LES, HYBRID LES-RANS AND SCALE-ADAPTIVE SIMULATIONS (SAS)

Lars Davidson, www.tfd.chalmers.se/~lada



- In LES, large (Grid) Scales (GS) are resolved and the small (Sub-Grid) Scales (SGS) are modelled.
- LES is suitable for bluff body flows where the flow is governed by large turbulent scales

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BLUFF-BODY FLOW: SURFACE-MOUNTED CUBE[1] Krajnović & Davidson (AIAA J., 2002)



Snapshots of large turbulent scales illustrated by $Q = -\frac{\partial \bar{u}_i}{\partial x_i} \frac{\partial \bar{u}_j}{\partial x_i}$

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BLUFF-BODY FLOW: FLOW AROUND A BUS[2]



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BLUFF-BODY FLOW: FLOW AROUND A CAR[3]



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BLUFF-BODY FLOW: FLOW AROUND A TRAIN[4]



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TIME-AVERAGED flow and INSTANTANEOUS flow

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- How easy is it to model fluctuations that are as large as the mean flow?
- Is it reasonable to require a turbulence model to fix this?
- Isn't it better to RESOLVE the large fluctuations?

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- The object is to develop a near-wall treatment which models the streaks (URANS) ⇒ much larger Δx and Δz
- In the presentation we use Hybrid LES-RANS for which the grid requirements are much smaller than for LES

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- Fluctuating streamwise velocity at $y^+ = 5$. DNS of channel flow.
- We find that the structures in the spanwise direction are very small which requires a very fine mesh in *z* direction.

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HYBRID LES-RANS

Near walls: a RANS one-eq. k or a $k - \omega$ model. In core region: a LES one-eq. k_{SGS} model.



Location of interface either pre-defined or automatically computed

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MOMENTUM EQUATIONS

• The Navier-Stokes, time-averaged in the near-wall regions and filtered in the core region, reads

$$\frac{\partial \bar{u}_{i}}{\partial t} + \frac{\partial}{\partial x_{j}} \left(\bar{u}_{i} \bar{u}_{j} \right) = \beta \delta_{1i} - \frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_{i}} + \frac{\partial}{\partial x_{j}} \left[(\nu + \nu_{T}) \frac{\partial \bar{u}_{i}}{\partial x_{j}} \right]$$
$$\nu_{T} = \nu_{t}, \mathbf{y} \leq \mathbf{y}_{ml}$$
$$\nu_{T} = \nu_{sgs}, \mathbf{y} \geq \mathbf{y}_{ml}$$

• The equation above: URANS or LES? Same boundary conditions ⇒ same solution!

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TURBULENCE MODEL

Use one-equation model in both URANS region and LES region.

$$\frac{\partial k_T}{\partial t} + \frac{\partial}{\partial x_j} (\bar{u}_j k_T) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_T) \frac{\partial k_T}{\partial x_j} \right] + P_{k_T} - C_{\varepsilon} \frac{k_T^{3/2}}{\ell}$$
$$P_{k_T} = 2\nu_T \bar{S}_{ij} \bar{S}_{ij}, \ \nu_T = C_k \ell k_T^{1/2}$$

- LES-region: $k_T = k_{sgs}$, $\nu_T = \nu_{sgs}$, $\ell = \Delta = (\delta V)^{1/3}$
- URANS-region: $k_T = k$, $\nu_T = \nu_t$, $\ell \equiv \ell_{RANS} = 2.5n[1 - \exp(-Ak^{1/2}y/\nu)]$, Chen-Patel model (AIAA J. 1988)
- Location of interface can be defined by $\min(0.65\Delta, y)$, $\Delta = \max(\Delta x, \Delta y, \Delta z)$

STANDARD HYBRID LES-RANS

• Coarse mesh: $\Delta x^+ = 2\Delta z^+ = 785$. $\delta/\Delta x \simeq 2.5$, $\delta/\Delta z \simeq 5$.



Too high velocity because too low shear stress

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WAYS TO IMPROVE THE RANS-LES METHOD[5, 6, 7]

- The reason is that LES region is supplied with bad boundary (i.e. interface) conditions by the URANS region.
- The flow going from the RANS region into the LES region has no proper turbulent length or time scales
- New approach: Synthesized isotropic turbulent fluctuations are added as momentum sources at the interface.
- The superimposed fluctuations should be regarded as forcing functions rather than boundary conditions.

FORCING FLUCTUATIONS ADDED AT THE INTERFACE

• Object: to trig the momentum equations into resolving large-scale turbulence



• For more info, see Davidson at al. [5, 7]

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IMPLEMENTATION



Fluctuations u'_f, v'_f, w'_f are added as sources in all three momentum equations. The source is

 −γρu'_{i,f}u'_{2,f}A_n = −γρu'_{i,f}u'_{2,f}V/Δy (A_n=area, V=volume of the C.V.)

 The source is scaled with γ = k_T/k_{svnt}

• The could be could with $f = R_f$

INLET BOUNDARY CONDITIONS U_{inlet} constant in time; u_{inlet} function of time.



Left: Inlet boundary profiles

Right: Evolution of *u* velocity depending of type of inlet B.C.

• With steady inlet B.C., *u* gets turbulent first at $x = x_E$.

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- $U_{in}+u'_{i}(t)$ used as B.C. for LES in the inner region.
- Examples of inner region: external mirror of a car; a flap/slat; a detail of a landing gear. Often in connection with aero-acoustics.

INLET BOUNDARY CONDITIONS VS. FORCING



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FULLY DEVELOPED CHANNEL FLOW (PERIODIC IN X)



no forcing; ____ forcing (isotropic fluctuations) $\circ 0.4 \ln(y^+) + 5.2$

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DIFFUSER[5]

- Instantaneous inlet data from channel DNS used.
- Domain: $-8 \le x \le 48, 0 \le y_{inlet} \le 1, 0 \le z \le 4$.
- $x_{max} = 40$ gave return flow at the outlet
- Grid: $258 \times 66 \times 32$.
- $Re = U_{in}H/\nu = 18\ 000$, angle 10^{o}
- The grid is much too coarse for LES (in the inlet region $\Delta z^+ \simeq$ 170)
- Matching plane fixed at y_{ml} at the inlet. In the diffuser it is located along the 2D instantaneous streamline corresponding to y_{ml} .



DIFFUSER: RESULTS WITH LES

Velocities. Markers: experiments by Buice & Eaton (1997)



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DIFFUSER: RESULTS WITH NEW RANS-LES



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RANS-LES: LOCATION OF MATCHING LINE



• Location of matching line. It is defined along 2D instantaneous streamline (defined by mass flow).

$$U_{b,in,k}y_{ml,in,k}\Delta z = \sum_{2}^{j_{ml,i,k}} (\bar{u}_e A_{e,x} + \bar{v}_e A_{e,y})$$

- This approach has successfully been used for asymmetric plane diffuser as well as 3D hill (Simpson & Byun)
- Other option: $\min(0.65\Delta, y)$, $\Delta = \max(\Delta x, \Delta y, \Delta z)$

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3D-HILL



NUMERICAL METHOD

- Implicit, finite volume (collocated),
- Central differencing in space and time (Crank-Nicolson (α = 0.6))
- Efficient multigrid solver for the pressure Poisson equation
- CPU/time step 25 seconds on a single AMD Opteron 244
- Time step $\Delta t U_{in}/H = 0.026$. Mesh $160 \times 80 \times 128$
- 8000 + 8000 time steps for fully developed+averaging (10 + 10 through flow or $T^* = TU_b/H = 200 + 200$)
- One simulation (8000 + 8000) takes one week

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3D HILL: RANS



• Similar results obtained with all other RANS models ($k - \omega$, Low-Re RSM, EARSM, SA-model etc) [9].

Image: Image:

STREAMWISE PROFILES AT x = 3.69H [8]



Hybrid LES-RANS; • Experiments

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SECONDARY VELOCITY VECTORS AT x = 3.69HHybrid LES-RANS



SECONDARY VELOCITY VECTORS AT x = 3.69HRANS, SST



RANS SST: STREAMWISE PROFILES AT x = 3.69H



RANS-SST; • Experiments

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3D HILL: SUMMARY

- All RANS models give a completely incorrect flow field
- LES and hybrid LES-RANS in good agreement with expts.
- Mesh sizes RANS
 U.5 – 1.2 million (half of the domain) Hybrid LES-RANS
 1.7 million
- CPU times RANS, EARSM 1 – 2 days LES-RANS 1 week (10+10 T-F)* 1-CPU DEC-Alpha 1 week (10+10 T-F)* 1-CPU Opteron 244
- * T-F=Through-Flows
- Hybrid LES-RANS results in Ref. [8]

MODELLED DISSIPATION, ε_M

The unsteady Navier-Stokes reads

$$\frac{\partial \bar{u}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\bar{u}_i \bar{u}_j \right) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \frac{\partial}{\partial x_j} \left[\left(\nu + \nu_T \right) \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right) \right]$$

The turbulent viscosity, ν_T , dampens the fluctuations, via the modelled dissipation, ε_M , which reads



STEADY VS. UNSTEADY REGIONS

$$\frac{\partial \bar{u}_{i}}{\partial t} + \frac{\partial}{\partial x_{j}} \left(\bar{u}_{i} \bar{u}_{j} \right) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_{i}} + \frac{\partial}{\partial x_{j}} \left[\left(\nu + \nu_{T} \right) \left(\frac{\partial \bar{u}_{i}}{\partial x_{j}} + \frac{\partial \bar{u}_{j}}{\partial x_{i}} \right) \right]$$

BJECT:

- In regions of fine grid: turbulence resolved by \bar{u}'_i , i.e. $\frac{\partial \bar{u}_i}{\partial t}$
- $\bullet\,$ In regions of coarse grid: turbulence modelled by $\nu_{\mathcal{T}}$
- **PROBLEM**: in fine-grid regions, ν_T increases too much which kills \bar{u}'_i
- SOLUTION: when \bar{u}'_i starts to grow, reduce ν_T

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VON KÁRMÁN LENGTH SCALE



• The von Kármán detects unsteadiness (i.e. resolved turbulence, \bar{u}'_i) and reduces the length scale

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THE SAS TURBULENCE MODEL[10, 11, 12]

$$\frac{Dk}{Dt} - \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right] = \nu_t \bar{s}^2 - c_1 k \omega$$

$$\underbrace{\frac{D\omega}{Dt} - \left[\left(\nu + \frac{\nu_t}{\sigma_\omega} \right) \frac{\partial \omega}{\partial x_j} \right]}_{\text{transport}} = c_2 \bar{s}^2 - c_3 \omega^2 + P_{SAS}$$

$$\nu_t = c_4 \frac{k}{\omega}, \quad P_{SAS} = c_5 \frac{L}{L_{\nu K, 3D}}, \quad L_{\nu K, 3D} = c_6 \frac{\bar{s}}{U''}$$

• Fine grid \Rightarrow unsteadiness \Rightarrow small $L_{vK,3D} \Rightarrow$ large $P_{SAS} \Rightarrow$ large $\omega \Rightarrow$ small k and low ν_t

SAS: Scale-Adapated Simulation

SAS: EVALUATION FROM DNS CHANNEL DATA

• $Re_{\tau} = 500, \Delta x^+ = 50, \Delta z^+ = 12, y^+_{min} = 0.3$



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DOMAIN, $Re_{\tau} = u_{\tau}\delta/\nu = 2000 \ (Re_b \simeq 80\,000)$



• 256 × 64 × 32 (*x*, *y*, *z*) cells. $z_{max} = 6.3\delta$, $\Delta x^+ \simeq 785$, $\Delta z^+ \simeq 393$.

- $\delta/\Delta z \simeq$ 5, $\delta/\Delta x \simeq$ 2.5
- MODELS: SAS and no SAS

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CHANNEL WITH INLET-OUTLET

• Synthesized inlet fluctuations $(\mathcal{U}')^m$, $(\mathcal{V}')^m$, $(\mathcal{W}')^m$ with time scale $\mathcal{T} = 0.2\delta/u_{\tau}$ and length scale $\mathcal{L} = 0.1\delta$.

• The streamwise fluctuations are superimposed to a mean profile obtained from 1D channel flow with $k - \omega$ model

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MEAN VELOCITY



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RESOLVED URMS



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PEAK RESOLVED FLUCTUATIONS



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TURBULENT VISCOSITY $\langle \nu_t \rangle / \nu$



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EVALUATION OF THE SECOND DERIVATIVE

• Option I: (used) compute the first derivatives at the faces

$$\begin{pmatrix} \frac{\partial u}{\partial y} \end{pmatrix}_{j+1/2} = \frac{u_{j+1} - u_j}{\Delta y}, \qquad \left(\frac{\partial u}{\partial y} \right)_{j-1/2} = \frac{u_j - u_{j-1}}{\Delta y}$$
$$\Rightarrow \left(\frac{\partial^2 u}{\partial y^2} \right)_j = \frac{u_{j+1} - 2u_j + u_{j-1}}{(\Delta y)^2} + \frac{(\Delta y)^2}{12} \frac{\partial^4 u}{\partial y^4}$$

Option II: compute the first derivatives at the centre

$$\begin{pmatrix} \frac{\partial u}{\partial y} \end{pmatrix}_{j+1} = \frac{u_{j+2} - u_j}{2\Delta y}, \qquad \left(\frac{\partial u}{\partial y} \right)_{j-1} = \frac{u_j - u_{j-2}}{2\Delta y}$$
$$\Rightarrow \left(\frac{\partial^2 u}{\partial y^2} \right)_j = \frac{u_{j+2} - 2u_j + u_{j-2}}{4(\Delta y)^2} + \frac{(\Delta y)^2}{3} \frac{\partial^4 u}{\partial y^4}$$

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SECOND DERIVATIVES



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SAS: CONCLUSIONS

- SAS: A model which controls the modelled dissipation, ε_M, has been presented
- It detects unsteadiness and then reduces ε_M
- In this way the model let the equations resolve the turbulence instead of modelling it
- The results is improved accuracy because of less modelling
- More details in [13]

CONCLUSIONS

- Flows with large turbulence fluctuations difficult to model with RANS models because $u' \simeq \overline{u}$
- Unsteady methods (URANS, DES, SAS, Hybrid LES-RANS, LES) are increasingly being used in universities as well as in industry
- LES is a suitable method for bluff body flows
- Methods based on a mixture of LES and RANS are likely to be the methods of the future
- For boundary layers $(Re_x \to \infty)$ some kind of forcing needed when going from (U)RANS region to LES region
- Fluctuating inlet boundary conditions can be regarded as a special case of forcing

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