LARGE EDDY SIMULATION (LES)

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THREE-DAY CFD COURSE AT CHALMERS

This lecture is a condensed version of the course

- Unsteady Simulations for Industrial Flows: LES, DES, hybrid LES-RANS and URANS
- 5-7 November 2012 at Chalmers, Gothenburg, Sweden
- Max 16 participants
- 50% lectures and 50% workshops in front of a PC
- For info, see http://www.tfd.chalmers.se/~lada/cfdkurs/cfdkurs.html

LECTURE NOTES

 The slides are partly based on the course material at (click here) http://www.tfd.chalmers.se/~lada/

comp_turb_model/lecture_notes.html

- This course is part of the MSc programme **Applied Mechanics** at Chalmers. For Fluid courses, click here http://www.tfd.chalmers.se/~lada/ msc/msc-programme.html
- The MSc programme is presented here http://www.chalmers.se/en/education/programmes/mast

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- In LES, large (Grid) Scales (GS) are resolved and the small (Sub-Grid) Scales (SGS) are modelled.
- LES is suitable for bluff body flows where the flow is governed by large turbulent scales

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BLUFF-BODY FLOW: SURFACE-MOUNTED CUBE[14] Krajnović & Davidson (AIAA J., 2002)



Snapshots of large turbulent scales illustrated by $Q = -\frac{\partial \bar{u}_i}{\partial x_i} \frac{\partial \bar{u}_j}{\partial x_i}$

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BLUFF-BODY FLOW: FLOW AROUND A BUS[15]





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BLUFF-BODY FLOW: FLOW AROUND A TRAIN[12]



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TIME-AVERAGED flow and INSTANTANEOUS flow

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- TIME-AVERAGED flow and INSTANTANEOUS flow
- In average there is backflow (negative velocities). Instantaneous, the negative velocities are often positive.



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- Is it reasonable to require a turbulence model to fix this?
- Isn't it better to RESOLVE the large fluctuations?

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TIME AVERAGING AND FILTERING

RANS: time average. This is called Reynolds time averaging:

$$\langle \Phi \rangle = \frac{1}{2T} \int_{-T}^{T} \Phi(t) dt, \ \Phi = \langle \Phi \rangle + \Phi'$$

In LES we filter (volume average) the equations. In 1D we get:



EQUATIONS

- The filtering is defined by the discretization (nothing is done)
- The filtered Navier-Stokes (N-S) eqns, i.e. the LES eqns, read

$$\frac{\partial \bar{u}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\bar{u}_i \bar{u}_j \right) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{u}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \frac{\partial \bar{u}_i}{\partial x_i} = 0$$
(2)

where the subgrid stresses are given by

$$\tau_{ij} = \overline{u_i u_j} - \overline{u}_i \overline{u}_j$$

Contrary to Reynolds time averaging where $\langle u'_i \rangle = 0$, we have here

$$\overline{u_i''} \neq 0$$
 $\overline{\overline{u}}_i \neq \overline{u}_i$

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FILTERING: HOW IS EQ. 2 OBTAINED?

- The N-S eqns are filtered (=discretized) using Eq. 1
- The pressure gradient term, for example, reads

$$\frac{\overline{\partial p}}{\partial x_i} = \frac{1}{V} \int_V \frac{\partial p}{\partial x_i} dV$$

- Now we want to move the derivative out of the integral. It is allowed if *V* is constant.
- The filtering volume, V=grid cell which is not constant
- Fortunately, the error is proportional to V^2 , i.e. it is 2nd-order error $\overline{\frac{\partial p}{\partial x_i}} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O} \left(V^2 \right) = \frac{\partial}{\partial x_i} (\bar{p}) + \mathcal{O} \left(V^2 \right)$

All linear terms are treated in the same way.

NON-LINEAR TERM

First we filter the term and move the derivative out of the integral

$$\frac{\overline{\partial u_i u_j}}{\partial x_j} = \frac{\partial}{\partial x_j} \left(\frac{1}{V} \int_V u_i u_j dV \right) + \mathcal{O}\left(V^2\right) = \frac{\partial}{\partial x_j} (\overline{u_i u_j}) + \mathcal{O}\left(V^2\right)$$

• We have
$$\frac{\partial}{\partial x_j} \overline{u_i u_j}$$
; we want $\frac{\partial}{\partial x_j} \overline{u}_i \overline{u}_j$

- Let's add want we want (on both LHS ans RHS) and subtract want we don't want
- This is how we end up with the convective term and the SGS term in Eq. 2, i.e. $-\frac{\partial \tau_{ij}}{\partial x_i} = -\frac{\partial}{\partial x_i} (\overline{u_i u_j} \overline{u}_i \overline{u}_j)$

LARGE EDDY SIMULATIONS



• Large scales (GS) are resolved; small scales (SGS) are modelled.

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ENERGY SPECTRUM

The limit (cut-off) between GS and SGS is supposed to take place in the inertial subrange (II)



SUBGRID MODEL

- We need a subgrid model for the SGS turbulent scales
- The simplest model is the Smagorinsky model [23]:

$$\tau_{ij} - \frac{1}{3} \delta_{ij} \tau_{kk} = -2\nu_{sgs} \bar{s}_{ij}$$

$$\nu_{sgs} = (C_S \Delta)^2 \sqrt{2 \bar{s}_{ij} \bar{s}_{ij}} \equiv (C_S \Delta)^2 |\bar{s}| \qquad (3)$$

$$\bar{s}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right), \quad \Delta = (\Delta V_{IJK})^{1/3}$$

- A damping function f_{μ} is added to ensure that $\nu_{sgs} \Rightarrow 0$ as $y \Rightarrow 0$ $f_{\mu} = 1 - \exp(-y^+/26)$
- A more convenient way to dampen the SGS viscosity near the wall is

$$\Delta = \min\left\{\left(\Delta V_{IJK}\right)^{1/3}, \kappa y\right\}$$

where y is the distance to the nearest wall.

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SMAGORINSKY MODEL VS. MIXING-LENGTH MODEL

• The eddy viscosity in the mixing length model reads in boundary-layer flow [13, 22]

$$\nu_t = \ell^2 \left| \frac{\partial U}{\partial y} \right|$$

• Generalized to three dimensions, we have

$$\nu_t = \ell^2 \left[\left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) \frac{\partial U_i}{\partial x_j} \right]^{1/2} = \ell^2 \left(2S_{ij}S_{ij} \right)^{1/2} \equiv \ell^2 |S|.$$

• In the Smagorinsky model the SGS length scale $\ell = C_S \Delta$ i.e.

$$u_{sgs} = (C_S \Delta)^2 |\bar{s}|$$

which is the same as Eq. 3

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LES vs. RANS

LES can handle many flows which RANS (<u>Reynolds Averaged Navier</u> <u>Stokes</u>) cannot; the reason is that in LES large, turbulent scales are resolved. Examples are:

- o Flows with large separation
- *o* Bluff-body flows (e.g. flow around a car); the wake often includes large, unsteady, turbulent structures
- o Transition
- In RANS all turbulent scales are modelled \Rightarrow inaccurate
- In LES only small, isotropic turbulent scales are modelled \Rightarrow <u>accurate</u> LES is *very* much more expensive than RANS.

FINITE VOLUME RANS AND LES CODES.

	RANS	LES
Domain	2D or 3D	always 3D
Time domain	steady or unsteady	always unsteady
Space discretization	2nd order upwind	central differencing
Time discretization	1st order	2nd order (e.g. C-N)
Turbulence model	\geq two-equations	zero- or one-eq

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TIME AVERAGING IN LES

- t1: Start time averaging
- t₂: Stop time averaging



 Biggest problem with LES: near walls, it requires very fine mesh in all directions, not only in the near-wall direction.

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- In the presentation we use Hybrid LES-RANS for which the grid requirements are much smaller than for LES

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 In RANS when using wall-functions, 30 < y⁺ < 100 for the wall-adjacent cells



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- In RANS when using wall-functions, 30 < y⁺ < 100 for the wall-adjacent cells
- In LES, $\Delta z^+ \simeq 30$ EVERYWHERE
- AND $\Delta x^+ \simeq 100$, $\Delta y^+_{min} \simeq 1$





NEAR-WALL TREATMENT



NEAR-WALL TREATMENT



- Fluctuating streamwise velocity at $y^+ = 5$. DNS of channel flow.
- We find that the structures in the spanwise direction are very small which requires a very fine mesh in *z* direction.

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ZONAL PANS MODEL

L. Davidson A New Approach of Zonal Hybrid RANS-LES Based on a Two-equation $k - \varepsilon$ Model [7] ETMM9, Thessaloniki, 7-9 June 2012

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PANS LOW REYNOLDS NUMBER MODEL [17]

$$\begin{split} \frac{\partial k}{\partial t} &+ \frac{\partial (kU_j)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{ku}} \right) \frac{\partial k}{\partial x_j} \right] + (P_k - \varepsilon) \\ \frac{\partial \varepsilon}{\partial t} &+ \frac{\partial (\varepsilon U_j)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{\varepsilon 1} P_k \frac{\varepsilon}{k} - C_{\varepsilon 2}^* \frac{\varepsilon^2}{k} \\ \nu_t &= C_\mu f_\mu \frac{k^2}{\varepsilon}, C_{\varepsilon 2}^* = C_{\varepsilon 1} + \frac{f_k}{f_\varepsilon} (C_{\varepsilon 2} f_2 - C_{\varepsilon 1}), \sigma_{ku} \equiv \sigma_k \frac{f_k^2}{f_\varepsilon}, \sigma_{\varepsilon u} \equiv \sigma_\varepsilon \frac{f_k^2}{f_\varepsilon} \end{split}$$

 $C_{\varepsilon 1}$, $C_{\varepsilon 2}$, σ_k , σ_{ε} and C_{μ} same values as [1]. $f_{\varepsilon} = 1$. f_2 and f_{μ} read

$$f_{2} = \left[1 - \exp\left(-\frac{y^{*}}{3.1}\right)\right]^{2} \left\{1 - 0.3\exp\left[-\left(\frac{R_{t}}{6.5}\right)^{2}\right]\right\}$$
$$f_{\mu} = \left[1 - \exp\left(-\frac{y^{*}}{14}\right)\right]^{2} \left\{1 + \frac{5}{R_{t}^{3/4}}\exp\left[-\left(\frac{R_{t}}{200}\right)^{2}\right]\right\}$$

• Baseline model: $f_k = 0.4$. Range of $0.2 < f_k < 0.6$ is evaluated

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CHANNEL FLOW: ZONAL RANS-LES $k_{u,int}, \varepsilon_{u,int}$ LES, $f_k < 1$ RANS, $f_k = 1.0$ ywall

Χ

- Interface: how to treat k and ε over the interface? They should be reduced from their RANS values to suitable LES values
- The usual convection and diffusion across the interface is cut off, and new "interface boundary" conditions are prescribed
- $k_{u,int} = f_k k_{RANS}$
- Nothing is done for ε
- x_{max} = 3.2 (64 cells), z_{max} = 1.6 (64 cells), y dir: 80 128 cells
- CDS in entire region

 $(N_x \times N_z) = (64 \times 64). y_{int}^+ = 500$



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INTERFACE LOCATION. $Re_{\tau} = 8000$.



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EFFECT OF f_k . $Re_{\tau} = 16\,000$. $y_{int}^+ = 500$



 $f_k = 0.2$ $f_k = 0.3$ $f_k = 0.5$ $f_k = 0.6$

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EFFECT OF RESOLUTION: VELOCITY



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EFFECT OF RESOLUTION: RESOLVED SHEAR STRESS



EFFECT OF RESOLUTION: TURBULENT VISCOSITY



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• When the grid is refined, ν_t gets smaller





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• $\varepsilon_{sgs,\Delta} = \varepsilon_{sgs,0.5\Delta}$

•
$$\varepsilon_{sgs} = 2 \langle \nu_t \bar{s}_{ij} \bar{s}_{ij} \rangle - \langle \tau_{12,t} \rangle \frac{\partial \langle \bar{u} \rangle}{\partial y}$$

- Grid refinement ⇒ must be accompanied with larger s
 _{ij}s
 _{ij}
- $\Rightarrow \bar{s}_{ij}\bar{s}_{ij}$ must take place at higher wavenumbers
- if not ⇒ grid dependent

Power Density Spectra of $\nu_t^{0.5} \frac{\partial \bar{w}'}{\partial z}$



SGS DISSIPATION VS. WAVENUMBER

• Energy spectra of the SGS dissipation show that the peak takes place at surprisingly low wavenumber (length scale corresponding to 10 cells or more).



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 Energy spectra of the SGS dissipation show that the peak takes place at surprisingly low wavenumber (length scale corresponding to 10 cells or more).



SGS DISSIPATION, $Re_{\tau} = 8000$

• SGS dissipation in the $\bar{u}'_i \bar{u}'_i / 2$ eq, $\varepsilon_{sgs} = 2 \langle \nu_t \bar{s}_{ij} \bar{s}_{ij} \rangle - \langle \tau_{12,t} \rangle \frac{\partial \langle \bar{u} \rangle}{\partial v}$



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LOCAL EQUILIBRIUM. $Re_{\tau} = 4000, N_x \times N_z = 64 \times 64.$



Left vertical axes: URANS region; right vertical axes: LES region.

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• How can both the k eq. and ε be in local equilibrium??

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$$\langle \boldsymbol{P}_{\boldsymbol{k}} \rangle = \langle \varepsilon \rangle$$

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$$\langle \boldsymbol{P}_{\boldsymbol{k}} \rangle = \langle \varepsilon \rangle$$

then

$$C_1 \frac{\langle \varepsilon \rangle}{\langle k \rangle} \langle P_k \rangle \neq C_2^* \frac{\langle \varepsilon \rangle^2}{\langle k \rangle}$$
, because $C_1 \neq C_2^*$

LOCAL EQUILIBRIUM IN ε Equation.

• How can both the k eq. and ε be in local equilibrium?? If

$$\langle \boldsymbol{P}_{\boldsymbol{k}} \rangle = \langle \varepsilon \rangle$$

then

$$C_1 \frac{\langle \varepsilon \rangle}{\langle k \rangle} \langle P_k \rangle \neq C_2^* \frac{\langle \varepsilon \rangle^2}{\langle k \rangle}$$
, because $C_1 \neq C_2^*$

However, the previous slide shows

$$C_1\left\langle \frac{\varepsilon}{k}P_k\right\rangle = C_2^*\left\langle \frac{\varepsilon^2}{k}\right\rangle$$

LOCAL EQUILIBRIUM IN ε EQUATION.

• How can both the k eq. and ε be in local equilibrium?? If

$$\langle \boldsymbol{P}_{\boldsymbol{k}} \rangle = \langle \varepsilon \rangle$$

then

$$C_1 \frac{\langle \varepsilon \rangle}{\langle k \rangle} \langle P_k \rangle \neq C_2^* \frac{\langle \varepsilon \rangle^2}{\langle k \rangle}$$
, because $C_1 \neq C_2^*$

However, the previous slide shows

$$C_1\left\langle \frac{\varepsilon}{k}P_k\right\rangle = C_2^*\left\langle \frac{\varepsilon^2}{k}\right\rangle$$

• Answer: when time-averaging $\langle ab \rangle \neq \langle a \rangle \langle b \rangle$

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• The answer is because of time averaging ($\langle ab \rangle < \langle a \rangle \langle b \rangle$, (see below)



RESOLVED AND MODELLED TURBULENT KINETIC ENERGY.



The Sec. 74

CONCLUDING REMARKS

- LRN PANS works well as zonal LES-RANS model for very high Re_{τ} (> 32 000)
- The model gives grid independent results
- The location of the interface is not important (it should not be too close to the wall)
- Values of $0.2 < f_k < 0.5$ have little impact on the results

HYBRID LES-RANS

Near walls: a RANS one-eq. k or a $k - \omega$ model. In core region: a LES one-eq. k_{SGS} model.



Location of interface either pre-defined or automatically computed

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MOMENTUM EQUATIONS

• The Navier-Stokes, time-averaged in the near-wall regions and filtered in the core region, reads

$$\frac{\partial \bar{u}_{i}}{\partial t} + \frac{\partial}{\partial x_{j}} \left(\bar{u}_{i} \bar{u}_{j} \right) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_{i}} + \frac{\partial}{\partial x_{j}} \left[(\nu + \nu_{T}) \frac{\partial \bar{u}_{i}}{\partial x_{j}} \right]$$
$$\nu_{T} = \nu_{t}, \mathbf{y} \leq \mathbf{y}_{ml}$$
$$\nu_{T} = \nu_{sgs}, \mathbf{y} \geq \mathbf{y}_{ml}$$

• The equation above: URANS or LES? Same boundary conditions ⇒ same solution!

TURBULENCE MODEL

Use one-equation model in both URANS region and LES region.

$$\frac{\partial k_T}{\partial t} + \frac{\partial}{\partial x_j} (\bar{u}_j k_T) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_T) \frac{\partial k_T}{\partial x_j} \right] + P_{k_T} - C_{\varepsilon} \frac{k_T^{3/2}}{\ell}$$
$$P_{k_T} = 2\nu_T \bar{S}_{ij} \bar{S}_{ij}, \ \nu_T = C_k \ell k_T^{1/2}$$

- LES-region: $k_T = k_{sgs}$, $\nu_T = \nu_{sgs}$, $\ell = \Delta = (\delta V)^{1/3}$
- URANS-region: $k_T = k$, $\nu_T = \nu_t$, $\ell \equiv \ell_{RANS} = 2.5n[1 - \exp(-Ak^{1/2}y/\nu)]$, Chen-Patel model (AIAA J. 1988)
- Location of interface can be defined by $\min(0.65\Delta, y)$, $\Delta = \max(\Delta x, \Delta y, \Delta z)$

DIFFUSER[9]

- Instantaneous inlet data from channel DNS used.
- Domain: $-8 \le x \le 48, 0 \le y_{inlet} \le 1, 0 \le z \le 4$.
- x_{max} = 40 gave return flow at the outlet
- Grid: $258 \times 66 \times 32$.
- $Re = U_{in}H/\nu = 18\ 000$, angle 10^{o}
- The grid is much too coarse for LES (in the inlet region $\Delta z^+ \simeq$ 170)
- Matching plane fixed at y_{ml} at the inlet. In the diffuser it is located along the 2D instantaneous streamline corresponding to y_{ml} .

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DIFFUSER: RESULTS WITH LES

• Velocities. Markers: experiments by Buice & Eaton (1997)



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$k - \omega$ model SST-DES

- DES [24]: Detached Eddy Simulation
- SST [18, 19]: A combination of the $k \varepsilon$ and the $k \omega$ model

$$\frac{\partial k}{\partial t} + \frac{\partial}{\partial x_j} (\bar{u}_j k) = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right] + P_k - \beta^* k \omega$$
$$\frac{\partial \omega}{\partial t} + \frac{\partial}{\partial x_j} (\bar{u}_j \omega) = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_\omega} \right) \frac{\partial \omega}{\partial x_j} \right] + \alpha \frac{P_k}{\nu_t} - \beta \omega^2 + \dots$$

• The dissipation term in the k equation is modified as [19, 25]

$$\beta^* k \omega \to \beta^* k \omega F_{DES}, \quad F_{DES} = \max\left\{\frac{L_t}{C_{DES}\Delta}, 1\right\}$$
$$\Delta = \max\left\{\Delta x_1, \Delta x_2, \Delta x_3\right\}, \quad L_t = \frac{k^{1/2}}{\beta^* \omega}$$

⇒ RANS near walls and LES away from walls

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- For the near-wall region, we know how fine the mesh should be in terms of viscous units (see Slide 22)
- An appropriate resolution for the fully turbulent part of the boundary layer is $\delta/\Delta x \simeq 10 20$ and $\delta/\Delta z \simeq 20 40$
- This may be relevant also for jets and shear layers

HOW TO ESTIMATE RESOLUTION IN GENERAL? [4, 5]

- Energy spectra (both in spanwise direction and time)
- Two-point correlations
- Ratio of SGS turbulent kinetic energy $\langle k_{sgs} \rangle$ to resolved $0.5 \langle u'u' + v'v' + w'w' \rangle$
- Ratio of SGS shear stress $\langle \tau_{sgs,12} \rangle$ to resolved $\langle u'v' \rangle$
- Ratio of SGS viscosity, $\langle \nu_{sgs} \rangle$ to molecular, ν
- Energy spectra of SGS dissipation
- Comparison of SGS dissipation due to $\partial u'_i / \partial x_i$ and $\partial \langle \bar{u}_i \rangle / \partial x_i$





Two-point correlation is better

• Shows that $2\Delta z$ and $2\Delta x$ (two-point corr in x) are too coarse.

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• Pope [20] suggests $\gamma > 0.8$ indicates well resolved flow ($\Delta x, \Delta z$) ____ 0.5 Δx ____ 0.5 Δz • 2 Δx ; +: 2 Δz

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• Pope [20] suggests $\gamma > 0.8$ indicates well resolved flow ($\Delta x, \Delta z$) ____ 0.5 Δx ____ 0.5 Δz $\circ 2\Delta x$; +: 2 Δz

Pope criterion does not work here

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SGS VS. MOLECULAR VISCOSITY [5]



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SGS VS. RESOLVED SHEAR STRESSES



 $N_z = 32;$ $N_z = 64;$ $N_z = 128.$

THE PANS MODEL

- The PANS model is a modified $k \varepsilon$ model
- It can operate both in RANS mode and LES mode
- In the present work a low-Reynolds turbulence version of the PANS is used
- A method how to implement embedded LES is proposed
- It is evaluated for channel flow and hump flow

Embedded LES Using PANS [10, 11] Lars Davidson¹ and Shia-Hui Peng^{1,2} Davidson& Peng

¹Department of Applied Mechanics Chalmers University of Technology, SE-412 96 Gothenburg, SWEDEN ²FOI, Swedish Defence Research Agency, SE-164 90, Stockholm, SWEDEN

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PANS LOW REYNOLDS NUMBER MODEL [17]

$$\begin{aligned} \frac{\partial k_{u}}{\partial t} &+ \frac{\partial (k_{u} U_{j})}{\partial x_{j}} = \frac{\partial}{\partial x_{j}} \left[\left(\nu + \frac{\nu_{u}}{\sigma_{ku}} \right) \frac{\partial k_{u}}{\partial x_{j}} \right] + (P_{u} - \varepsilon_{u}) \\ \frac{\partial \varepsilon_{u}}{\partial t} &+ \frac{\partial (\varepsilon_{u} U_{j})}{\partial x_{j}} = \frac{\partial}{\partial x_{j}} \left[\left(\nu + \frac{\nu_{u}}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon_{u}}{\partial x_{j}} \right] + C_{\varepsilon 1} P_{u} \frac{\varepsilon_{u}}{k_{u}} - C_{\varepsilon 2}^{*} \frac{\varepsilon_{u}^{2}}{k_{u}} \\ \nu_{u} &= C_{\mu} f_{\mu} \frac{k_{u}^{2}}{\varepsilon_{u}}, C_{\varepsilon 2}^{*} = C_{\varepsilon 1} + \frac{f_{k}}{f_{\varepsilon}} (C_{\varepsilon 2} f_{2} - C_{\varepsilon 1}), \sigma_{ku} \equiv \sigma_{k} \frac{f_{k}^{2}}{f_{\varepsilon}}, \sigma_{\varepsilon u} \equiv \sigma_{\varepsilon} \frac{f_{k}^{2}}{f_{\varepsilon}} \end{aligned}$$

 $C_{\varepsilon 1}, C_{\varepsilon 2}, \sigma_k, \sigma_{\varepsilon}$ and C_{μ} same values as [1]. $f_{\varepsilon} = 1$. f_2 and f_{μ} read

$$f_{2} = \left[1 - \exp\left(-\frac{y^{*}}{3.1}\right)\right]^{2} \left\{1 - 0.3\exp\left[-\left(\frac{R_{t}}{6.5}\right)^{2}\right]\right\}$$
$$f_{\mu} = \left[1 - \exp\left(-\frac{y^{*}}{14}\right)\right]^{2} \left\{1 + \frac{5}{R_{t}^{3/4}}\exp\left[-\left(\frac{R_{t}}{200}\right)^{2}\right]\right\}$$

• Baseline model: $f_k = 0.4$. Range of $0.2 < f_k < 0.6$ is evaluated

CHANNEL FLOW: DOMAIN



- Interface: Synthetic turbulent fluctuations are introduced as additional convective fluxes in the momentum equations and the continuity equation
- $f_k = 0.4$ is the baseline value for LES [17]

INLET FLUCTUATIONS



- Anisotropic synthetic fluctuations, u', v', w',
- Integral length scale $\mathcal{L} \simeq 0.13$ (see 2-p point correlation)
- Asymmetric time filter $(\mathcal{U}')^m = a(\mathcal{U}')^{m-1} + b(u')^m$ with $a = 0.954, b = (1 a^2)^{1/2}$ gives a time integral scale $\mathcal{T} = 0.015$ $(\Delta t = 0.00063)$

INTERFACE CONDITIONS FOR k_u and ε_u

- For k_u & ε_u we prescribe "inlet" boundary conditions at the interface.
- First, the usual convective and diffusive fluxes at the interface are set to zero
- Next, new convective fluxes are added. Which "inlet" values should be used at the interface?

►
$$k_{u,int} = f_k k_{RANS}(x = 0.5\delta), \ \varepsilon_{u,int} = C_{\mu}^{3/4} k_{u,int}^{3/2} / \ell_{sgs}, \ \ell_{sgs} = C_s \Delta,$$

 $\Delta = V^{1/3}$

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$$k_{u,int} = f_k k_{RANS}(x = 0.5\delta), \ \varepsilon_{u,int} = C_{\mu}^{3/4} k_{u,int}^{3/2} / \ell_{sgs}, \ \ell_{sgs} = C_s \Delta,$$

 $\Delta = V^{1/3}$

• Baseline $C_s = 0.07$; different C_s values are tested

CHANNEL FLOW: VELOCITY AND SHEAR STRESSES



CHANNEL FLOW: STRESSES AND PEAK VALUES VS. X



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CHANNEL FLOW: DIFFERENT C_s VALUE FOR $\varepsilon_{interface}$



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CHANNEL FLOW: DIFFERENT C_s VALUE FOR $\varepsilon_{interface}$



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CHANNEL FLOW: DIFFERENT f_k VALUES



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CHANNEL FLOW: DIFFERENT f_k VALUES





• Inlet, Separation $x_S/c = 0.65$; reattachment $x_R/c = 1.1$

•
$$Re_c = 936\,000 \frac{U_{ij}c}{\nu} (U_{in} = c = \rho = 1, \nu = 1/Re_c)$$

• Mesh: $312 \times 120 \times 64$, $Z_{max} = 0.2c$ (baseline)

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BASELINE INLET FLUCTUATIONS



- Integral length scale $\mathcal{L} \simeq 0.04$ (see 2-p point correlation)
- Asymmetric time filter $(\mathcal{U}')^m = a(\mathcal{U}')^{m-1} + b(u')^m$ with $a = 0.954, b = (1 a^2)^{1/2}$ gives a time integral scale $\mathcal{T} = 0.038$
- $\Delta t = 0.002$. 7500 + 7500 time steps (100 hours one core)
- Fluctuations multiplied by $f_{bl} = \max \{ 0.5 [1 - \tanh(y - y_{bl} - y_{wall})/b], 0.02 \}, y_{bl} = 0.2, b = 0.01.$

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PRESSURE: AMPLITUDES OF INLET FLUCT



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SKIN FRICTION: AMPLITUDES OF INLET FLUCT





VELOCITIES: AMPLITUDES OF INLET FLUCT



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SHEAR STRESSES: AMPLITUDES OF INLET FLUCT





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TURB VISCOSITY: AMPLITUDES OF INLET FLUCT



baseline ____ 1.5× (baseline) ____ 0.5× (baseline)

PRESSURE: $f_k = 0.5$; NO INLET FLUCT; $N_k = 128$



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Skin Friction: $f_k = 0.5$; no inlet fluct; $N_k = 128$



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Helsinki 4 October 2012 84/1 Velocities: $f_k = 0.5$; no inlet fluct; $N_k = 128$



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Shear stresses: $f_k = 0.5$; no inlet fluct; $N_k = 128$

• Resolved and Modelled (< 0) Shear stresses



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TURB VISCOSITY: $f_k = 0.5$; no inlet fluct; $N_k = 128$



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CONCLUDING REMARKS

- LRN PANS has been shown to work well as an embedded LES method
- Channel flow: At two δ downstream the interface, the resolved turbulence in good agreement with DNS data and the wall friction velocity has reached 99% of its fully developed value.
- Channel flow: The treatment of the modelled k_u and ε_u across the interface is important.
- LRN PANS predicts the hump flow well but the recover rate sligtly too slow
- Hump flow: large (small) inlet fluctuations gives a smaller (larger) recirculation

4 3 5 4 3 5 5

• Embedded LES with $k - \varepsilon$ PANS and Synthetic b.c.

- Embedded LES with $k \varepsilon$ PANS and Synthetic b.c.
- Channel flow

- Embedded LES with $k \varepsilon$ PANS and Synthetic b.c.
- Channel flow
 - Isotropic fluctuations work well for channel flow

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- Channel flow
 - Isotropic fluctuations work well for channel flow
 - Strong dependence on interface $k_u \& \varepsilon_u$ values

- Embedded LES with $k \varepsilon$ PANS and Synthetic b.c.
- Channel flow
 - Isotropic fluctuations work well for channel flow
 - Strong dependence on interface $k_u \& \varepsilon_u$ values
 - No strong dependence on amplitude, L or T of fluctuations

Hump flow

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Hump flow

 PANS & synthetic inlet b.c. with f_k everywhere gives good results except C_f (error > 50%)

Hump flow

- PANS & synthetic inlet b.c. with f_k everywhere gives good results except C_f (error > 50%)
- With embedded isotropic fluctuations, interface must be located far upstream

Hump flow

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- With embedded isotropic fluctuations, interface must be located far upstream
- ► With embedded anisotropic fluctuations, good results are obtained, still poor C_f

Hump flow

- PANS & synthetic inlet b.c. with f_k everywhere gives good results except C_f (error > 50%)
- With embedded isotropic fluctuations, interface must be located far upstream
- ► With embedded anisotropic fluctuations, good results are obtained, still poor C_f
- On-going work ...

Large Eddy Simulation of Heat Transfer in Boundary layer and Backstep Flow Using PANS [6]

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Lars Davidson THMT-12, Palermo, Sept 2012 PANS LOW REYNOLDS NUMBER MODEL [17]

$$\begin{split} \frac{\partial k_{u}}{\partial t} &+ \frac{\partial (k_{u} U_{j})}{\partial x_{j}} = \frac{\partial}{\partial x_{j}} \left[\left(\nu + \frac{\nu_{u}}{\sigma_{ku}} \right) \frac{\partial k_{u}}{\partial x_{j}} \right] + (P_{u} - \varepsilon_{u}) \\ \frac{\partial \varepsilon_{u}}{\partial t} &+ \frac{\partial (\varepsilon_{u} U_{j})}{\partial x_{j}} = \frac{\partial}{\partial x_{j}} \left[\left(\nu + \frac{\nu_{u}}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon_{u}}{\partial x_{j}} \right] + C_{\varepsilon 1} P_{u} \frac{\varepsilon_{u}}{k_{u}} - C_{\varepsilon 2}^{*} \frac{\varepsilon_{u}^{2}}{k_{u}} \\ \nu_{u} &= C_{\mu} f_{\mu} \frac{k_{u}^{2}}{\varepsilon_{u}}, C_{\varepsilon 2}^{*} = C_{\varepsilon 1} + \frac{f_{k}}{f_{\varepsilon}} (C_{\varepsilon 2} f_{2} - C_{\varepsilon 1}), \sigma_{ku} \equiv \sigma_{k} \frac{f_{k}^{2}}{f_{\varepsilon}}, \sigma_{\varepsilon u} \equiv \sigma_{\varepsilon} \frac{f_{k}^{2}}{f_{\varepsilon}} \end{split}$$

 $C_{\varepsilon 1}$, $C_{\varepsilon 2}$, σ_k , σ_{ε} and C_{μ} same values as [1]. $f_{\varepsilon} = 1$. f_2 and f_{μ} read

$$f_{2} = \left[1 - \exp\left(-\frac{y^{*}}{3.1}\right)\right]^{2} \left\{1 - 0.3\exp\left[-\left(\frac{R_{t}}{6.5}\right)^{2}\right]\right\}$$
$$f_{\mu} = \left[1 - \exp\left(-\frac{y^{*}}{14}\right)\right]^{2} \left\{1 + \frac{5}{R_{t}^{3/4}}\exp\left[-\left(\frac{R_{t}}{200}\right)^{2}\right]\right\}$$

• Baseline model: $f_k = 0.4$.

NUMERICAL METHOD

- Incompressible finite volume method
- Pressure-velocity coupling treated with fractional step
- Differencing scheme for momentum eqns:
 - 95% 2nd order central and 5% 2nd order upwind differencing scheme (baseline) OR
 - 100% 2nd order central differencing
- Hybrid 1st order upwind/2nd order central scheme $k \& \varepsilon$ eqns.
- 2nd-order Crank-Nicholson for time discretization



- Inlet: $\delta_{inlet} = 1$ (covered by 45 cells), $Re_{\theta} = 3600$, $U_{in} = \rho = 1$. Stretching 1.12 up to $y/\delta \simeq 1$.
- Domain: $L/\delta_{in} = 3.2, H/\delta_{in} = 15.6, Z_{max} = 1.5\delta_{in}$
- Resolution: $\Delta z_{in}^+ \simeq$ 27, $\Delta x_{in}^+ \simeq$ 54
- Grid: 66 × 96 × 64 (*x*, *y*, *z*)

ANISOTROPIC SYNTHETIC FLUCTUATIONS: I [3, 2, 8]

- Prescribe an homogeneous Reynolds tensor, <u>uiuj</u> (here from DNS)
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ANISOTROPIC SYNTHETIC FLUCTUATIONS: I [3, 2, 8]



- Prescribe an homogeneous Reynolds tensor, <u>u</u>_i<u>u</u>_j (here from DNS)
- isotropic fluctuations in principal directions, $(u'_1u'_1)_{\lambda} = (u'_2u'_2)_{\lambda}$, $u'_{1,\lambda}u'_{2,\lambda} = 0$
- ۲

ANISOTROPIC SYNTHETIC FLUCTUATIONS: I [3, 2, 8]



- Prescribe an homogeneous Reynolds tensor, <u>u</u>_i<u>u</u>_j (here from DNS)
- isotropic fluctuations in principal directions, $(u'_1u'_1)_{\lambda} = (u'_2u'_2)_{\lambda}$, $u'_{1,\lambda}u'_{2,\lambda} = 0$
- re-scale the normal components, $(u_1'u_1')_{\lambda} > (u_2'u_2')_{\lambda}$, $u_{1,\lambda}'u_{2,\lambda}' = 0$

ANISOTROPIC SYNTHETIC FLUCTUATIONS: II

- Transform from $(x_{1,\lambda}, x_{2,\lambda})$ to (x_1, x_2)
- $\frac{u_1'^2}{u_2'^2} = 23$, $\frac{u_1'^2}{u_3'^2} = 5$ from $(u_1'u_1')_{peak}$ in DNS channel flow, $Re_{\tau} = 500$

INLET CONDITIONS FOR k_u and ε_u as in [10]

• A pre-cursor RANS simulation using the AKN model (i.e. PANS with $f_k = 1$) is carried out. At $Re_{\theta} = 3600$, U_{RANS} , V_{RANS} , k_{RANS} are taken.

•
$$\bar{u}_{in} = U_{RANS} + u'_{synt}, \ \bar{v}_{in} = V_{RANS} + v'_{synt}, \ \bar{w}_{in} = w'_{synt}$$

 Anisotropic synthetic fluctuations are used. The fluctuations are scaled with k_u/k_{u,max}.

•
$$k_{u,in} = f_k k_{RANS}$$
, $\varepsilon_{u,in} = C_{\mu}^{3/4} k_{u,in}^{3/2} / \ell_{sgs}$, $\ell_{sgs} = C_s \Delta$, $\Delta = V^{1/3}$, $C_s = 0.05$

INLET TURB. FLUCTUATION, TWO-POINT CORRELATIONS



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REYNOLDS STRESSES



BACKWARD FACING STEP: DOMAIN



Re_H = 28 000 Experiments by Vogel & Eaton [26]

- Mean inlet profiles from RANS (same as in boundary layer)
- Grid: 336×120 in $x \times y$ plane. $Z_{max} = 1.6H$, $N_k = 64$, $\Delta z_{in}^+ = 31$.
- Anisotropic synthetic fluctuations, u', v', w' (same as for boundary layer flow); no fluctuations for t'
- Constant heat flux, q_w, on lower wall.

BACKSTEP FLOW. SKIN FRICTION AND STANTON NUMBER



PANS; PANS, 50% smaller inlet fluctuations; WALE; •: PANS, no inlet fluctuations; ---: 2D RANS; •,•: experiments [26].

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BACKSTEP FLOW: VELOCITIES.



PANS; PANS, 50% smaller inlet fluctuations; WALE;

•: PANS, no inlet fluctuations; ---: 2D RANS; o: experiments [26].

BACKSTEP FLOW: RESOLVED STREAMWISE STRESS.



PANS; PANS, 50% smaller inlet fluctuations; WALE;

•: PANS, no inlet fluctuations; ---: 2D RANS; o: experiments [26].

BACKSTEP FLOW: TURBULENT VISCOSITIES.



PANS; PANS, 50% smaller inlet fluctuations; WALE;

•: PANS, no inlet fluctuations; ---: 2D RANS/10;

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FORWARD/BACKWARD FLOW

 Fraction of time, γ, when the flow along the bottom wall is in the downstream direction.



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SHEAR STRESSES. x = 3.2H


Shear Stresses. x = 14.86



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TERMS IN THE $\langle \bar{u} \rangle$ EQUATION. x = 3.2H



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Terms in the $\langle \bar{u} \rangle$ Equation. x = 14.86H



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HEAT FLUXES. x = 3.2H



HEAT FLUXES. x = 14.86H



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TERMS IN THE $\langle \overline{T} \rangle$ EQUATION. x = 3.2H



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TERMS IN THE $\langle \overline{T} \rangle$ EQUATION. x = 14.86H



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CONCLUDING REMARKS

Developing boundary layer

- Synthetic fluctuations give fully developed conditions after a couple of boundary layer thicknesses
- 5% upwinding dampens resolved fluctuations; can be compensated by 25% larger inlet fluctuations
- Backstep flow
 - Very good agreement with experiments
 - 2D RANS predicts turbulent diffusion surprisingly well
 - Synthetic inlet fluctuations give an improved Stanton number; otherwise small effect in the reciculation region
 - LRN PANS and WALE equally good
 - ► 5% upwinding has a negligble effect in the recirculation region

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