frac{\gamma + 1}{\gamma - 1} \right) \left(\frac{\rho_2}{\rho_1} \right) + \left(\frac{\rho_2}{\rho_1} \right)^2} \right]^{1/2}$$

Note that

$$\lim_{\frac{\rho_2}{\rho_1} \to \infty} M_{\rho} \to \sqrt{\frac{2}{\gamma(\gamma - 1)}}$$

for air ($\gamma = 1.4$)

$$\lim_{\frac{\rho_2}{\rho_1}\to\infty} M_{\rho} \to 1.89$$

Note that $h_{O_1} \neq h_{O_2}$

constant total enthalpy is only valid for stationary shocks!

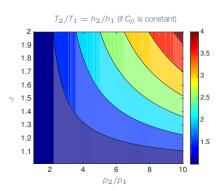
shock is uniquely defined by pressure ratio p_2/p_1

$$u_{1} = 0$$

$$h_{o_{1}} = h_{1} + \frac{1}{2}u_{1}^{2} = h_{1}$$

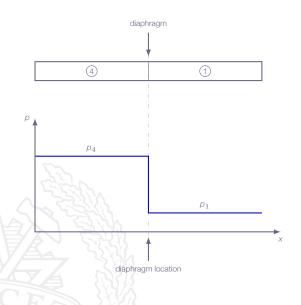
$$h_{o_{2}} = h_{2} + \frac{1}{2}u_{2}^{2}$$

$$h_{2} > h_{1} \Rightarrow h_{o_{2}} > h_{o_{1}}$$



The Shock Tube

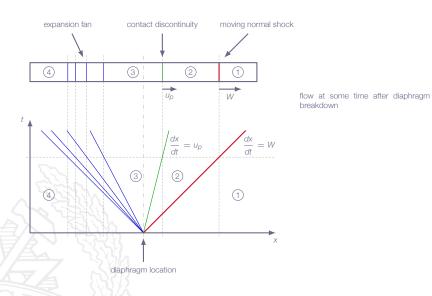


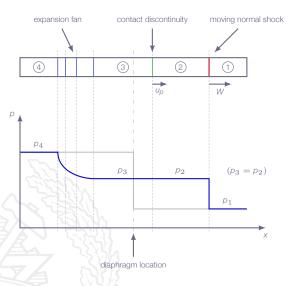


tube with closed ends diaphragm inside, separating two different constant states (could also be two different gases)

if diaphragm is removed suddenly (by inducing a breakdown) the two states come into contact and a flow develops

assume that $p_4 > p_1$: state 4 is "driver" section state 1 is "driven" section

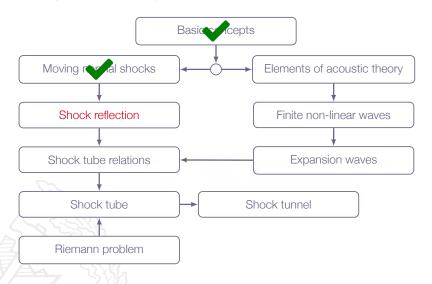




flow at some time after diaphragm breakdown

- ▶ By using light gases for the driver section (e.g. He) and heavier gases for the driven section (e.g. air) the pressure p_4 required for a specific p_2/p_1 ratio is significantly reduced
- If T_4/T_1 is increased, the pressure p_4 required for a specific p_2/p_1 is also reduced

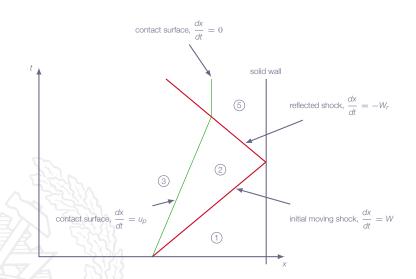
Roadmap - Unsteady Wave Motion



Chapter 7.3 Reflected Shock Wave



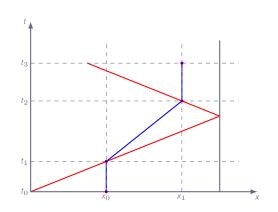
Shock Reflection



Shock Reflection - Particle Path

A fluid particle located at x_0 at time t_0 (a location ahead of the shock) will be affected by the moving shock and follow the blue path

time	location	velocity
t_0	X_0	0
t_1	X_0	$U_{\mathcal{D}}$
t_2	X_1	U_p
t_3	<i>X</i> ₁	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\



Shock Reflection Relations

- velocity ahead of reflected shock: $W_r + u_p$
- ▶ velocity behind reflected shock: W_r

Continuity:

$$\rho_2(W_r + u_p) = \rho_5 W_r$$

Momentum:

$$p_2 + \rho_2 (W_r + u_p)^2 = p_5 + \rho_5 W_r^2$$

Energy:

$$h_2 + \frac{1}{2}(W_r + u_p)^2 = h_5 + \frac{1}{2}W_r^2$$

Shock Reflection Relations

Reflected shock is determined such that $u_5 = 0$

$$\frac{M_r}{M_r^2 - 1} = \frac{M_s}{M_s^2 - 1} \sqrt{1 + \frac{2(\gamma - 1)}{(\gamma + 1)^2} (M_s^2 - 1) \left(\gamma + \frac{1}{M_s^2}\right)}$$

where

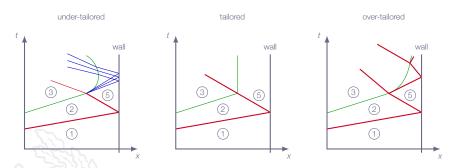
$$M_r = \frac{W_r + u_p}{a_2}$$

Tailored v.s. Non-Tailored Shock Reflection

- ► The time duration of condition 5 is determined by what happens after interaction between reflected shock and contact discontinuity
- For special choice of initial conditions (tailored case), this interaction is negligible, thus prolonging the duration of condition 5

Tailored v.s. Non-Tailored Shock Reflection

shock wave contact surface expansion wave



Under-tailored conditions:

Mach number of incident wave lower than in tailored conditions

Over-tailored conditions:

Mach number of incident wave higher than in tailored conditions

Shock Reflection - Example

Shock reflection in shock tube ($\gamma=1.4$) (Example 7.1 in Anderson)

Incident shock (given data)

$$p_2/p_1$$
 10.0
 M_s 2.95
 T_2/T_1 2.623
 p_1 1.0 [bar]
 T_1 300.0 [K]

Calculated data

$$M_r$$
 2.09
Table A.2
 p_5/p_2 4.978
 T_5/T_2 1.77

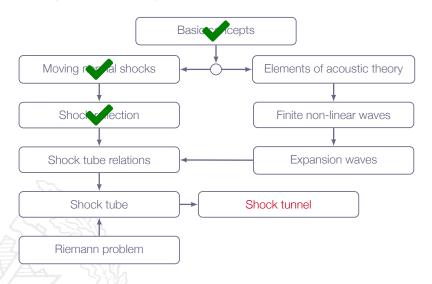
$$\rho_5 = \left(\frac{\rho_5}{\rho_2}\right) \left(\frac{\rho_2}{\rho_1}\right) \rho_1 = 49.78$$

$$T_5 = \left(\frac{T_5}{T_2}\right) \left(\frac{T_2}{T_1}\right) T_1 = 1393$$

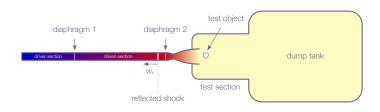
Shock Reflection - Shock Tube

- ▶ Very high pressure and temperature conditions in a specified location with very high precision (p_5 , T_5)
 - measurements of thermodynamic properties of various gases at extreme conditions, e.g. dissociation energies, molecular relaxation times, etc.
 - measurements of chemical reaction properties of various gas mixtures at extreme conditions

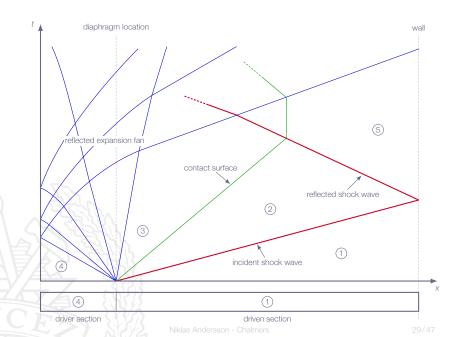
Roadmap - Unsteady Wave Motion



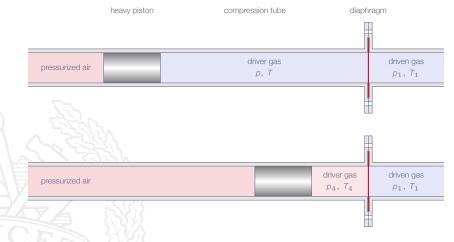
- Addition of a convergent-divergent nozzle to a shock tube configuration
- Capable of producing flow conditions which are close to those during the reentry of a space vehicles into the earth's atmosphere
 - high-enthalpy, hypersonic flows (short time)
 - real gas effects
- Example Aachen TH2:
 - velocities up to 4 km/s
 - stagnation temperatures of several thousand degrees



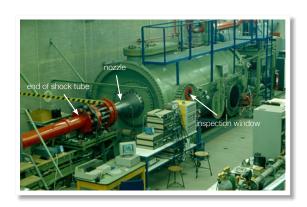
- 1. High pressure in region 4 (driver section)
 - diaphragm 1 burst
 - primary shock generated
- 2. Primary shock reaches end of shock tube
 - shock reflection
- 3. High pressure in region 5
 - diaphragm 2 burst
 - nozzle flow initiated
 - hypersonic flow in test section



By adding a compression tube to the shock tube a very high p_4 and T_4 may be achieved for any gas in a fairly simple manner



Shock tunnel built 1975



Shock tube specifications:

diameter
driver section
driven section
diaphragm 1
diaphragm 2
max operating (steady) pressure

6.0 m 15.4 m 10 mm stainless steel copper/brass sheet

1500 bar

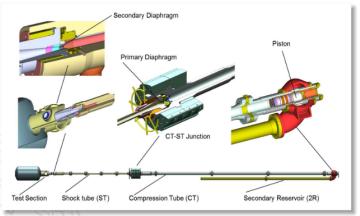
140 mm

- ► Driver gas (usually helium):
 - ▶ 100 bar $< p_4 < 1500$ bar
 - electrical preheating (optional) to 600 K
- ▶ Driven gas:
 - \triangleright 0.1 bar $< p_1 < 10$ bar
- Dump tank evacuated before test

$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	initial conditions		shock		reservoir		free stream				
370 500 1.0 4.6 26 175 2500 7.4 250 2350 20.0 720 500 0.7 5.6 50 325 3650 6.8 460 3910 42.0 1200 500 0.6 6.8 50 560 4600 6.5 700 3400 73.0 100 293 0.9 3.4 12 65 1500 11.3 60 1780 0.6 450 500 1.2 4.9 29 225 2700 11.3 120 2480 1.5 1300 520 0.7 6.4 46 630 4600 12.1 220 3560 1.2 26 293 0.2 3.4 12 15 1500 11.4 60 1780 0.1 480 500 0.2 6.6 50 210 4600 11.0 270 3630 0.7 100				M _S				M_{∞}			
	370 720 1200 100 450 1300 26 480 100	500 500 500 293 500 520 293 500 293	1.0 0.7 0.6 0.9 1.2 0.7 0.2 0.2 1.0	4.6 5.6 6.8 3.4 4.9 6.4 3.4 6.6 3.4	26 50 50 12 29 46 12 50	175 325 560 65 225 630 15 210 65	2500 3650 4600 1500 2700 4600 1500 4600 1500	7.4 6.8 6.5 11.3 12.1 11.4 11.0 7.7	250 460 700 60 120 220 60 270 130	2350 3910 3400 1780 2480 3560 1780 3630 1750	20.0 42.0 73.0 0.6 1.5 1.2 0.1 0.7 7.3

The Caltech Shock Tunnel - T5

Free-piston shock tunnel



The Caltech Shock Tunnel - T5

- Compression tube (CT):
 - length 30 m, diameter 300 mm
 - ► free piston (120 kg)
 - max piston velocity: 300 m/s
 - driven by compressed air (80 bar 150 bar)
- Shock tube (ST):
 - length 12 m, diameter 90 mm
 - driver gas: helium + argon
 - driven gas: air
 - diaphragm 1: 7 mm stainless steel
 - p₄ max 1300 bar

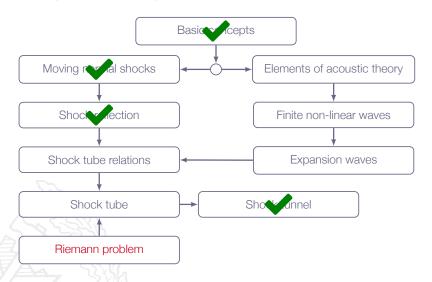
The Caltech Shock Tunnel - T5

- ▶ Reservoir conditions:
 - ▶ p₅ 1000 bar
 - ► T₅ 10000 K
- ► Freestream conditions (design conditions):
 - ► M_∞ 5.2
 - T_{∞} 2000 K
 - $p_{\infty} = 0.3$ bar
 - typical test time 1 ms

Other Examples of Shock Tunnels



Roadmap - Unsteady Wave Motion



Riemann Problem

The shock tube problem is a special case of the general Riemann Problem

"... A Riemann problem, named after Bernhard Riemann, consists of an initial value problem composed by a conservation equation together with piecewise constant data having a single discontinuity ..."

Wikipedia

Riemann Problem

May show that solutions to the shock tube problem have the general form:

$$\rho = \rho(x/t)$$

$$\rho = \rho(x/t)$$

$$u = u(x/t)$$

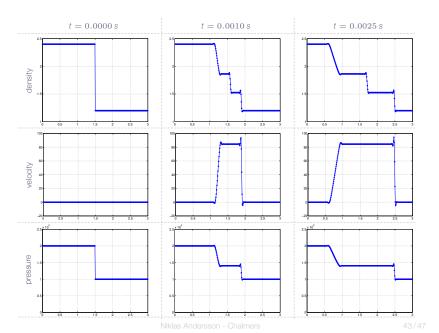
$$T = T(x/t)$$

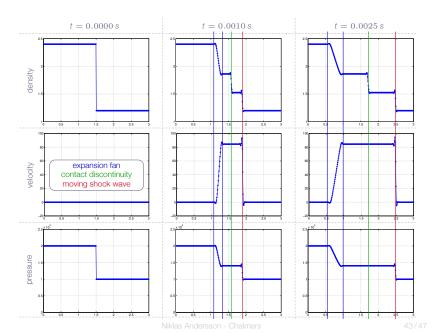
a = a(x/t)

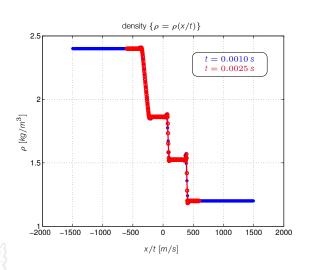
where x = 0 denotes the position of the initial jump between states 1 and 4

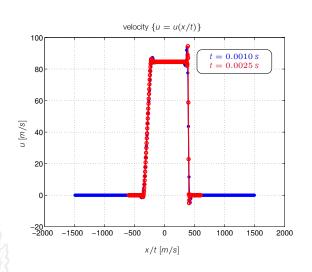
Shock tube simulation:

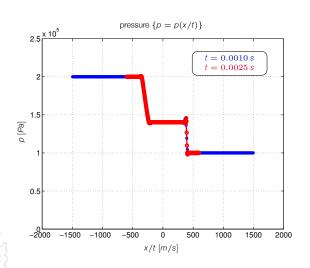
- left side conditions (state 4):
 - $\rho = 2.4 \, kg/m^3$
 - $u = 0.0 \, \text{m/s}$
 - \triangleright p=2.0 bar
- ▶ right side conditions (state 1):
 - $\rho = 1.2 \, \text{kg/m}^3$
 - $u = 0.0 \, m/s$
 - $p = 1.0 \, bar$
- Numerical method
 - Finite-Volume Method (FVM) solver
 - three-stage Runge-Kutta time stepping
 - third-order characteristic upwinding scheme
 - local artificial damping











Roadmap - Unsteady Wave Motion

