

On-line Lecture 1

¶ See Section 11.1.1, Flow equations

► Boussinesq approximation: density variation only in gravitation (buoyancy) term

$$\frac{\partial \rho_0 \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\rho_0 \bar{v}_i \bar{v}_j) = -\frac{\partial \bar{p}}{\partial x_i} + \mu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \rho_0 \frac{\partial \overline{v'_i v'_j}}{\partial x_j} - \rho_0 \beta (\bar{\theta} - \theta_0) g_i$$

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\bar{p} is hydrodynamic pressure: $\rho f_i \rightarrow (\rho - \rho_0) g_i$

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$$d\rho = \left(\frac{\partial \rho}{\partial \theta} \right)_p d\theta + \left(\frac{\partial \rho}{\partial p} \right)_\theta dp$$

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$$\rho_0 f_i = (\rho - \rho_0) g_i = -\rho_0 \beta (\bar{\theta} - \theta_0) g_i$$

¶ See Section 11.1.2, Temperature equation

▶ Temperature equation

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▶ Temperature equation

$$\frac{\partial \theta}{\partial t} + \frac{\partial v_i \theta}{\partial x_i} = \alpha \frac{\partial^2 \theta}{\partial x_i \partial x_i}$$

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▶ Temperature equation

$$\frac{\partial \theta}{\partial t} + \frac{\partial v_i \theta}{\partial x_i} = \alpha \frac{\partial^2 \theta}{\partial x_i \partial x_i}$$

where $\alpha = k/(\rho c_p)$.

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► Temperature equation

$$\frac{\partial \theta}{\partial t} + \frac{\partial v_i \theta}{\partial x_i} = \alpha \frac{\partial^2 \theta}{\partial x_i \partial x_i}$$

where $\alpha = k/(\rho c_p)$.

Introducing $\theta = \bar{\theta} + \theta'$ gives the mean temperature equation

$$\frac{\partial \bar{v}_i \bar{\theta}}{\partial x_i} = \alpha \frac{\partial^2 \bar{\theta}}{\partial x_i \partial x_i} - \overline{\frac{\partial v_i' \theta'}{\partial x_i}} \quad (30.1)$$

► Total (viscous plus turbulent) flux: momentum and temperature equation

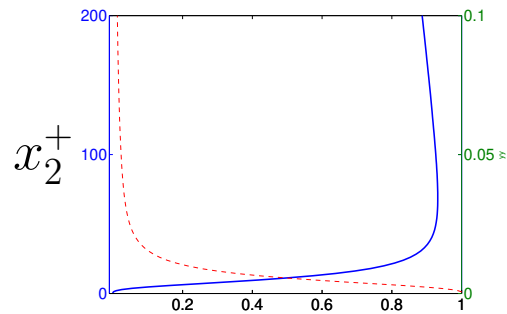
$$-\frac{q_{2,tot}}{\rho c_p} = -\frac{q_{2,visc}}{\rho c_p} - \frac{q_{2,turb}}{\rho c_p} = \alpha \frac{\partial \bar{\theta}}{\partial x_2} - \overline{v'_2 \theta'}, \quad \alpha = \frac{k}{\rho c_p}$$

$$\tau_{tot} = \tau_{visc} + \tau_{turb} = \mu \frac{\partial \bar{v}_1}{\partial x_2} - \overline{\rho v'_1 v'_2}$$

► Total (viscous plus turbulent) flux: momentum and temperature equation

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Reynolds shear stress.

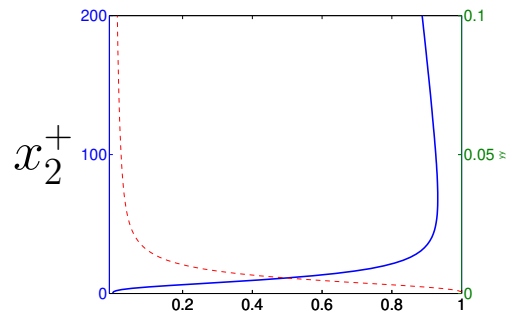
—: $-\overline{\rho v'_1 v'_2} / \tau_w$

- -: $\mu (\partial \bar{v}_1 / \partial x_2) / \tau_w$.

► Total (viscous plus turbulent) flux: momentum and temperature equation

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$$\tau_{tot} = \tau_{visc} + \tau_{turb} = \mu \frac{\partial \bar{v}_1}{\partial x_2} - \overline{\rho v_1' v_2'}$$



Reynolds shear stress.

—: $-\overline{\rho v_1' v_2'} / \tau_w$

- -: $\mu (\partial \bar{v}_1 / \partial x_2) / \tau_w$.

¶ See Section 11.2, The exact $\overline{v'_i v'_j}$ equation

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- Set up the momentum equation for the instantaneous velocity $v_i = \bar{v}_i + v'_i \rightarrow$ Eq. (A)

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- Set up the momentum equation for the instantaneous velocity $v_i = \bar{v}_i + v'_i \rightarrow$ Eq. (A)
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- Subtract Eq. (B) from Eq. (A) \rightarrow equation for v'_i , Eq. (C)

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- Set up the momentum equation for the instantaneous velocity $v_i = \bar{v}_i + v'_i \rightarrow$ Eq. (A)
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- Subtract Eq. (B) from Eq. (A) \rightarrow equation for v'_i , Eq. (C)
- Do the same procedure for $v_j \rightarrow$ equation for v'_j , Eq. (D)

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- Set up the momentum equation for the instantaneous velocity $v_i = \bar{v}_i + v'_i \rightarrow$ Eq. (A)
- Time average \rightarrow equation for \bar{v}_i , Eq. (B)
- Subtract Eq. (B) from Eq. (A) \rightarrow equation for v'_i , Eq. (C)
- Do the same procedure for $v_j \rightarrow$ equation for v'_j , Eq. (D)
- Multiply Eq. (C) with v'_j and Eq. (D) with v'_i , time average and add them together \rightarrow equation for $\overline{v'_i v'_j}$

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- Multiply Eq. (C) with v'_j and Eq. (D) with v'_i , time average and add them together \rightarrow equation for $\overline{v'_i v'_j}$

In Section 9 these steps are given in some detail.

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- Set up the momentum equation for the instantaneous velocity $v_i = \bar{v}_i + v'_i \rightarrow$ Eq. (A)
- Time average \rightarrow equation for \bar{v}_i , Eq. (B)
- Subtract Eq. (B) from Eq. (A) \rightarrow equation for v'_i , Eq. (C)
- Do the same procedure for $v_j \rightarrow$ equation for v'_j , Eq. (D)
- Multiply Eq. (C) with v'_j and Eq. (D) with v'_i , time average and add them together \rightarrow equation for $\overline{v'_i v'_j}$

In Section 9 these steps are given in some detail.

The final $\overline{v'_i v'_j}$ -equation (Reynolds Stress equation) reads (see Eq. 9.12)

► $\overline{v'_i v'_j}$ -equation

$$\begin{aligned}
 \underbrace{\overline{\bar{v}_k \frac{\partial v'_i v'_j}{\partial x_k}}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 \underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} &+ \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 \underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} &- \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned} \tag{30.2}$$

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 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{\overline{g_i \beta v'_j \theta'} - g_j \beta v'_i \theta'}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned} \tag{30.2}$$

- Unknown terms

► $\overline{v'_i v'_j}$ -equation

$$\begin{aligned}
 \underbrace{\overline{v_k \frac{\partial v'_i v'_j}{\partial x_k}}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned} \tag{30.2}$$

• Unknown terms

Π_{ij} Pressure-strain

► $\overline{v'_i v'_j}$ -equation

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 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned} \tag{30.2}$$

• Unknown terms

Π_{ij} Pressure-strain

$D_{ij,t}$ Turbulent diffusion

► $\overline{v'_i v'_j}$ -equation

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
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 \end{aligned} \tag{30.2}$$

• Unknown terms

Π_{ij} Pressure-strain

$D_{ij,t}$ Turbulent diffusion

ε_{ij} Dissipation

¶ See Section 11.3, The exact $\overline{v'_i \theta'}$ equation

▶ $\overline{v'_i \theta'}$ equation

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▶ $\overline{v'_i \theta'}$ equation

$$\frac{\partial \theta'}{\partial t} + \frac{\partial}{\partial x_k} (v'_k \bar{\theta} + \bar{v}_k \theta' + v'_k \theta') = \alpha \frac{\partial^2 \theta'}{\partial x_k \partial x_k} - \frac{\partial \overline{v'_k \theta'}}{\partial x_k} \quad (30.3)$$

¶ See Section 11.3, The exact $\overline{v'_i \theta'}$ equation

▶ $\overline{v'_i \theta'}$ equation

$$\frac{\partial \theta'}{\partial t} + \frac{\partial}{\partial x_k} (v'_k \bar{\theta} + \bar{v}_k \theta' + v'_k \theta') = \alpha \frac{\partial^2 \theta'}{\partial x_k \partial x_k} - \frac{\partial \overline{v'_k \theta'}}{\partial x_k} \quad (30.3)$$

$$\frac{\partial v'_i}{\partial t} + \frac{\partial}{\partial x_k} (v'_k \bar{v}_i + \bar{v}_k v'_i + v'_k v'_i) = -\frac{1}{\rho} \frac{\partial p'}{\partial x_i} + \nu \frac{\partial^2 v'_i}{\partial x_k \partial x_k} - \frac{\partial \overline{v'_i v'_j}}{\partial x_k} - g_i \beta \theta' \quad (30.4)$$

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▶ $\overline{v'_i\theta'}$ equation

$$\frac{\partial \theta'}{\partial t} + \frac{\partial}{\partial x_k} (v'_k \bar{\theta} + \bar{v}_k \theta' + v'_k \theta') = \alpha \frac{\partial^2 \theta'}{\partial x_k \partial x_k} - \frac{\partial \overline{v'_k \theta'}}{\partial x_k} \quad (30.3)$$

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Multiply Eq. 30.3 with v'_i and multiply Eq. 30.4 with θ' , add them together and time average

¶ See Section 11.3, The exact $\overline{v'_i \theta'}$ equation

► $\overline{v'_i \theta'}$ equation

$$\frac{\partial \theta'}{\partial t} + \frac{\partial}{\partial x_k} (v'_k \bar{\theta} + \bar{v}_k \theta' + v'_k \theta') = \alpha \frac{\partial^2 \theta'}{\partial x_k \partial x_k} - \frac{\partial \overline{v'_k \theta'}}{\partial x_k} \quad (30.3)$$

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Multiply Eq. 30.3 with v'_i and multiply Eq. 30.4 with θ' , add them together and time average

$$\begin{aligned} & \overline{v'_i \frac{\partial}{\partial x_k} (v'_k \bar{\theta} + \bar{v}_k \theta' + v'_k \theta') + \theta' \frac{\partial}{\partial x_k} (\bar{v}_i v'_k + \bar{v}_k v'_i + v'_i v'_k)} \\ & = -\frac{\overline{\theta' \partial p'}}{\rho \partial x_i} + \alpha \overline{v'_i \frac{\partial^2 \theta'}{\partial x_k \partial x_k}} + \nu \overline{\theta' \frac{\partial^2 v'_i}{\partial x_k \partial x_k}} - g_i \beta \overline{\theta' \theta'} \end{aligned}$$

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► $\overline{v'_i \theta'}$ equation

$$\frac{\partial \theta'}{\partial t} + \frac{\partial}{\partial x_k} (v'_k \bar{\theta} + \bar{v}_k \theta' + v'_k \theta') = \alpha \frac{\partial^2 \theta'}{\partial x_k \partial x_k} - \frac{\partial \overline{v'_k \theta'}}{\partial x_k} \quad (30.3)$$

$$\frac{\partial v'_i}{\partial t} + \frac{\partial}{\partial x_k} (v'_k \bar{v}_i + \bar{v}_k v'_i + v'_k v'_i) = -\frac{1}{\rho} \frac{\partial p'}{\partial x_i} + \nu \frac{\partial^2 v'_i}{\partial x_k \partial x_k} - \frac{\partial \overline{v'_i v'_j}}{\partial x_k} - g_i \beta \theta' \quad (30.4)$$

Multiply Eq. 30.3 with v'_i and multiply Eq. 30.4 with θ' , add them together and time average

$$\begin{aligned} & \overline{v'_i \frac{\partial}{\partial x_k} (v'_k \bar{\theta} + \bar{v}_k \theta' + v'_k \theta') + \theta' \frac{\partial}{\partial x_k} (\bar{v}_i v'_k + \bar{v}_k v'_i + v'_i v'_k)} \\ & = -\frac{\overline{\theta' \partial p'}}{\rho \partial x_i} + \alpha \overline{v'_i \frac{\partial^2 \theta'}{\partial x_k \partial x_k}} + \nu \overline{\theta' \frac{\partial^2 v'_i}{\partial x_k \partial x_k}} - g_i \beta \overline{\theta' \theta'} \end{aligned}$$

$$\begin{aligned}
\frac{\partial}{\partial x_k} \overline{\bar{v}_k v'_i \theta'} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{\theta}}{\partial x_k}}_{P_{i\theta}} - \underbrace{\overline{v'_k \theta'} \frac{\partial \bar{v}_i}{\partial x_k}}_{\Pi_{i\theta}} - \underbrace{\frac{\overline{\theta' \partial p'}}{\rho \partial x_i} - \frac{\partial}{\partial x_k} \overline{v'_k v'_i \theta'}}_{D_{i\theta,t}} \\
&+ (\nu + \alpha) \underbrace{\frac{\partial^2 \overline{v'_i \theta'}}{\partial x_k \partial x_k}}_{D_{i\theta,\nu}} - (\nu + \alpha) \underbrace{\frac{\overline{\partial v'_i} \partial \theta'}{\partial x_k \partial x_k}}_{\varepsilon_{i\theta}} - \underbrace{g_i \beta \overline{\theta'^2}}_{G_{i\theta}}
\end{aligned}$$

- Unknown terms

- Unknown terms

$\Pi_{i\theta}$ Scramble

- Unknown terms

$\Pi_{i\theta}$ Scramble

$D_{i\theta,t}$ Turbulent diffusion

- Unknown terms

$\Pi_{i\theta}$ Scramble

$D_{i\theta,t}$ Turbulent diffusion

$\varepsilon_{i\theta}$ Dissipation

¶ The original derivation of the k equation is shown in Section 8.2.

▶ In 11.4, [The \$k\$ equation](#), we derive the k equation as follows

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$$\begin{aligned} \bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k} &= -\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k} + \overline{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)} - \frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{\overline{p' v'_j}}{\rho} \delta_{ik} + \frac{\overline{p' v'_i}}{\rho} \delta_{jk} \right] \\ &+ \nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k} - g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'} - 2\nu \overline{\frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}} \end{aligned}$$

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$$\underbrace{\bar{v}_j \frac{\partial k}{\partial x_j}}_{C^k} = -\underbrace{\overline{v'_j v'_k} \frac{\partial \bar{v}_j}{\partial x_k}}_{P^k} - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_k \left(\frac{1}{2} v'_i v'_i + \frac{p'}{\rho} \right)} \right]}_{D_t^k} + \nu \underbrace{\frac{\partial^2 k}{\partial x_k \partial x_k}}_{D_\nu^k} - \underbrace{g_i \beta \overline{v'_i \theta'}}_{G^k} - \nu \underbrace{\overline{\frac{\partial v'_i}{\partial x_k} \frac{\partial v'_i}{\partial x_k}}}_{\varepsilon} \quad (30.5)$$

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$\overline{v'_i v'_j}$ Reynolds stress in P^k

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D_t^k Turbulent diffusion

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¶ See Section 11.6, The Boussinesq assumption

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▶ The Boussinesq assumption: a model for $\overline{v'_i v'_j}$

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► The Boussinesq assumption: a model for $\overline{v'_i v'_j}$

The diffusion term of time-averaged Navier-Stokes

$$\frac{\partial}{\partial x_j} \left\{ \nu \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) - \overline{v'_i v'_j} \right\} \Rightarrow \frac{\partial}{\partial x_j} \left\{ (\nu + \nu_t) \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) \right\}$$

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► The Boussinesq assumption: a model for $\overline{v'_i v'_j}$

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$$\overline{v'_i v'_j} = -\nu_t \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right)$$

► When this equation is contracted, the LHS is not zero ($\overline{v'_i v'_i}$) whereas the RHS is zero due to continuity ($v\bar{v}/\partial x_i = 0$)

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▶ The Boussinesq assumption: a model for $\overline{v'_i v'_j}$

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▶ Add $(2/3)\delta_{ij}k$ on the RHS:

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The diffusion term of time-averaged Navier-Stokes

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▶ The turbulent viscosity:

¶ See Section 11.6, [The Boussinesq assumption](#)

▶ The Boussinesq assumption: a model for $\overline{v'_i v'_j}$

The diffusion term of time-averaged Navier-Stokes

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▶ The Boussinesq assumption: a model for $\overline{v'_i v'_j}$

The diffusion term of time-averaged Navier-Stokes

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▶ The Boussinesq assumption: a model for $\overline{v'_i v'_j}$

The diffusion term of time-averaged Navier-Stokes

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On-line Lecture 2

¶ See Section 11.7.1, Production terms

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- First let's repeat the definition of the strain-rate and vorticity tensors, see Eq. 1.11

On-line Lecture 2

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$$\frac{\partial \bar{v}_i}{\partial x_j} = \bar{s}_{ij} + \bar{\Omega}_{ij}, \quad \bar{s}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_j}{\partial x_i} - \frac{\partial \bar{v}_i}{\partial x_j} \right)$$

On-line Lecture 2

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- First let's repeat the definition of the strain-rate and vorticity tensors, see Eq. 1.11

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- Recall that the product $\bar{s}_{ij} \bar{\Omega}_{ij} = 0$ (product of symmetric and anti-symmetric tensor, see Section 1.5)

On-line Lecture 2

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- First let's repeat the definition of the strain-rate and vorticity tensors, see Eq. 1.11

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On-line Lecture 2

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On-line Lecture 2

¶ See Section 11.7.1, Production terms

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$$\frac{\partial \bar{v}_i}{\partial x_j} = \bar{s}_{ij} + \bar{\Omega}_{ij}, \quad \bar{s}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_j}{\partial x_i} - \frac{\partial \bar{v}_i}{\partial x_j} \right)$$

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$$P^k = -\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j} = \nu_t \left[\left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) - \frac{2}{3} \delta_{ij} k \right] \frac{\partial \bar{v}_i}{\partial x_j}$$

On-line Lecture 2

¶ See Section 11.7.1, Production terms

- First let's repeat the definition of the strain-rate and vorticity tensors, see Eq. 1.11

$$\frac{\partial \bar{v}_i}{\partial x_j} = \bar{s}_{ij} + \bar{\Omega}_{ij}, \quad \bar{s}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_j}{\partial x_i} - \frac{\partial \bar{v}_i}{\partial x_j} \right)$$

- Recall that the product $\bar{s}_{ij}\bar{\Omega}_{ij} = 0$ (product of symmetric and anti-symmetric tensor, see Section 1.5)

▶ Production term in k equation needs to be modeled.

$$\begin{aligned} P^k &= -\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j} = \nu_t \left[\left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) - \frac{2}{3} \delta_{ij} k \right] \frac{\partial \bar{v}_i}{\partial x_j} \\ &= \nu_t \left[\left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) \right] \frac{\partial \bar{v}_i}{\partial x_j} - \frac{2}{3} \nu_t \delta_{ij} k \frac{\partial \bar{v}_i}{\partial x_j} \end{aligned}$$

On-line Lecture 2

¶ See Section 11.7.1, Production terms

- First let's repeat the definition of the strain-rate and vorticity tensors, see Eq. 1.11

$$\frac{\partial \bar{v}_i}{\partial x_j} = \bar{s}_{ij} + \bar{\Omega}_{ij}, \quad \bar{s}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_j}{\partial x_i} - \frac{\partial \bar{v}_i}{\partial x_j} \right)$$

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On-line Lecture 2

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On-line Lecture 2

¶ See Section 11.7.1, Production terms

- First let's repeat the definition of the strain-rate and vorticity tensors, see Eq. 1.11

$$\frac{\partial \bar{v}_i}{\partial x_j} = \bar{s}_{ij} + \bar{\Omega}_{ij}, \quad \bar{s}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_j}{\partial x_i} - \frac{\partial \bar{v}_i}{\partial x_j} \right)$$

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On-line Lecture 2

¶ See Section 11.7.1, Production terms

- First let's repeat the definition of the strain-rate and vorticity tensors, see Eq. 1.11

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▶ Diffusion term in k eq, Eq. 30.5, must be modelled.

▶ The exact k equation:

$$\bar{v}_j \frac{\partial k}{\partial x_j} = -\overline{v'_j v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \frac{\partial}{\partial x_k} \left[\overline{v'_k \left(\frac{1}{2} v'_i v'_i + \frac{p'}{\rho} \right)} \right] + \nu \frac{\partial^2 k}{\partial x_k \partial x_k} - g_i \beta \overline{v'_i \theta'} - \nu \overline{\frac{\partial v'_i}{\partial x_k} \frac{\partial v'_i}{\partial x_k}}$$

▶ The constitutive model for heat conduction, Fourier's law, (see Section 2.2)

$$q_i = -k \frac{\partial \bar{\theta}}{\partial x_i}.$$

Flux of k :

▶ Diffusion term in k eq, Eq. 30.5, must be modelled.

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$$d_{j,t}^k = \frac{1}{2} \overline{v'_j v'_i v'_i} = -\frac{\nu_t}{\sigma_k} \frac{\partial k}{\partial x_j}$$

$$\Rightarrow -\frac{1}{2} \overline{\frac{\partial v'_j v'_i v'_i}{\partial x_j}} = \frac{\partial}{\partial x_j} \left(\frac{\nu_t}{\sigma_k} \frac{\partial k}{\partial x_j} \right)$$

► Diffusion term in k eq, Eq. 30.5, must be modelled.

► The exact k equation:

$$\bar{v}_j \frac{\partial k}{\partial x_j} = -\overline{v'_j v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \frac{\partial}{\partial x_k} \left[\overline{v'_k \left(\frac{1}{2} v'_i v'_i + \frac{p'}{\rho} \right)} \right] + \nu \frac{\partial^2 k}{\partial x_k \partial x_k} - g_i \beta \overline{v'_i \theta'} - \nu \overline{\frac{\partial v'_i}{\partial x_k} \frac{\partial v'_i}{\partial x_k}}$$

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► The heat flux is an unknown both in the mean temperature equation, Eq. 30.1, and in the exact k equation above. Taking guidance from Fourier's law . It is modeled as

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$$\bar{v}_j \frac{\partial k}{\partial x_j} = -\overline{v'_j v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \frac{\partial}{\partial x_k} \left[\overline{v'_k \left(\frac{1}{2} v'_i v'_i + \frac{p'}{\rho} \right)} \right] + \nu \frac{\partial^2 k}{\partial x_k \partial x_k} - g_i \beta \overline{v'_i \theta'} - \nu \overline{\frac{\partial v'_i}{\partial x_k} \frac{\partial v'_i}{\partial x_k}}$$

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► The heat flux is an unknown both in the mean temperature equation, Eq. 30.1, and in the exact k equation above. Taking guidance from Fourier's law . It is modeled as

$$\overline{v'_i \theta'} = -\alpha_t \frac{\partial \bar{\theta}}{\partial x_i}, \quad \alpha_t = \frac{\nu_t}{\sigma_t}$$

¶ See Section 11.8, The $k - \varepsilon$ model

¶ See Section 11.8, The $k - \varepsilon$ model

▶ Modeled k equation

¶ See Section 11.8, The $k - \varepsilon$ model

► Modeled k equation

$$\bar{v}_j \frac{\partial k}{\partial x_j} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} + \frac{\partial}{\partial x_j} \left\{ \left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right\} + g_i \beta \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} - \varepsilon$$

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► Modeled k equation

$$\bar{v}_j \frac{\partial k}{\partial x_j} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} + \frac{\partial}{\partial x_j} \left\{ \left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right\} + g_i \beta \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} - \varepsilon$$

► Exact k equation

$$\underbrace{\bar{v}_j \frac{\partial k}{\partial x_j}}_{C^k} = - \underbrace{\overline{v'_j v'_k} \frac{\partial \bar{v}_j}{\partial x_k}}_{P^k} - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_k \left(\frac{1}{2} v'_i v'_i + \frac{p'}{\rho} \right)} \right]}_{D_t^k} + \underbrace{\nu \frac{\partial^2 k}{\partial x_k \partial x_k}}_{D_\nu^k} - \underbrace{g_i \beta \overline{v'_i t \theta'}}_{G^k} - \underbrace{\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_i}{\partial x_k}}_{\varepsilon}$$

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$$\bar{v}_j \frac{\partial k}{\partial x_j} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} + \frac{\partial}{\partial x_j} \left\{ \left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right\} + g_i \beta \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} - \varepsilon$$

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¶ See Section 11.5, The ε equation

► ε equation

¶ See Section 11.8, The $k - \varepsilon$ model

► Modeled k equation

$$\bar{v}_j \frac{\partial k}{\partial x_j} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} + \frac{\partial}{\partial x_j} \left\{ \left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right\} + g_i \beta \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} - \varepsilon$$

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¶ See Section 11.5, The ε equation

► ε equation

$$C^\varepsilon = P^\varepsilon + D^\varepsilon + G^\varepsilon - \Psi^\varepsilon$$

¶ See Section 11.8, The $k - \varepsilon$ model

► Modeled k equation

$$\bar{v}_j \frac{\partial k}{\partial x_j} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} + \frac{\partial}{\partial x_j} \left\{ \left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right\} + g_i \beta \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} - \varepsilon$$

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► ε equation

$$C^\varepsilon = P^\varepsilon + D^\varepsilon + G^\varepsilon - \Psi^\varepsilon$$

Use the same source terms as in k equation and add turbulent time-scale ε/k to get the right dimensions:

$$P^\varepsilon + G^\varepsilon - \Psi^\varepsilon = \frac{\varepsilon}{k} (c_{\varepsilon 1} P^k + c_{\varepsilon 3} G^k - c_{\varepsilon 2} \varepsilon)$$

¶ See Section 11.8, The $k - \varepsilon$ model

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$$\bar{v}_j \frac{\partial k}{\partial x_j} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} + \frac{\partial}{\partial x_j} \left\{ \left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right\} + g_i \beta \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} - \varepsilon$$

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► The final form modelled ε equation

¶ See Section 11.8, The $k - \varepsilon$ model

► Modeled k equation

$$\bar{v}_j \frac{\partial k}{\partial x_j} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} + \frac{\partial}{\partial x_j} \left\{ \left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right\} + g_i \beta \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} - \varepsilon$$

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► The final form modelled ε equation

$$\frac{\partial \varepsilon}{\partial t} + \bar{v}_j \frac{\partial \varepsilon}{\partial x_j} = c_{\varepsilon 1} \frac{\varepsilon}{k} P^k + \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + c_{\varepsilon 3} \frac{\varepsilon}{k} G^k - c_{\varepsilon 2} \frac{\varepsilon}{k} \varepsilon$$

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► Modeled k equation

$$\bar{v}_j \frac{\partial k}{\partial x_j} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} + \frac{\partial}{\partial x_j} \left\{ \left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right\} + g_i \beta \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} - \varepsilon$$

► Exact k equation

$$\underbrace{\bar{v}_j \frac{\partial k}{\partial x_j}}_{C^k} = - \underbrace{\overline{v'_j v'_k} \frac{\partial \bar{v}_j}{\partial x_k}}_{P^k} - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_k \left(\frac{1}{2} v'_i v'_i + \frac{p'}{\rho} \right)} \right]}_{D_t^k} + \underbrace{\nu \frac{\partial^2 k}{\partial x_k \partial x_k}}_{D_\nu^k} - \underbrace{g_i \beta \overline{v'_i t \theta'}}_{G^k} - \underbrace{\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_i}{\partial x_k}}_{\varepsilon}$$

¶ See Section 11.5, The ε equation

► ε equation

$$C^\varepsilon = P^\varepsilon + D^\varepsilon + G^\varepsilon - \Psi^\varepsilon$$

Use the same source terms as in k equation and add turbulent time-scale ε/k to get the right dimensions:

$$P^\varepsilon + G^\varepsilon - \Psi^\varepsilon = \frac{\varepsilon}{k} (c_{\varepsilon 1} P^k + c_{\varepsilon 3} G^k - c_{\varepsilon 2} \varepsilon)$$

► The final form modelled ε equation

$$\frac{\partial \varepsilon}{\partial t} + \bar{v}_j \frac{\partial \varepsilon}{\partial x_j} = c_{\varepsilon 1} \frac{\varepsilon}{k} P^k + \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + c_{\varepsilon 3} \frac{\varepsilon}{k} G^k - c_{\varepsilon 2} \frac{\varepsilon}{k} \varepsilon$$

¶ See Section 11.7.3, Dissipation term, ε_{ij}

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

¶ See Section 11.7.3, Dissipation term, ε_{ij}

$$\begin{aligned}
 \overline{v_k \frac{\partial v'_i v'_j}{\partial x_k}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

► The dissipation term, ε_{ij} , in the $\overline{v'_i v'_j}$ equation (eq. 30.2), is modeled as follows:

See Section 11.7.3, Dissipation term, ε_{ij}

$$\begin{aligned}
 \overline{v_k \frac{\partial v'_i v'_j}{\partial x_k}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

► The dissipation term, ε_{ij} , in the $\overline{v'_i v'_j}$ equation (eq. 30.2), is modeled as follows:
 Small-scale turbulence is isotropic

1.

See Section 11.7.3, Dissipation term, ε_{ij}

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

► The dissipation term, ε_{ij} , in the $\overline{v'_i v'_j}$ equation (eq. 30.2), is modeled as follows:

Small-scale turbulence is isotropic

1. $\overline{v_1'^2} = \overline{v_2'^2} = \overline{v_3'^2}$.

See Section 11.7.3, Dissipation term, ε_{ij}

$$\begin{aligned}
 \overline{v_k \frac{\partial v'_i v'_j}{\partial x_k}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

► The dissipation term, ε_{ij} , in the $\overline{v'_i v'_j}$ equation (eq. 30.2), is modeled as follows:

Small-scale turbulence is isotropic

1. $\overline{v_1'^2} = \overline{v_2'^2} = \overline{v_3'^2}$.
 2. All shear stresses are zero (if we flip one coordinate axis the sign will change: hence not isotropic)
- ⇒

¶ See Section 11.7.3, Dissipation term, ε_{ij}

$$\begin{aligned}
 \overline{v_k \frac{\partial v'_i v'_j}{\partial x_k}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

► The dissipation term, ε_{ij} , in the $\overline{v'_i v'_j}$ equation (eq. 30.2), is modeled as follows:

Small-scale turbulence is isotropic

1. $\overline{v_1'^2} = \overline{v_2'^2} = \overline{v_3'^2}$.

2. All shear stresses are zero (if we flip one coordinate axis the sign will change: hence not isotropic)

⇒

$$\varepsilon_{ij} = \frac{2}{3} \varepsilon \delta_{ij} \tag{31.1}$$

¶ See Section 11.7.2, Diffusion terms

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 \underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} &+ \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 \underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} &- \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

Flux of $\overline{v'_i v'_j}$:

¶ See Section 11.7.2, Diffusion terms

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 \underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} &+ \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 \underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} &- \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

Flux of $\overline{v'_i v'_j}$:

$$D_{ij,t} = \overline{v'_i v'_j v'_k}$$

¶ See Section 11.7.2, Diffusion terms

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 \underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} &+ \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 \underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} &- \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

Flux of $\overline{v'_i v'_j}$:

$$D_{ij,t} = \overline{v'_i v'_j v'_k} =$$

¶ See Section 11.7.2, Diffusion terms

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 \underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} &+ \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 \underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} &- \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

Flux of $\overline{v'_i v'_j}$:

$$D_{ij,t} = \overline{v'_i v'_j v'_k} = -\frac{\nu_t}{\sigma_k} \frac{\partial \overline{v'_i v'_j}}{\partial x_k}$$

¶ See Section 11.7.2, Diffusion terms

$$\begin{aligned}
 \underbrace{\frac{\overline{\partial v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

Flux of $\overline{v'_i v'_j}$:

$$\begin{aligned}
 D_{ij,t} = \overline{v'_i v'_j v'_k} &= -\frac{\nu_t}{\sigma_k} \frac{\partial \overline{v'_i v'_j}}{\partial x_k} \\
 \Rightarrow -\frac{\partial \overline{v'_i v'_j v'_k}}{\partial x_k} &= \frac{\partial}{\partial x_k} \left(\frac{\nu_t}{\sigma_k} \frac{\partial \overline{v'_i v'_j}}{\partial x_k} \right)
 \end{aligned}$$

¶ See Section 11.7.2, Diffusion terms

$$\begin{aligned}
 \underbrace{\frac{\overline{\partial v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\underbrace{-\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\underbrace{-g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

Flux of $\overline{v'_i v'_j}$:

$$\begin{aligned}
 D_{ij,t} = \overline{v'_i v'_j v'_k} &= -\frac{\nu_t}{\sigma_k} \frac{\partial \overline{v'_i v'_j}}{\partial x_k} \\
 \Rightarrow -\frac{\partial \overline{v'_i v'_j v'_k}}{\partial x_k} &= \frac{\partial}{\partial x_k} \left(\frac{\nu_t}{\sigma_k} \frac{\partial \overline{v'_i v'_j}}{\partial x_k} \right)
 \end{aligned}$$

¶ See Section 11.7.4, Slow pressure-strain term

¶ See Section 11.7.4, [Slow pressure-strain term](#)

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

► The pressure-strain term is the last unknown term that needs to be modelled in the $\overline{v'_i v'_j}$ equation, Eq. 11.11.

See Section 11.7.4, [Slow pressure-strain term](#)

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

► The pressure-strain term is the last unknown term that needs to be modelled in the $\overline{v'_i v'_j}$ equation, Eq. 11.11.

► When modeled, it is divided into two parts:

•

¶ See Section 11.7.4, [Slow pressure-strain term](#)

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

▶ The pressure-strain term is the last unknown term that needs to be modelled in the $\overline{v'_i v'_j}$ equation, Eq. 11.11.

▶ When modeled, it is divided into two parts:

- a **slow** part which depends on turbulence

See Section 11.7.4, Slow pressure-strain term

$$\begin{aligned}
 \underbrace{\bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

► The pressure-strain term is the last unknown term that needs to be modelled in the $\overline{v'_i v'_j}$ equation, Eq. 11.11.

► When modeled, it is divided into two parts:

- a **slow** part which depends on turbulence
- a **rapid** part which depends on mean flow gradients and turbulence

¶ See Section 11.7.4, [Slow pressure-strain term](#)

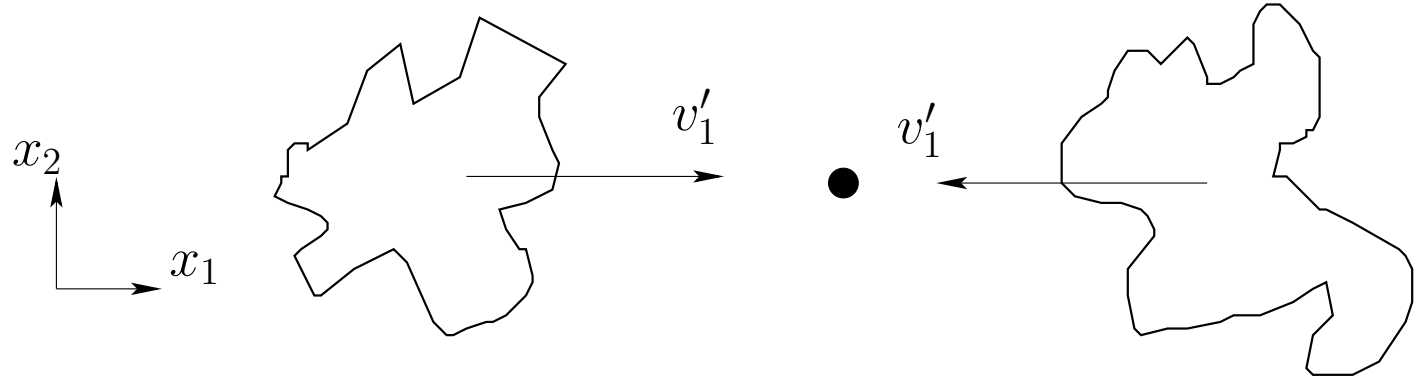
$$\begin{aligned}
 \underbrace{\overline{\bar{v}_k \frac{\partial v'_i v'_j}{\partial x_k}}}_{C_{ij}} &= \underbrace{-\overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k}}_{P_{ij}} + \underbrace{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)}_{\Pi_{ij}} \\
 &\quad - \underbrace{\frac{\partial}{\partial x_k} \left[\overline{v'_i v'_j v'_k} + \frac{p' v'_j}{\rho} \delta_{ik} + \frac{p' v'_i}{\rho} \delta_{jk} \right]}_{D_{ij,t}} + \underbrace{\nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k}}_{D_{ij,\nu}} \\
 &\quad - \underbrace{g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}}_{G_{ij}} - \underbrace{2\nu \frac{\partial v'_i}{\partial x_k} \frac{\partial v'_j}{\partial x_k}}_{\varepsilon_{ij}}
 \end{aligned}$$

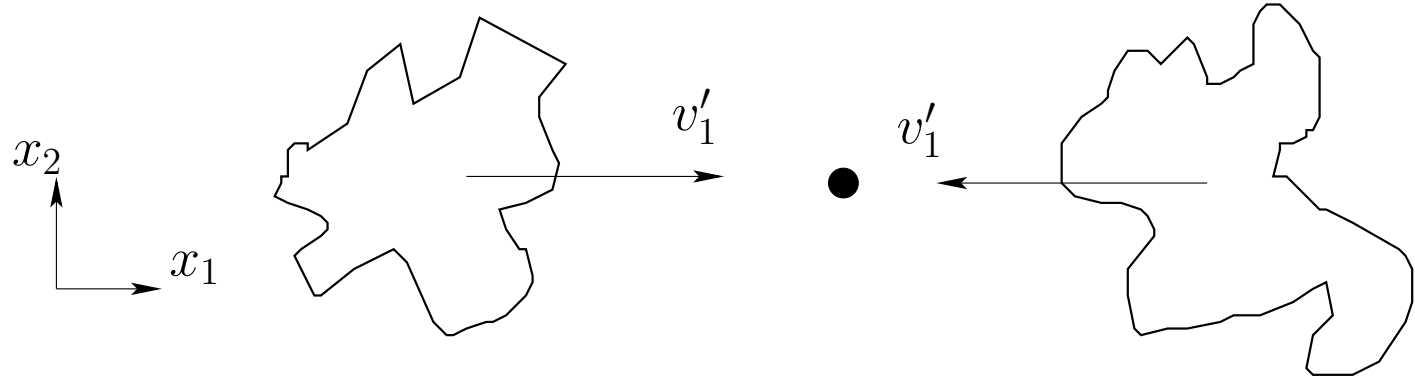
▶ The pressure-strain term is the last unknown term that needs to be modelled in the $\overline{v'_i v'_j}$ equation, Eq. 11.11.

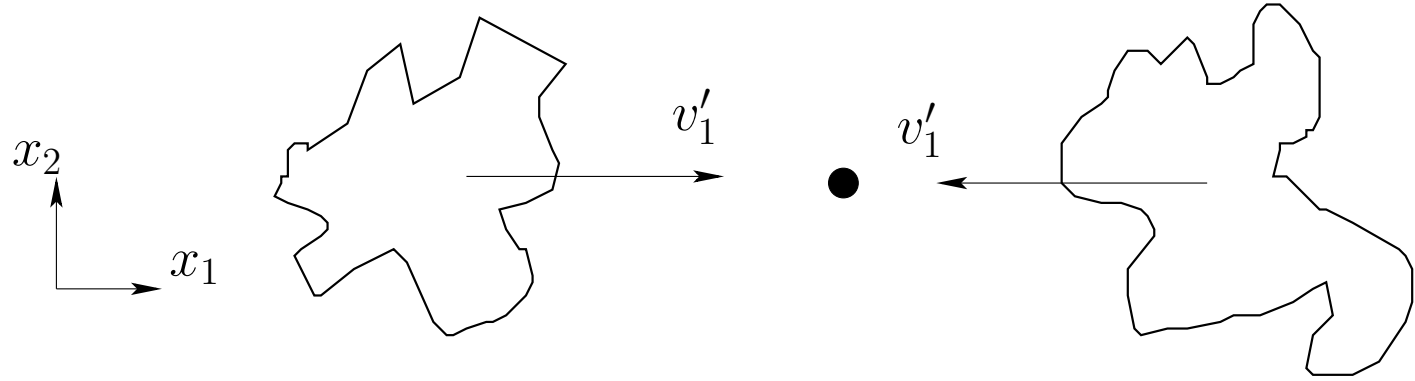
▶ When modeled, it is divided into two parts:

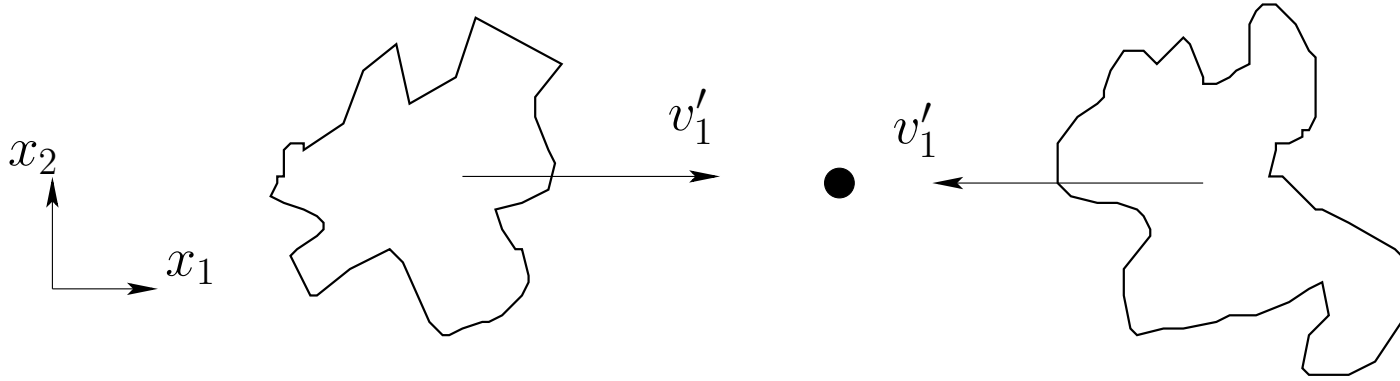
- a **slow** part which depends on turbulence
- a **rapid** part which depends on mean flow gradients and turbulence

▶ We start with the slow part of the pressure-strain term

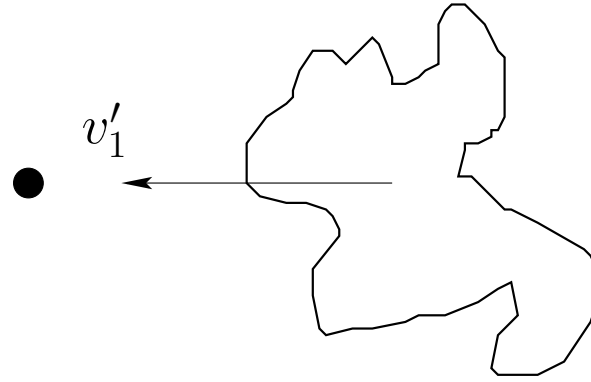
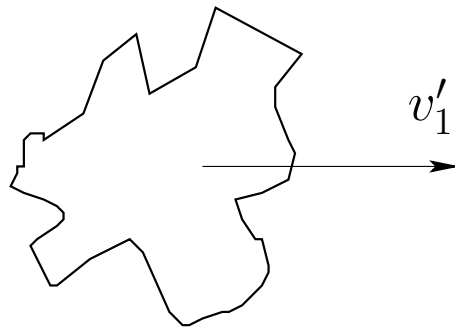
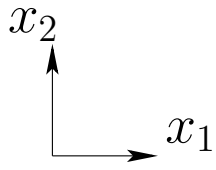




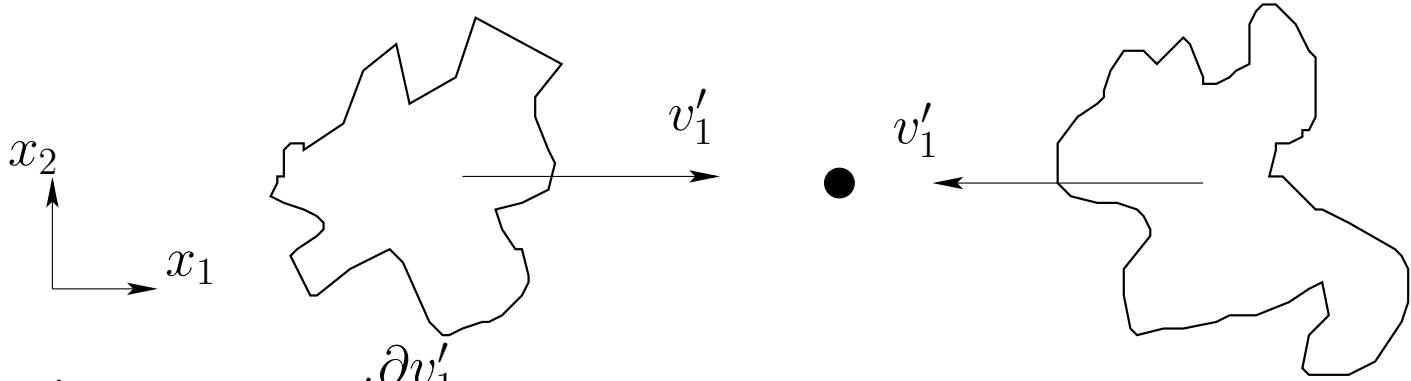




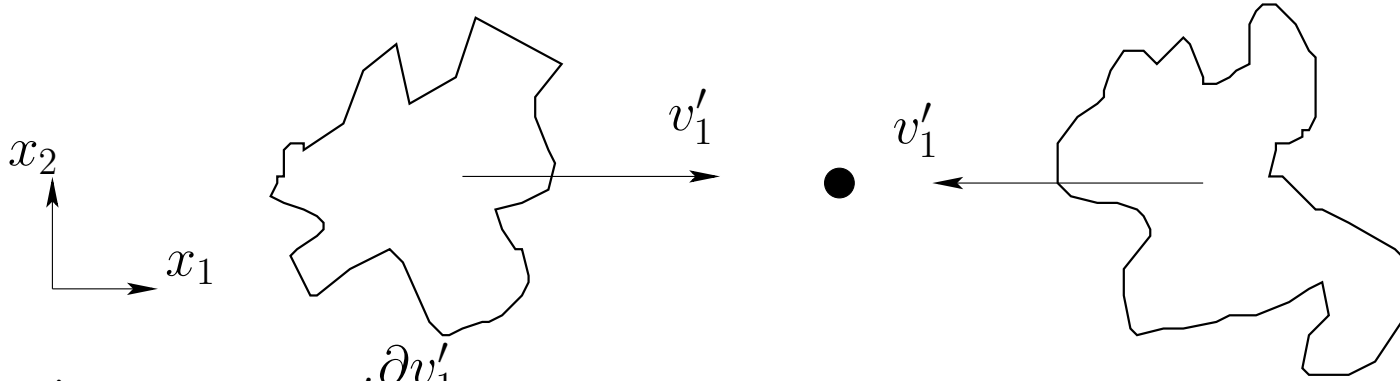
$$\partial v'_1 / \partial x_1 < 0$$



$\partial v'_1 / \partial x_1 < 0$ and $p' > 0$

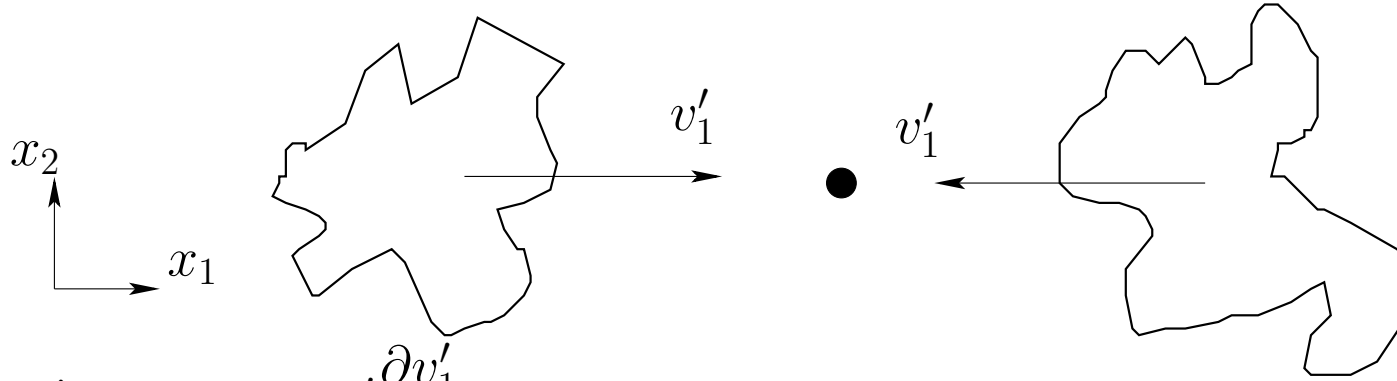


$\partial v'_1 / \partial x_1 < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$



$\partial v'_1 / \partial x_1 < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

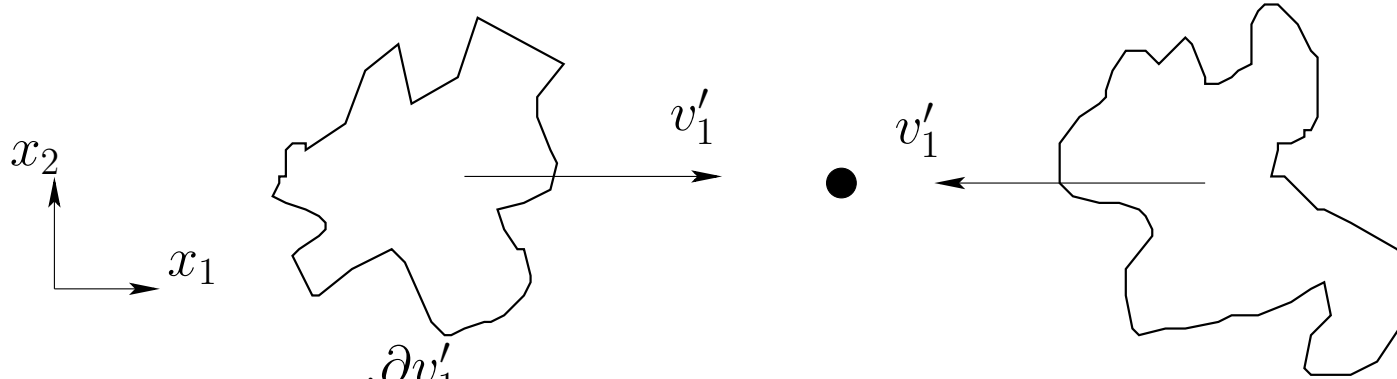
$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$



$\partial v'_1 / \partial x_1 < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

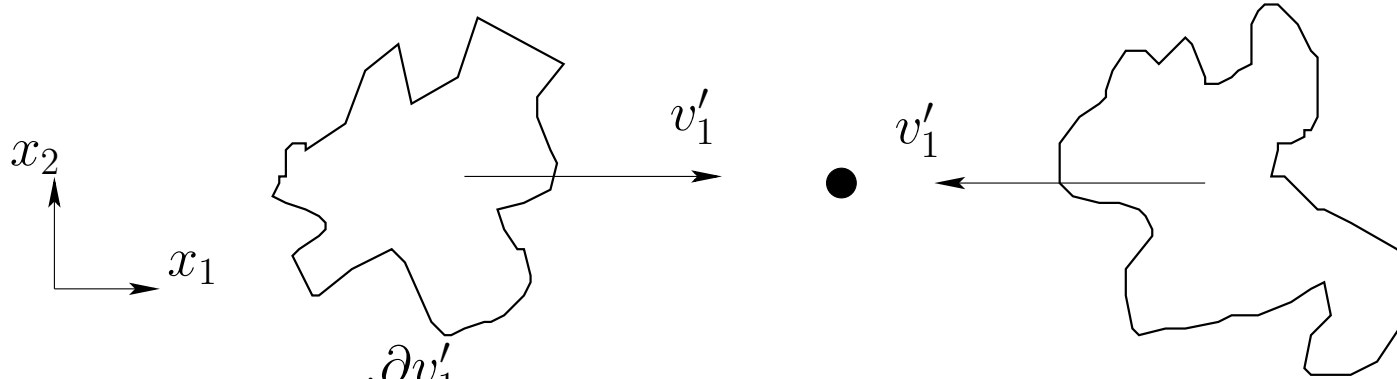


$\partial v'_1 / \partial x_1 < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v'_1} > \overline{v'_2}, \quad \overline{v'_1} > \overline{v'_3}$$

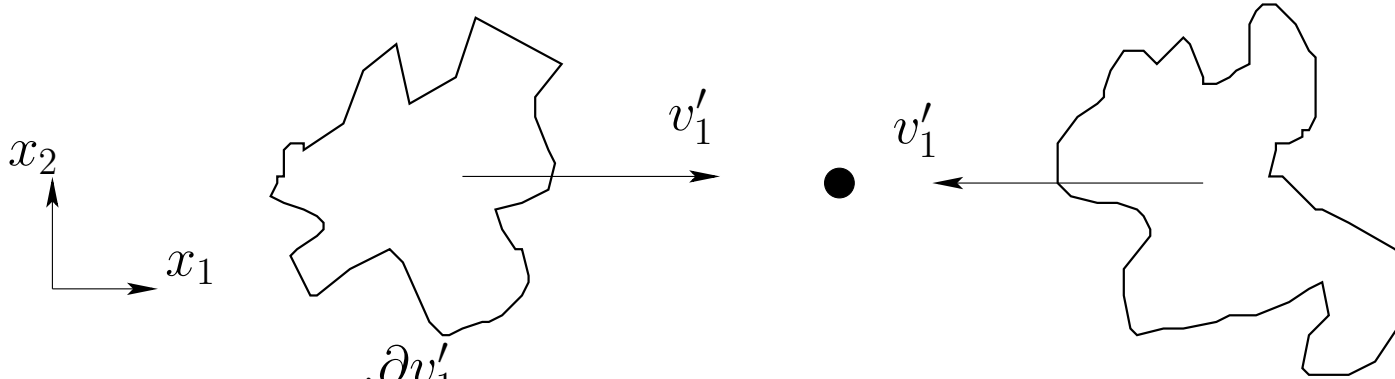


$\partial v'_1 / \partial x_1 < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v'_1} > \overline{v'_2}, \quad \overline{v'_1} > \overline{v'_3}$$



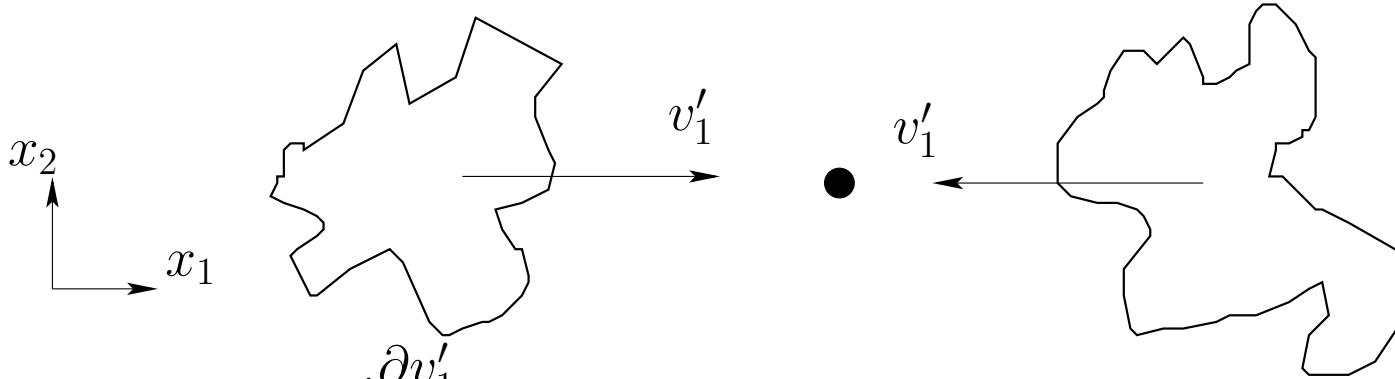
$\frac{\partial v'_1}{\partial x_1} < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v'_1} > \overline{v'_2}, \quad \overline{v'_1} > \overline{v'_3}$$

$$\overline{p' \frac{\partial v'_1}{\partial x_1}}$$



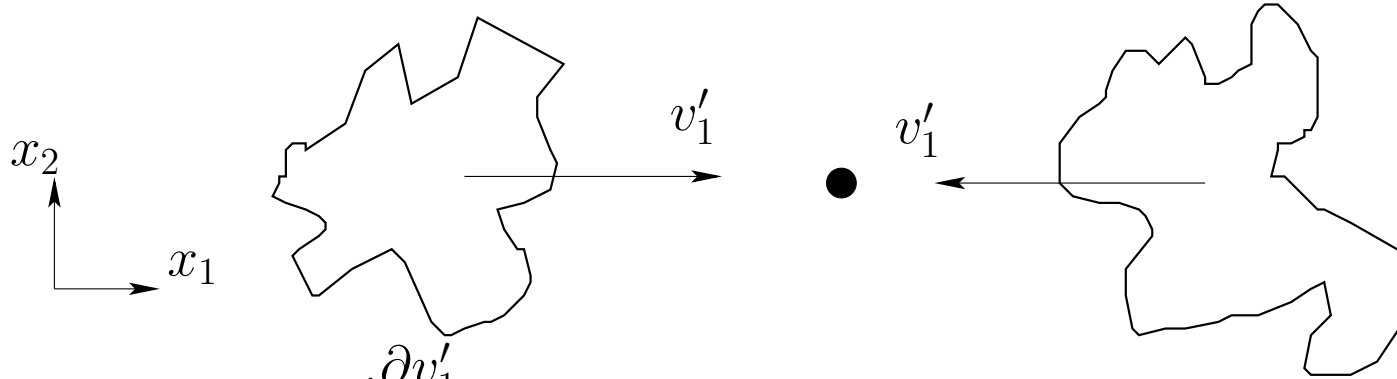
$\frac{\partial v'_1}{\partial x_1} < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v'_1} > \overline{v'_2}, \quad \overline{v'_1} > \overline{v'_3}$$

$$\overline{p' \frac{\partial v'_1}{\partial x_1}} \propto$$



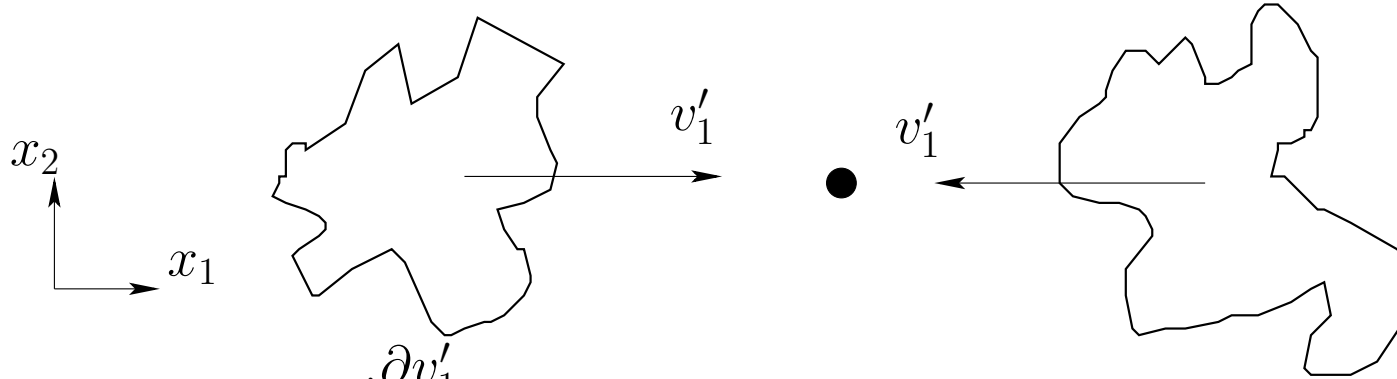
$\frac{\partial v'_1}{\partial x_1} < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v_1'^2} > \overline{v_2'^2}, \overline{v_1'^2} > \overline{v_3'^2}$$

$$\overline{p' \frac{\partial v'_1}{\partial x_1}} \propto -\frac{\rho}{2t} \left[\left(\overline{v_1'^2} - \overline{v_2'^2} \right) + \left(\overline{v_1'^2} - \overline{v_3'^2} \right) \right]$$



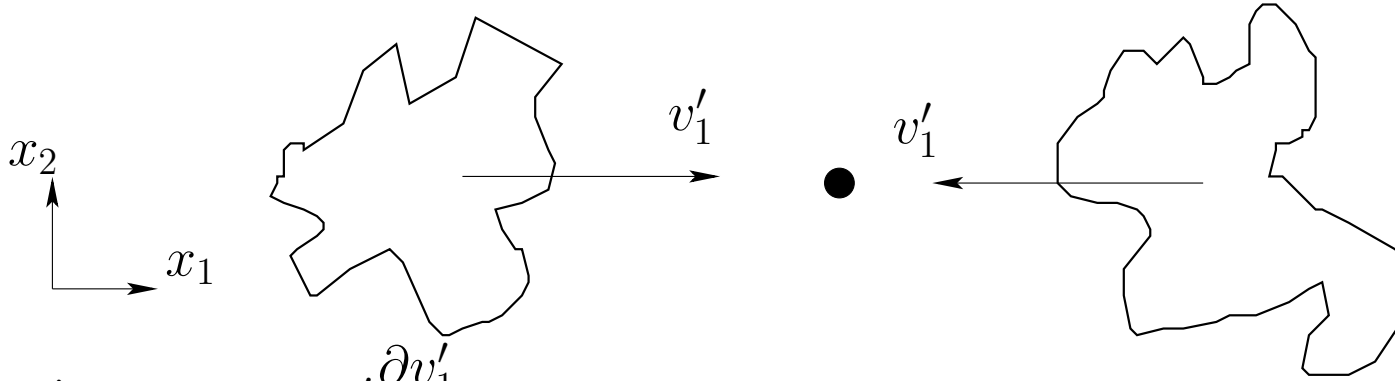
$\frac{\partial v'_1}{\partial x_1} < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v'_1{}^2} > \overline{v'_2{}^2}, \overline{v'_1{}^2} > \overline{v'_3{}^2}$$

$$\overline{p' \frac{\partial v'_1}{\partial x_1}} \propto -\frac{\rho}{2t} \left[\left(\overline{v'_1{}^2} - \overline{v'_2{}^2} \right) + \left(\overline{v'_1{}^2} - \overline{v'_3{}^2} \right) \right] = -\frac{\rho}{t} \left[\overline{v'_1{}^2} - \frac{1}{2} \left(\overline{v'_2{}^2} + \overline{v'_3{}^2} \right) \right]$$



$\frac{\partial v'_1}{\partial x_1} < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

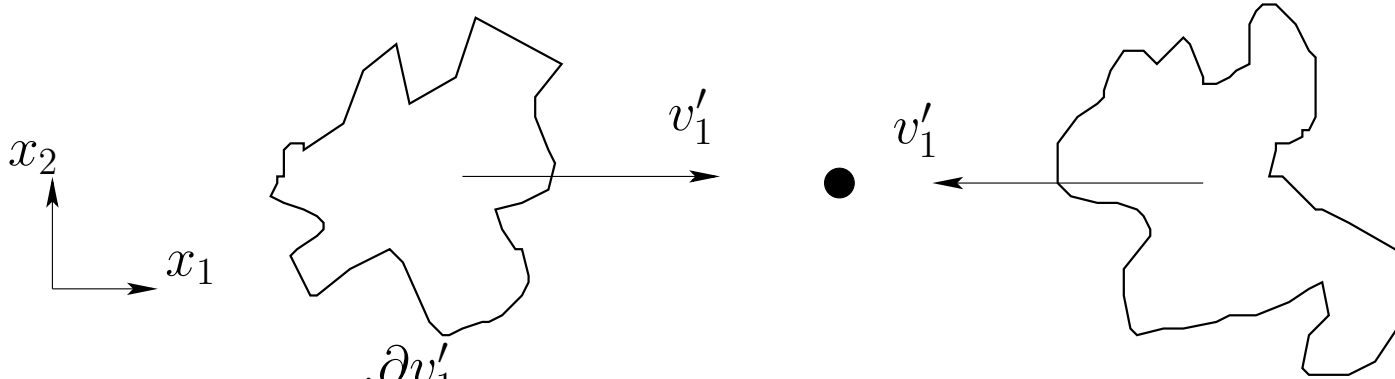
$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v'_1{}^2} > \overline{v'_2{}^2}, \overline{v'_1{}^2} > \overline{v'_3{}^2}$$

$$\overline{p' \frac{\partial v'_1}{\partial x_1}} \propto -\frac{\rho}{2t} \left[\left(\overline{v'_1{}^2} - \overline{v'_2{}^2} \right) + \left(\overline{v'_1{}^2} - \overline{v'_3{}^2} \right) \right] = -\frac{\rho}{t} \left[\overline{v'_1{}^2} - \frac{1}{2} \left(\overline{v'_2{}^2} + \overline{v'_3{}^2} \right) \right]$$

=



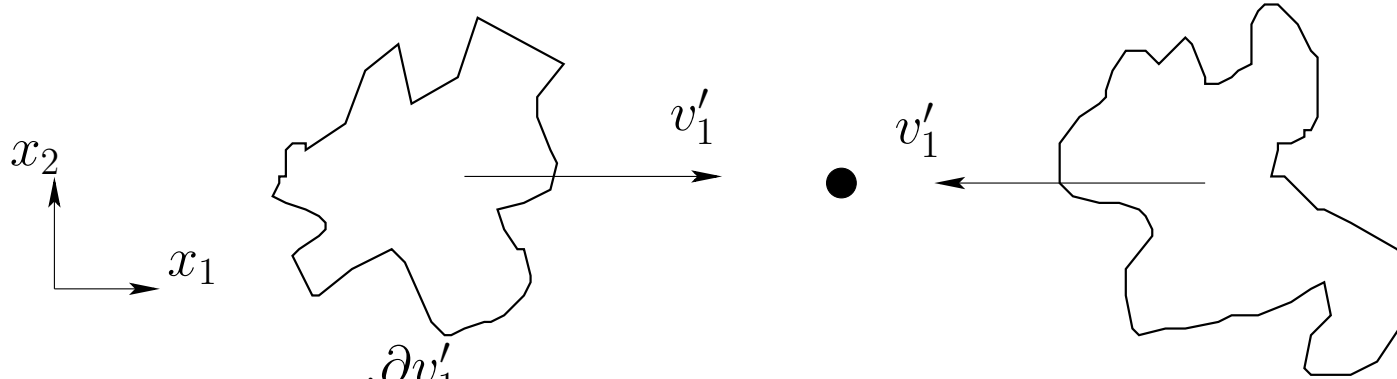
$\frac{\partial v'_1}{\partial x_1} < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v_1'^2} > \overline{v_2'^2}, \overline{v_1'^2} > \overline{v_3'^2}$$

$$\begin{aligned} \overline{p' \frac{\partial v'_1}{\partial x_1}} &\propto -\frac{\rho}{2t} \left[\left(\overline{v_1'^2} - \overline{v_2'^2} \right) + \left(\overline{v_1'^2} - \overline{v_3'^2} \right) \right] = -\frac{\rho}{t} \left[\overline{v_1'^2} - \frac{1}{2} \left(\overline{v_2'^2} + \overline{v_3'^2} \right) \right] \\ &= -\frac{\rho}{t} \left[\frac{3}{2} \overline{v_1'^2} - \frac{1}{2} \left(\overline{v_1'^2} + \overline{v_2'^2} + \overline{v_3'^2} \right) \right] \end{aligned}$$



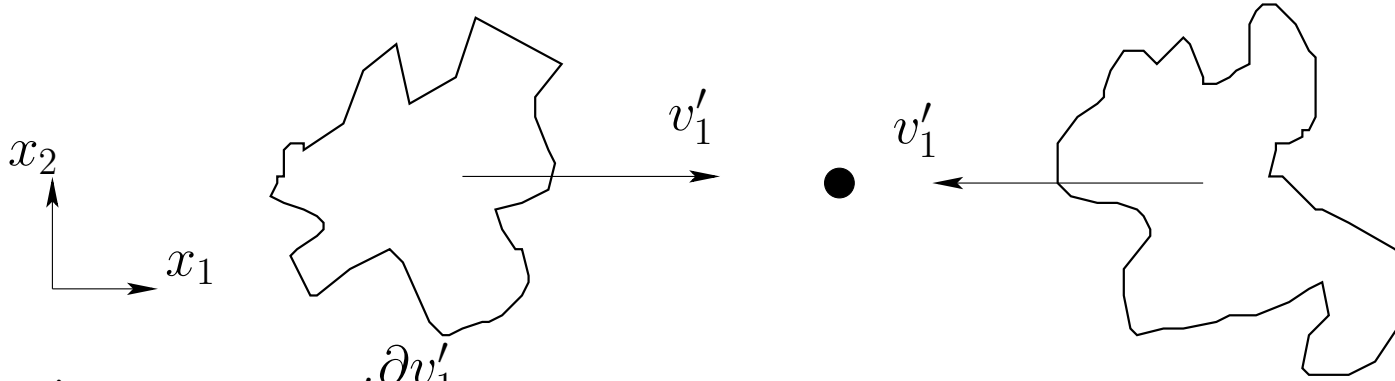
$\frac{\partial v'_1}{\partial x_1} < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v_1'^2} > \overline{v_2'^2}, \overline{v_1'^2} > \overline{v_3'^2}$$

$$\begin{aligned} \overline{p' \frac{\partial v'_1}{\partial x_1}} &\propto -\frac{\rho}{2t} \left[\left(\overline{v_1'^2} - \overline{v_2'^2} \right) + \left(\overline{v_1'^2} - \overline{v_3'^2} \right) \right] = -\frac{\rho}{t} \left[\overline{v_1'^2} - \frac{1}{2} \left(\overline{v_2'^2} + \overline{v_3'^2} \right) \right] \\ &= -\frac{\rho}{t} \left[\frac{3}{2} \overline{v_1'^2} - \frac{1}{2} \left(\overline{v_1'^2} + \overline{v_2'^2} + \overline{v_3'^2} \right) \right] = -\frac{\rho}{t} \left(\frac{3}{2} \overline{v_1'^2} - k \right) \end{aligned}$$



$\frac{\partial v'_1}{\partial x_1} < 0$ and $p' > 0$ so that $p' \frac{\partial v'_1}{\partial x_1} < 0$

$$\frac{\partial v'_2}{\partial x_2} > 0, \quad \frac{\partial v'_3}{\partial x_3} > 0$$

If this happens then

$$\overline{v_1'^2} > \overline{v_2'^2}, \overline{v_1'^2} > \overline{v_3'^2}$$

$$\begin{aligned} \overline{p' \frac{\partial v'_1}{\partial x_1}} &\propto -\frac{\rho}{2t} \left[\left(\overline{v_1'^2} - \overline{v_2'^2} \right) + \left(\overline{v_1'^2} - \overline{v_3'^2} \right) \right] = -\frac{\rho}{t} \left[\overline{v_1'^2} - \frac{1}{2} \left(\overline{v_2'^2} + \overline{v_3'^2} \right) \right] \\ &= -\frac{\rho}{t} \left[\frac{3}{2} \overline{v_1'^2} - \frac{1}{2} \left(\overline{v_1'^2} + \overline{v_2'^2} + \overline{v_3'^2} \right) \right] = -\frac{\rho}{t} \left(\frac{3}{2} \overline{v_1'^2} - k \right) \end{aligned}$$

$$\Phi_{ij,1} \equiv \overline{p' \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)} = -c_1 \rho \frac{\varepsilon}{k} \left(\overline{v'_i v'_j} - \frac{2}{3} \delta_{ij} k \right) \quad (31.2)$$

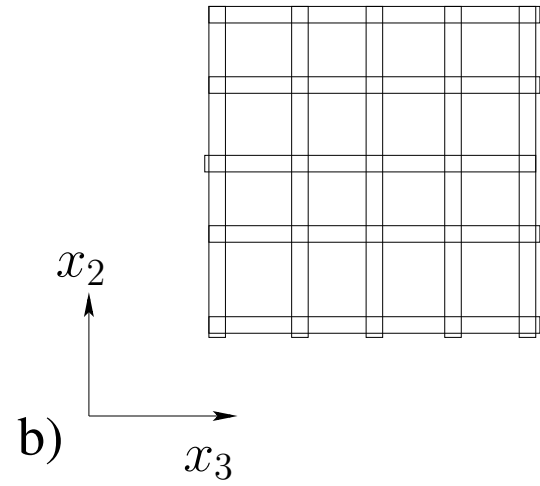
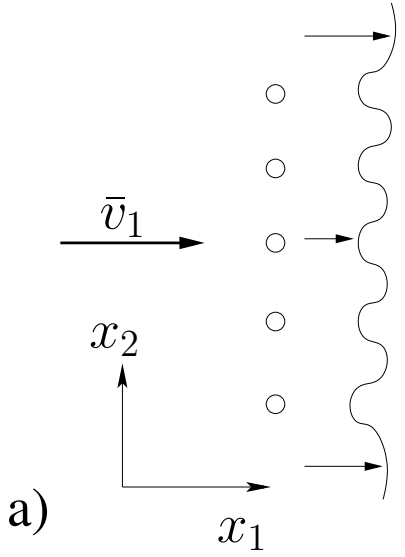
see Eq. 11.57

¶ See Eq. 11.2

▶ Decaying grid turbulence

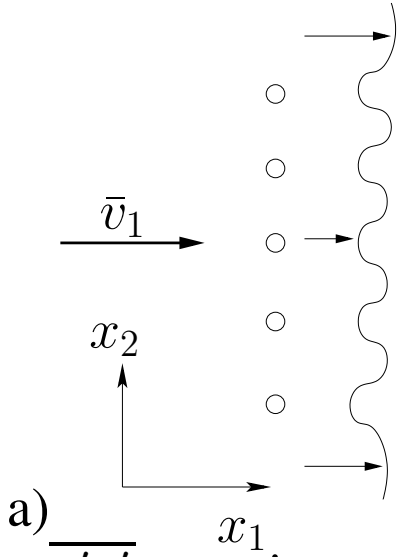
¶ See Eq. 11.2

► Decaying grid turbulence

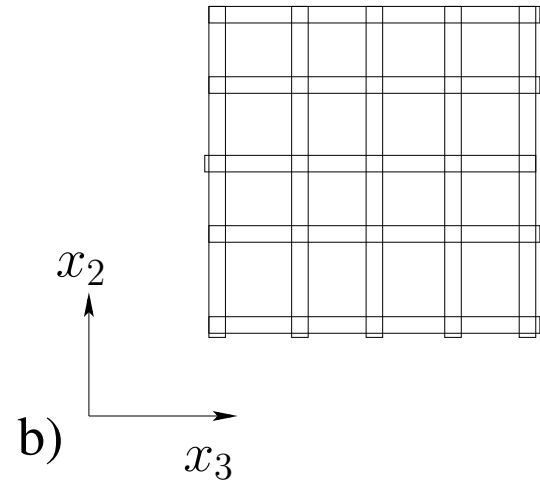


¶ See Eq. 11.2

► Decaying grid turbulence



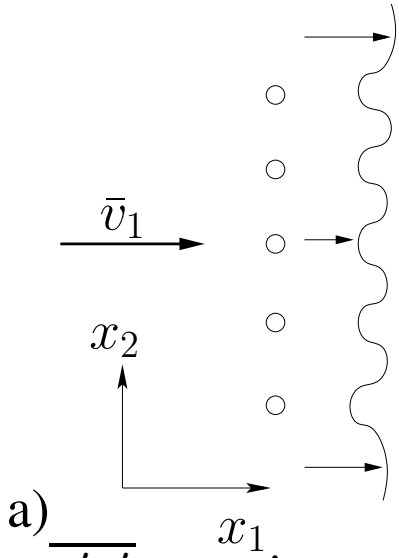
► $\overline{v'_i v'_j}$ equation



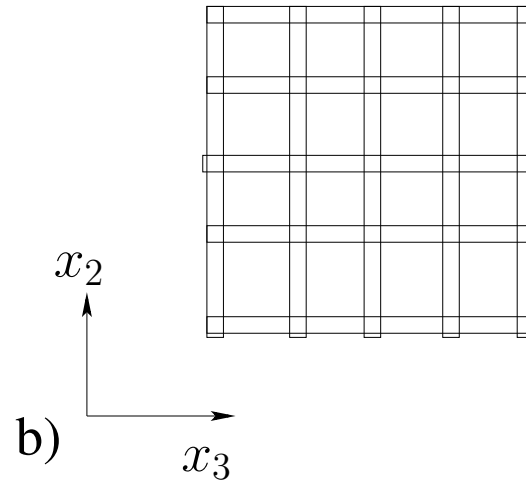
$$\bar{v}_1 \frac{d\overline{v'_i v'_j}}{dx_1} = \frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) - \varepsilon_{ij} \quad (31.3)$$

¶ See Eq. 11.2

► Decaying grid turbulence



► $\overline{v'_i v'_j}$ equation



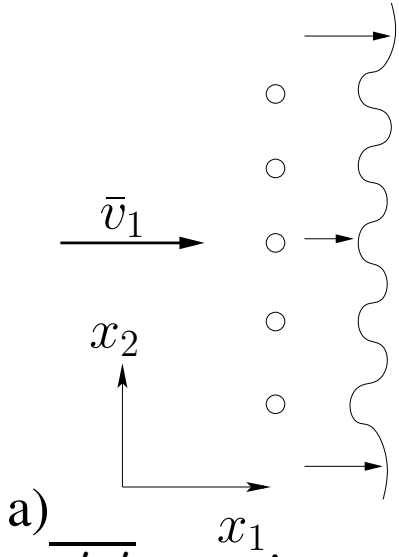
$$\bar{v}_1 \frac{d\overline{v'_i v'_j}}{dx_1} = \frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) - \varepsilon_{ij} \quad (31.3)$$

An anisotropy stress tensor is defined as

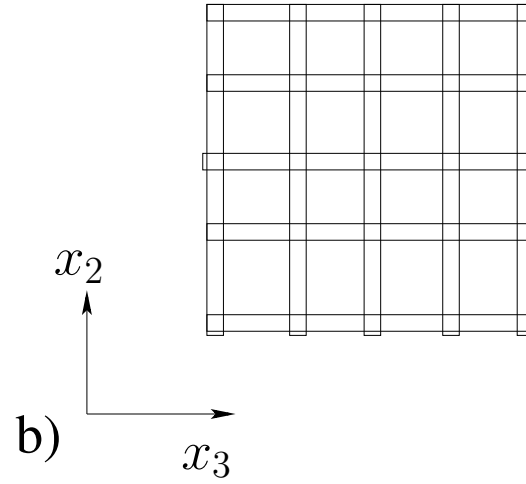
(31.4)

¶ See Eq. 11.2

► Decaying grid turbulence



► $\overline{v'_i v'_j}$ equation



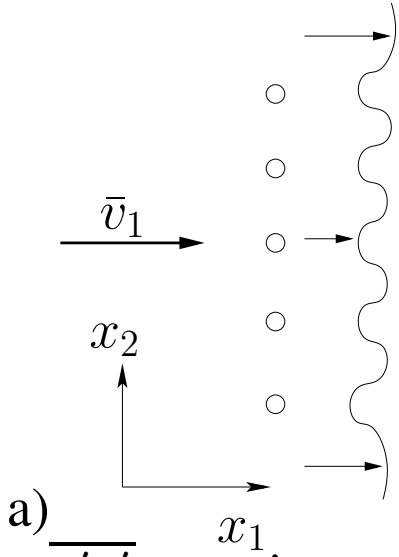
$$\bar{v}_1 \frac{d\overline{v'_i v'_j}}{dx_1} = \frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) - \varepsilon_{ij} \quad (31.3)$$

An anisotropy stress tensor is defined as

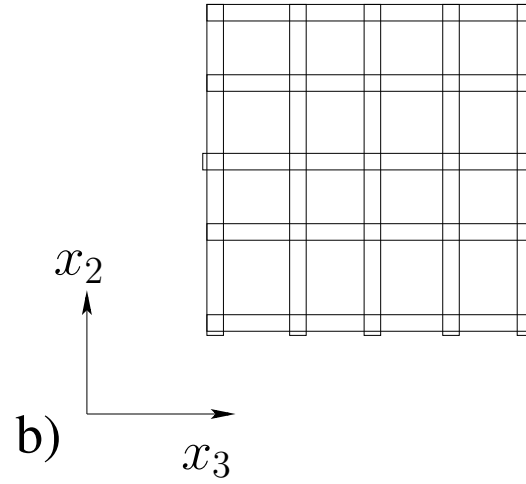
$$a_{ij} = \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij} \quad (31.4)$$

¶ See Eq. 11.2

► Decaying grid turbulence



► $\overline{v'_i v'_j}$ equation



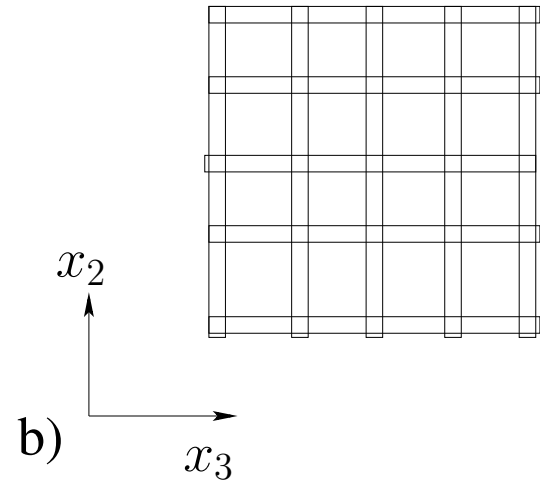
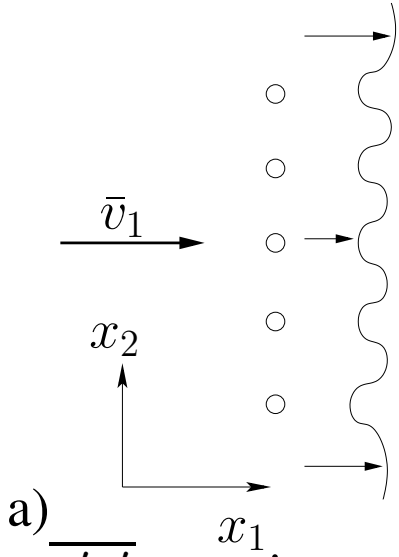
$$\bar{v}_1 \frac{d\overline{v'_i v'_j}}{dx_1} = \frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) - \varepsilon_{ij} \quad (31.3)$$

An anisotropy stress tensor is defined as

$$a_{ij} = \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij} \quad \Rightarrow \quad (31.4)$$

¶ See Eq. 11.2

► Decaying grid turbulence



► $\overline{v'_i v'_j}$ equation

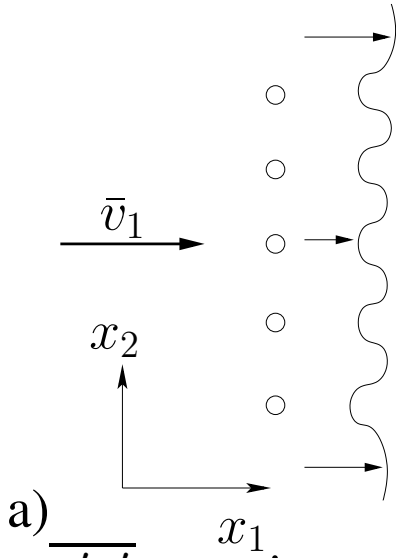
$$\bar{v}_1 \frac{d\overline{v'_i v'_j}}{dx_1} = \frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) - \varepsilon_{ij} \quad (31.3)$$

An anisotropy stress tensor is defined as

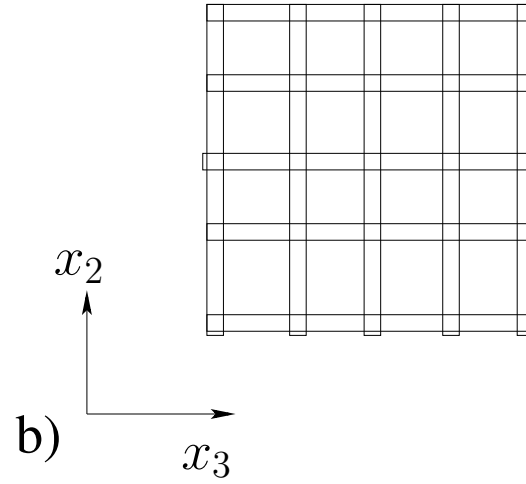
$$a_{ij} = \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij} \quad \Rightarrow \quad \overline{v'_i v'_j} = k a_{ij} + \frac{2k}{3} \delta_{ij} \quad (31.4)$$

¶ See Eq. 11.2

► Decaying grid turbulence



a) $\overline{v'_i v'_j}$ equation



$$\bar{v}_1 \frac{d\overline{v'_i v'_j}}{dx_1} = \frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) - \varepsilon_{ij} \quad (31.3)$$

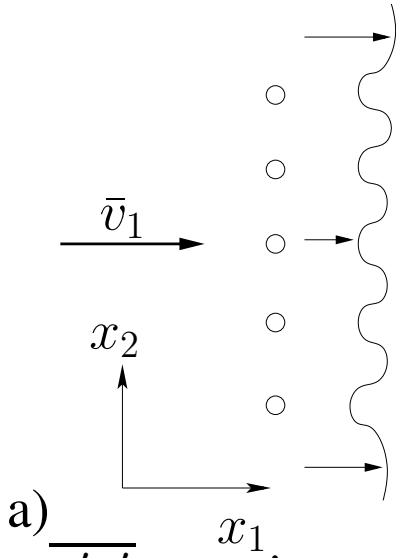
An anisotropy stress tensor is defined as

$$a_{ij} = \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij} \quad \Rightarrow \quad \overline{v'_i v'_j} = k a_{ij} + \frac{2k}{3} \delta_{ij} \quad (31.4)$$

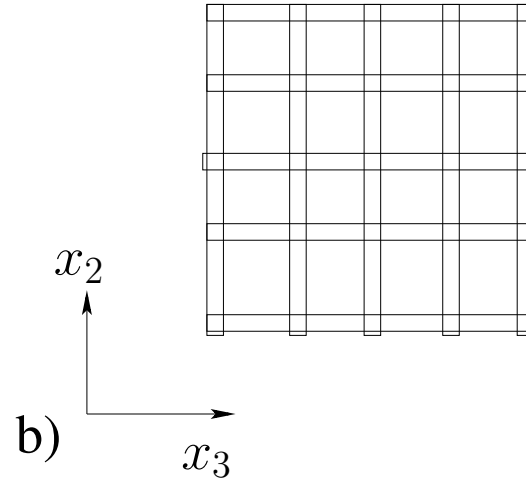
In isotropic turbulence, $a_{ij} = 0$.

¶ See Eq. 11.2

► Decaying grid turbulence



a) $\overline{v'_i v'_j}$ equation



$$\bar{v}_1 \frac{d\overline{v'_i v'_j}}{dx_1} = \frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) - \varepsilon_{ij} \quad (31.3)$$

An anisotropy stress tensor is defined as

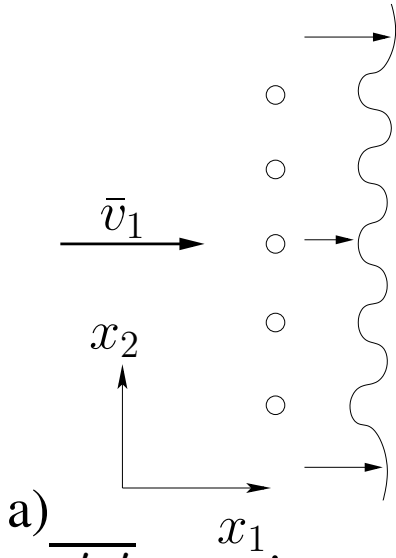
$$a_{ij} = \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij} \quad \Rightarrow \quad \overline{v'_i v'_j} = k a_{ij} + \frac{2k}{3} \delta_{ij} \quad (31.4)$$

In isotropic turbulence, $a_{ij} = 0$.

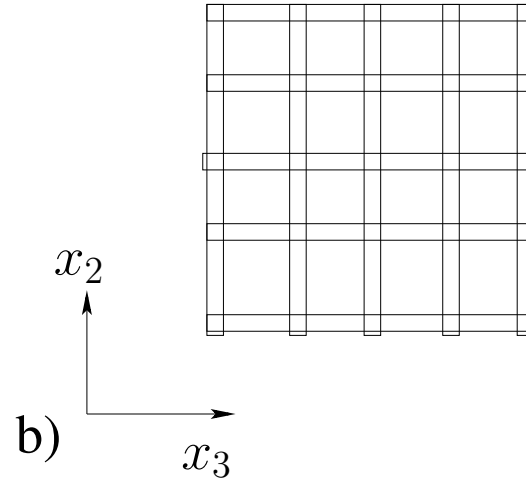
We insert Eq. 31.4 into Eq. 31.3 and use the models for the pressure strain term, $\phi_{ij,1}$ (Eq. 31.2)

¶ See Eq. 11.2

► Decaying grid turbulence



a) $\overline{v'_i v'_j}$ equation



$$\bar{v}_1 \frac{d\overline{v'_i v'_j}}{dx_1} = \frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) - \varepsilon_{ij} \quad (31.3)$$

An anisotropy stress tensor is defined as

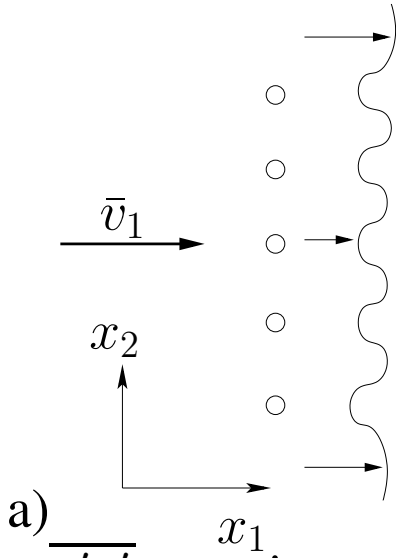
$$a_{ij} = \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij} \quad \Rightarrow \quad \overline{v'_i v'_j} = k a_{ij} + \frac{2k}{3} \delta_{ij} \quad (31.4)$$

In isotropic turbulence, $a_{ij} = 0$.

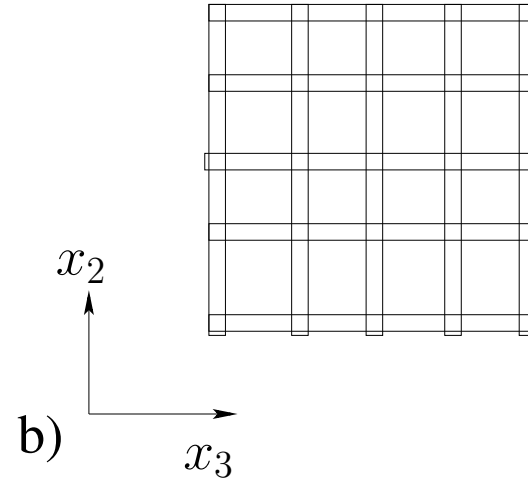
We insert Eq. 31.4 into Eq. 31.3 and use the models for the pressure strain term, $\phi_{ij,1}$ (Eq. 31.2) and dissipation, $\varepsilon_{ij} = (2/3)\delta_{ij}$ (Eq. 31.1) so that

¶ See Eq. 11.2

► Decaying grid turbulence



a) $\overline{v'_i v'_j}$ equation



$$\bar{v}_1 \frac{d\overline{v'_i v'_j}}{dx_1} = \frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) - \varepsilon_{ij} \quad (31.3)$$

An anisotropy stress tensor is defined as

$$a_{ij} = \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij} \quad \Rightarrow \quad \overline{v'_i v'_j} = k a_{ij} + \frac{2k}{3} \delta_{ij} \quad (31.4)$$

In isotropic turbulence, $a_{ij} = 0$.

We insert Eq. 31.4 into Eq. 31.3 and use the models for the pressure strain term, $\phi_{ij,1}$ (Eq. 31.2) and dissipation, $\varepsilon_{ij} = (2/3)\delta_{ij}$ (Eq. 31.1) so that

$$\bar{v}_1 \left(\frac{d(ka_{ij})}{dx_1} + \frac{2}{3} \delta_{ij} \frac{dk}{dx_1} \right) = -c_1 \varepsilon a_{ij} - \frac{2}{3} \delta_{ij} \varepsilon$$

$$\bar{v}_1 \left(\frac{d(ka_{ij})}{dx_1} + \frac{2}{3} \delta_{ij} \frac{dk}{dx_1} \right) = \underline{-c_1 \varepsilon a_{ij} - \frac{2}{3} \delta_{ij} \varepsilon}$$

$$\bar{v}_1 \left(\frac{d(ka_{ij})}{dx_1} + \frac{2}{3} \delta_{ij} \frac{dk}{dx_1} \right) = \underline{-c_1 \varepsilon a_{ij} - \frac{2}{3} \delta_{ij} \varepsilon}$$

$$\bar{v}_1 \left(k \frac{da_{ij}}{dx_1} + a_{ij} \frac{dk}{dx_1} + \frac{2}{3} \delta_{ij} \frac{dk}{dx_1} \right) = \underline{-c_1 \varepsilon a_{ij} - \frac{2}{3} \delta_{ij} \varepsilon}$$

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$da_{ij}/dx < 0$ (the turbulence becomes isotropic). Hence we find that c_1 must be larger than one.

On-line Lecture 3

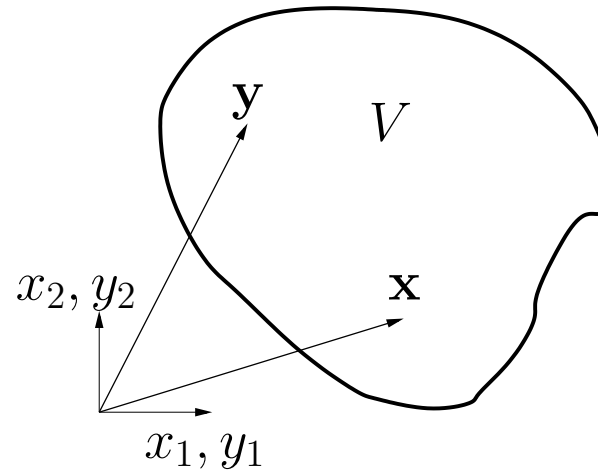
¶ See Section 11.7.5, Rapid pressure-strain term

▶ Pressure strain: rapid part

On-line Lecture 3

¶ See Section 11.7.5, Rapid pressure-strain term

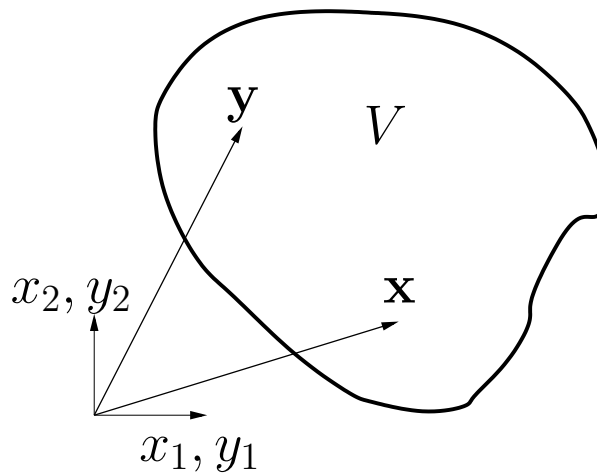
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On-line Lecture 3

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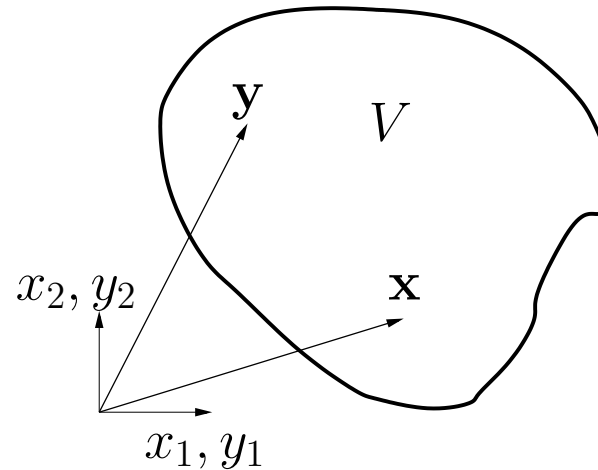


1.

On-line Lecture 3

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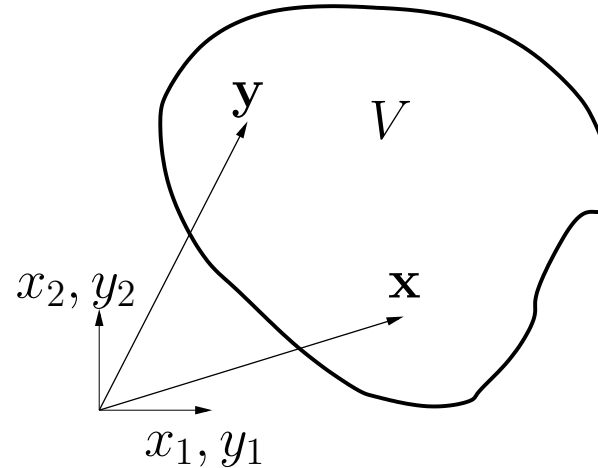


1. Take the divergence of the incompressible Navier-Stokes equation assuming constant viscosity (see Eq. 6.6)

On-line Lecture 3

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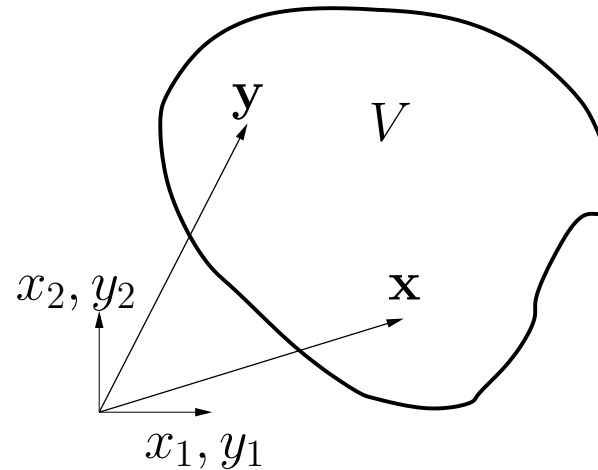
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On-line Lecture 3

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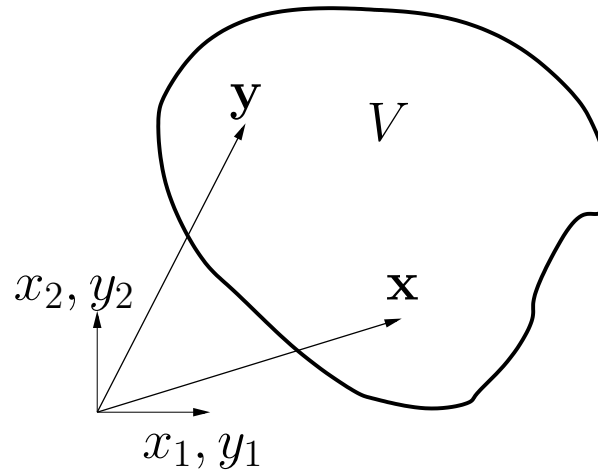


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On-line Lecture 3

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► Pressure strain: rapid part



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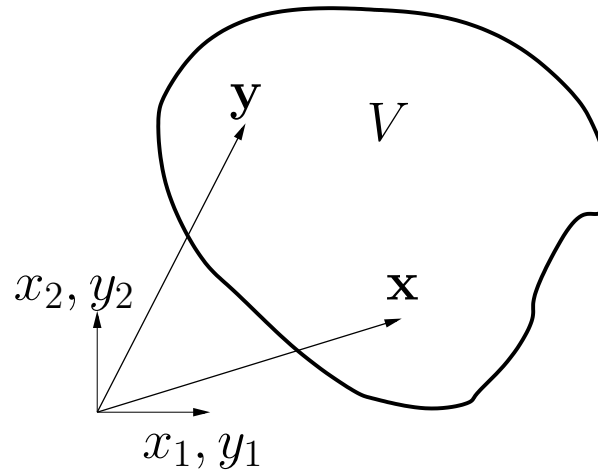
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On-line Lecture 3

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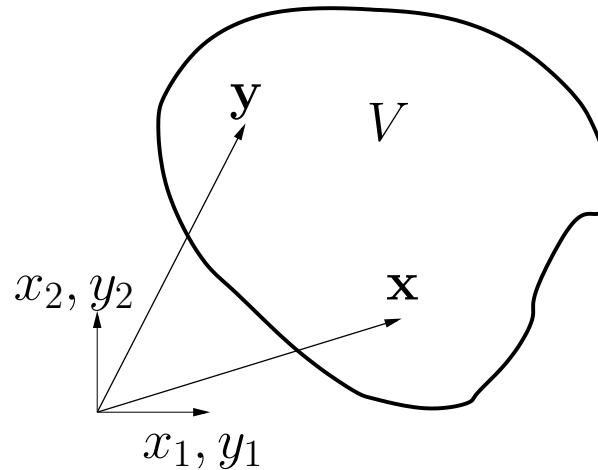
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Eq. A - Eq. B gives

On-line Lecture 3

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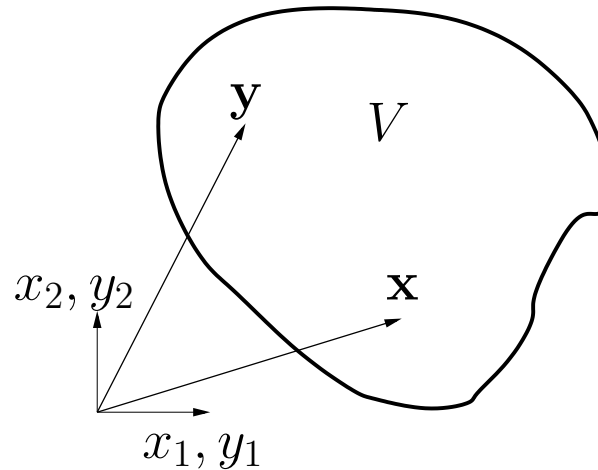
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On-line Lecture 3

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- ii) the variation of $\partial \bar{v}_i / \partial x_j$ in space is small because $\partial \bar{v}_i / \partial x_j$ varies much more slowly $\partial v'_j(\mathbf{y}) / \partial y_i$

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Assumption *ii*) \Rightarrow mean velocity gradient moved outside the integral.

$$p'(\mathbf{x}) = \frac{\rho}{2\pi} \frac{\partial \bar{v}_i(\mathbf{x})}{\partial x_j} \int_V \frac{\partial v'_j(\mathbf{y})}{\partial y_i} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|} - \frac{\rho}{4\pi} \int_V \frac{\partial^2}{\partial y_i \partial y_j} (v'_i(\mathbf{y}) v'_j(\mathbf{y})) \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

$$p'(\mathbf{x}) = \frac{\rho}{2\pi} \frac{\partial \bar{v}_i(\mathbf{x})}{\partial x_j} \int_V \frac{\partial v'_j(\mathbf{y})}{\partial y_i} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|} - \frac{\rho}{4\pi} \int_V \frac{\partial^2}{\partial y_i \partial y_j} (v'_i(\mathbf{y})v'_j(\mathbf{y})) \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

► Multiply Eq. 32.2 with $\partial v'_i/\partial x_j + \partial v'_j/\partial x_i$ and average:

$$p'(\mathbf{x}) = \frac{\rho}{2\pi} \frac{\partial \bar{v}_i(\mathbf{x})}{\partial x_j} \int_V \frac{\partial v'_j(\mathbf{y})}{\partial y_i} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|} - \frac{\rho}{4\pi} \int_V \frac{\partial^2}{\partial y_i \partial y_j} (v'_i(\mathbf{y})v'_j(\mathbf{y})) \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

► Multiply Eq. 32.2 with $\partial v'_i/\partial x_j + \partial v'_j/\partial x_i$ and average:

$$\frac{p'(\mathbf{x})}{\rho} \left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) = \frac{\partial \bar{v}_k(\mathbf{x})}{\partial x_\ell} \frac{1}{2\pi} \int_V \underbrace{\left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial v'_\ell(\mathbf{y})}{\partial y_k}}_{M_{ijkl}} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

$$+ \frac{1}{4\pi} \int_V \underbrace{\left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial^2}{\partial y_k \partial y_\ell} (v'_k(\mathbf{y})v'_\ell(\mathbf{y}))}_{A_{ij}} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

(32.3)

$$p'(\mathbf{x}) = \frac{\rho}{2\pi} \frac{\partial \bar{v}_i(\mathbf{x})}{\partial x_j} \int_V \frac{\partial v'_j(\mathbf{y})}{\partial y_i} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|} - \frac{\rho}{4\pi} \int_V \frac{\partial^2}{\partial y_i \partial y_j} (v'_i(\mathbf{y})v'_j(\mathbf{y})) \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

► Multiply Eq. 32.2 with $\partial v'_i/\partial x_j + \partial v'_j/\partial x_i$ and average:

$$\frac{p'(\mathbf{x})}{\rho} \left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) = \frac{\partial \bar{v}_k(\mathbf{x})}{\partial x_\ell} \frac{1}{2\pi} \int_V \underbrace{\left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial v'_\ell(\mathbf{y})}{\partial y_k}}_{M_{ijkl}} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

$$+ \frac{1}{4\pi} \int_V \underbrace{\left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial^2}{\partial y_k \partial y_\ell} (v'_k(\mathbf{y})v'_\ell(\mathbf{y}))}_{A_{ij}} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

(32.3)

Short form of Eq. 32.3:

$$p'(\mathbf{x}) = \frac{\rho}{2\pi} \frac{\partial \bar{v}_i(\mathbf{x})}{\partial x_j} \int_V \frac{\partial v'_j(\mathbf{y})}{\partial y_i} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|} - \frac{\rho}{4\pi} \int_V \frac{\partial^2}{\partial y_i \partial y_j} (v'_i(\mathbf{y})v'_j(\mathbf{y})) \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

► Multiply Eq. 32.2 with $\partial v'_i/\partial x_j + \partial v'_j/\partial x_i$ and average:

$$\overline{\frac{p'(\mathbf{x})}{\rho} \left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right)} = \frac{\partial \bar{v}_k(\mathbf{x})}{\partial x_\ell} \underbrace{\frac{1}{2\pi} \int_V \left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial v'_\ell(\mathbf{y})}{\partial y_k} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}}_{M_{ijkl}}$$

$$+ \underbrace{\frac{1}{4\pi} \int_V \left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial^2}{\partial y_k \partial y_\ell} (v'_k(\mathbf{y})v'_\ell(\mathbf{y})) \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}}_{A_{ij}}$$

(32.3)

Short form of Eq. 32.3:

$$\overline{\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right)} = A_{ij} + M_{ijkl} \frac{\partial \bar{v}_k}{\partial x_\ell} = \Phi_{ij,1} + \Phi_{ij,2}$$



$$p'(\mathbf{x}) = \frac{\rho}{2\pi} \frac{\partial \bar{v}_i(\mathbf{x})}{\partial x_j} \int_V \frac{\partial v'_j(\mathbf{y})}{\partial y_i} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|} - \frac{\rho}{4\pi} \int_V \frac{\partial^2}{\partial y_i \partial y_j} (v'_i(\mathbf{y})v'_j(\mathbf{y})) \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

► Multiply Eq. 32.2 with $\partial v'_i/\partial x_j + \partial v'_j/\partial x_i$ and average:

$$\frac{p'(\mathbf{x})}{\rho} \left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) = \frac{\partial \bar{v}_k(\mathbf{x})}{\partial x_\ell} \frac{1}{2\pi} \int_V \underbrace{\left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial v'_\ell(\mathbf{y})}{\partial y_k}}_{M_{ijkl}} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

$$+ \frac{1}{4\pi} \int_V \underbrace{\left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial^2}{\partial y_k \partial y_\ell} (v'_k(\mathbf{y})v'_\ell(\mathbf{y}))}_{A_{ij}} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

(32.3)

Short form of Eq. 32.3:

$$\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) = A_{ij} + M_{ijkl} \frac{\partial \bar{v}_k}{\partial x_\ell} = \Phi_{ij,1} + \Phi_{ij,2}$$

- First term=slow term, $\Phi_{ij,1}$,

$$p'(\mathbf{x}) = \frac{\rho}{2\pi} \frac{\partial \bar{v}_i(\mathbf{x})}{\partial x_j} \int_V \frac{\partial v'_j(\mathbf{y})}{\partial y_i} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|} - \frac{\rho}{4\pi} \int_V \frac{\partial^2}{\partial y_i \partial y_j} (v'_i(\mathbf{y})v'_j(\mathbf{y})) \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

► Multiply Eq. 32.2 with $\partial v'_i/\partial x_j + \partial v'_j/\partial x_i$ and average:

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$$+ \frac{1}{4\pi} \int_V \underbrace{\left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial^2}{\partial y_k \partial y_\ell} (v'_k(\mathbf{y})v'_\ell(\mathbf{y}))}_{A_{ij}} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

(32.3)

Short form of Eq. 32.3:

$$\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) = A_{ij} + M_{ijkl} \frac{\partial \bar{v}_k}{\partial x_\ell} = \Phi_{ij,1} + \Phi_{ij,2}$$

- First term=slow term, $\Phi_{ij,1}$,
- second term=rapid term, $\Phi_{ij,2}$ (index 2 denotes the rapid part).

$$p'(\mathbf{x}) = \frac{\rho}{2\pi} \frac{\partial \bar{v}_i(\mathbf{x})}{\partial x_j} \int_V \frac{\partial v'_j(\mathbf{y})}{\partial y_i} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|} - \frac{\rho}{4\pi} \int_V \frac{\partial^2}{\partial y_i \partial y_j} (v'_i(\mathbf{y})v'_j(\mathbf{y})) \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

► Multiply Eq. 32.2 with $\partial v'_i/\partial x_j + \partial v'_j/\partial x_i$ and average:

$$\frac{p'(\mathbf{x})}{\rho} \left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) = \frac{\partial \bar{v}_k(\mathbf{x})}{\partial x_\ell} \frac{1}{2\pi} \int_V \underbrace{\left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial v'_\ell(\mathbf{y})}{\partial y_k}}_{M_{ijkl}} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

$$+ \frac{1}{4\pi} \int_V \underbrace{\left(\frac{\partial v'_i(\mathbf{x})}{\partial x_j} + \frac{\partial v'_j(\mathbf{x})}{\partial x_i} \right) \frac{\partial^2}{\partial y_k \partial y_\ell} (v'_k(\mathbf{y})v'_\ell(\mathbf{y}))}_{A_{ij}} \frac{d\mathbf{y}^3}{|\mathbf{y} - \mathbf{x}|}$$

(32.3)

Short form of Eq. 32.3:

$$\frac{p'}{\rho} \left(\frac{\partial v'_i}{\partial x_j} + \frac{\partial v'_j}{\partial x_i} \right) = A_{ij} + M_{ijkl} \frac{\partial \bar{v}_k}{\partial x_\ell} = \Phi_{ij,1} + \Phi_{ij,2}$$

- First term=slow term, $\Phi_{ij,1}$,
- second term=rapid term, $\Phi_{ij,2}$ (index 2 denotes the rapid part).

$$\Phi_{ij,2} = -c_2 \rho \left(P_{ij} - \frac{2}{3} \delta_{ij} P^k \right) \quad \text{IP model}$$

¶ See Section 11.7.6, Wall model of the pressure-strain term

¶ See Section 11.7.6, [Wall model of the pressure-strain term](#)

▶ Wall models of pressure-strain:

¶ See Section 11.7.6, [Wall model of the pressure-strain term](#)

▶ Wall models of pressure-strain:

$$\Phi_{ij} = \Phi_{ij,1} + \Phi_{ij,2} + \Phi_{ij,1w} + \Phi_{ij,2w}$$

¶ See Section 11.7.6, Wall model of the pressure-strain term

► Wall models of pressure-strain:

$$\Phi_{ij} = \Phi_{ij,1} + \Phi_{ij,2} + \Phi_{ij,1w} + \Phi_{ij,2w}$$

$$\Phi_{22,1w} = -2c_{1w} \frac{\varepsilon}{k} \overline{v_2'^2} f, \quad f \propto \frac{L_t}{|x_i - x_{i,wall}|} = \frac{k^{\frac{3}{2}}}{2.55 |n_{i,w} (x_i - x_{i,w})| \varepsilon}, \quad 0 < f < 1$$

¶ See Section 11.7.6, Wall model of the pressure-strain term

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$$\Phi_{ij} = \Phi_{ij,1} + \Phi_{ij,2} + \Phi_{ij,1w} + \Phi_{ij,2w}$$

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Traceless \Rightarrow

¶ See Section 11.7.6, Wall model of the pressure-strain term

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Traceless \Rightarrow

$$\Phi_{11,1w} = \Phi_{33,1w} = c_{1w} \frac{\varepsilon \overline{v_2'^2}}{k} f$$

¶ See Section 11.7.6, Wall model of the pressure-strain term

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$$\Phi_{ij} = \Phi_{ij,1} + \Phi_{ij,2} + \Phi_{ij,1w} + \Phi_{ij,2w}$$

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Traceless \Rightarrow

$$\Phi_{11,1w} = \Phi_{33,1w} = c_{1w} \frac{\varepsilon \overline{v_2'^2}}{k} f$$

The wall model for the shear stress is set as

$$\Phi_{12,1w} = -\frac{3}{2} c_{1w} \frac{\varepsilon \overline{v_1' v_2'}}{k} f$$

¶ See Section 11.7.6, Wall model of the pressure-strain term

► Wall models of pressure-strain:

$$\Phi_{ij} = \Phi_{ij,1} + \Phi_{ij,2} + \Phi_{ij,1w} + \Phi_{ij,2w}$$

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Traceless \Rightarrow

$$\Phi_{11,1w} = \Phi_{33,1w} = c_{1w} \frac{\varepsilon \overline{v_2'^2}}{k} f$$

The wall model for the shear stress is set as

$$\Phi_{12,1w} = -\frac{3}{2} c_{1w} \frac{\varepsilon \overline{v_1' v_2'}}{k} f$$

The general form reads:

¶ See Section 11.7.6, Wall model of the pressure-strain term

► Wall models of pressure-strain:

$$\Phi_{ij} = \Phi_{ij,1} + \Phi_{ij,2} + \Phi_{ij,1w} + \Phi_{ij,2w}$$

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Traceless \Rightarrow

$$\Phi_{11,1w} = \Phi_{33,1w} = c_{1w} \frac{\varepsilon}{k} \overline{v_2'^2} f$$

The wall model for the shear stress is set as

$$\Phi_{12,1w} = -\frac{3}{2} c_{1w} \frac{\varepsilon}{k} \overline{v_1' v_2'} f$$

The general form reads:

$$\Phi_{ij,1w} = c_{1w} \frac{\varepsilon}{k} \left(\overline{v_k' v_m'} n_{k,w} n_{m,w} \delta_{ij} - \frac{3}{2} \overline{v_k' v_i'} n_{k,w} n_{j,w} - \frac{3}{2} \overline{v_k' v_j'} n_{i,w} n_{k,w} \right) f$$

¶ See Section 11.7.6, Wall model of the pressure-strain term

► Wall models of pressure-strain:

$$\Phi_{ij} = \Phi_{ij,1} + \Phi_{ij,2} + \Phi_{ij,1w} + \Phi_{ij,2w}$$

$$\Phi_{22,1w} = -2c_{1w} \frac{\varepsilon}{k} \overline{v_2'^2} f, \quad f \propto \frac{L_t}{|x_i - x_{i,wall}|} = \frac{k^{\frac{3}{2}}}{2.55 |n_{i,w} (x_i - x_{i,w})| \varepsilon}, \quad 0 < f < 1$$

Traceless \Rightarrow

$$\Phi_{11,1w} = \Phi_{33,1w} = c_{1w} \frac{\varepsilon}{k} \overline{v_2'^2} f$$

The wall model for the shear stress is set as

$$\Phi_{12,1w} = -\frac{3}{2} c_{1w} \frac{\varepsilon}{k} \overline{v_1' v_2'} f$$

The general form reads:

$$\Phi_{ij,1w} = c_{1w} \frac{\varepsilon}{k} \left(\overline{v_k' v_m'} n_{k,w} n_{m,w} \delta_{ij} - \frac{3}{2} \overline{v_k' v_i'} n_{k,w} n_{j,w} - \frac{3}{2} \overline{v_k' v_j'} n_{i,w} n_{k,w} \right) f$$

The analogous wall model for the rapid part reads

¶ See Section 11.7.6, Wall model of the pressure-strain term

► Wall models of pressure-strain:

$$\Phi_{ij} = \Phi_{ij,1} + \Phi_{ij,2} + \Phi_{ij,1w} + \Phi_{ij,2w}$$

$$\Phi_{22,1w} = -2c_{1w} \frac{\varepsilon}{k} \overline{v_2'^2} f, \quad f \propto \frac{L_t}{|x_i - x_{i,wall}|} = \frac{k^{\frac{3}{2}}}{2.55 |n_{i,w} (x_i - x_{i,w})| \varepsilon}, \quad 0 < f < 1$$

Traceless \Rightarrow

$$\Phi_{11,1w} = \Phi_{33,1w} = c_{1w} \frac{\varepsilon}{k} \overline{v_2'^2} f$$

The wall model for the shear stress is set as

$$\Phi_{12,1w} = -\frac{3}{2} c_{1w} \frac{\varepsilon}{k} \overline{v_1' v_2'} f$$

The general form reads:

$$\Phi_{ij,1w} = c_{1w} \frac{\varepsilon}{k} \left(\overline{v_k' v_m'} n_{k,w} n_{m,w} \delta_{ij} - \frac{3}{2} \overline{v_k' v_i'} n_{k,w} n_{j,w} - \frac{3}{2} \overline{v_k' v_j'} n_{i,w} n_{k,w} \right) f$$

The analogous wall model for the rapid part reads

$$\Phi_{ij,2w} = c_{2w} \left(\Phi_{km,2} n_{k,w} n_{m,w} \delta_{ij} - \frac{3}{2} \Phi_{ki,2} n_{k,w} n_{j,w} - \frac{3}{2} \Phi_{kj,2} n_{i,w} n_{k,w} \right) f$$

¶ See Section 11.9, The modeled $\overline{v'_i v'_j}$ equation with IP model

▶ We can finally formulate the **modelled** $\overline{v'_i v'_j}$ equation (with IP model), the Reynolds Stress Model

(RSM)

$$\begin{aligned}
& \frac{\partial \overline{v'_i v'_j}}{\partial t} + \quad (\text{unsteady term}) \\
& \bar{v}_k \frac{\partial \overline{v'_i v'_j}}{\partial x_k} = \quad (\text{convection}) \\
& - \overline{v'_i v'_k} \frac{\partial \bar{v}_j}{\partial x_k} - \overline{v'_j v'_k} \frac{\partial \bar{v}_i}{\partial x_k} \quad (\text{production}) \\
& - c_1 \frac{\varepsilon}{k} \left(\overline{v'_i v'_j} - \frac{2}{3} \delta_{ij} k \right) \quad (\text{slow part}) \\
& - c_2 \left(P_{ij} - \frac{2}{3} \delta_{ij} P^k \right) \quad (\text{rapid part, IP model}) \\
& + c_{1w} \rho \frac{\varepsilon}{k} \left[\overline{v'_k v'_m n_k n_m} \delta_{ij} - \frac{3}{2} \overline{v'_i v'_k n_k n_j} - \frac{3}{2} \overline{v'_j v'_k n_k n_i} \right] f \quad (\text{wall, slow part}) \\
& + c_{2w} \left[\Phi_{km,2} n_k n_m \delta_{ij} - \frac{3}{2} \Phi_{ik,2} n_k n_j - \frac{3}{2} \Phi_{jk,2} n_k n_i \right] f \quad (\text{wall, rapid part, IP model}) \\
& + \nu \frac{\partial^2 \overline{v'_i v'_j}}{\partial x_k \partial x_k} \quad (\text{viscous diffusion}) \\
& + \frac{\partial}{\partial x_k} \left[\frac{\nu_t}{\sigma_k} \frac{\partial \overline{v'_i v'_j}}{\partial x_m} \right] \quad (\text{turbulent diffusion}) \\
& - g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'} \quad (\text{buoyancy production}) \\
& - \frac{2}{3} \varepsilon \delta_{ij} \quad (\text{dissipation})
\end{aligned} \tag{32.4}$$

¶ See Section 11.10, Algebraic Reynolds Stress Model (ASM)

▶ The Algebraic Reynolds Stress Model (ASM) is a simplified Reynolds Stress Model (RSM)

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▶ The Algebraic Reynolds Stress Model (ASM) is a simplified Reynolds Stress Model (RSM)

$$\text{RSM} : C_{ij} - D_{ij} = P_{ij} + \Phi_{ij} - \varepsilon_{ij}$$

¶ See Section 11.10, Algebraic Reynolds Stress Model (ASM)

▶ The Algebraic Reynolds Stress Model (ASM) is a simplified Reynolds Stress Model (RSM)

$$\begin{aligned} \text{RSM} : C_{ij} - D_{ij} &= P_{ij} + \Phi_{ij} - \varepsilon_{ij} \\ k - \varepsilon : C^k - D^k &= P^k - \varepsilon \end{aligned}$$

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Assumption in ASM:

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Assumption in ASM:

$$C_{ij} - D_{ij}$$

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Assumption in ASM:

$$C_{ij} - D_{ij} =$$

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$$\begin{aligned} \text{RSM} : C_{ij} - D_{ij} &= P_{ij} + \Phi_{ij} - \varepsilon_{ij} \\ k - \varepsilon : C^k - D^k &= P^k - \varepsilon \end{aligned}$$

Assumption in ASM:

$$C_{ij} - D_{ij} = (C^k - D^k)$$

¶ See Section 11.10, Algebraic Reynolds Stress Model (ASM)

► The Algebraic Reynolds Stress Model (ASM) is a simplified Reynolds Stress Model (RSM)

$$\begin{aligned} \text{RSM} : C_{ij} - D_{ij} &= P_{ij} + \Phi_{ij} - \varepsilon_{ij} \\ k - \varepsilon : C^k - D^k &= P^k - \varepsilon \end{aligned}$$

Assumption in ASM:

$$C_{ij} - D_{ij} = (C^k - D^k) \frac{\overline{v'_i v'_j}}{k}$$

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▶ We will consider source terms in the modelled $\overline{v'_i v'_j}$ equation for boundary layer flow.

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$\varepsilon_{12} = 0$: No sink term in $\overline{v'_1 v'_2}$ eq? Answer: the pressure strain terms $\Phi_{12,1}$ and $\Phi_{12,2}$ act as sink terms.

¶ See Section 12.1, [Stable and unstable stratification](#)

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► Assume there is a non-constant temperature field and that the natural convection is important (no forced convection). We have then two different flow conditions, stable or unstable conditions.

¶ See Section 12.1, [Stable and unstable stratification](#)

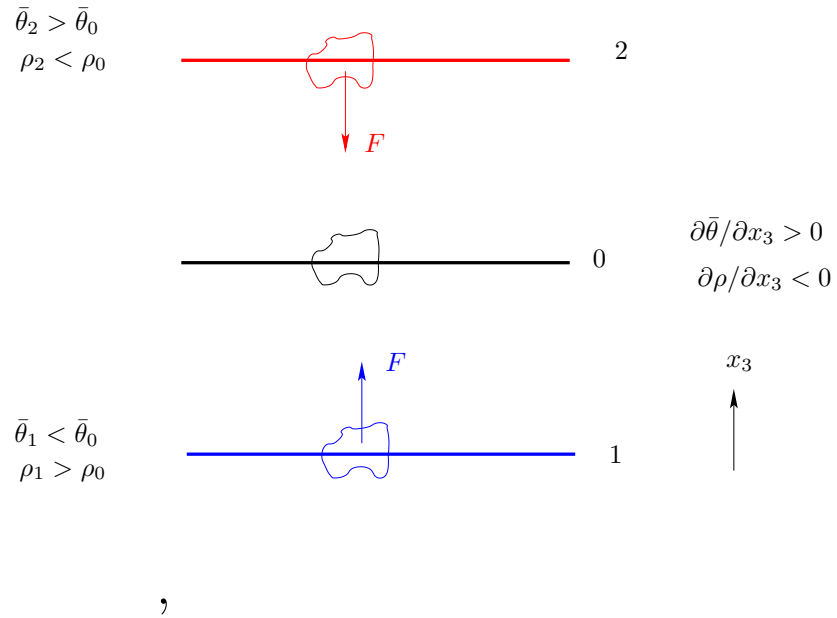
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▶ We start with stable stratification for which $\partial\bar{\theta}/\partial x_3 > 0$.

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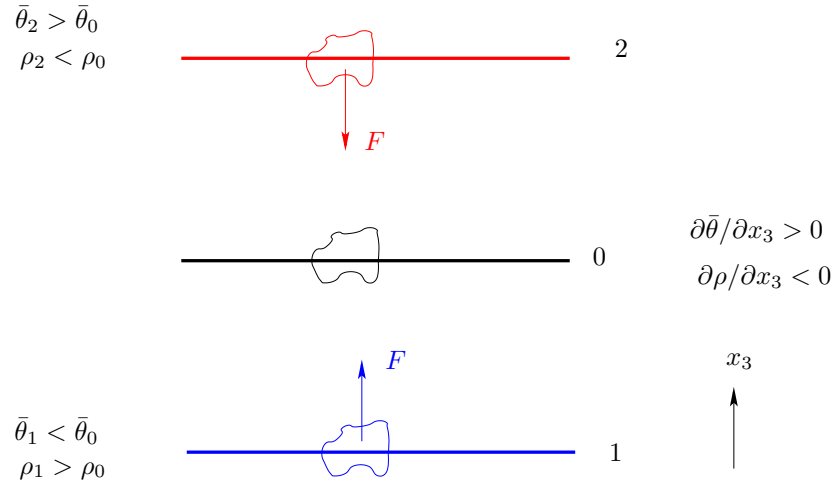
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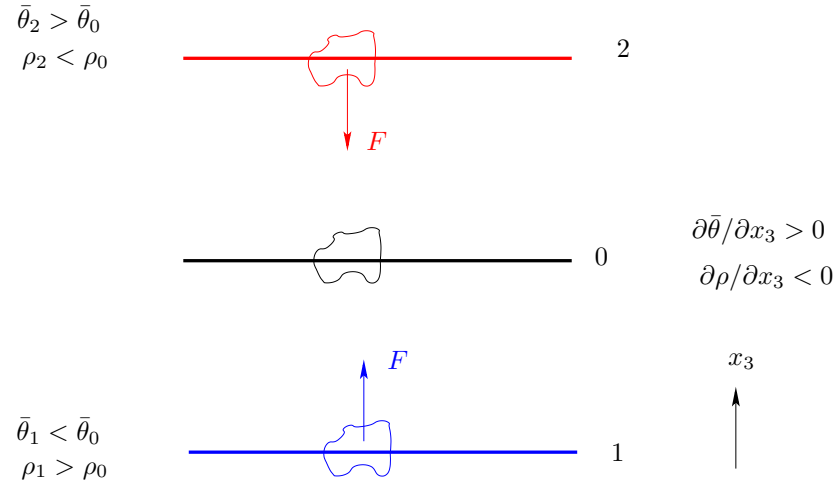


$$G_{ij} = -g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'},$$

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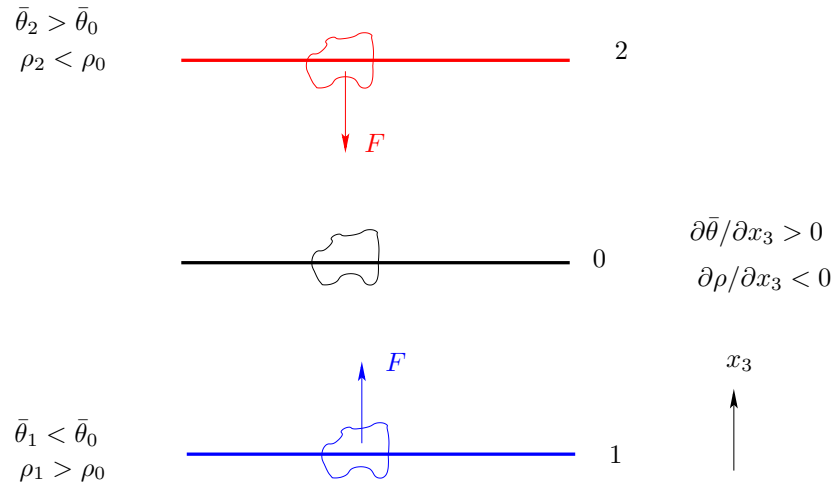


$$G_{ij} = -g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}, \quad g_i = (0, 0, -g)$$

¶ See Section 12.1, [Stable and unstable stratification](#)

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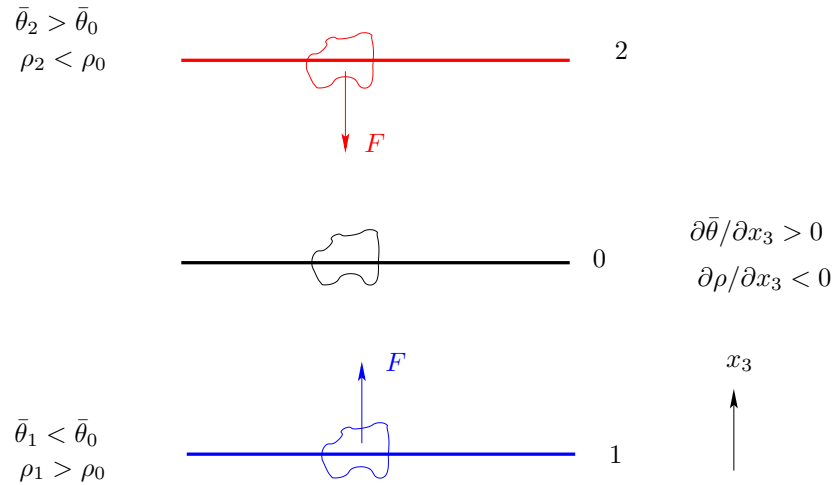


$$G_{ij} = -g_i \beta \overline{v'_j \theta'} - g_j \beta \overline{v'_i \theta'}, \quad g_i = (0, 0, -g) \quad \Rightarrow \quad \overline{v_3'^2} \text{ eq.: } G_{33} = 2g\beta \overline{v_3' \theta'}$$

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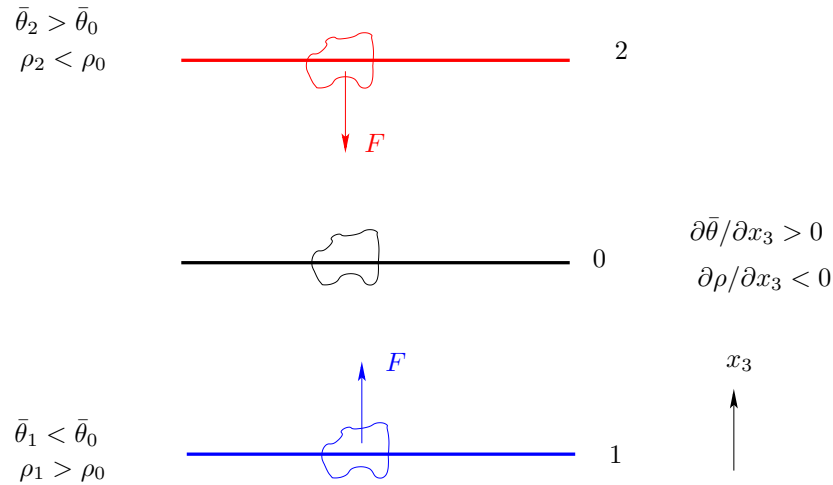
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which is the source term in the $\overline{v_3'^2}$ eq due to buoyancy.

¶ See Section 12.1, [Stable and unstable stratification](#)

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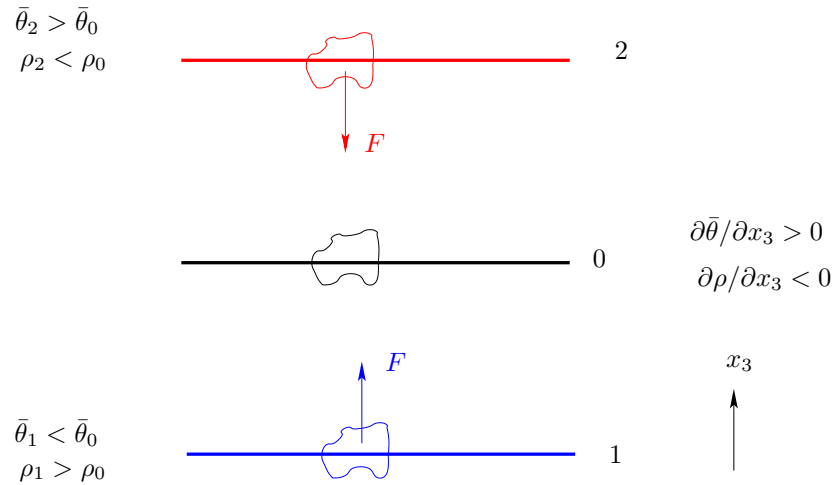
which is the source term in the $\overline{v_3'^2}$ eq due to buoyancy.

Now we need $\overline{v_3' \theta'}$.

¶ See Section 12.1, [Stable and unstable stratification](#)

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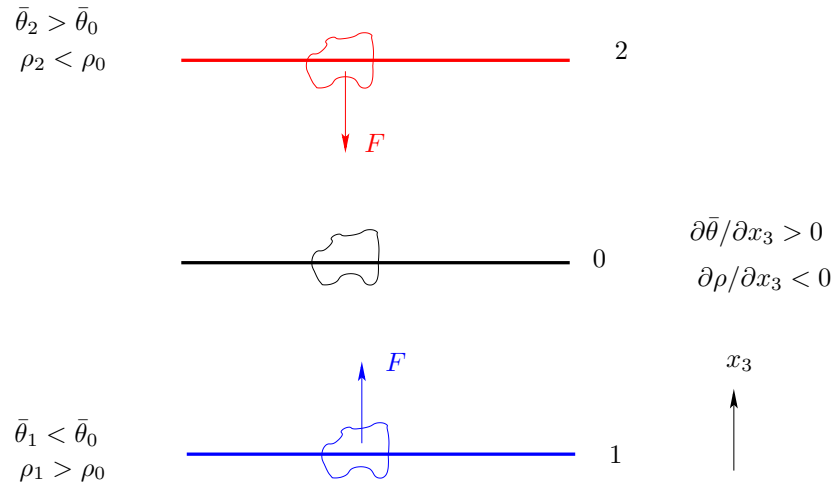
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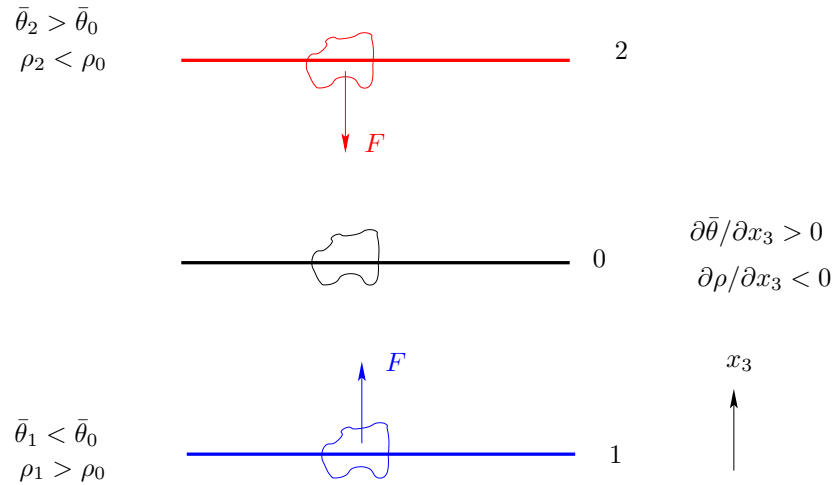
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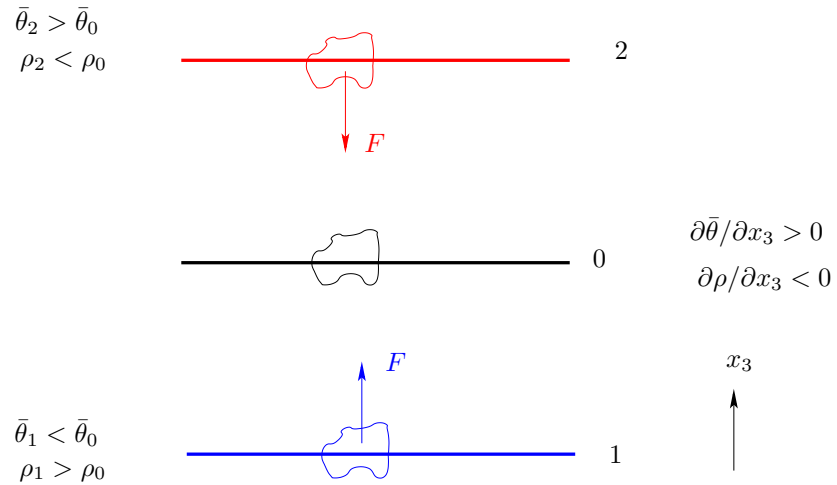
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► Note that the $k - \varepsilon$ model incorrectly dampens all normal stress, not only the vertical one

On-line Lecture 4

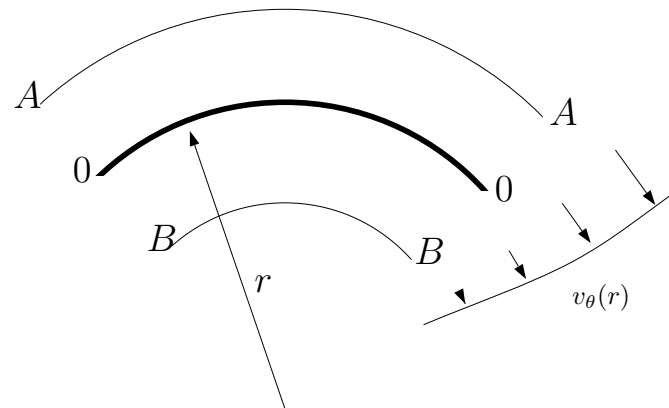
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On-line Lecture 4

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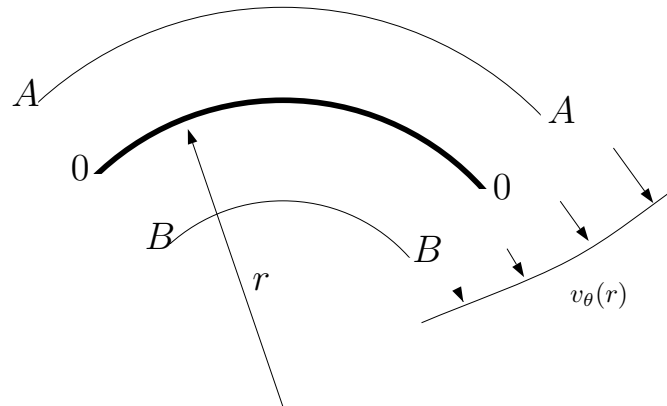


Flow aligned with the θ axis. $\partial v_\theta / \partial r > 0$

On-line Lecture 4

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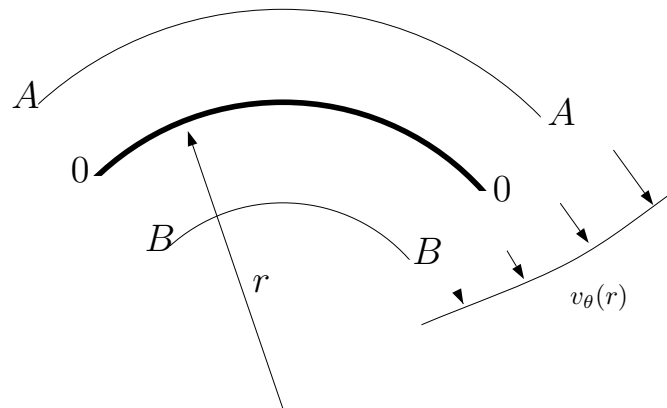
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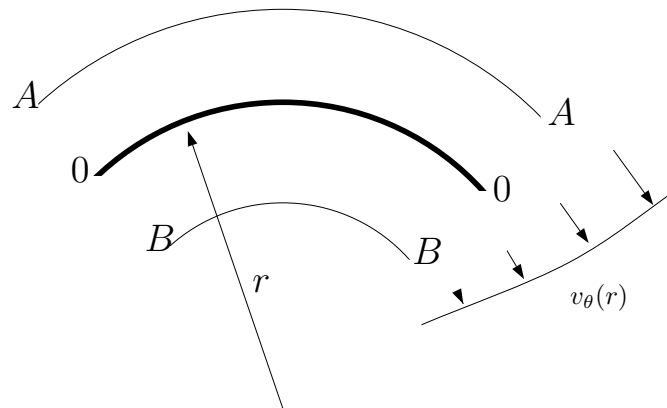
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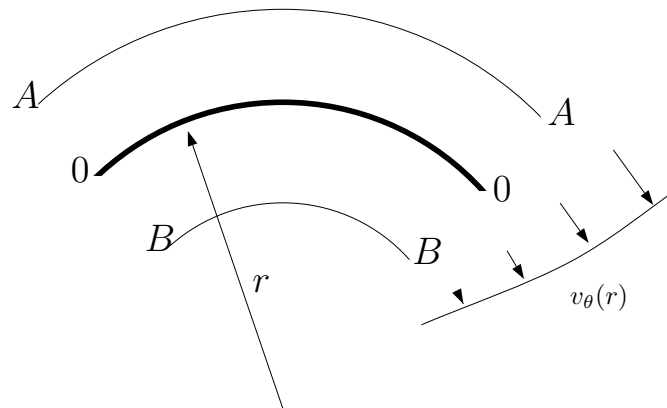
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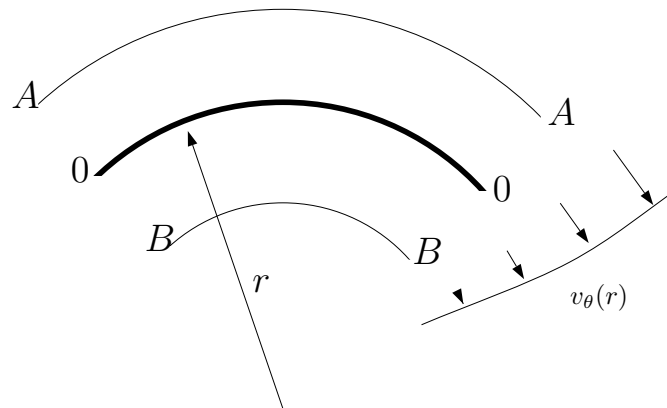
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On-line Lecture 4

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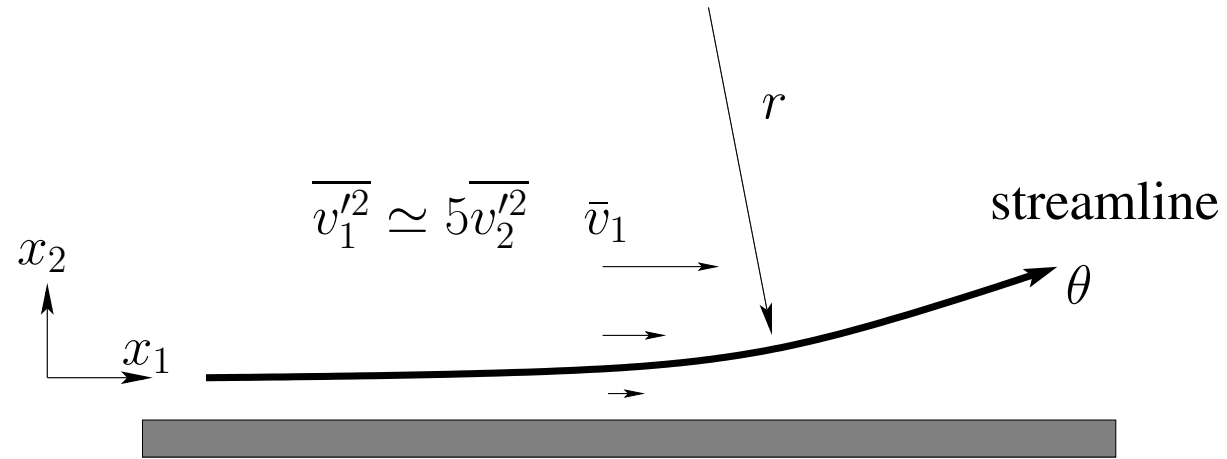
▶ The streamline curvature stabilized (decreases) the turbulence

▶ Change sign of velocity gradient $\partial v_\theta / \partial r < 0$: now streamline curvature will **increase** the turbulence

► Now we will find out how well the effect of streamline curvature is modeled by RSM (and ASM).

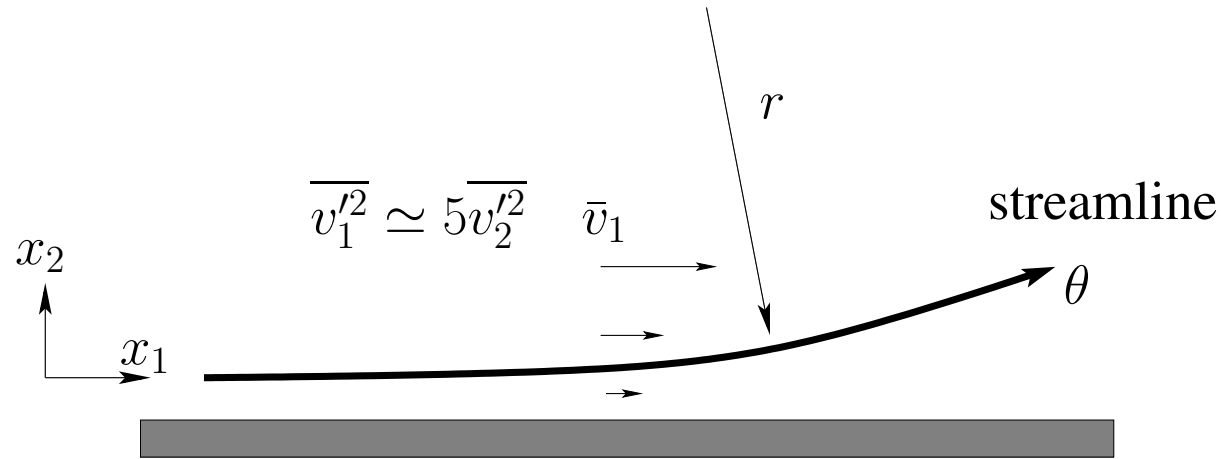
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► We choose a boundary layer flow as below



A boundary layer flow that gradually departs from the wall. $\frac{\partial \bar{v}_2}{\partial x_1} > 0$, $\frac{\partial \bar{v}_1}{\partial x_2} > 0$

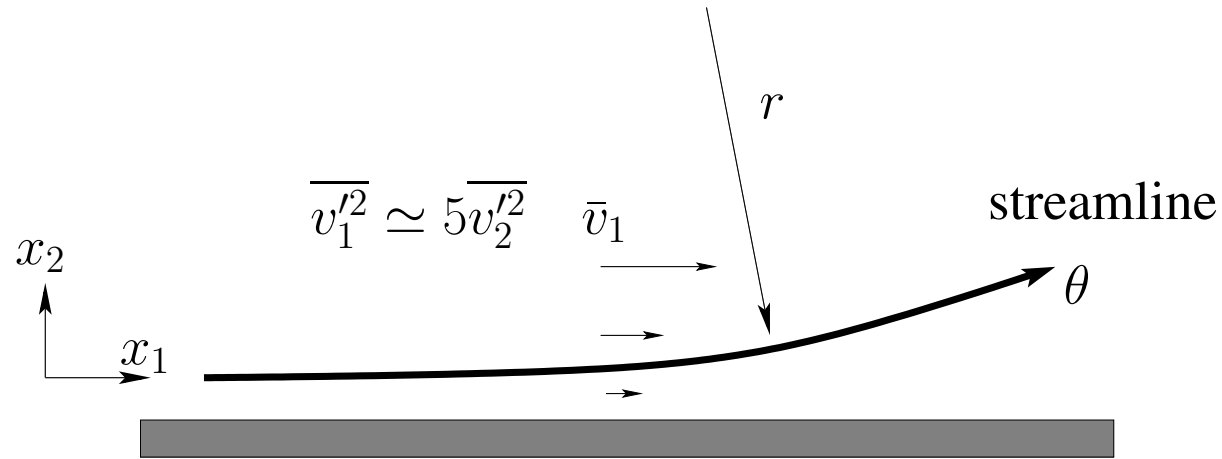
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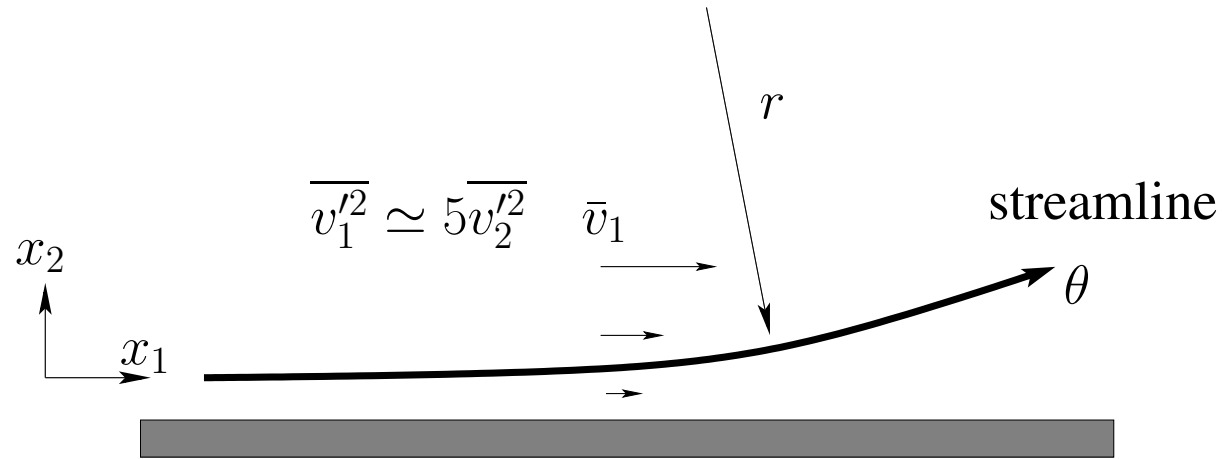
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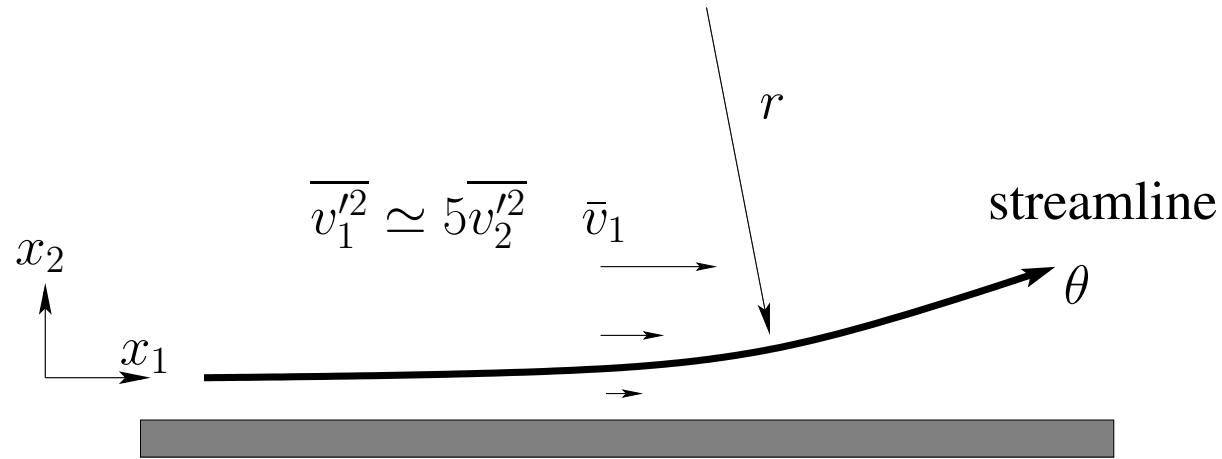


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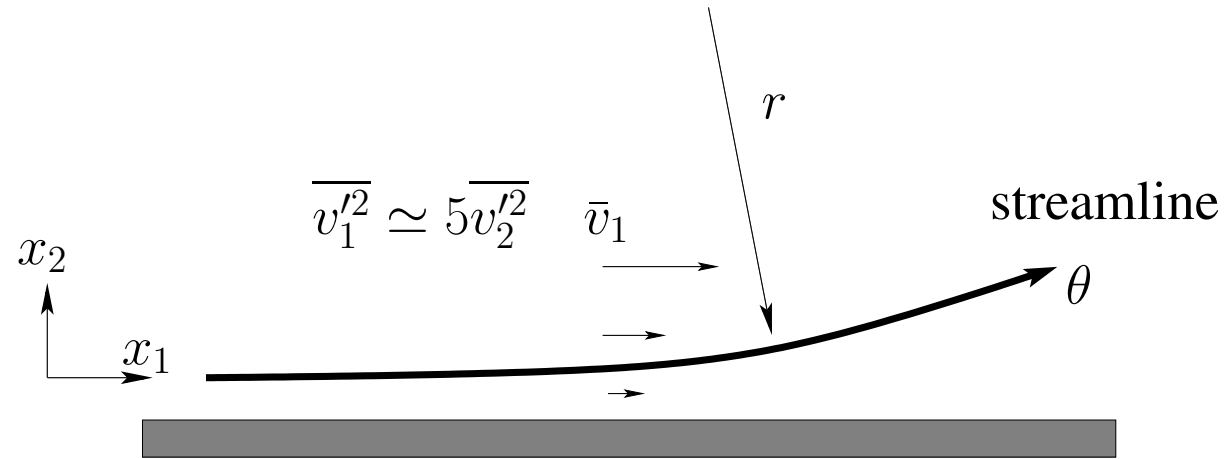


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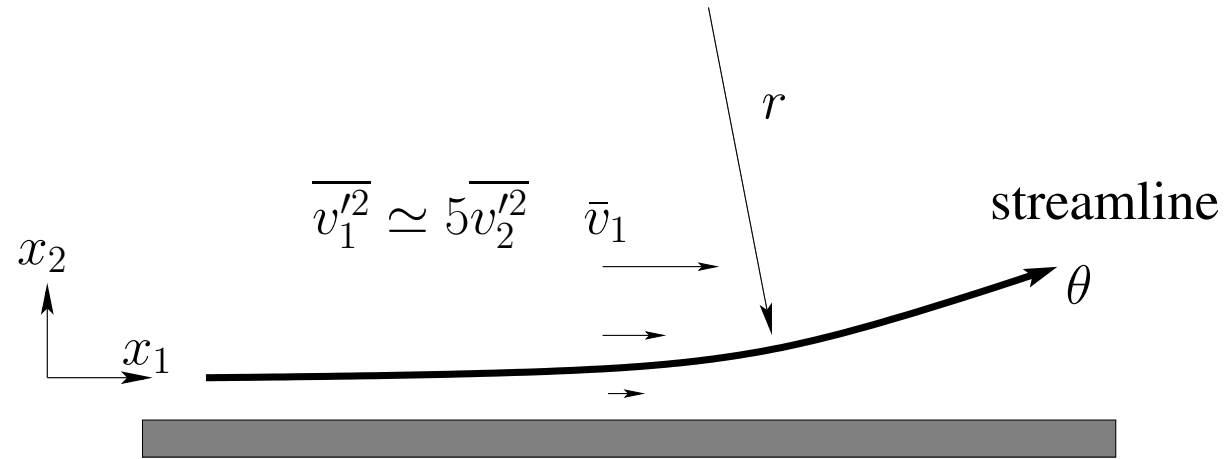


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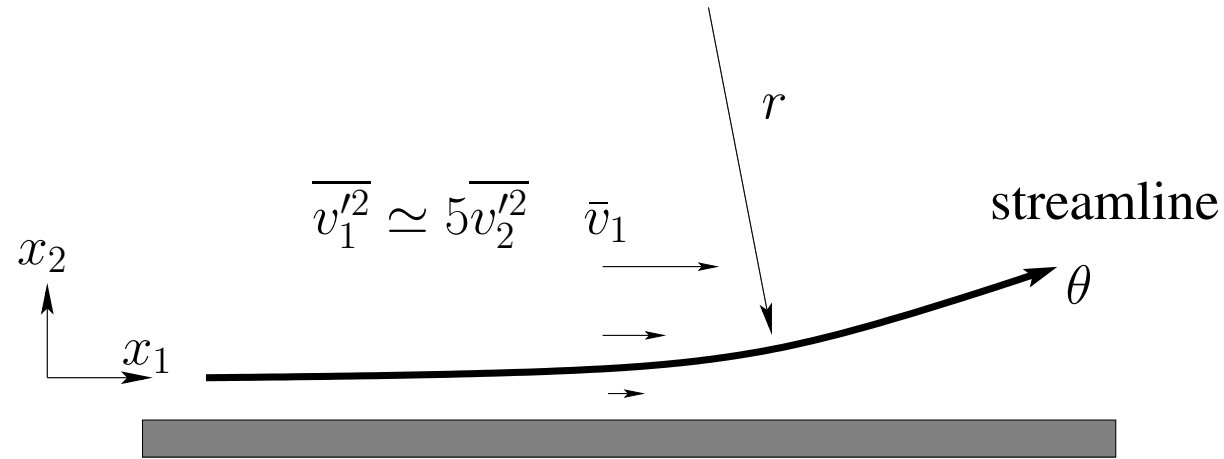
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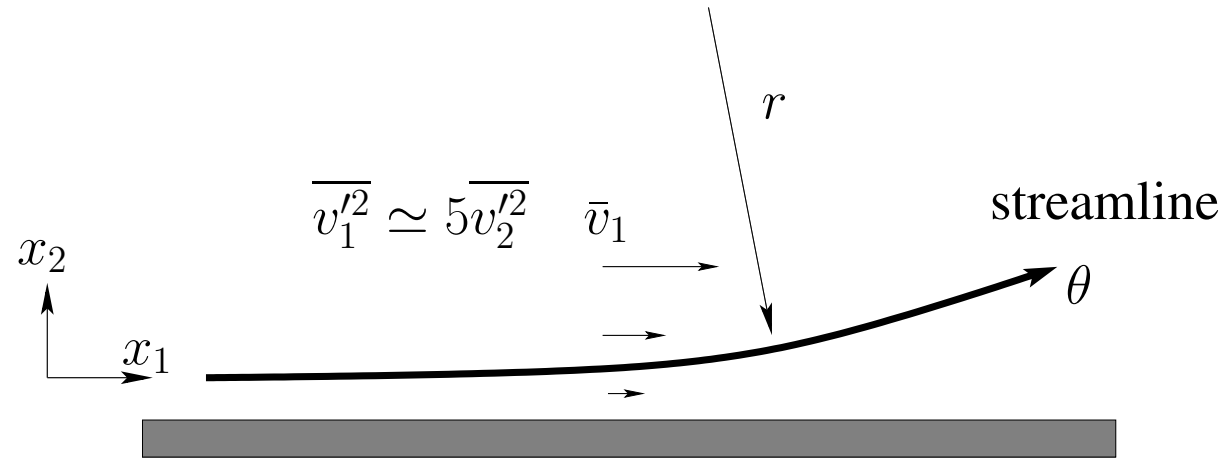
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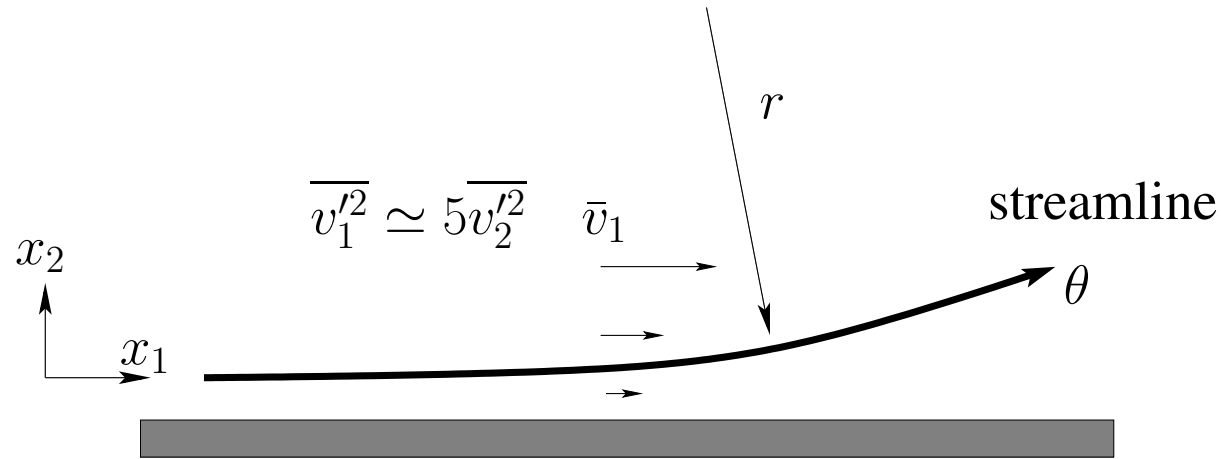
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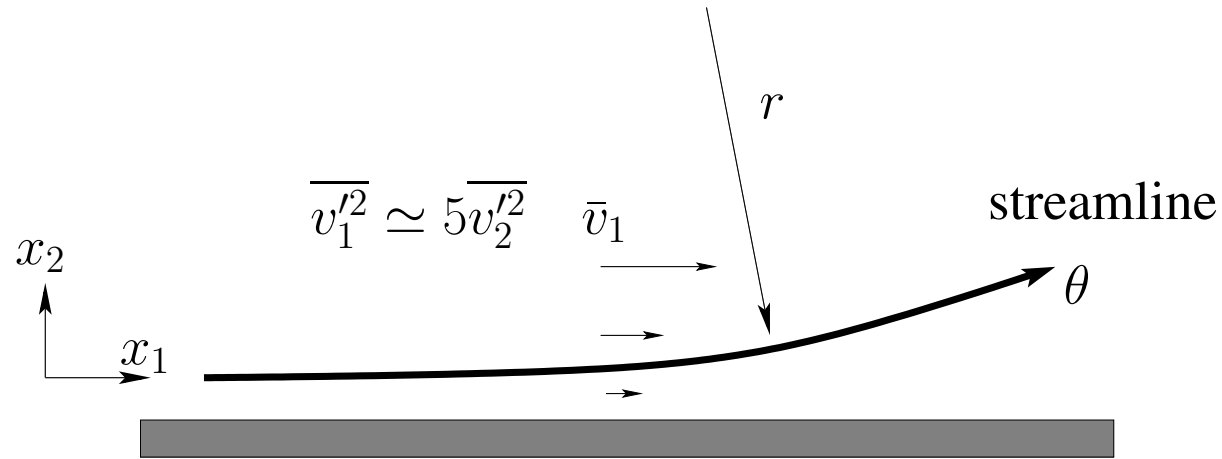
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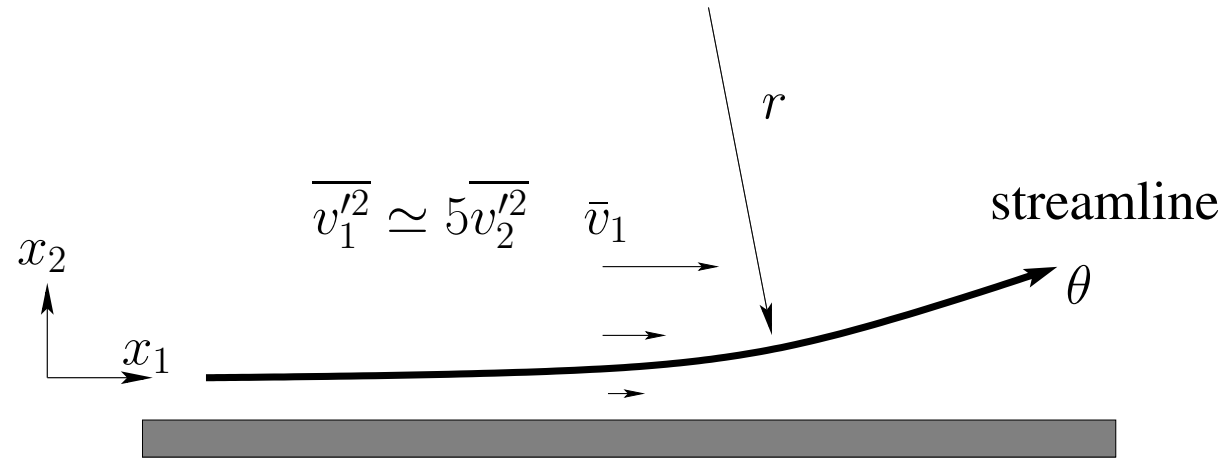
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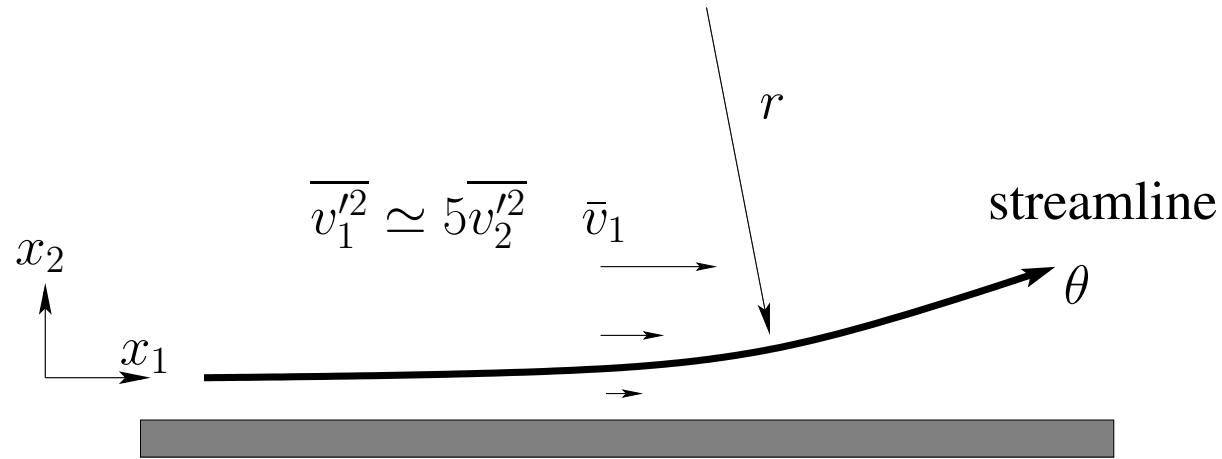
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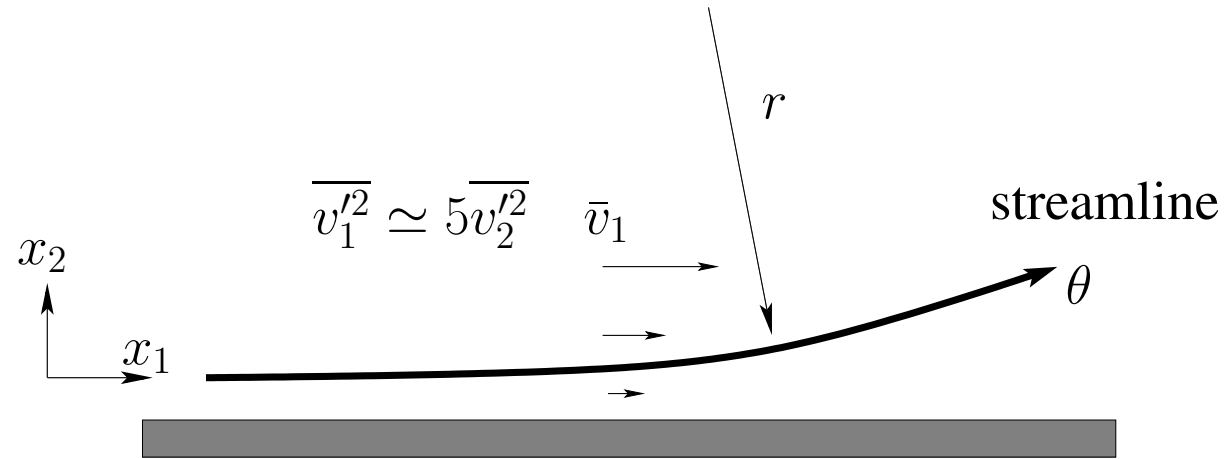
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$$k - \varepsilon \quad P^k$$

► We choose a boundary layer flow as below



A boundary layer flow that gradually departs from the wall. $\frac{\partial \bar{v}_2}{\partial x_1} > 0$, $\frac{\partial \bar{v}_1}{\partial x_2} > 0$

► For this flow, the production terms read (boxed terms appear because $\frac{\partial \bar{v}_2}{\partial x_1}$ is not negligible)

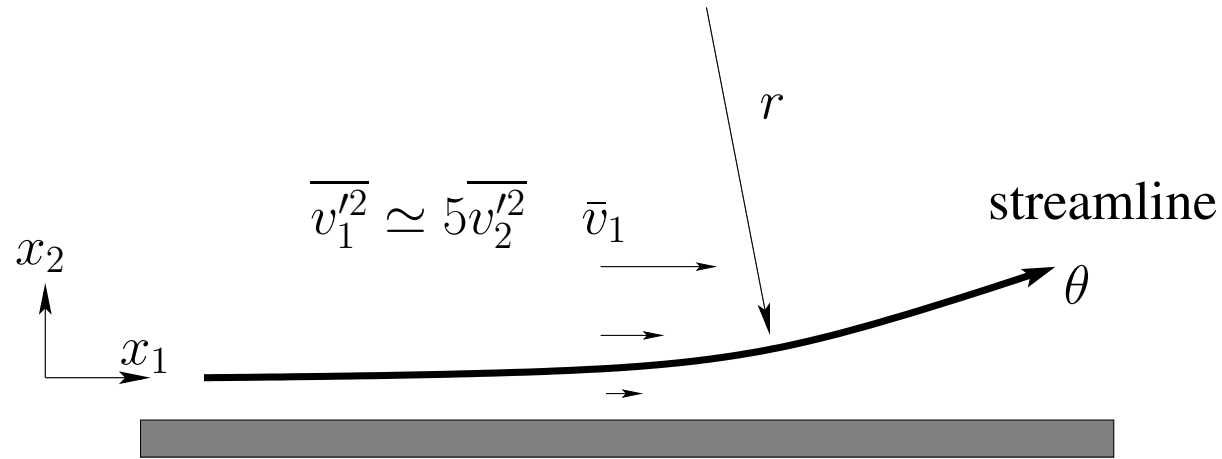
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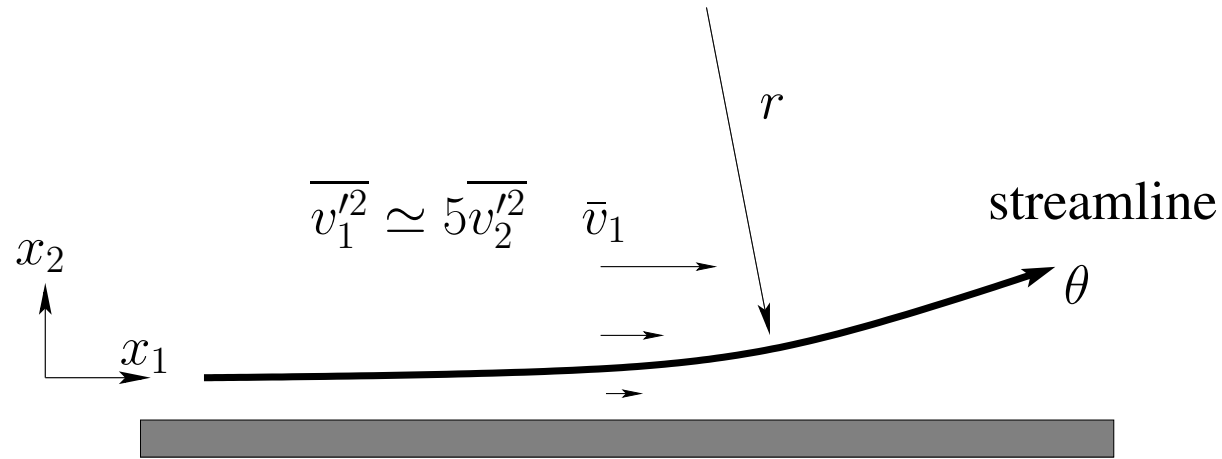
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A boundary layer flow that gradually departs from the wall. $\frac{\partial \bar{v}_2}{\partial x_1} > 0$, $\frac{\partial \bar{v}_1}{\partial x_2} > 0$

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▶ $k - \varepsilon$ model: it does react to streamline curvature but much less ▶ Why?

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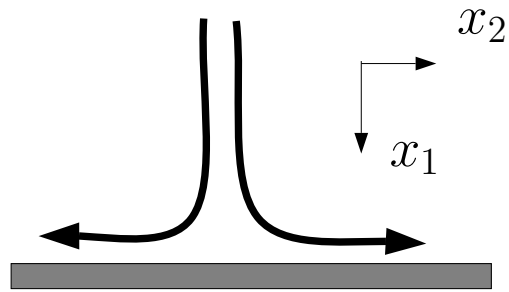
Contrary to RSM, the two velocity gradients are multiplied by the same coefficient

¶ See Section 12.3, Stagnation flow

▶ Stagnation 2D flow

¶ See Section 12.3, Stagnation flow

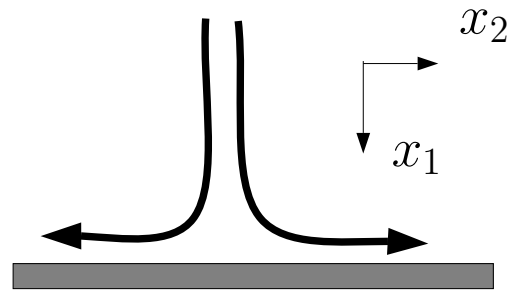
▶ Stagnation 2D flow



The flow pattern for stagnation flow.

¶ See Section 12.3, Stagnation flow

► Stagnation 2D flow

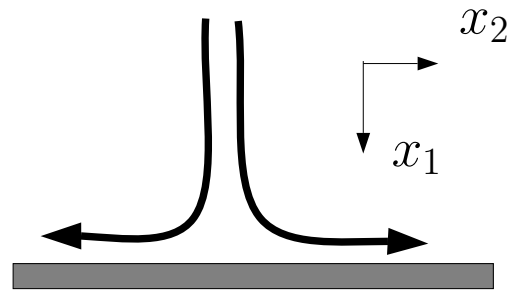


The flow pattern for stagnation flow.

► Near the plate, strong deceleration, i.e. large $\frac{\partial \bar{v}_1}{\partial x_1}$.

¶ See Section 12.3, Stagnation flow

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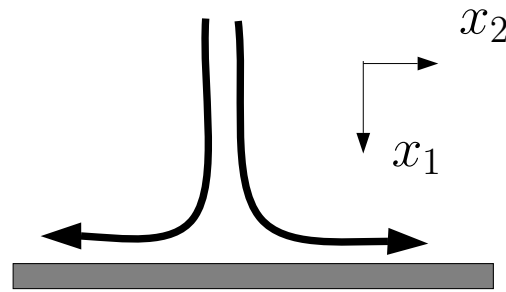


The flow pattern for stagnation flow.

▶ Near the plate, strong deceleration, i.e. large $\frac{\partial \bar{v}_1}{\partial x_1}$. ▶ Continuity equation \Rightarrow large $\frac{\partial \bar{v}_2}{\partial x_2}$

¶ See Section 12.3, Stagnation flow

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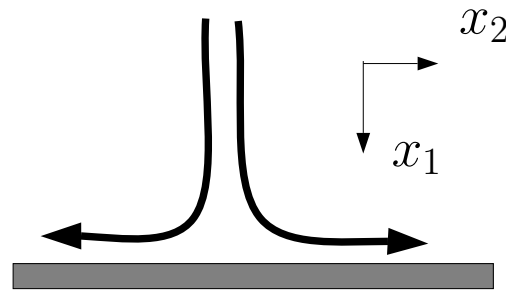


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- ▶ Near the plate, strong deceleration, i.e. large $\frac{\partial \bar{v}_1}{\partial x_1}$. ▶ Continuity equation \Rightarrow large $\frac{\partial \bar{v}_2}{\partial x_2}$
- ▶ The velocity gradient $\frac{\partial \bar{v}_1}{\partial x_2}$ and $\frac{\partial \bar{v}_2}{\partial x_1}$ are in this flow negligible.

¶ See Section 12.3, Stagnation flow

▶ Stagnation 2D flow



The flow pattern for stagnation flow.

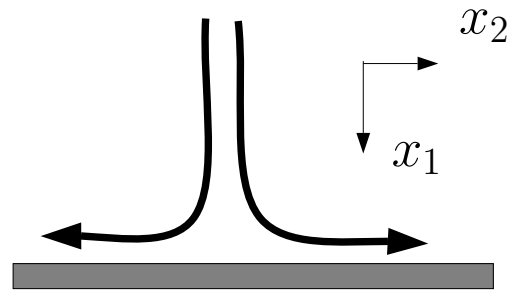
▶ Near the plate, strong deceleration, i.e. large $\frac{\partial \bar{v}_1}{\partial x_1}$. ▶ Continuity equation \Rightarrow large $\frac{\partial \bar{v}_2}{\partial x_2}$

▶ The velocity gradient $\frac{\partial \bar{v}_1}{\partial x_2}$ and $\frac{\partial \bar{v}_2}{\partial x_1}$ are in this flow negligible.

RSM/ASM :

See Section 12.3, Stagnation flow

▶ Stagnation 2D flow



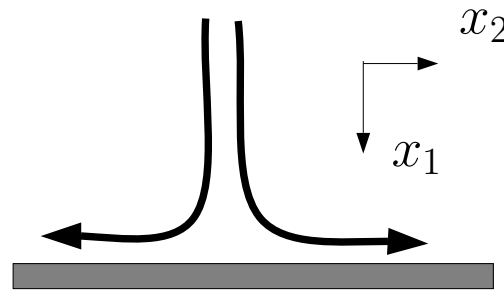
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$$RSM/ASM : 0.5 (P_{11} + P_{22})$$

See Section 12.3, Stagnation flow

Stagnation 2D flow



The flow pattern for stagnation flow.

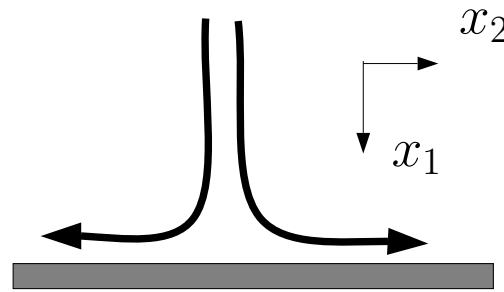
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The velocity gradient $\frac{\partial \bar{v}_1}{\partial x_2}$ and $\frac{\partial \bar{v}_2}{\partial x_1}$ are in this flow negligible.

$$RSM/ASM : 0.5 (P_{11} + P_{22}) = -\bar{v}_1'^2 \frac{\partial \bar{v}_1}{\partial x_1} - \bar{v}_2'^2 \frac{\partial \bar{v}_2}{\partial x_2}$$

See Section 12.3, Stagnation flow

▶ Stagnation 2D flow



The flow pattern for stagnation flow.

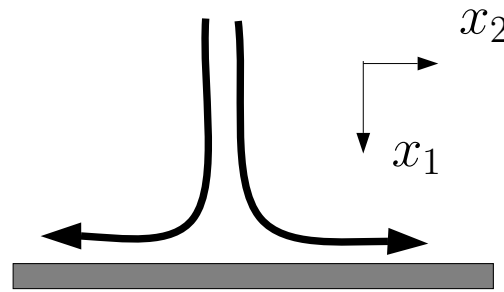
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See Section 12.3, Stagnation flow

▶ Stagnation 2D flow



The flow pattern for stagnation flow.

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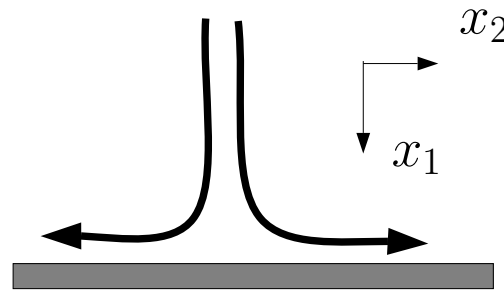
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$k - \varepsilon$:

See Section 12.3, Stagnation flow

▶ Stagnation 2D flow



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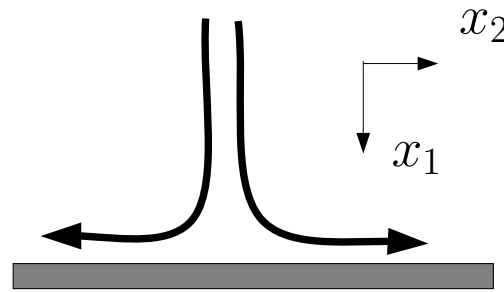
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$$k - \varepsilon : P^k = 2\nu_t \left\{ \left(\frac{\partial \bar{v}_1}{\partial x_1} \right)^2 + \left(\frac{\partial \bar{v}_2}{\partial x_2} \right)^2 \right\}$$

See Section 12.3, Stagnation flow

Stagnation 2D flow



The flow pattern for stagnation flow.

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For RSM/ASM, $\overline{v_1'^2} - \overline{v_2'^2}$ nearly cancels whereas for $k - \varepsilon$ they don't since the sum of squared velocity gradients is used.

¶ See Section 13, Realizability

▶ Realizability

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▶ Realizability

$$\overline{v_i^2}$$

¶ See Section 13, Realizability

▶ Realizability

$$\overline{v_i^2} \geq$$

¶ See Section 13, [Realizability](#)

► Realizability

$$\overline{v_i^2} \geq 0 \text{ for all } i$$

¶ See Section 13, **Realizability**

► **Realizability**

$$\overline{v_i'^2} \geq 0 \text{ for all } i$$
$$\frac{|\overline{v_i' v_j'}|}{\left(\overline{v_i'^2} \overline{v_j'^2}\right)^{1/2}}$$

¶ See Section 13, [Realizability](#)

► Realizability

$$\begin{aligned} \overline{v_i'^2} &\geq 0 \text{ for all } i \\ \frac{|\overline{v_i' v_j'}|}{\left(\overline{v_i'^2} \overline{v_j'^2}\right)^{1/2}} &\leq \end{aligned}$$

¶ See Section 13, [Realizability](#)

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¶ See Section 13, Realizability

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\bar{s}_{11} largest in the principal coordinate directions. Hence, let's find the eigenvalues of \bar{s}_{ij}

¶ See Section 13, [Realizability](#)

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which gives in 2D

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¶ See Section 13, Realizability

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See Section 13, [Realizability](#)

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$$I_2^{2D} = \frac{1}{2}(\bar{s}_{ii}\bar{s}_{jj} - \bar{s}_{ij}\bar{s}_{ij}) = \det(C_{ij}) = -\bar{s}_{ij}\bar{s}_{ij}/2$$

See Section 13, [Realizability](#)

► Realizability

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$$\left(\overline{v_1'^2} \right)_{\lambda_1}$$

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In 3D

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In 3D

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¶ See Section 14, Non-linear Eddy-viscosity Models

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¶ See Section 14, [Non-linear Eddy-viscosity Models](#)

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$$\begin{aligned}
 a_{ij} &\equiv \frac{\overline{v'_i v'_j}}{k} - \frac{2}{3} \delta_{ij} \\
 a_{ij} &= \boxed{-2c_\mu \tau \bar{s}_{ij}} + c_1 \tau^2 \left(\bar{s}_{ik} \bar{s}_{kj} - \frac{1}{3} \bar{s}_{mk} \bar{s}_{mk} \delta_{ij} \right) + c_2 \tau^2 \left(\bar{\Omega}_{ik} \bar{s}_{kj} - \bar{s}_{ik} \bar{\Omega}_{kj} \right) \\
 &+ c_3 \tau^2 \left(\bar{\Omega}_{ik} \bar{\Omega}_{jk} - \frac{1}{3} \bar{\Omega}_{mk} \bar{\Omega}_{mk} \delta_{ij} \right) + c_4 \tau^3 \left(\bar{s}_{ik} \bar{s}_{km} \bar{\Omega}_{mj} - \bar{\Omega}_{im} \bar{s}_{mk} \bar{s}_{kj} \right) \\
 &+ c_5 \tau^3 \left(\bar{\Omega}_{im} \bar{\Omega}_{mm} \bar{s}_{mj} + \bar{s}_{im} \bar{\Omega}_{mm} \bar{\Omega}_{mj} - \frac{2}{3} \bar{\Omega}_{mn} \bar{\Omega}_{nm} \bar{s}_{mm} \delta_{ij} \right) + c_6 \tau^3 \bar{s}_{km} \bar{s}_{km} \bar{s}_{ij} + c_7 \tau^3 \bar{\Omega}_{km} \bar{\Omega}_{km} \bar{s}_{ij} \\
 \bar{s}_{ij} &= \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \bar{\Omega}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{v}_i}{\partial x_j} - \frac{\partial \bar{v}_j}{\partial x_i} \right), \quad \tau = \frac{k}{\varepsilon} \text{ or } \tau = \frac{1}{c_\mu \omega}
 \end{aligned} \tag{33.2}$$

See Section 14, [Non-linear Eddy-viscosity Models](#)

- It is non-linear in velocity gradients.
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(33.2)

► symmetric

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(33.2)

► symmetric, ► trace-less

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- ▶ Why no cubic terms? Caley-Hamilton theorem which is based on the characteristic equation in 3D

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- ▶ Why no cubic terms? Caley-Hamilton theorem which is based on the characteristic equation in 3D

$$\lambda^3 + I_1^{3D} \lambda^2 - I_2^{3D} \lambda + I_3^{3D} = 0$$

► Let's verify that the three first terms are indeed symmetric and traceless

▶ Let's verify that the three first terms are indeed symmetric and traceless

▶ Term 1

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▶ Term 1

$$-2c_\mu \tau \bar{s}_{ij}$$

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▶ Term 1

$$-2c_{\mu}\tau\bar{s}_{ij} \quad \text{symmetric:}$$

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► Term 1

$$-2c_{\mu\tau}\bar{s}_{ij} \quad \text{symmetric: } \bar{s}_{ij} = \bar{s}_{ji}$$

► Let's verify that the three first terms are indeed symmetric and traceless

► Term 1

$-2c_\mu \tau \bar{s}_{ij}$ symmetric: $\bar{s}_{ij} = \bar{s}_{ji}$, traceless:

► Let's verify that the three first terms are indeed symmetric and traceless

► Term 1

$$-2c_{\mu}\tau\bar{s}_{ij} \quad \text{symmetric: } \bar{s}_{ij} = \bar{s}_{ji}, \quad \text{traceless: } \bar{s}_{ii} = 0$$

▶ Let's verify that the three first terms are indeed symmetric and traceless

▶ Term 1

$$-2c_{\mu\tau}\bar{s}_{ij} \quad \text{symmetric: } \bar{s}_{ij} = \bar{s}_{ji}, \quad \text{traceless: } \bar{s}_{ii} = 0$$

▶ Term 2

► Let's verify that the three first terms are indeed symmetric and traceless

► Term 1

$$-2c_\mu \tau \bar{s}_{ij} \quad \text{symmetric: } \bar{s}_{ij} = \bar{s}_{ji}, \quad \text{traceless: } \bar{s}_{ii} = 0$$

► Term 2

$$\left(\bar{s}_{ik} \bar{s}_{kj} - \frac{1}{3} \bar{s}_{mk} \bar{s}_{mk} \delta_{ij} \right)$$

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$$-2c_{\mu}\tau\bar{s}_{ij} \quad \text{symmetric: } \bar{s}_{ij} = \bar{s}_{ji}, \quad \text{traceless: } \bar{s}_{ii} = 0$$

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$$\left(\bar{s}_{ik}\bar{s}_{kj} - \frac{1}{3}\bar{s}_{mk}\bar{s}_{mk}\delta_{ij} \right) \quad \text{symmetric :}$$

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► Term 3

► Let's verify that the three first terms are indeed symmetric and traceless

► Term 1

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► Term 2

$$\left(\bar{s}_{ik}\bar{s}_{kj} - \frac{1}{3}\bar{s}_{mk}\bar{s}_{mk}\delta_{ij} \right) \quad \text{symmetric : } \bar{s}_{ik}\bar{s}_{kj} = \bar{s}_{jk}\bar{s}_{ki} = \bar{s}_{kj}\bar{s}_{ik} \quad \delta_{ij} = \delta_{ji}$$
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► Term 3

$$\left(\bar{\Omega}_{ik}\bar{\Omega}_{jk} - \frac{1}{3}\bar{\Omega}_{mk}\bar{\Omega}_{mk}\delta_{ij} \right)$$

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► We find that the normal stresses are indeed not equal (contrary to the standard linear $k - \varepsilon$ model)

On-line Lecture 5

¶ See Section 15, The V2F Model



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► Now solve it (with a 1D finite volume code) for different L and S

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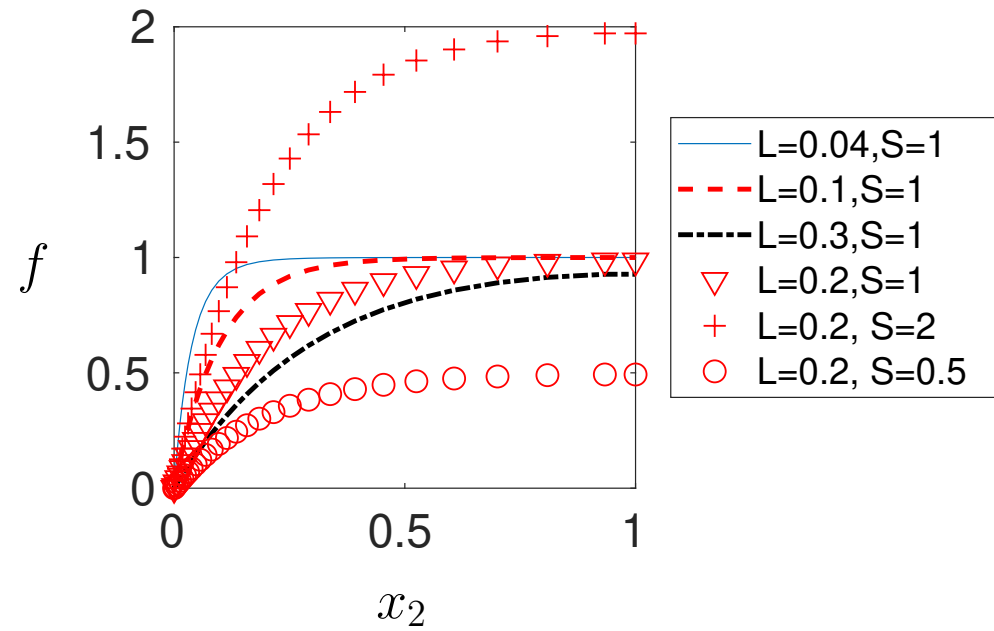
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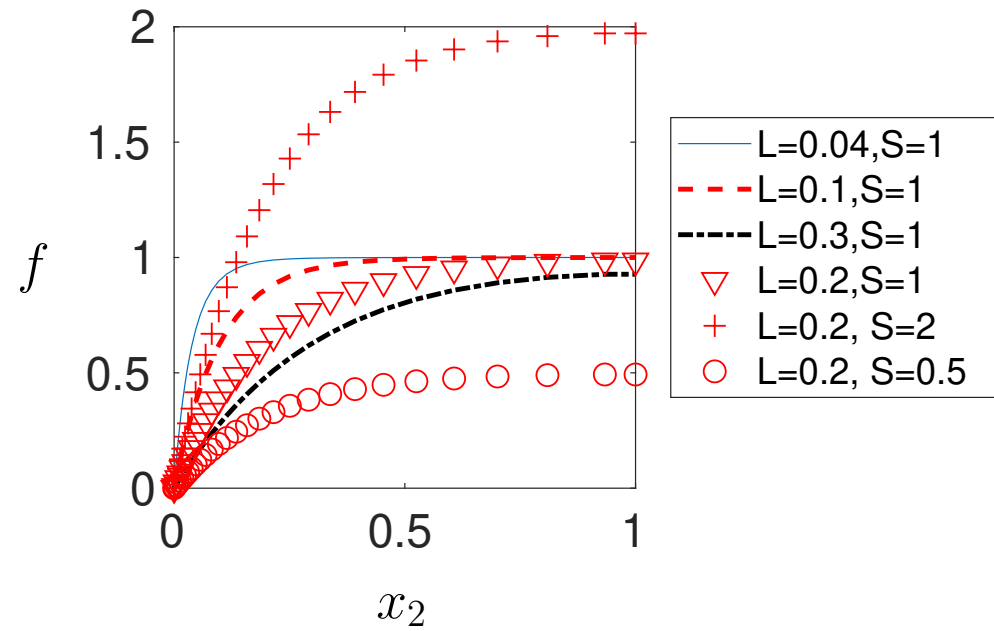
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Solution of Eq. 34.1 for different L and S

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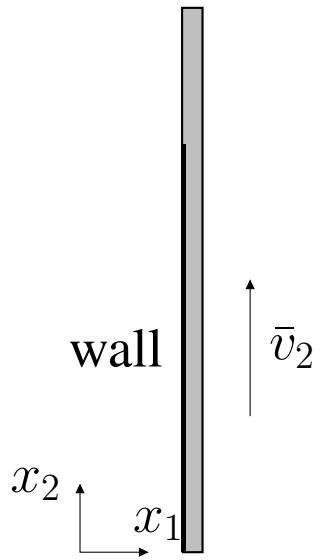
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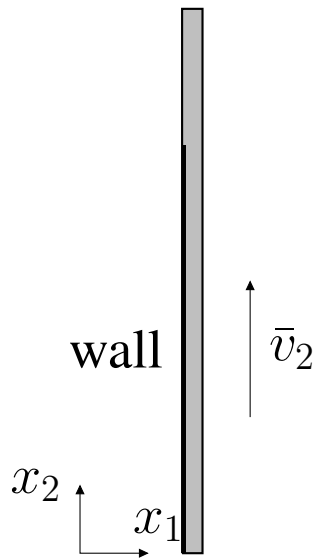
► How does the V2F model behave near a vertical wall?

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Boundary later along a vertical wall

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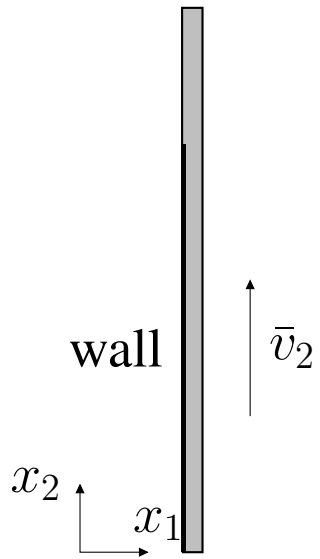


Boundary later along a vertical wall

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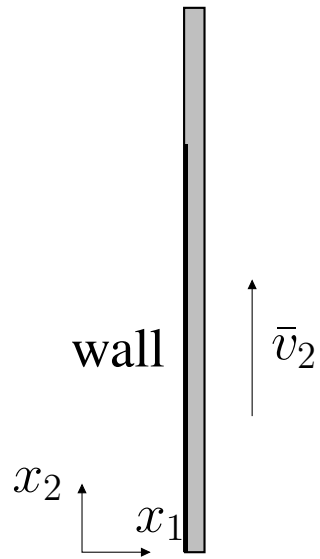


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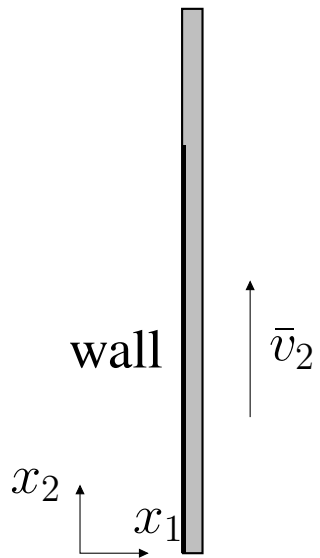


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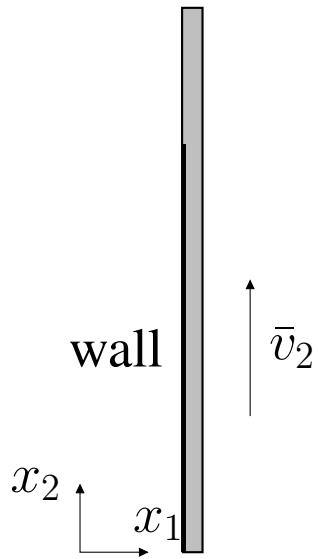


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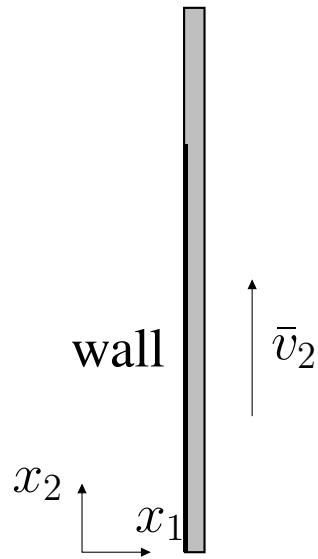


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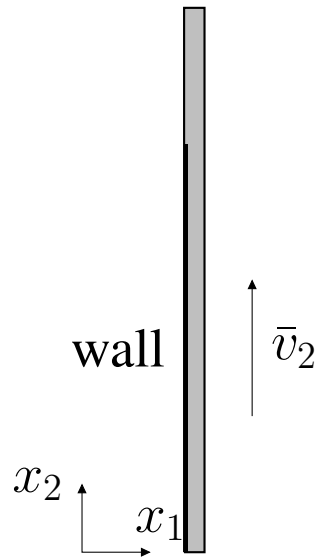


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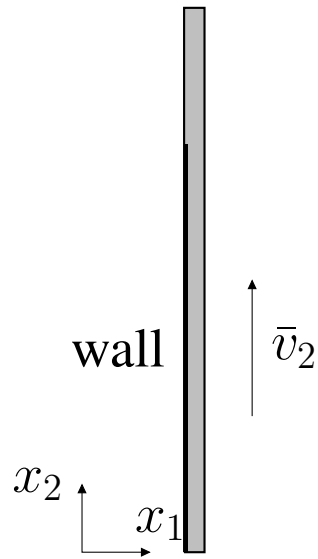


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- For the vertical plate, P^k is dominated by $\frac{\partial \bar{v}_2}{\partial x_1}$
- Hence, in this case (the vertical plate), v^2 corresponds to $\overline{v_1'^2}$
- P^k in the expression of Φ_{22} explains why v^2 is equal to $\overline{v_2'^2}$, $\overline{v_1'^2}$ or $\overline{v_3'^2}$ depending on orientation of the nearest wall (the largest velocity gradient).

¶ See Section 16, [The SST Model](#)

▶ The SST (Shear Stress Transport) model

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1.(a)

¶ See Section 16, [The SST Model](#)

► The SST (Shear Stress Transport) model

1. Combination of a $k - \omega$ model (in the inner boundary layer) and $k - \varepsilon$ model (in the outer region of the boundary layer as well as outside of it)

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¶ See Section 16, [The SST Model](#)

► The SST (Shear Stress Transport) model

1. Combination of a $k - \omega$ model (in the inner boundary layer) and $k - \varepsilon$ model (in the outer region of the boundary layer as well as outside of it)

(a) $k - \omega$ is good for near-wall turbulence (well-defined b.c., no additional near-wall terms)

¶ See Section 16, [The SST Model](#)

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1. Combination of a $k - \omega$ model (in the inner boundary layer) and $k - \varepsilon$ model (in the outer region of the boundary layer as well as outside of it)
 - (a) $k - \omega$ is good for near-wall turbulence (well-defined b.c., no additional near-wall terms)
 - (b) $k - \omega$ has a problem with far-field boundary conditions; $k - \varepsilon$ can handle these b.c.

¶ See Section 16, [The SST Model](#)

► The SST (Shear Stress Transport) model

1. Combination of a $k - \omega$ model (in the inner boundary layer) and $k - \varepsilon$ model (in the outer region of the boundary layer as well as outside of it)
 - (a) $k - \omega$ is good for near-wall turbulence (well-defined b.c., no additional near-wall terms)
 - (b) $k - \omega$ has a problem with far-field boundary conditions; $k - \varepsilon$ can handle these b.c.
2. A limitation of the shear stress in adverse pressure gradient regions

¶ See Section 16, [The SST Model](#)

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2. A limitation of the shear stress in adverse pressure gradient regions

► $\omega = \varepsilon / (\beta^* k) = \varepsilon / (c_\mu k)$. Use this to obtain an eq. for ω

¶ See Section 16, [The SST Model](#)

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$$\frac{d\omega}{dt}$$

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$$\frac{d\omega}{dt} =$$

¶ See Section 16, The SST Model

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$$\frac{d\omega}{dt} = \frac{d}{dt} \left(\frac{\varepsilon}{\beta^* k} \right) =$$

¶ See Section 16, The SST Model

► The SST (Shear Stress Transport) model

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¶ See Section 16, The SST Model

► The SST (Shear Stress Transport) model

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► Production term

¶ See Section 16, The SST Model

► The SST (Shear Stress Transport) model

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$$P_\omega =$$

¶ See Section 16, The SST Model

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► Production term

$$P_\omega = \frac{1}{\beta^* k} P_\varepsilon - \frac{\omega}{k} P^k =$$

¶ See Section 16, The SST Model

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► Production term

$$P_\omega = \frac{1}{\beta^* k} P_\varepsilon - \frac{\omega}{k} P^k = \frac{1}{\beta^* k} C_{\varepsilon 1} \frac{\varepsilon}{k} P^k - \frac{\omega}{k} P^k =$$

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► The SST (Shear Stress Transport) model

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$$P_\omega = \frac{1}{\beta^* k} P_\varepsilon - \frac{\omega}{k} P^k = \frac{1}{\beta^* k} C_{\varepsilon 1} \frac{\varepsilon}{k} P^k - \frac{\omega}{k} P^k = (C_{\varepsilon 1} - 1) \frac{\omega}{k} P^k$$

¶ See Section 16, The SST Model

► The SST (Shear Stress Transport) model

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► Destruction term

¶ See Section 16, The SST Model

► The SST (Shear Stress Transport) model

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$$\Psi_\omega =$$

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$$\Psi_\omega = \frac{1}{\beta^* k} \Psi_\varepsilon - \frac{\omega}{k} \Psi_k =$$

See Section 16, The SST Model

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$$P_\omega = \frac{1}{\beta^* k} P_\varepsilon - \frac{\omega}{k} P^k = \frac{1}{\beta^* k} C_{\varepsilon 1} \frac{\varepsilon}{k} P^k - \frac{\omega}{k} P^k = (C_{\varepsilon 1} - 1) \frac{\omega}{k} P^k$$

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$$\Psi_\omega = \frac{1}{\beta^* k} \Psi_\varepsilon - \frac{\omega}{k} \Psi_k = \frac{1}{\beta^* k} C_{\varepsilon 2} \frac{\varepsilon^2}{k} - \frac{\omega}{k} \varepsilon =$$

See Section 16, The SST Model

► The SST (Shear Stress Transport) model

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See Section 16, The SST Model

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$$P_\omega = \frac{1}{\beta^* k} P_\varepsilon - \frac{\omega}{k} P^k = \frac{1}{\beta^* k} C_{\varepsilon 1} \frac{\varepsilon}{k} P^k - \frac{\omega}{k} P^k = (C_{\varepsilon 1} - 1) \frac{\omega}{k} P^k$$

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$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

► Viscous diffusion term

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

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► Viscous diffusion term

$$D_{\omega}^{\nu} =$$

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

► Viscous diffusion term

$$D_{\omega}^{\nu} = \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} =$$

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

► Viscous diffusion term

$$D_{\omega}^{\nu} = \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2}$$

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► Viscous diffusion term

$$D_{\omega}^{\nu} = \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2}$$

$$=$$

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

► Viscous diffusion term

$$\begin{aligned} D_{\omega}^{\nu} &= \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} \\ &= \frac{\nu}{k} \left[\frac{\partial}{\partial x_j} \left(\omega \frac{\partial k}{\partial x_j} + k \frac{\partial \omega}{\partial x_j} \right) \right] - \nu \frac{\omega}{k} \frac{\partial^2 k}{\partial x_j^2} \end{aligned}$$

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

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$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

► Viscous diffusion term

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► The ω eq. (which really is an ε eq. when the $k - \varepsilon$ constants are used) reads

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

► Viscous diffusion term

$$\begin{aligned} D_{\omega}^{\nu} &= \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} \\ &= \frac{\nu}{k} \left[\frac{\partial}{\partial x_j} \left(\omega \frac{\partial k}{\partial x_j} + k \frac{\partial \omega}{\partial x_j} \right) \right] - \nu \frac{\omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{2\nu}{k} \frac{\partial \omega}{\partial x_j} \frac{\partial k}{\partial x_j} + \frac{\partial}{\partial x_j} \left(\nu \frac{\partial \omega}{\partial x_j} \right) \end{aligned}$$

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► Viscous diffusion term

$$\begin{aligned} D_{\omega}^{\nu} &= \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} \\ &= \frac{\nu}{k} \left[\frac{\partial}{\partial x_j} \left(\omega \frac{\partial k}{\partial x_j} + k \frac{\partial \omega}{\partial x_j} \right) \right] - \nu \frac{\omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{2\nu}{k} \frac{\partial \omega}{\partial x_j} \frac{\partial k}{\partial x_j} + \frac{\partial}{\partial x_j} \left(\nu \frac{\partial \omega}{\partial x_j} \right) \end{aligned}$$

► The ω eq. (which really is an ε eq. when the $k - \varepsilon$ constants are used) reads

$$\frac{\partial}{\partial x_j} (\bar{v}_j \omega) =$$

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

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$$\begin{aligned} D_\omega^\nu &= \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} \\ &= \frac{\nu}{k} \left[\frac{\partial}{\partial x_j} \left(\omega \frac{\partial k}{\partial x_j} + k \frac{\partial \omega}{\partial x_j} \right) \right] - \nu \frac{\omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{2\nu}{k} \frac{\partial \omega}{\partial x_j} \frac{\partial k}{\partial x_j} + \frac{\partial}{\partial x_j} \left(\nu \frac{\partial \omega}{\partial x_j} \right) \end{aligned}$$

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$$\frac{\partial}{\partial x_j} (\bar{v}_j \omega) = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_\omega} \right) \frac{\partial \omega}{\partial x_j} \right] + \alpha \frac{\omega}{k} P^k - \beta \omega^2 + \frac{2}{k} \left(\nu + \frac{\nu_t}{\sigma_\varepsilon} \right) \frac{\partial k}{\partial x_i} \frac{\partial \omega}{\partial x_i}$$

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

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$\alpha =$

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

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$$\begin{aligned} D_\omega^\nu &= \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} \\ &= \frac{\nu}{k} \left[\frac{\partial}{\partial x_j} \left(\omega \frac{\partial k}{\partial x_j} + k \frac{\partial \omega}{\partial x_j} \right) \right] - \nu \frac{\omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{2\nu}{k} \frac{\partial \omega}{\partial x_j} \frac{\partial k}{\partial x_j} + \frac{\partial}{\partial x_j} \left(\nu \frac{\partial \omega}{\partial x_j} \right) \end{aligned}$$

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$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

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$$\begin{aligned} D_\omega^\nu &= \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} \\ &= \frac{\nu}{k} \left[\frac{\partial}{\partial x_j} \left(\omega \frac{\partial k}{\partial x_j} + k \frac{\partial \omega}{\partial x_j} \right) \right] - \nu \frac{\omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{2\nu}{k} \frac{\partial \omega}{\partial x_j} \frac{\partial k}{\partial x_j} + \frac{\partial}{\partial x_j} \left(\nu \frac{\partial \omega}{\partial x_j} \right) \end{aligned}$$

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► Inner region: $k - \omega$ coefficients; outer region: $k - \varepsilon$ coefficients. Blending function reads

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$$F_1 = \tanh(\xi^4), \quad \xi \propto \frac{L_t}{x_n} = \frac{k^{1/2}}{\omega x_n}$$

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► $F_1 = 1$ in the near-wall region and $F_1 = 0$ in the outer region. The β -coefficient, e.g., reads

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

► Viscous diffusion term

$$\begin{aligned} D_\omega^\nu &= \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} \\ &= \frac{\nu}{k} \left[\frac{\partial}{\partial x_j} \left(\omega \frac{\partial k}{\partial x_j} + k \frac{\partial \omega}{\partial x_j} \right) \right] - \nu \frac{\omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{2\nu}{k} \frac{\partial \omega}{\partial x_j} \frac{\partial k}{\partial x_j} + \frac{\partial}{\partial x_j} \left(\nu \frac{\partial \omega}{\partial x_j} \right) \end{aligned}$$

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$$\beta_{SST} = F_1 \beta_{k-\omega} + (1 - F_1) \beta_{k-\varepsilon}$$

$$\frac{d\omega}{dt} = \frac{1}{\beta^* k} \frac{d\varepsilon}{dt} - \frac{\omega}{k} \frac{dk}{dt}$$

► Viscous diffusion term

$$\begin{aligned} D_\omega^\nu &= \frac{\nu}{\beta^* k} \frac{\partial^2 \varepsilon}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{\nu}{k} \frac{\partial^2 \omega k}{\partial x_j^2} - \frac{\nu \omega}{k} \frac{\partial^2 k}{\partial x_j^2} \\ &= \frac{\nu}{k} \left[\frac{\partial}{\partial x_j} \left(\omega \frac{\partial k}{\partial x_j} + k \frac{\partial \omega}{\partial x_j} \right) \right] - \nu \frac{\omega}{k} \frac{\partial^2 k}{\partial x_j^2} = \frac{2\nu}{k} \frac{\partial \omega}{\partial x_j} \frac{\partial k}{\partial x_j} + \frac{\partial}{\partial x_j} \left(\nu \frac{\partial \omega}{\partial x_j} \right) \end{aligned}$$

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► Inner region: $k - \omega$ coefficients; outer region: $k - \varepsilon$ coefficients. Blending function reads

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► SST model. Limitation of shear stress in adverse pressure gradient flow (APG).

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▶ The $k - \omega$ gives too high shear stress. The JK model $-\overline{v'_1 v'_2} = a_1 k$ ($a_1 = c_\mu^{1/2}$) gives good results.

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- ▶ Two formulas for ν_t .

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▶ Two formulas for ν_t . ▶ $\Omega = \partial \bar{v}_1 / \partial x_2$.

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- ▶ Two formulas for ν_t . ▶ $\Omega = \partial \bar{v}_1 / \partial x_2$. ▶ Formulate JK model with Boussinesq.

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▶ Two formulas for ν_t . ▶ $\Omega = \partial \bar{v}_1 / \partial x_2$. ▶ Formulate JK model with Boussinesq.

$$\left. \begin{array}{l} \text{JK Model:} \\ k - \omega \text{ model:} \end{array} \right\} \nu_t = \frac{a_1 k}{\max(a_1 \omega, F_2 \Omega)}$$

Detailed description: The image shows a mathematical derivation for the turbulent viscosity ν_t . It starts with two models: the JK Model and the $k - \omega$ model. For the JK Model, $\nu_t = \frac{-\overline{v'_1 v'_2}}{\Omega} = \frac{a_1 k}{\Omega}$. For the $k - \omega$ model, $\nu_t = \frac{k}{\omega} = \frac{a_1 k}{a_1 \omega}$. A large right-facing curly bracket groups these two expressions, pointing to a final formula: $\nu_t = \frac{a_1 k}{\max(a_1 \omega, F_2 \Omega)}$.

▶ SST model. Limitation of shear stress in adverse pressure gradient flow (APG).

▶ The $k - \omega$ gives too high shear stress. The JK model $-\overline{v'_1 v'_2} = a_1 k$ ($a_1 = c_\mu^{1/2}$) gives good results.

▶ Two formulas for ν_t . ▶ $\Omega = \partial \bar{v}_1 / \partial x_2$. ▶ Formulate JK model with Boussinesq.

$$\left. \begin{array}{l} \text{JK Model:} \\ k - \omega \text{ model:} \end{array} \right\} \nu_t = \frac{a_1 k}{\max(a_1 \omega, F_2 \Omega)}$$

The equations shown are:

$$\text{JK Model: } \nu_t = \frac{-\overline{v'_1 v'_2}}{\Omega} = \frac{a_1 k}{\Omega}$$
$$k - \omega \text{ model: } \nu_t = \frac{k}{\omega} = \frac{a_1 k}{a_1 \omega}$$

F_2 is one near walls and zero elsewhere

▶ SST model. Limitation of shear stress in adverse pressure gradient flow (APG).

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$\nu_t = \frac{-\overline{v'_1 v'_2}}{\Omega} = \frac{a_1 k}{\Omega}$
 $\nu_t = \frac{k}{\omega} = \frac{a_1 k}{a_1 \omega}$

F_2 is one near walls and zero elsewhere

▶ The purpose of the underlined term above is:



▶ SST model. Limitation of shear stress in adverse pressure gradient flow (APG).

▶ The $k - \omega$ gives too high shear stress. The JK model $-\overline{v'_1 v'_2} = a_1 k$ ($a_1 = c_\mu^{1/2}$) gives good results.

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$$\left. \begin{array}{l} \text{JK Model:} \\ k - \omega \text{ model:} \end{array} \right\} \nu_t = \frac{-\overline{v'_1 v'_2}}{\Omega} = \frac{a_1 k}{\Omega} \left. \vphantom{\frac{-\overline{v'_1 v'_2}}{\Omega}} \right\} \nu_t = \frac{a_1 k}{\max(a_1 \omega, F_2 \Omega)}$$

F_2 is one near walls and zero elsewhere

▶ The purpose of the underlined term above is:

- the second part, $F_2 \Omega$ (the Johnson-King model), should be used in APG flow (where $P^k > \varepsilon$)

▶ SST model. Limitation of shear stress in adverse pressure gradient flow (APG).

▶ The $k - \omega$ gives too high shear stress. The JK model $-\overline{v'_1 v'_2} = a_1 k$ ($a_1 = c_\mu^{1/2}$) gives good results.

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$$\left. \begin{array}{l} \text{JK Model:} \quad \nu_t = \frac{-\overline{v'_1 v'_2}}{\Omega} = \frac{a_1 k}{\Omega} \\ k - \omega \text{ model:} \quad \nu_t = \frac{k}{\omega} = \frac{a_1 k}{a_1 \omega} \end{array} \right\} \nu_t = \frac{a_1 k}{\max(a_1 \omega, F_2 \Omega)}$$

F_2 is one near walls and zero elsewhere

▶ The purpose of the underlined term above is:

- the second part, $F_2 \Omega$ (the Johnson-King model), should be used in APG flow (where $P^k > \varepsilon$)
- the first part, $a_1 \omega$ (the usual Boussinesq model), should be in the remaining part of the flow domain

▶ SST model. Limitation of shear stress in adverse pressure gradient flow (APG).

▶ The $k - \omega$ gives too high shear stress. The JK model $-\overline{v'_1 v'_2} = a_1 k$ ($a_1 = c_\mu^{1/2}$) gives good results.

▶ Two formulas for ν_t . ▶ $\Omega = \partial \bar{v}_1 / \partial x_2$. ▶ Formulate JK model with Boussinesq.

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Detailed description: The image shows a mathematical derivation for the turbulent viscosity ν_t . It starts with two models: the Johnson-King (JK) model and the $k - \omega$ model. The JK model defines $\nu_t = \frac{-\overline{v'_1 v'_2}}{\Omega} = \frac{a_1 k}{\Omega}$. The $k - \omega$ model defines $\nu_t = \frac{k}{\omega} = \frac{a_1 k}{a_1 \omega}$. These two expressions are combined into a single formula for ν_t as $\frac{a_1 k}{\max(a_1 \omega, F_2 \Omega)}$, where F_2 is a function that is one near walls and zero elsewhere.

F_2 is one near walls and zero elsewhere

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- F_2 makes sure that the Johnson-King model is used only near the wall

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▶ Two formulas for ν_t . ▶ $\Omega = \partial \bar{v}_1 / \partial x_2$. ▶ Formulate JK model with Boussinesq.

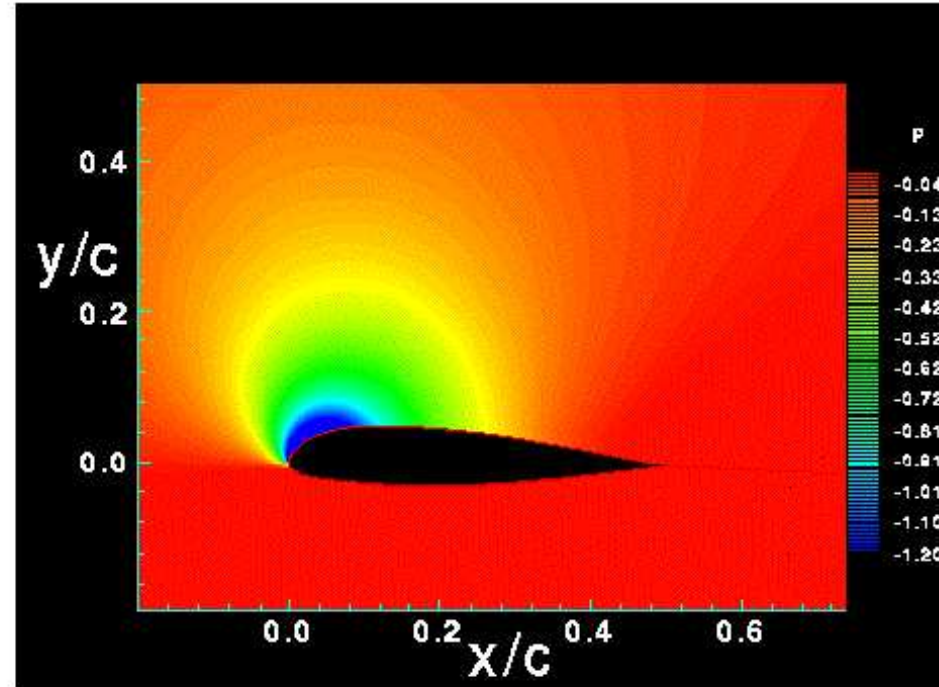
$$\left. \begin{array}{l} \text{JK Model:} \quad \nu_t = \frac{-\overline{v'_1 v'_2}}{\Omega} = \frac{a_1 k}{\Omega} \\ k - \omega \text{ model:} \quad \nu_t = \frac{k}{\omega} = \frac{a_1 k}{a_1 \omega} \end{array} \right\} \nu_t = \frac{a_1 k}{\max(a_1 \omega, F_2 \Omega)}$$

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- F_2 makes sure that the Johnson-King model is used only near the wall

► Adverse pressure gradient flow (APG).



Flow around an airfoil. Angle of attack, $\alpha = 13^\circ$. Pressure contours.

On-line Lecture 6

¶ See Section 5, Turbulence

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▶ $v_i = \bar{v}_i + v'_i$, is irregular and consists of eddies of different size

On-line Lecture 6

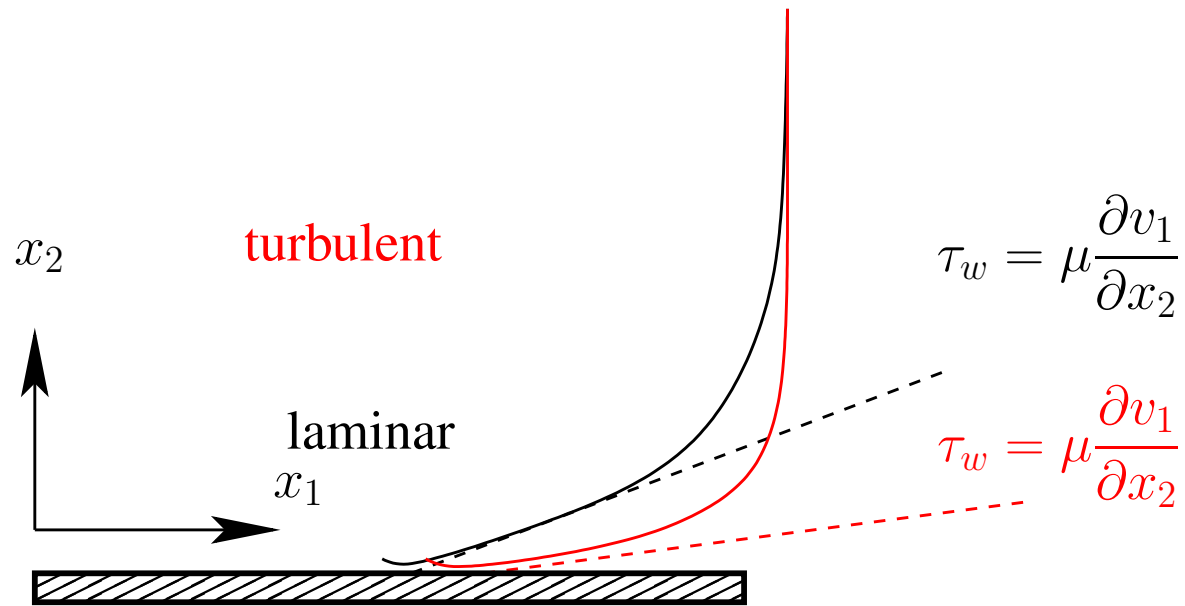
¶ See Section 5, Turbulence

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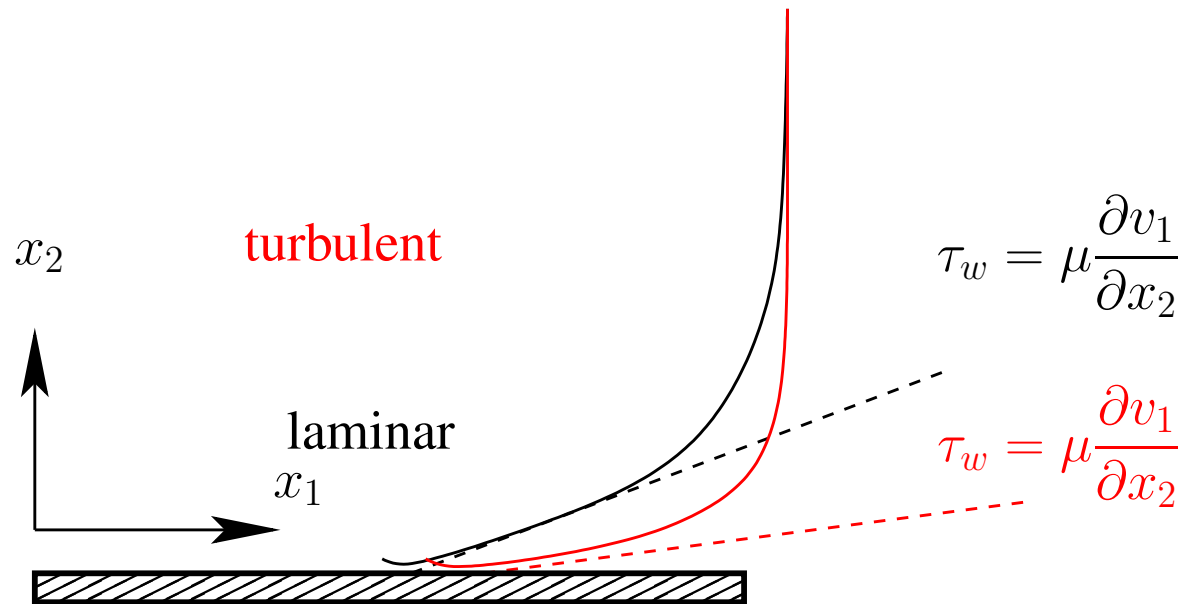


Difference between a laminar and **turbulent** boundary later

On-line Lecture 6

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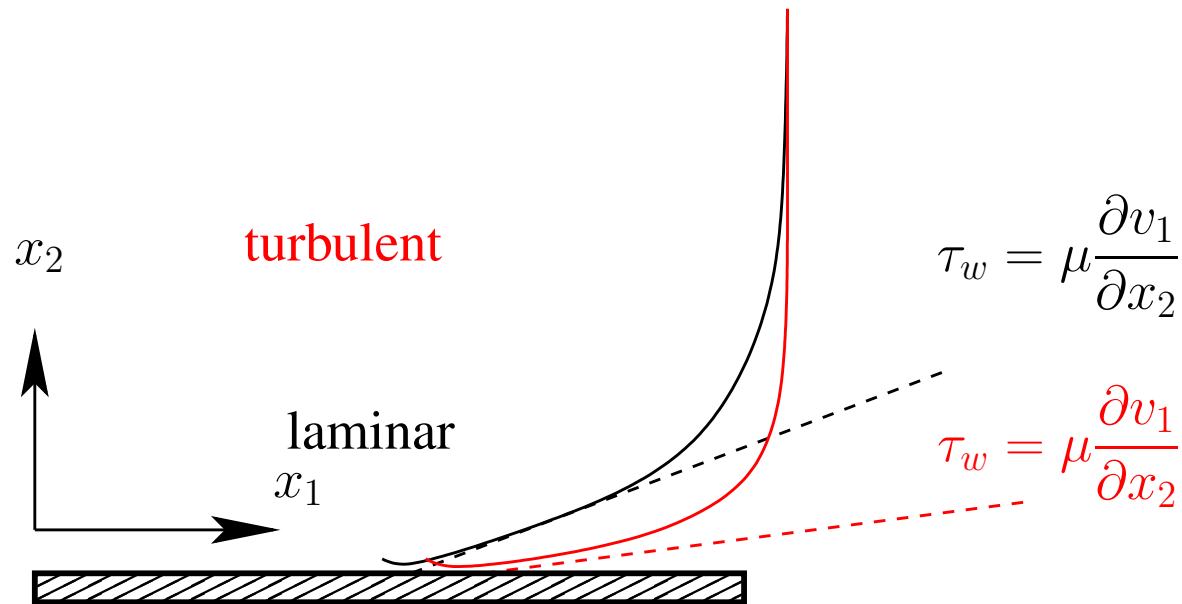
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On-line Lecture 6

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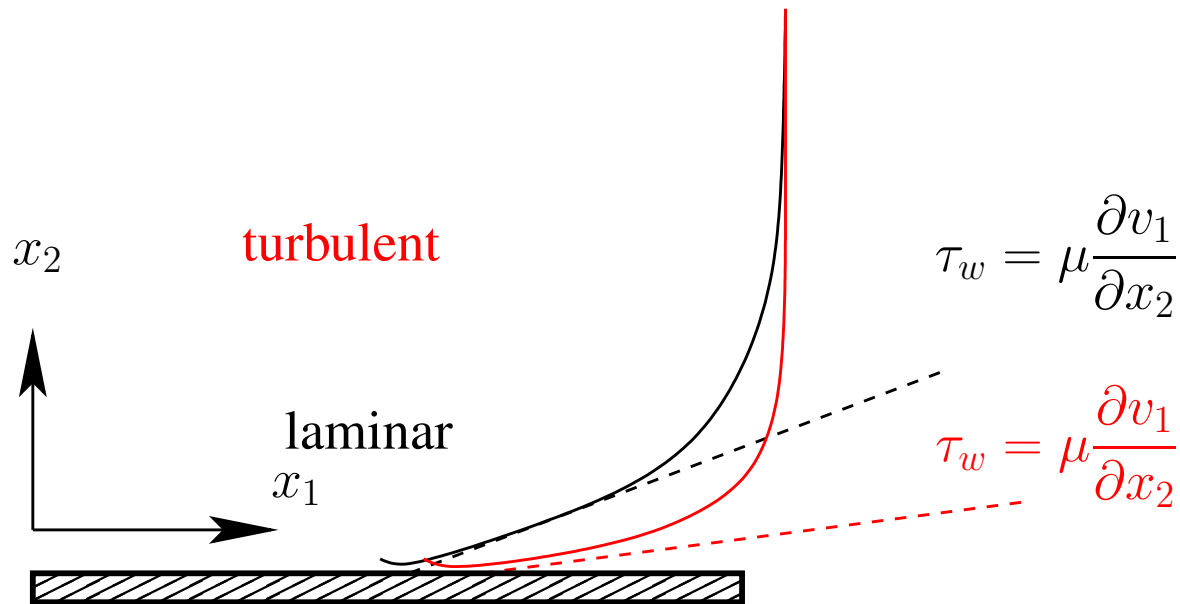
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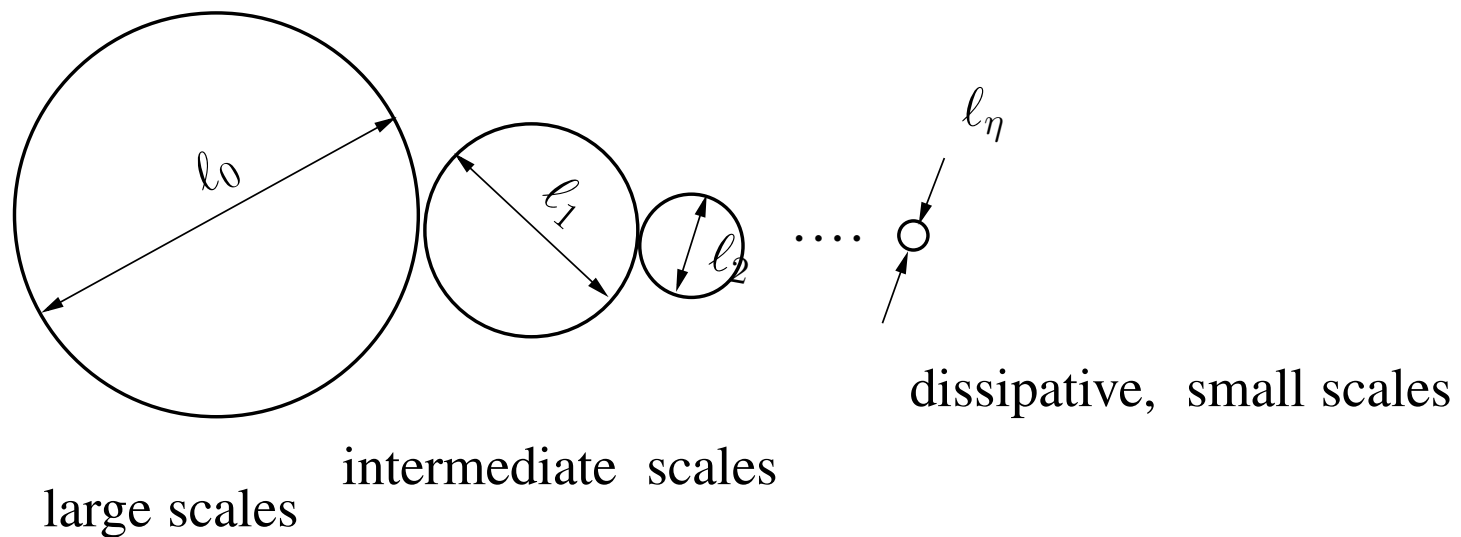
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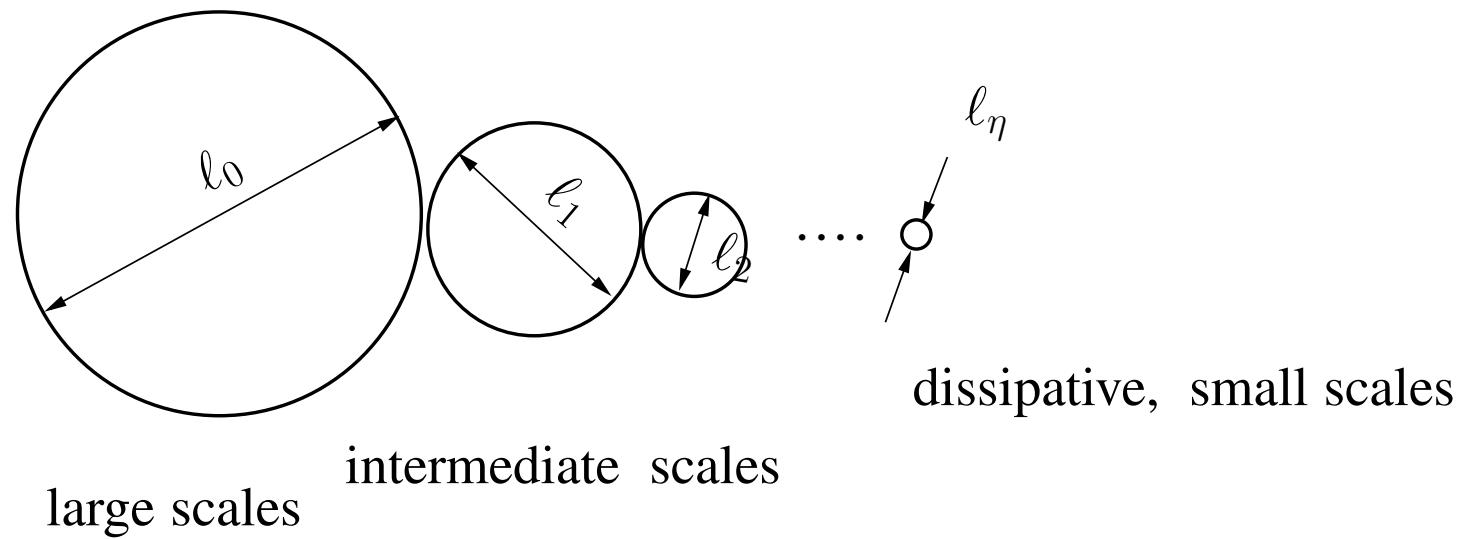
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▶ is dissipative. Kinetic energy, $v'_i v'_i / 2$, in the small (dissipative) eddies are transformed into thermal energy (increases temperature).

spectral transfer of kinetic energy per unit time = ε

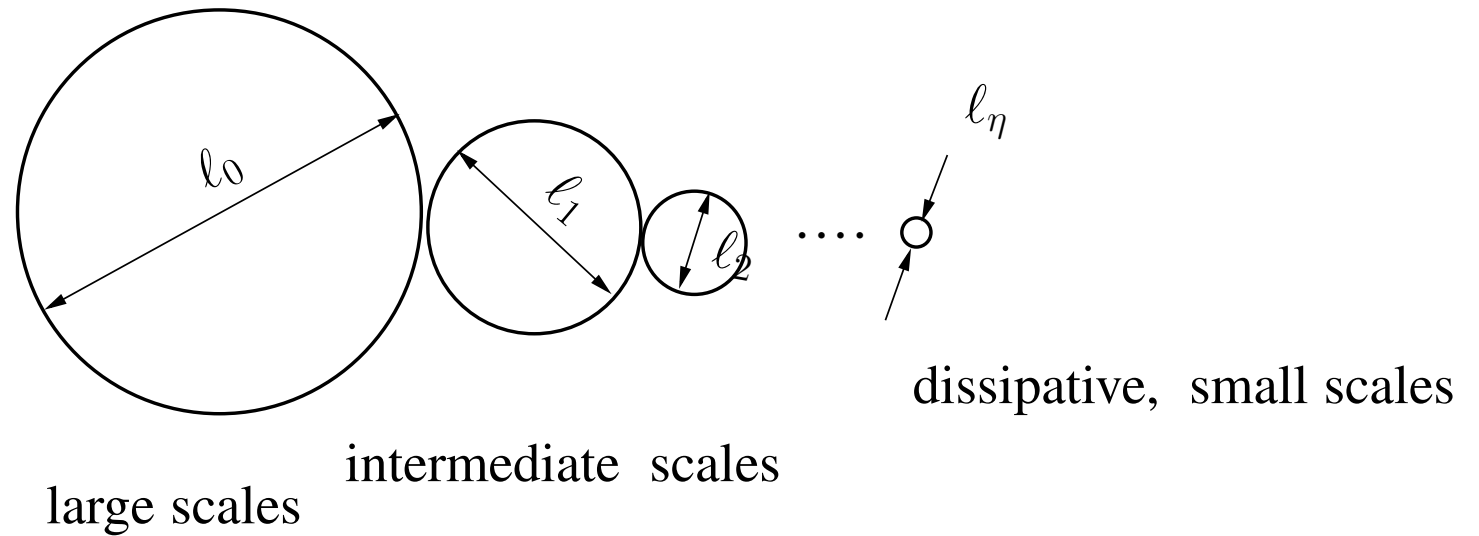


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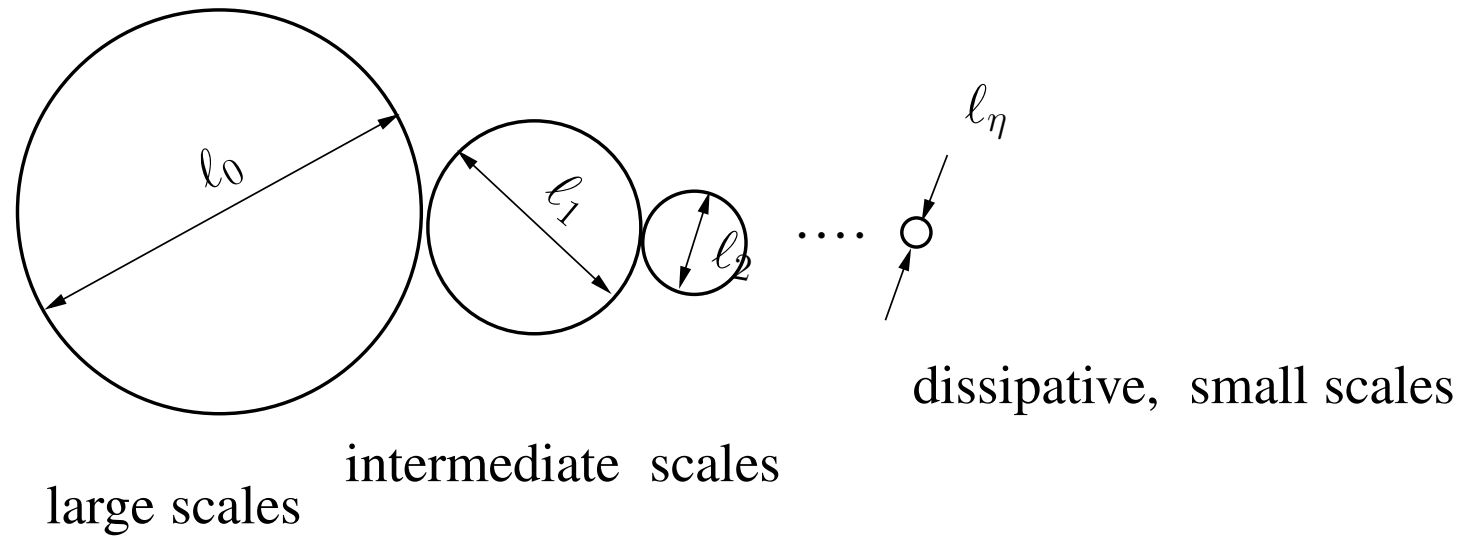
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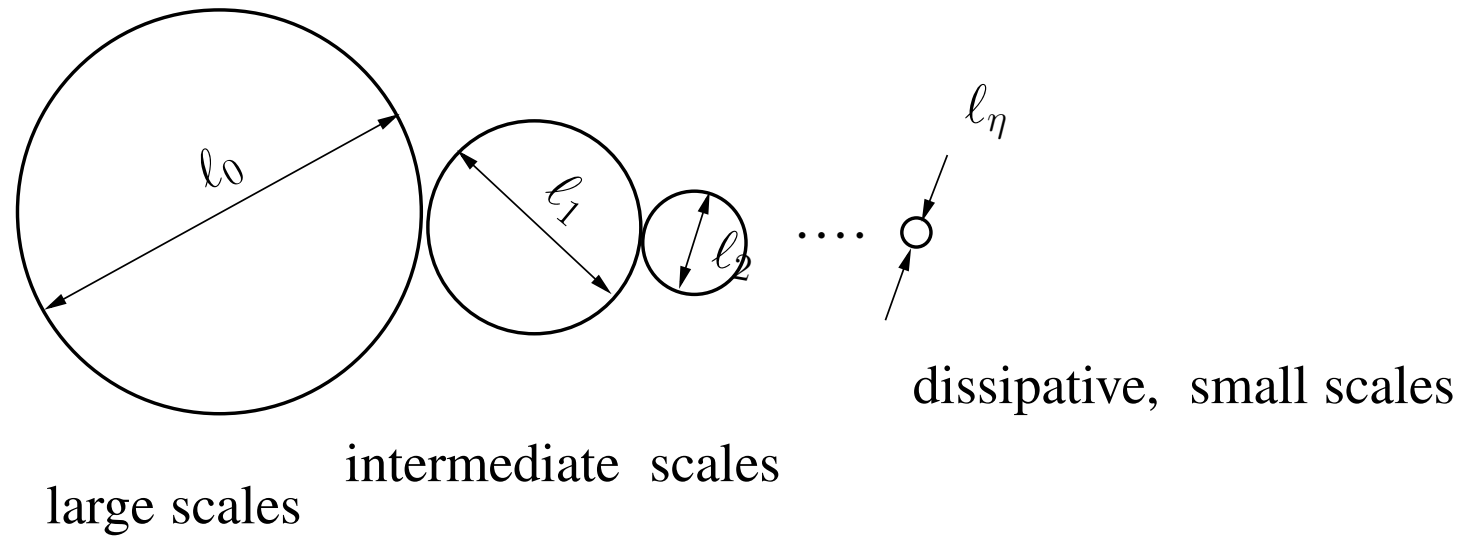
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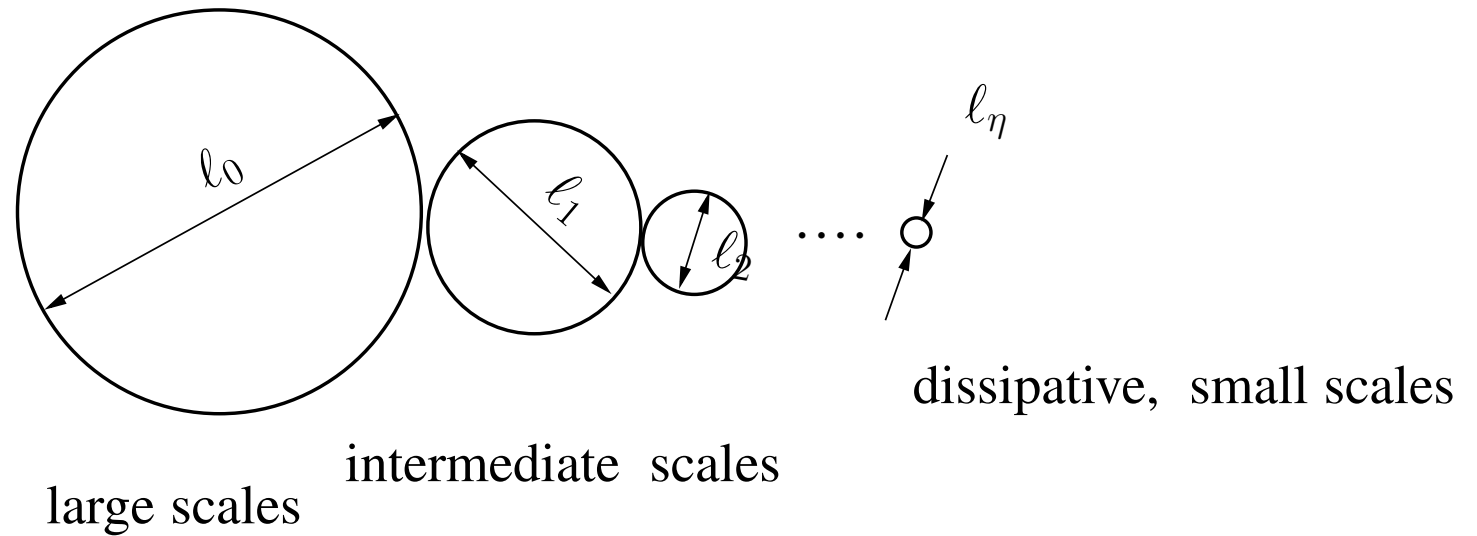


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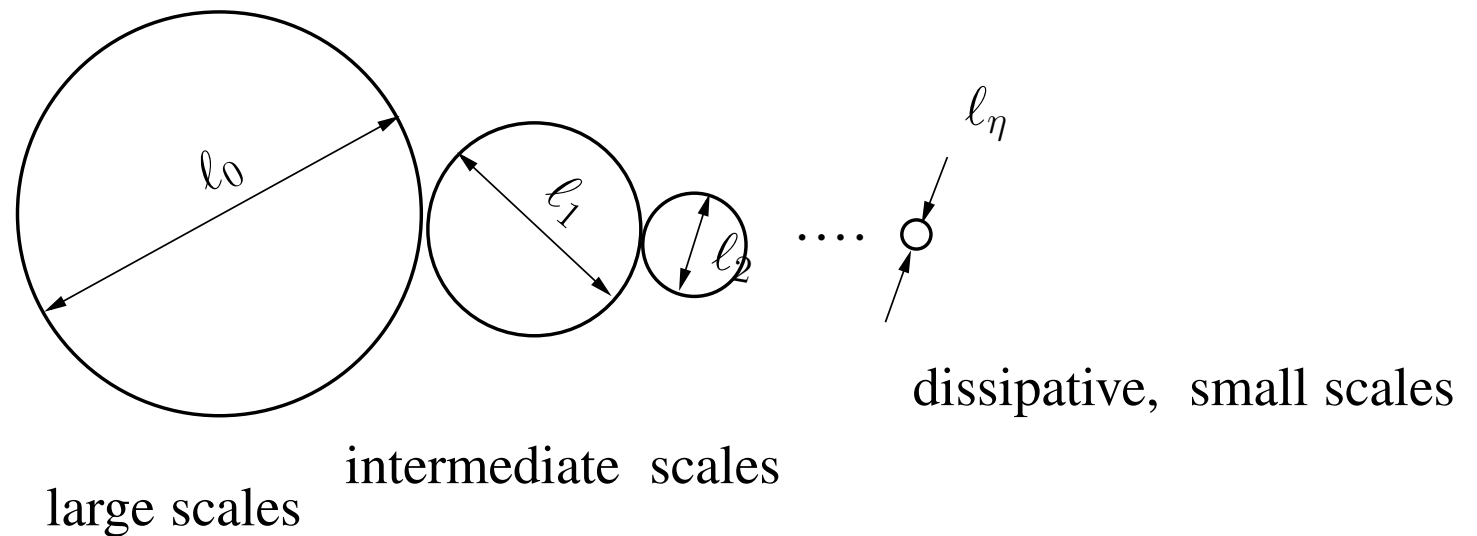
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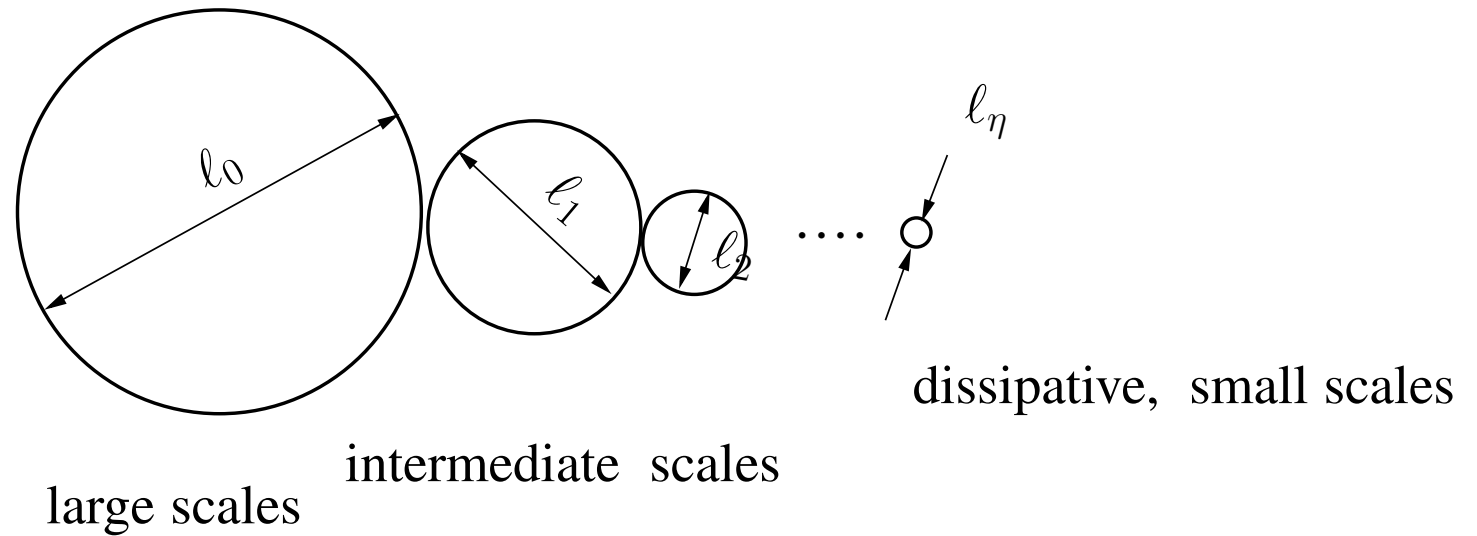


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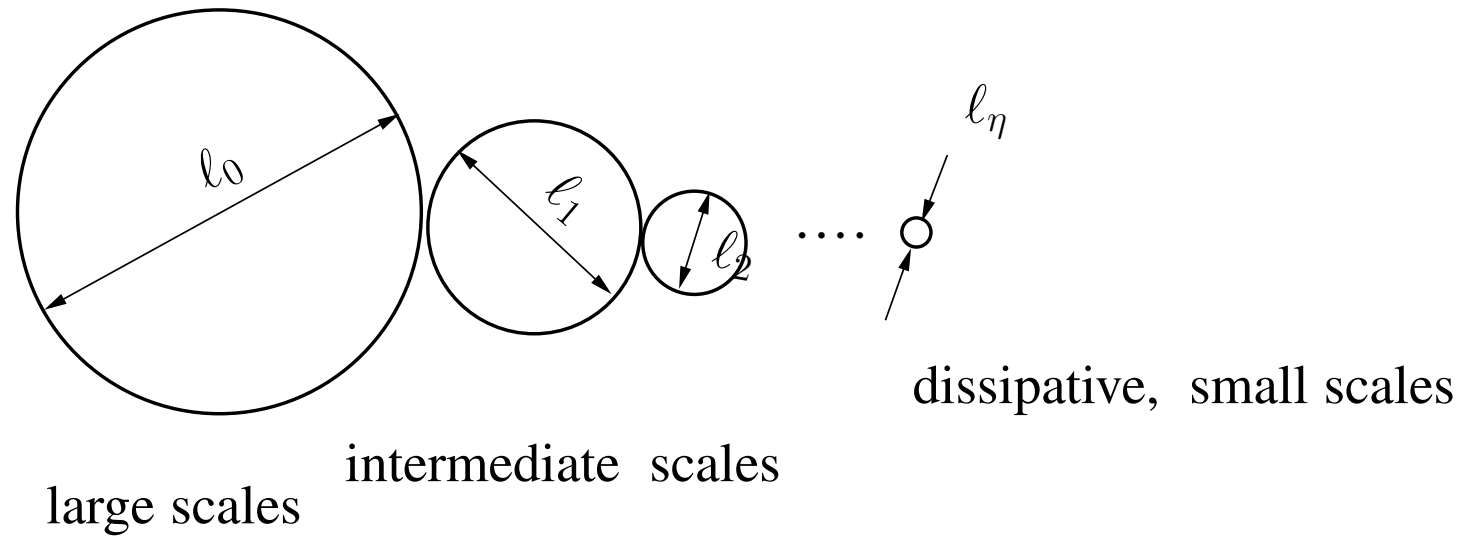
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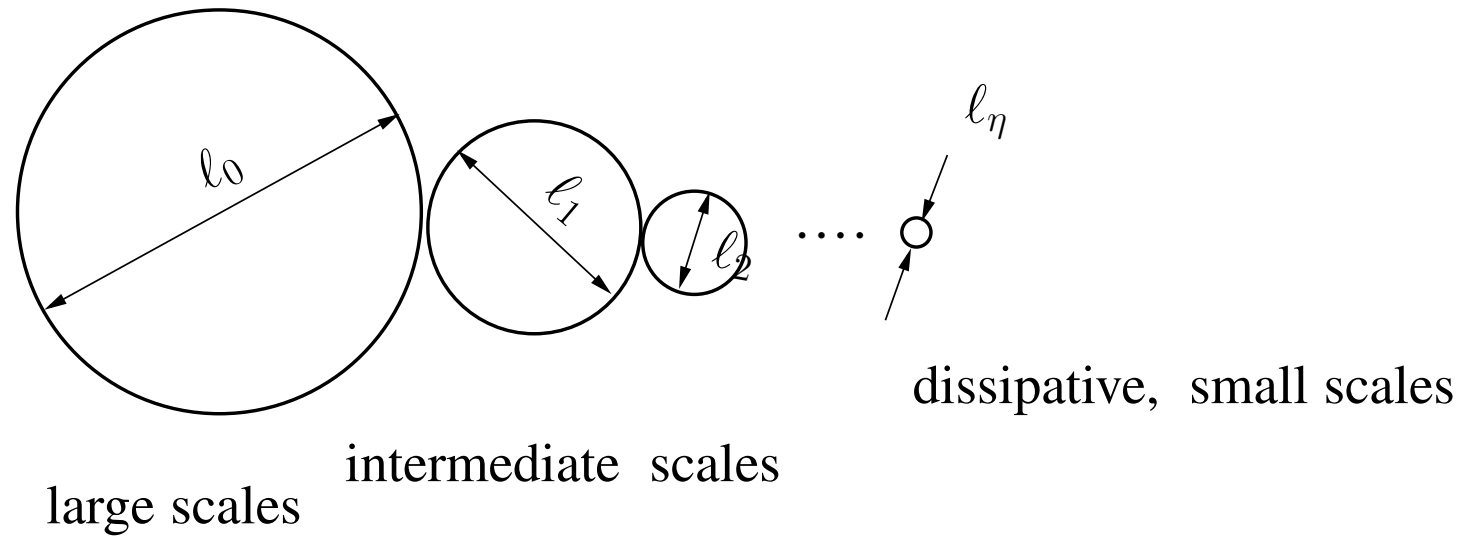
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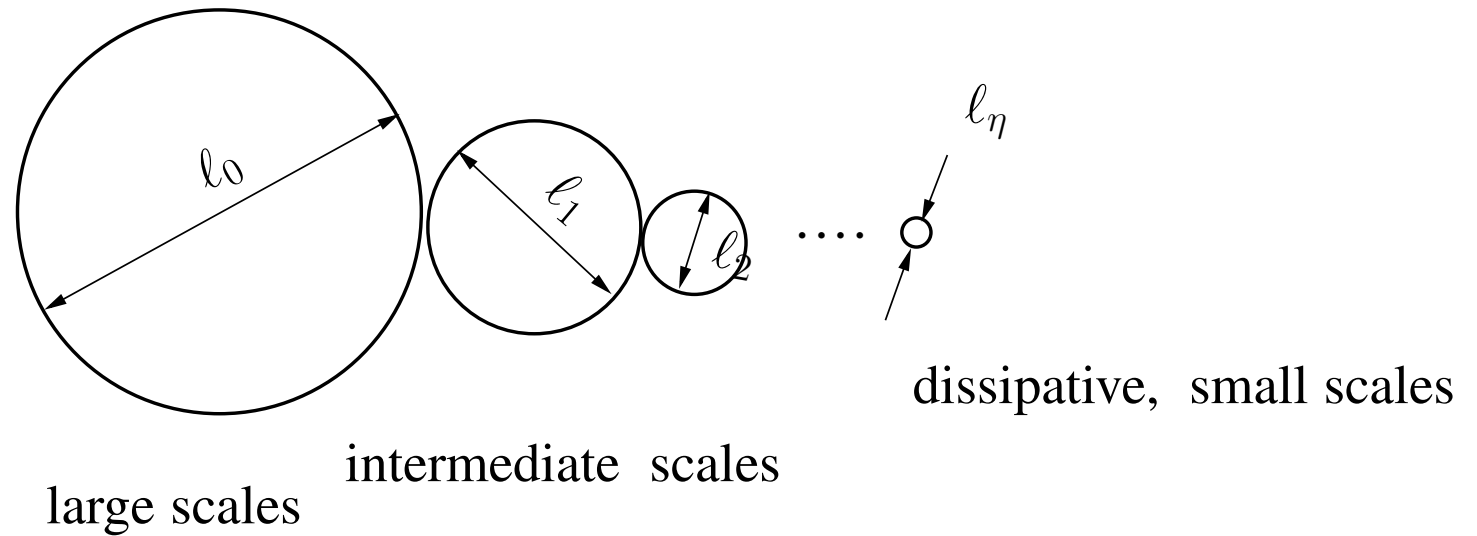
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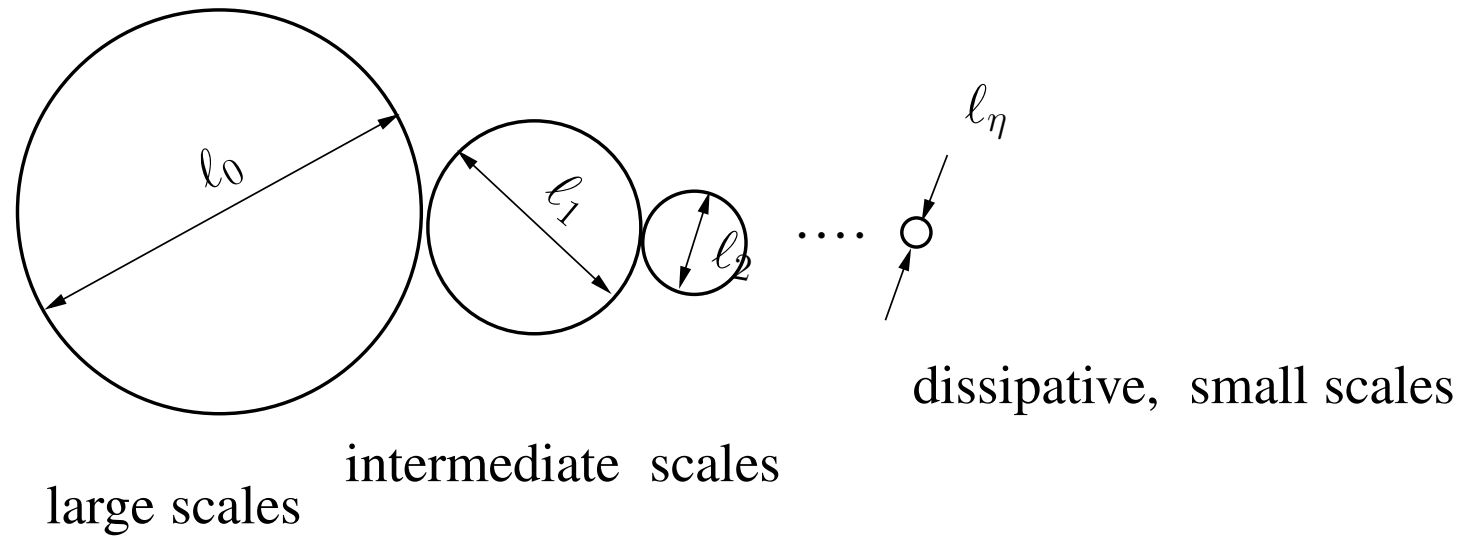
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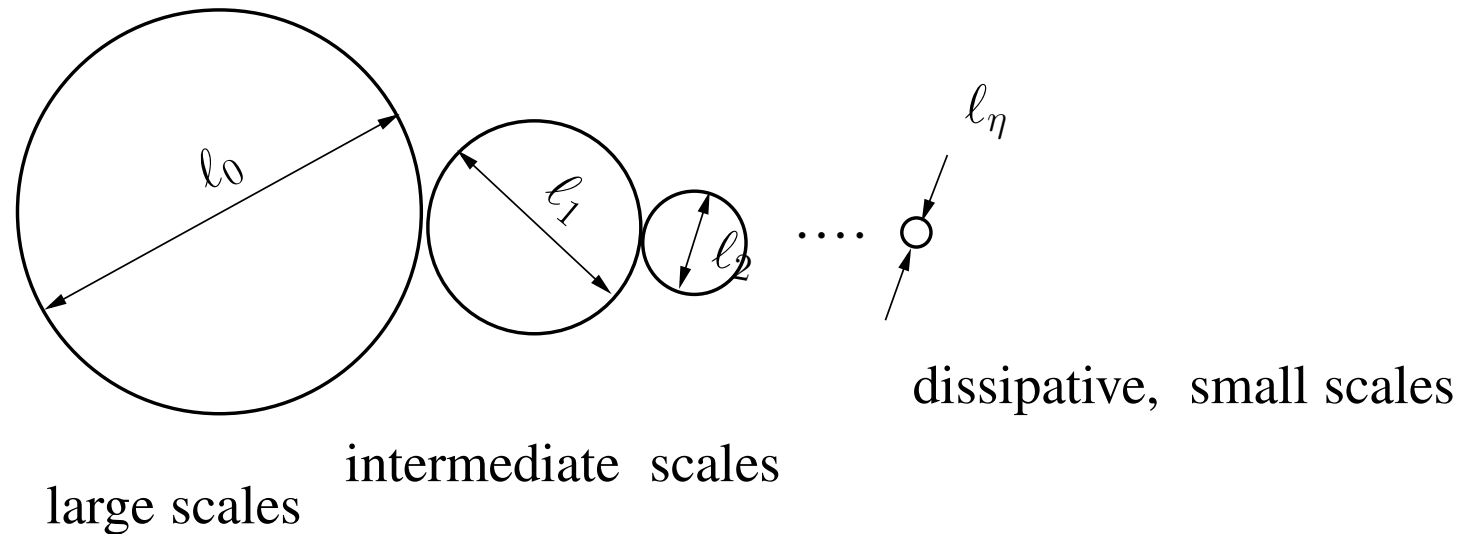
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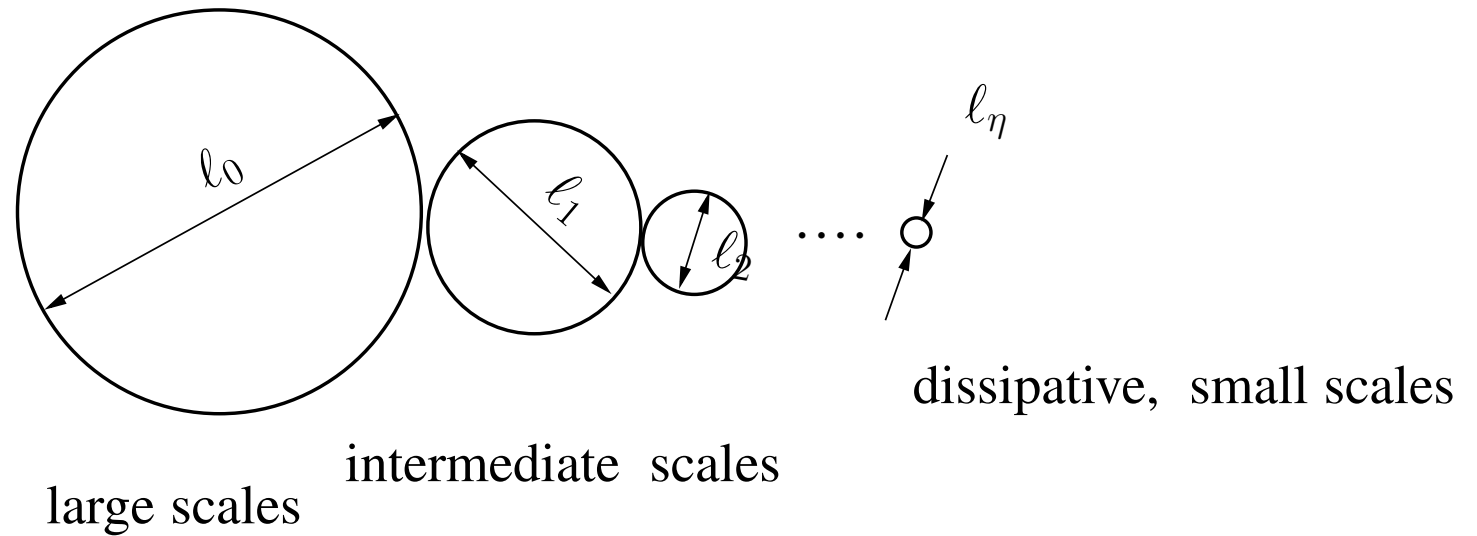
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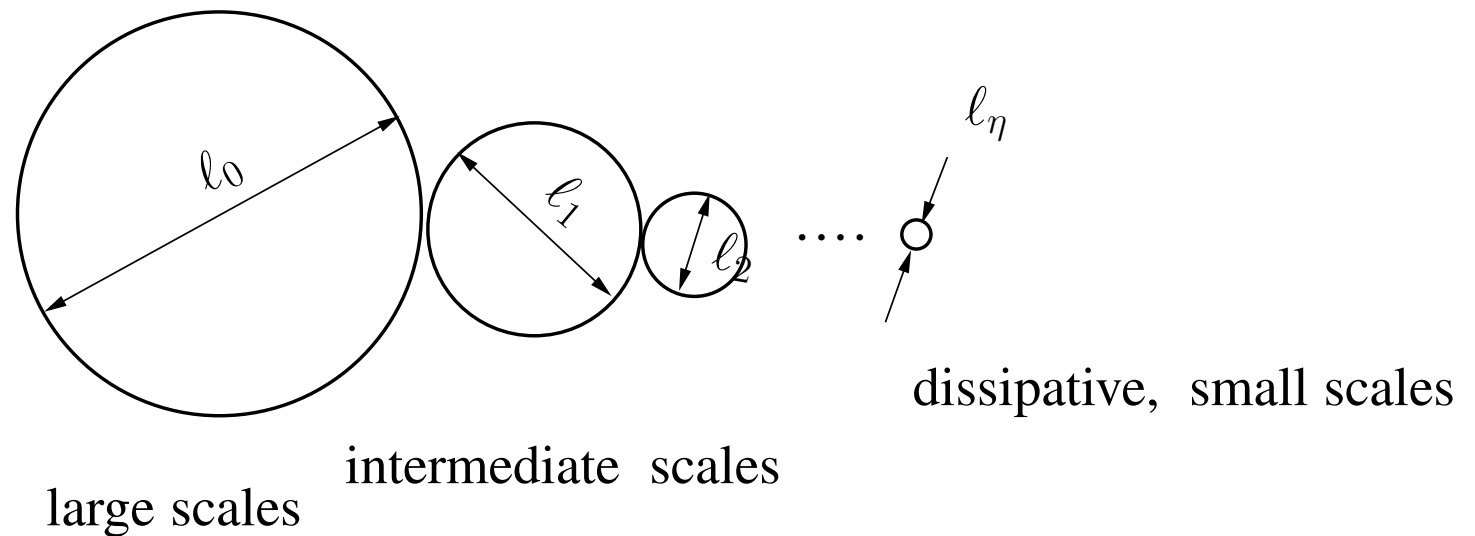
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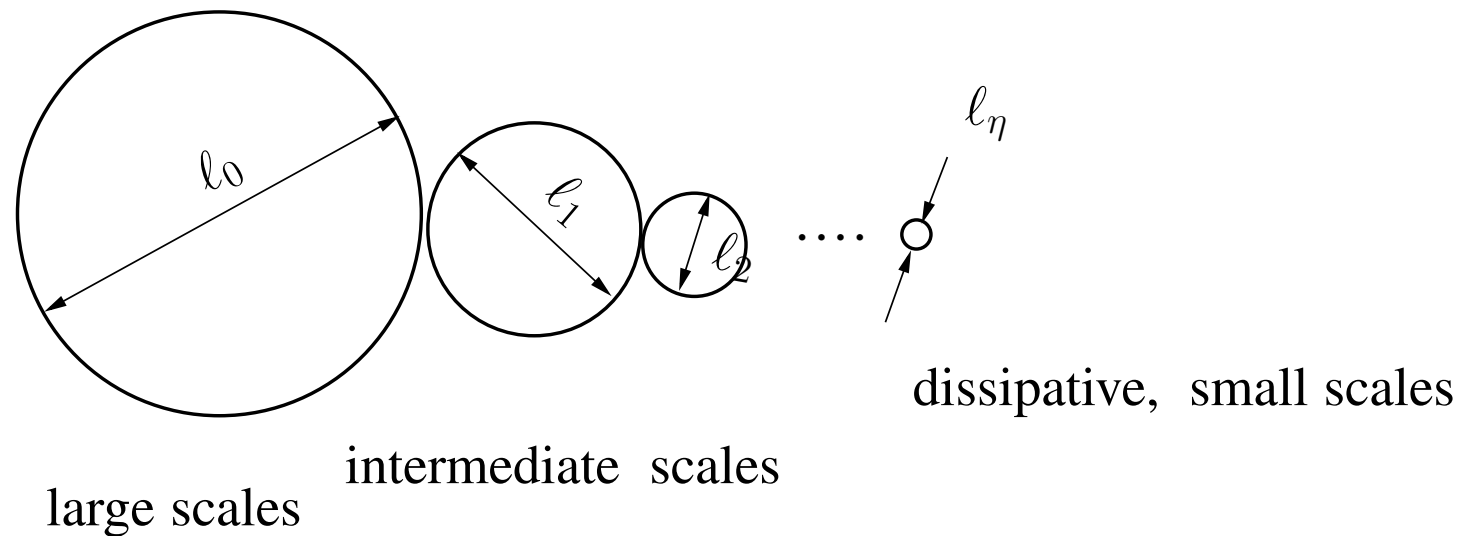
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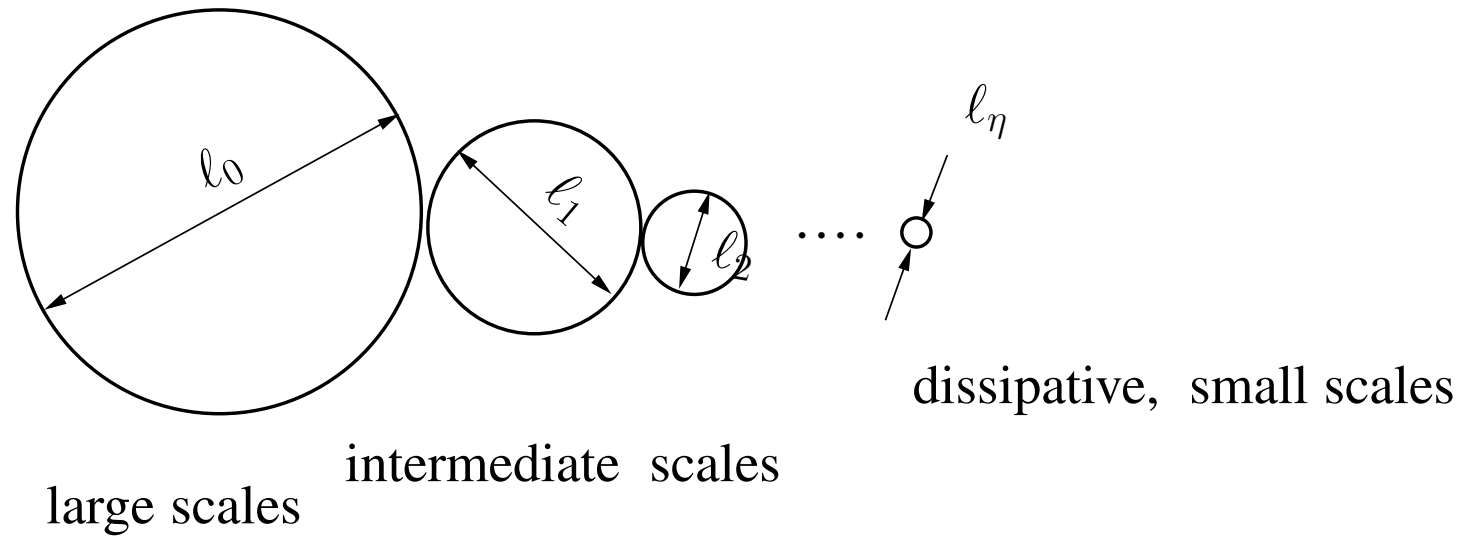
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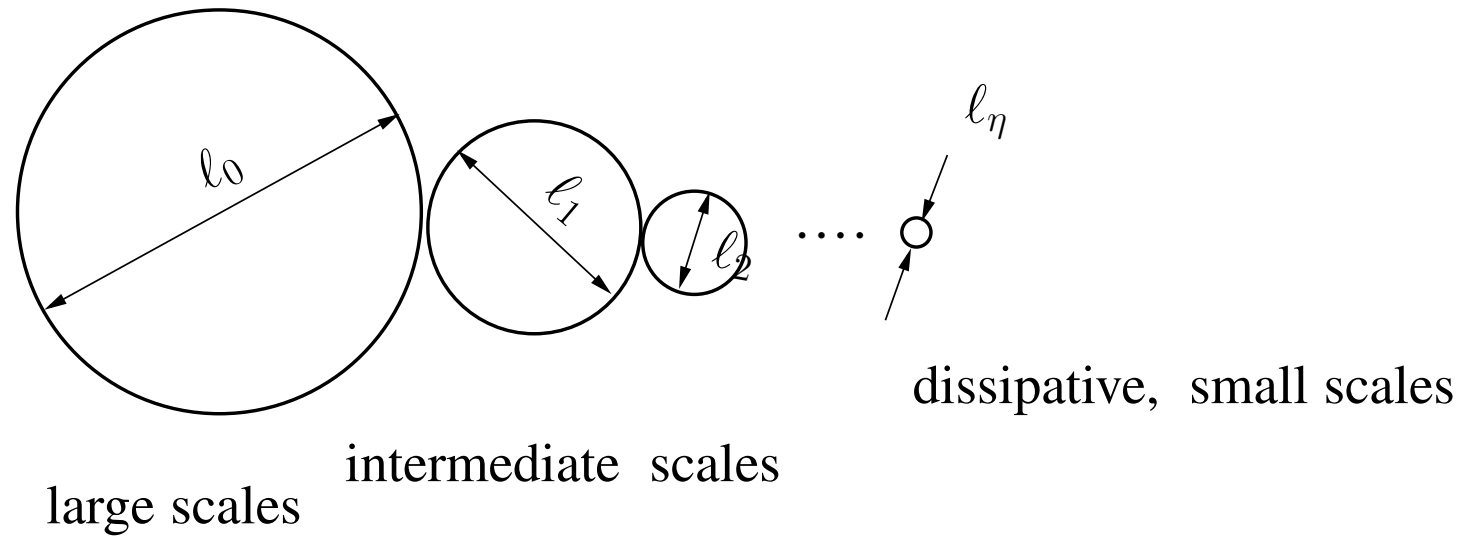
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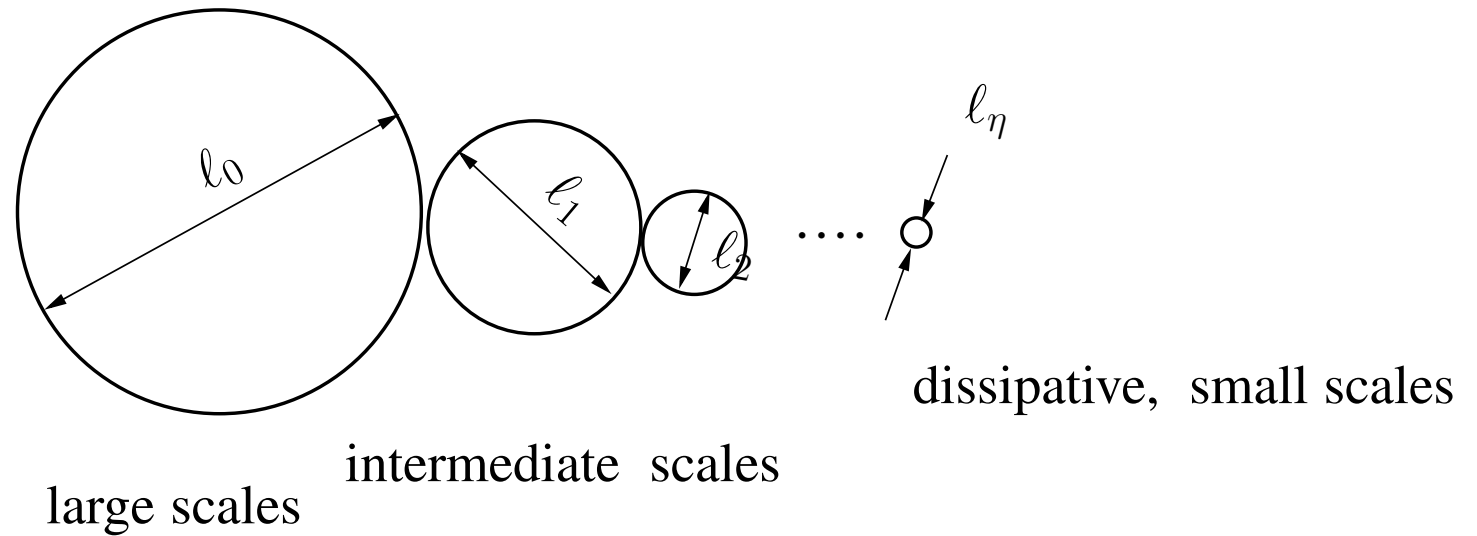
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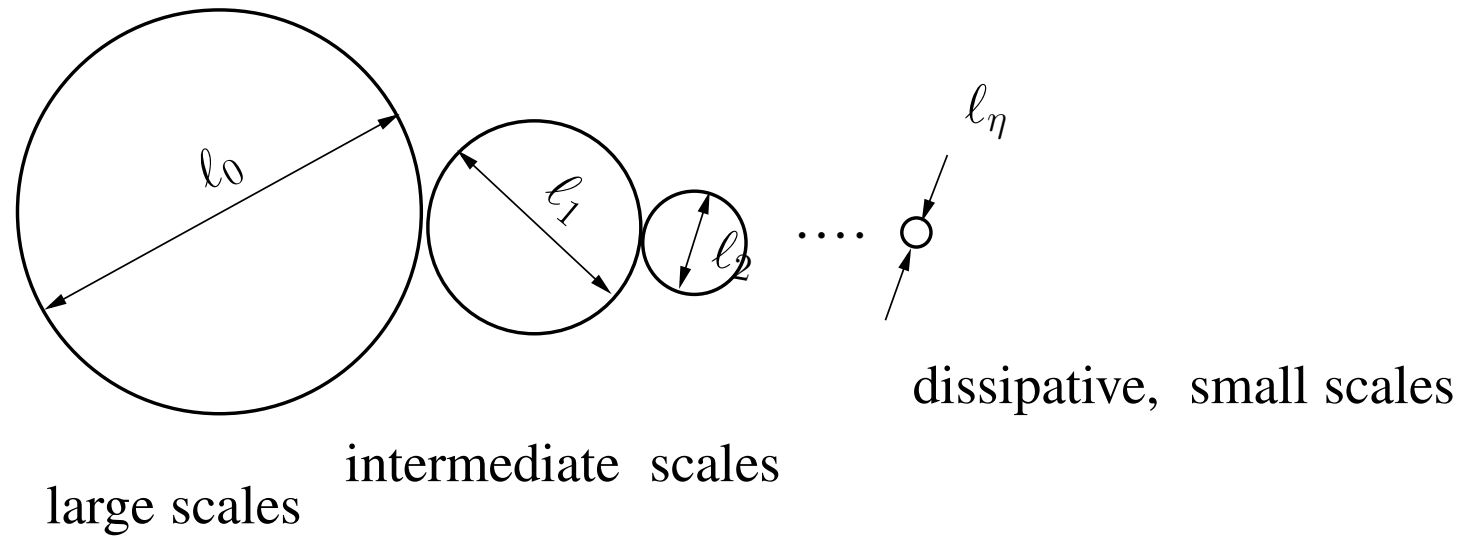
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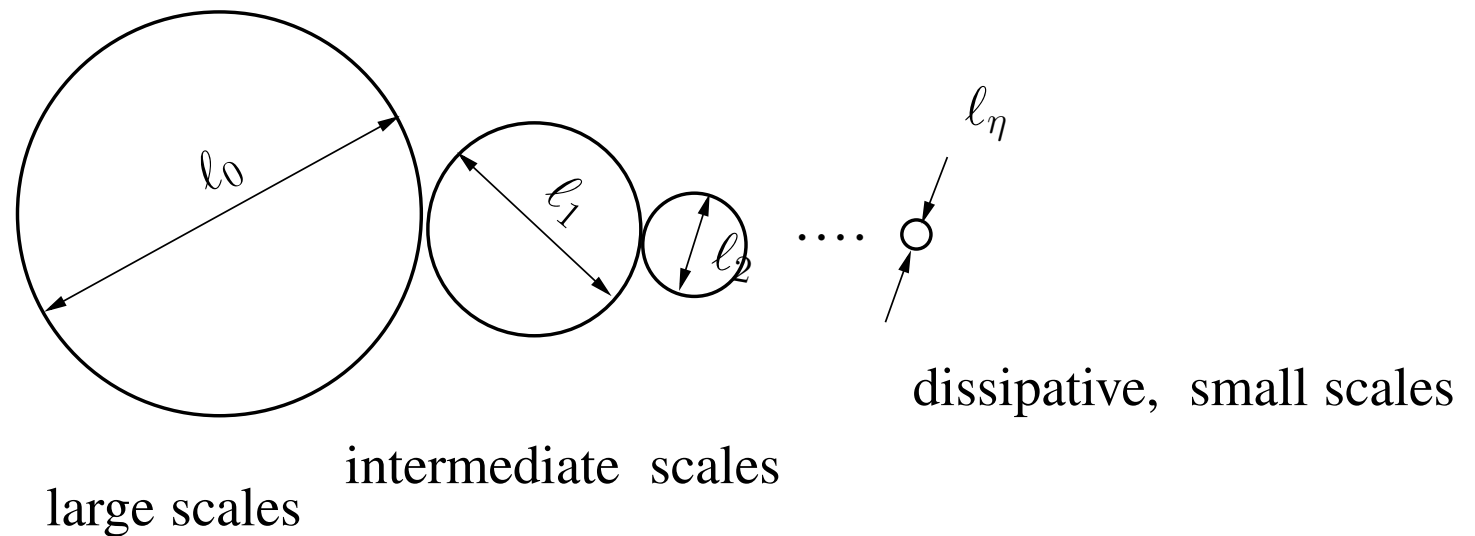
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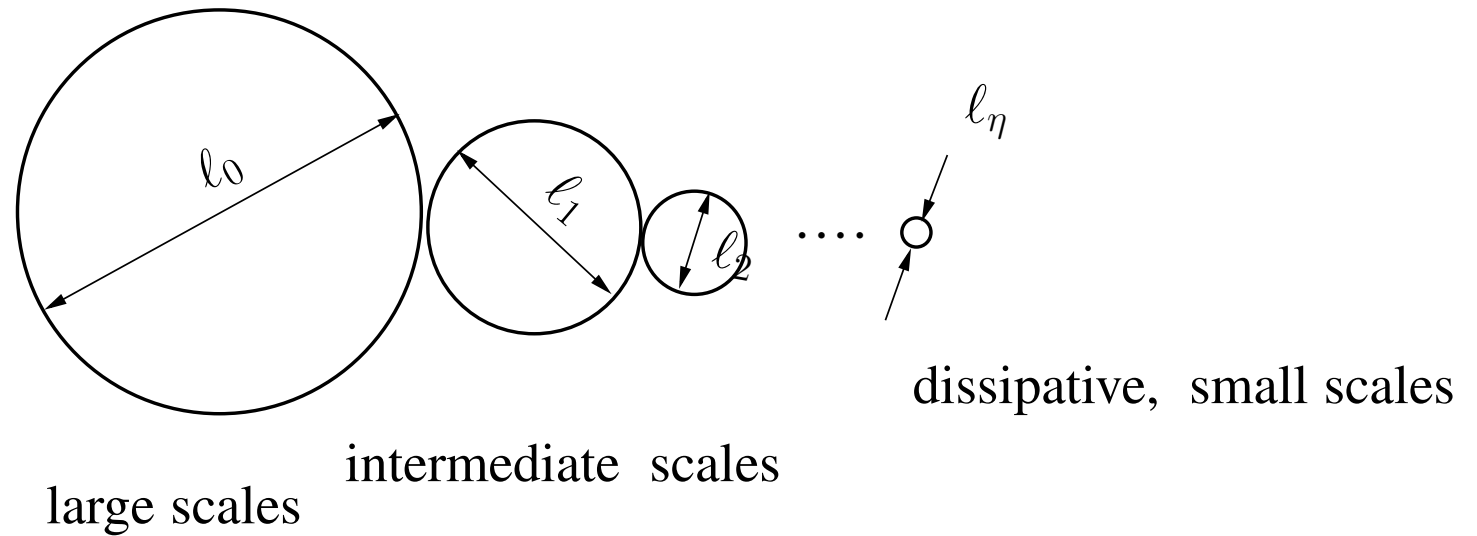
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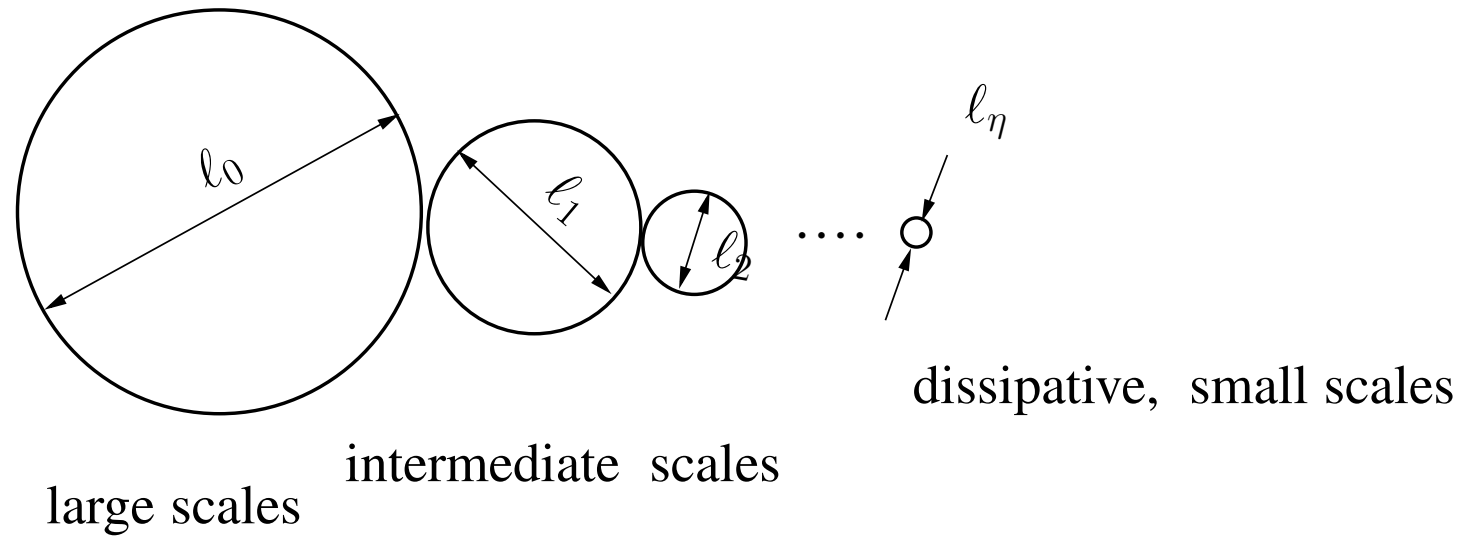
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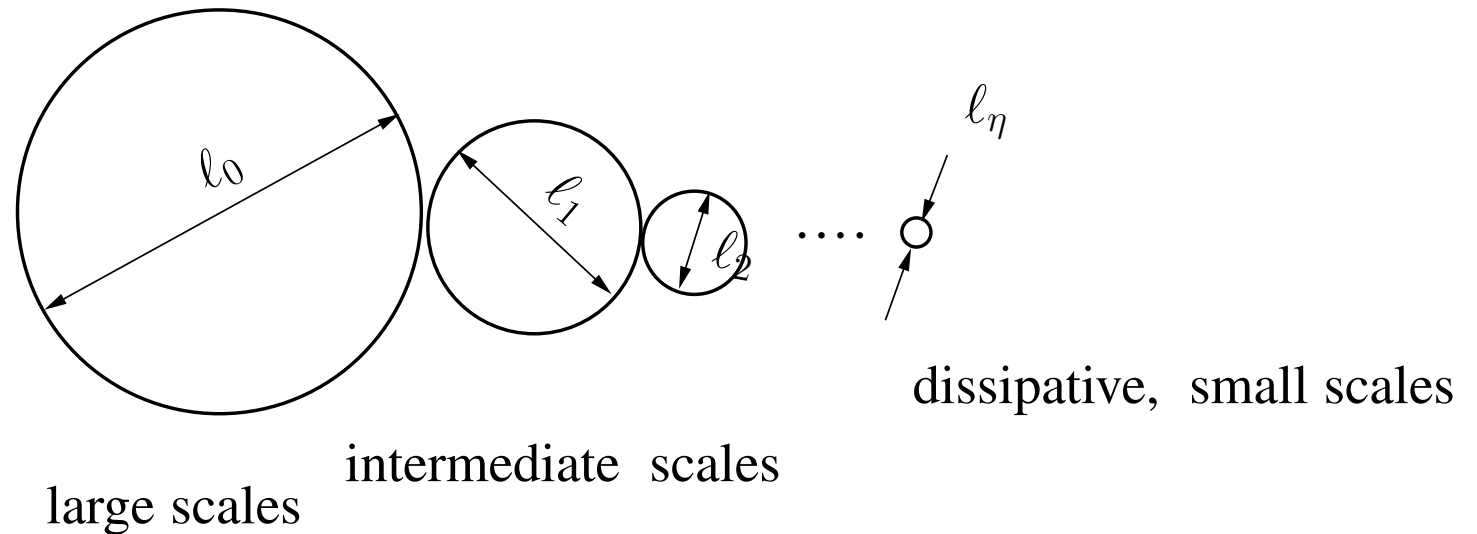
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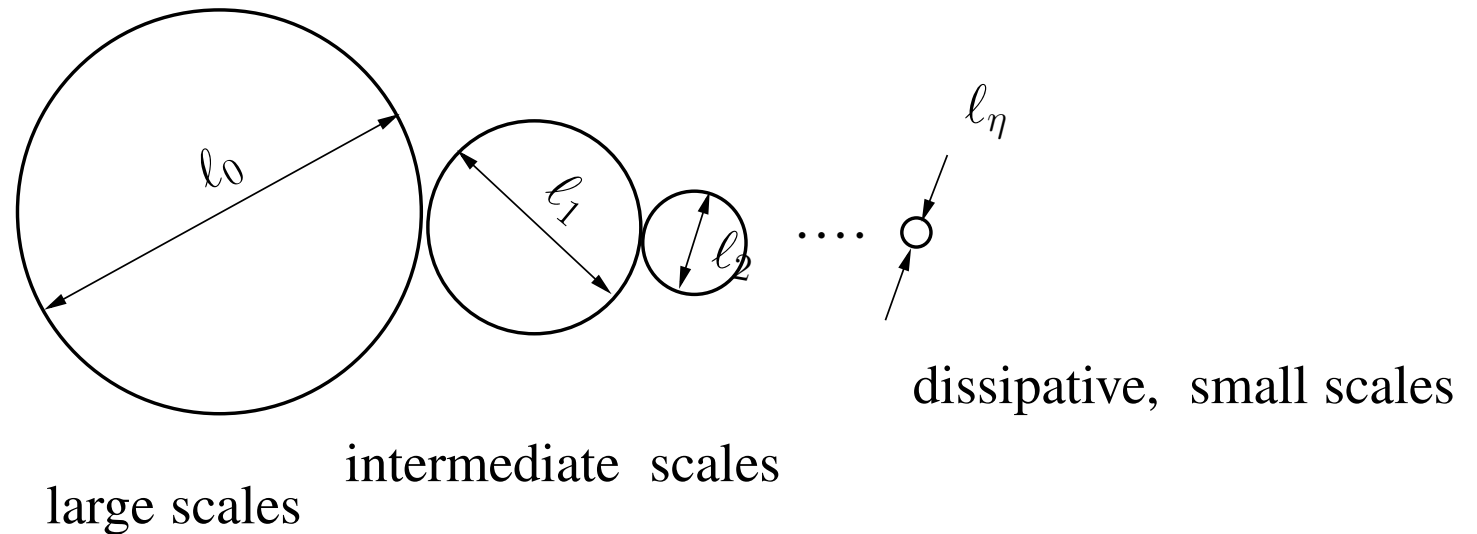
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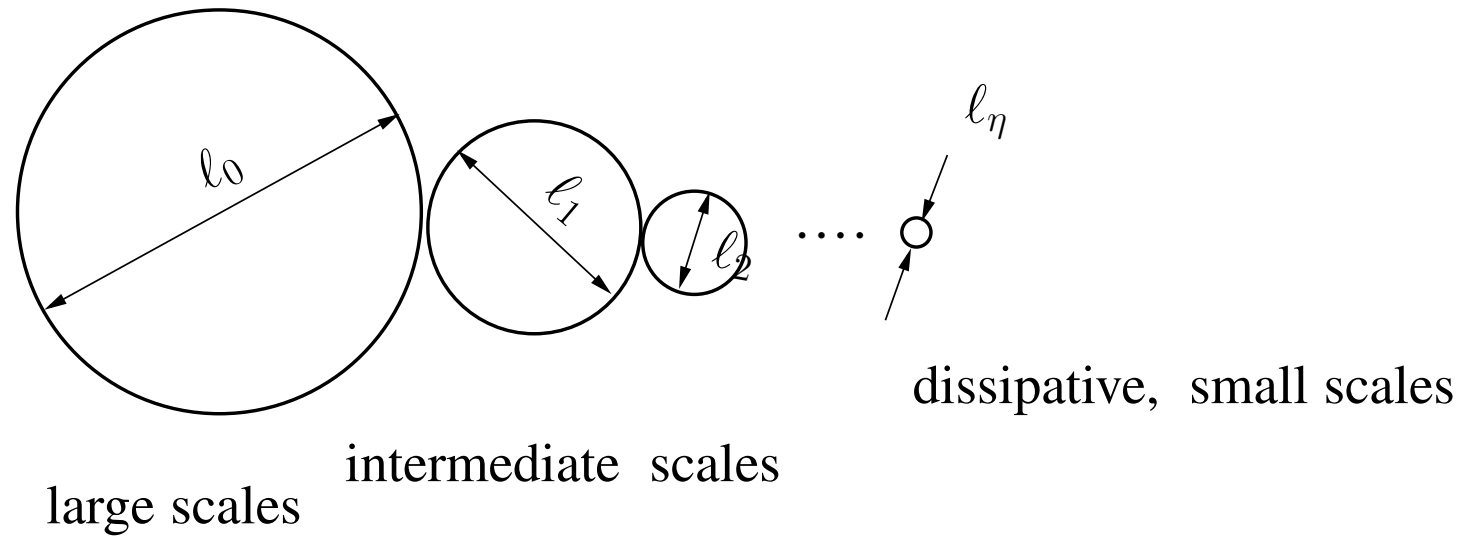
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► Hence, you can compute the kinetic energy by:



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► Any periodic function, f , can be expressed as a Fourier series

$$f(x) = \frac{1}{2}a_0 + \sum_{n=1}^{\infty} (a_n \cos(\kappa_n x) + b_n \sin(\kappa_n x)), \quad f = v', \quad \kappa_n = \frac{n\pi}{L}$$

$$a_n = \frac{1}{L} \int_{-L}^L f(x) \cos(\kappa_n x) dx, \quad b_n = \frac{1}{L} \int_{-L}^L f(x) \sin(\kappa_n x) dx$$

► Parseval's formula states that the kinetic energy can be computed as

$$\int_{-L}^L v'^2(x) dx = \frac{L}{2} a_0^2 + L \sum_{n=1}^{\infty} (a_n^2 + b_n^2) \quad (35.1)$$

► Hence, you can compute the kinetic energy by:

- integrating in Fourier (wavenumber) space (right-hand side)

► At the next slide, we will look at energy spectra. It is based on Fourier series.

► Any periodic function, f , can be expressed as a Fourier series

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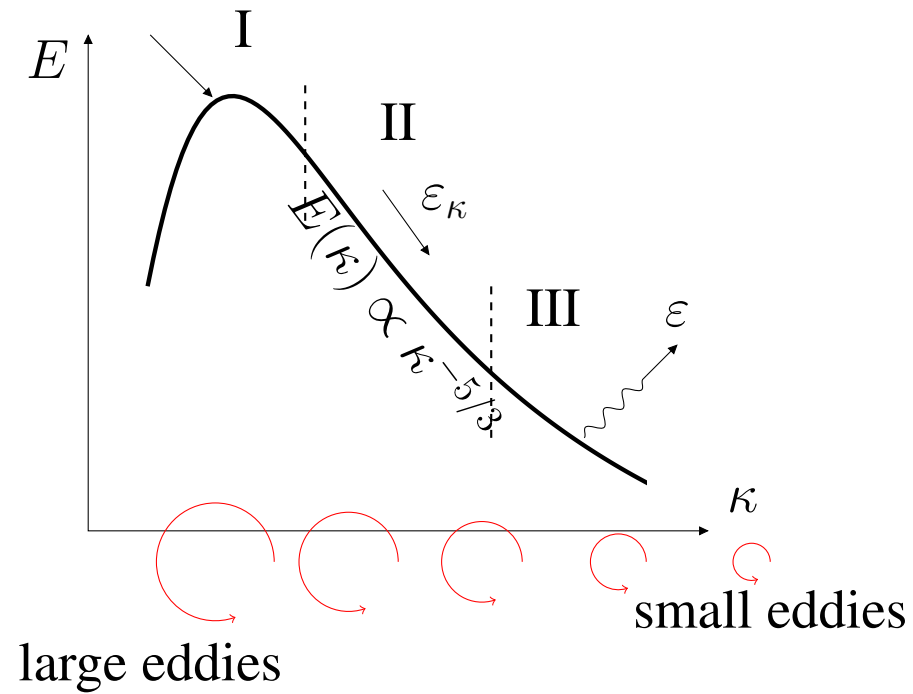
► Hence, you can compute the kinetic energy by:

- integrating in Fourier (wavenumber) space (right-hand side)
- or integrating in physical space over all fluctuations (left-hand side)

► Spectrum for turbulent kinetic energy, k

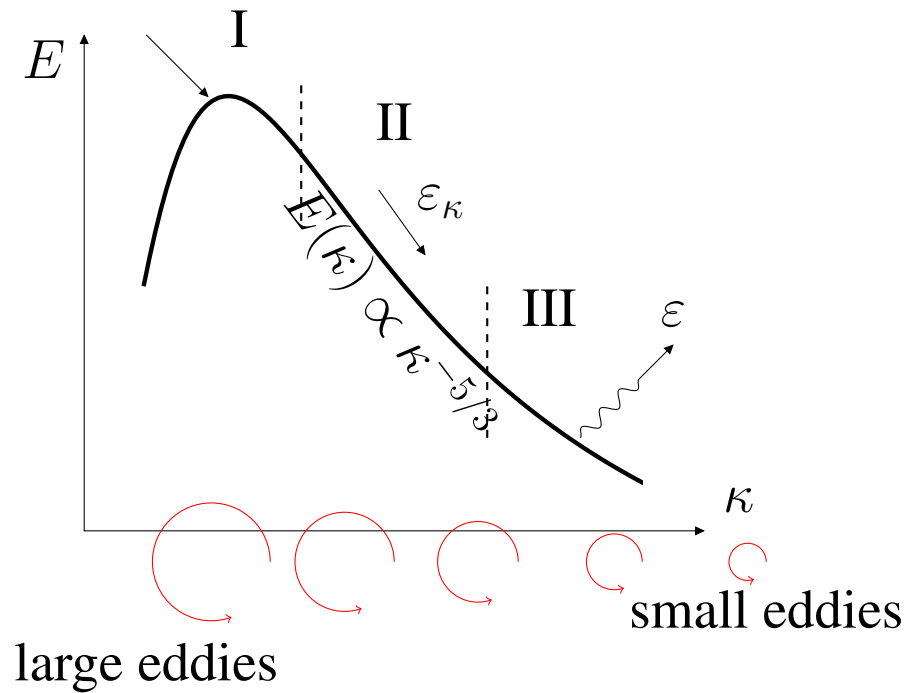
► Spectrum for turbulent kinetic energy, k

$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



► Spectrum for turbulent kinetic energy, k

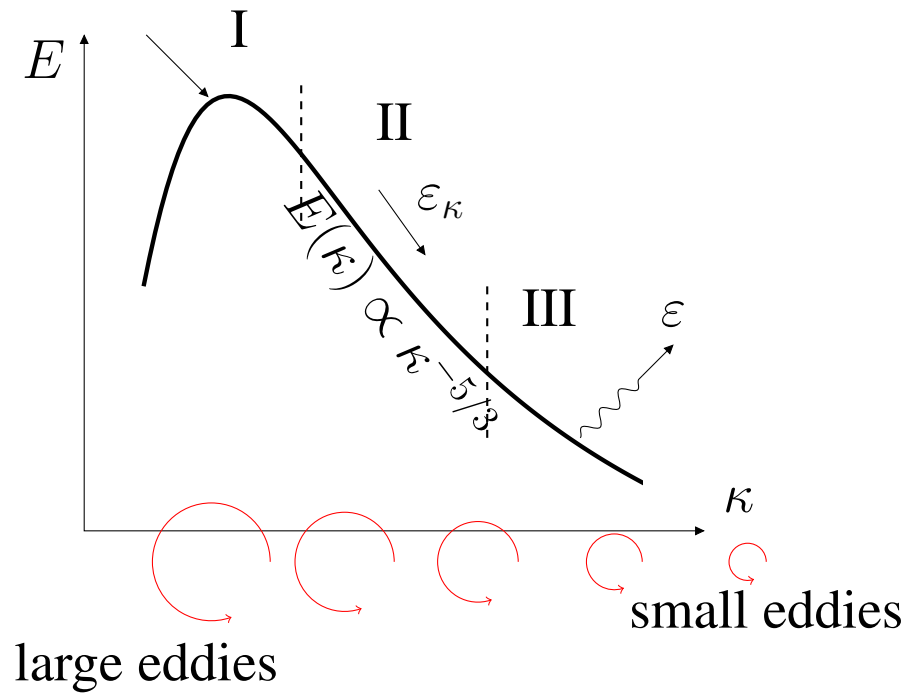
$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



► $E(\kappa_n) \propto a_n^2 + b_n^2$, see the Fourier series on the previous slide

► Spectrum for turbulent kinetic energy, k

$$-\langle \bar{v}_i' \bar{v}_j' \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$

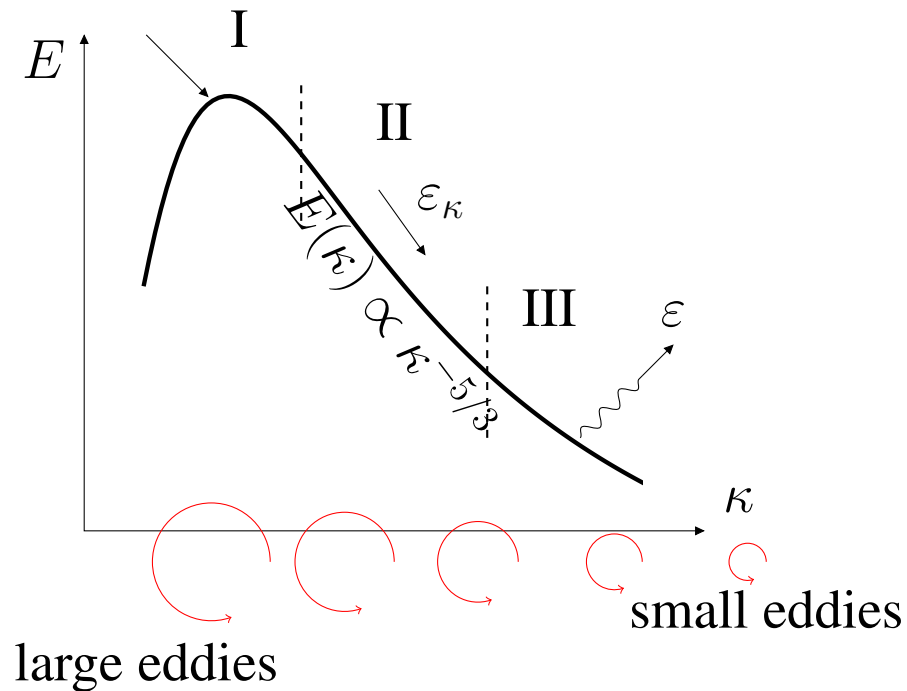


► $E(\kappa_n) \propto a_n^2 + b_n^2$, see the Fourier series on the previous slide ►

$$k = \int_0^\infty E(\kappa) d\kappa = \sum_0^\infty E(\kappa_n) \Delta\kappa_n \quad (35.2)$$

► Spectrum for turbulent kinetic energy, k

$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$

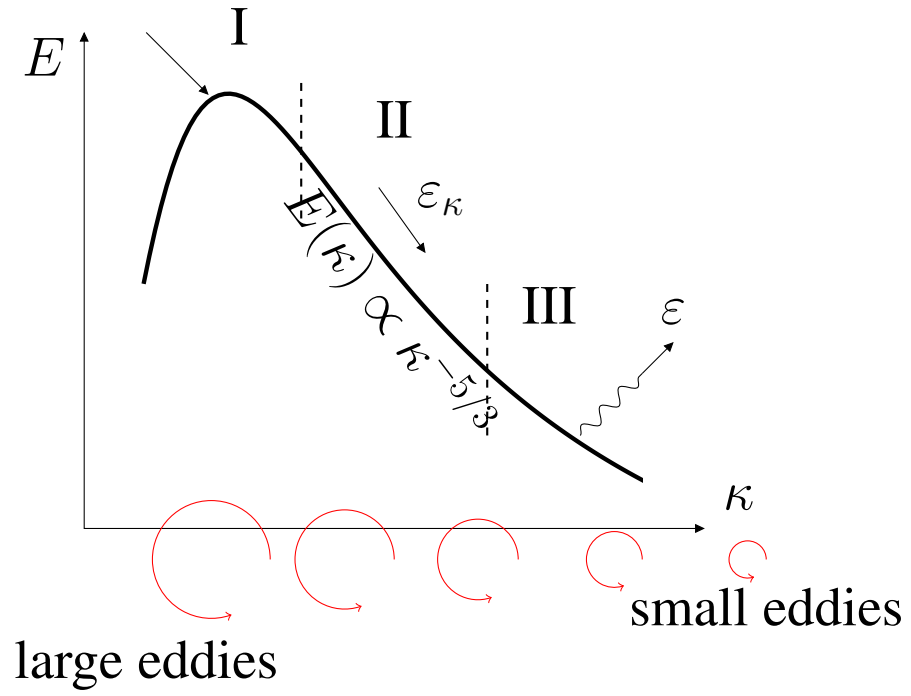


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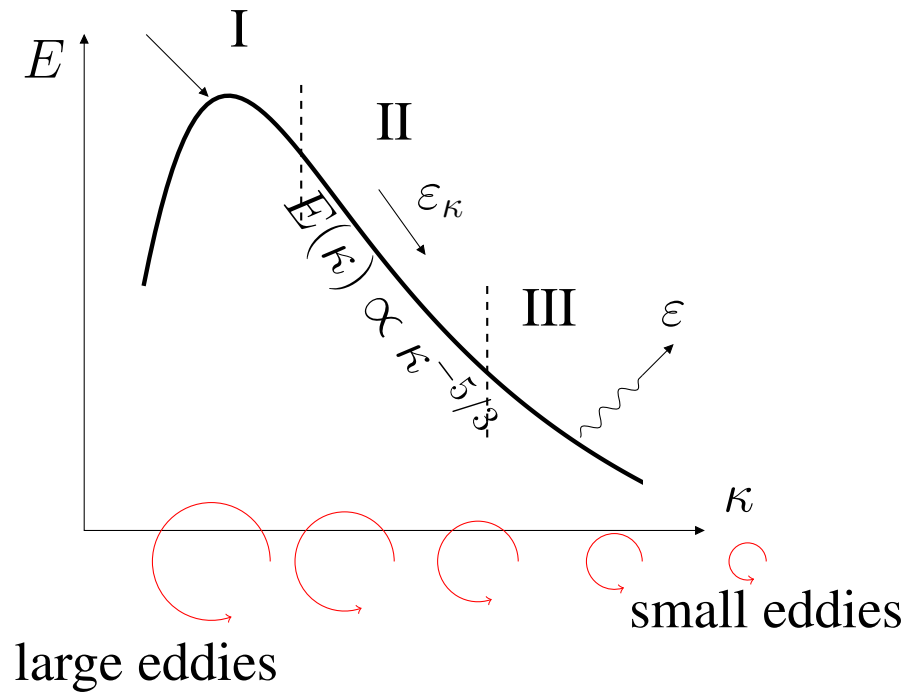
$$k = \int_0^\infty E(\kappa) d\kappa = \sum_0^\infty E(\kappa_n) \Delta\kappa_n \quad (35.2)$$

► which corresponds to Parseval's formula

$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$

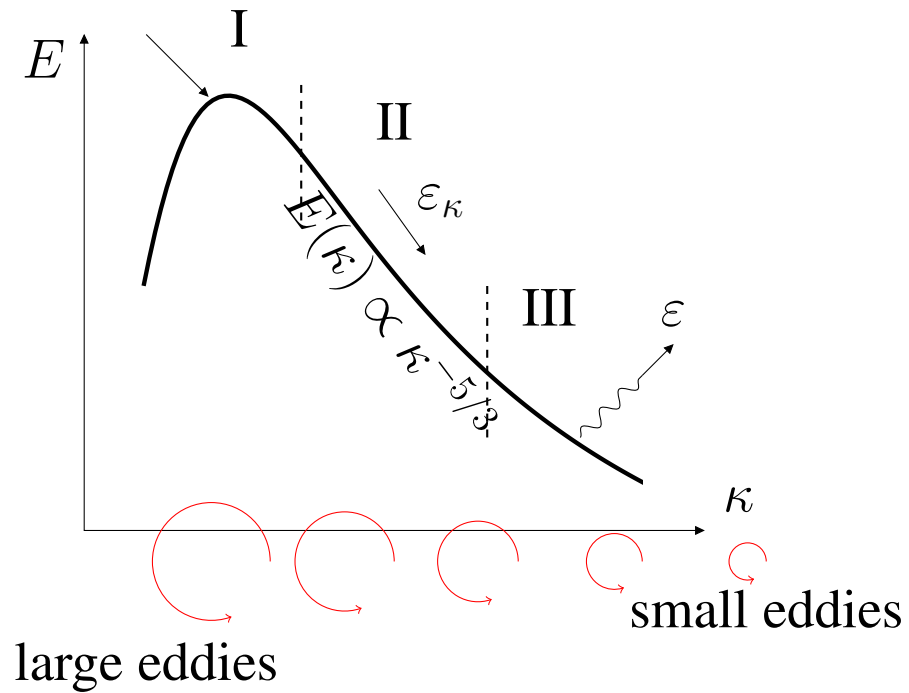


$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



► The turbulence spectrum is divided into three regions:

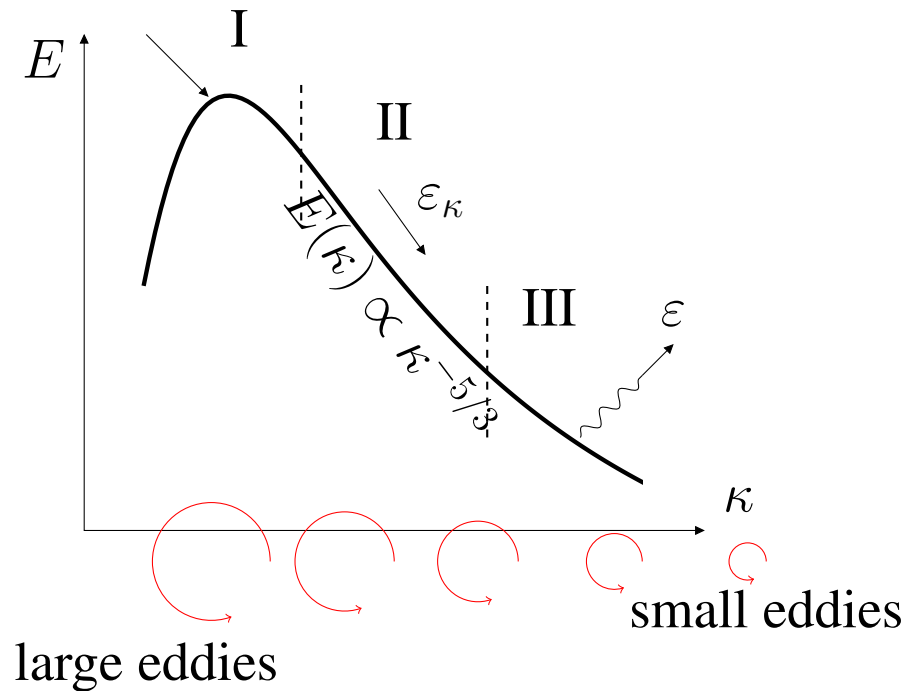
$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



► The turbulence spectrum is divided into three regions:

I. Large eddies carry most of the turb. kinetic energy. They extract energy from the mean flow, P^k .

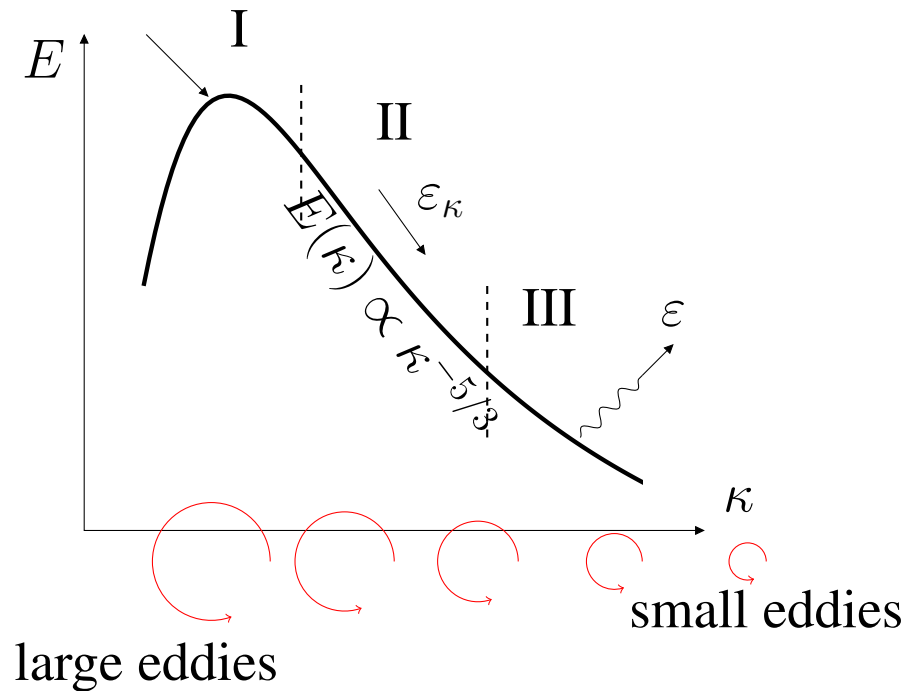
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► The turbulence spectrum is divided into three regions:

- I. Large eddies carry most of the turb. kinetic energy. They extract energy from the mean flow, P^k .
- II. Inertial subrange. Independent of both large eddies (mean flow) and viscosity. Isotropic eddies.

$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



► The turbulence spectrum is divided into three regions:

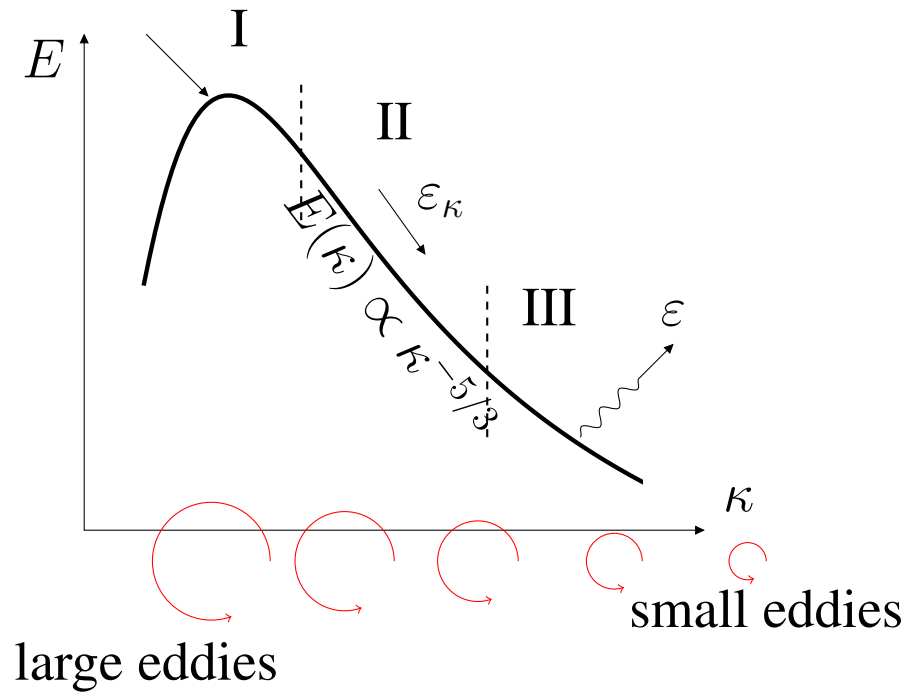
I. Large eddies carry most of the turb. kinetic energy. They extract energy from the mean flow, P^k .

II. Inertial subrange. Independent of both large eddies (mean flow) and viscosity. Isotropic eddies.

III. Dissipation range. Isotropic eddies ($\overline{v'_i v'_j} = c_1 \delta_{ij}$) described by the Kolmogorov scales.

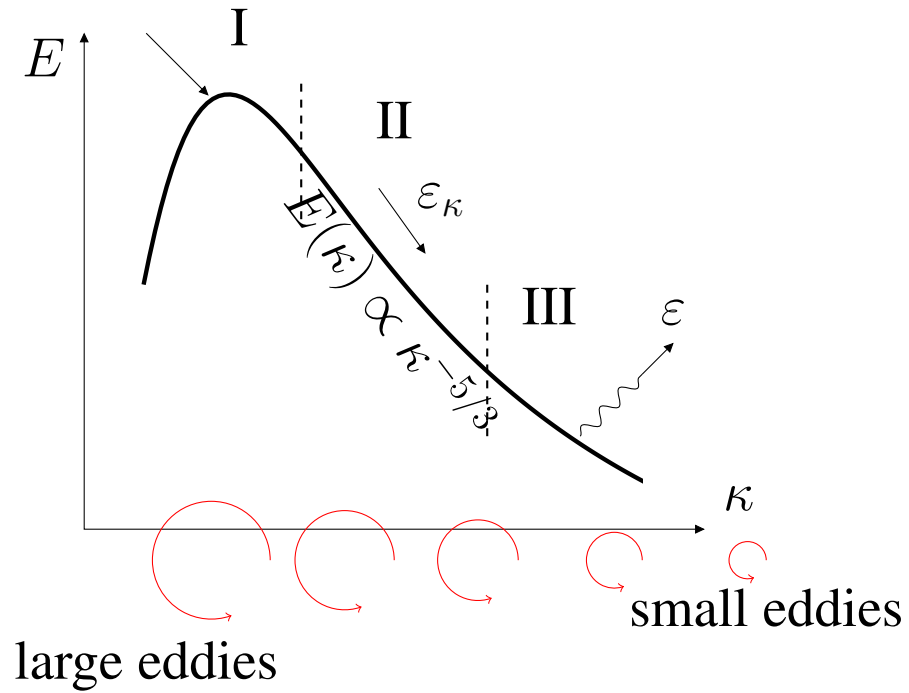
► Turb. kinetic energy in Region II

$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



► Turb. kinetic energy in Region II

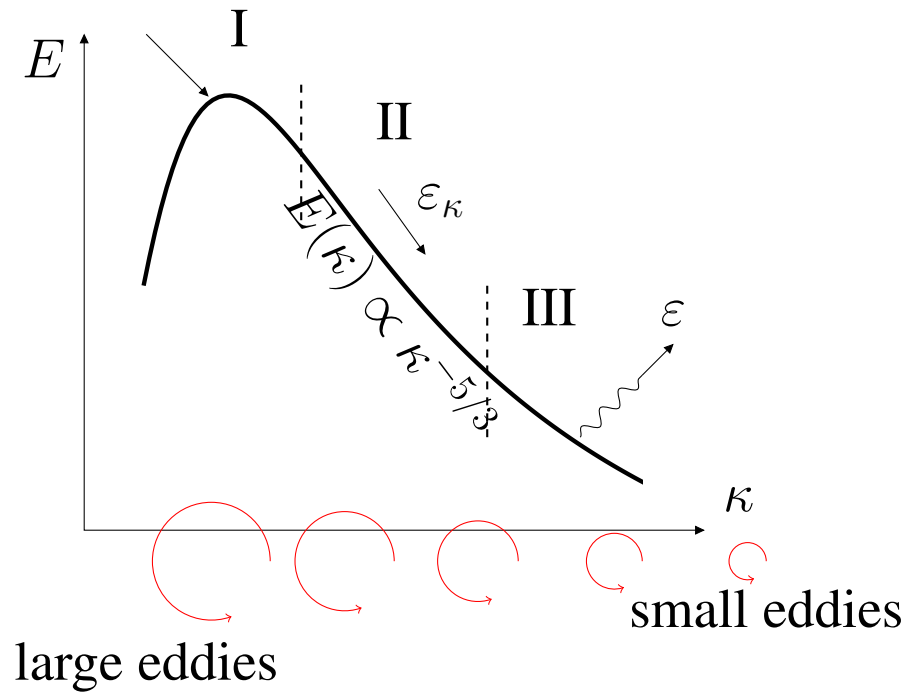
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► Turb. kinetic energy in Region II depends on:

► Turb. kinetic energy in Region II

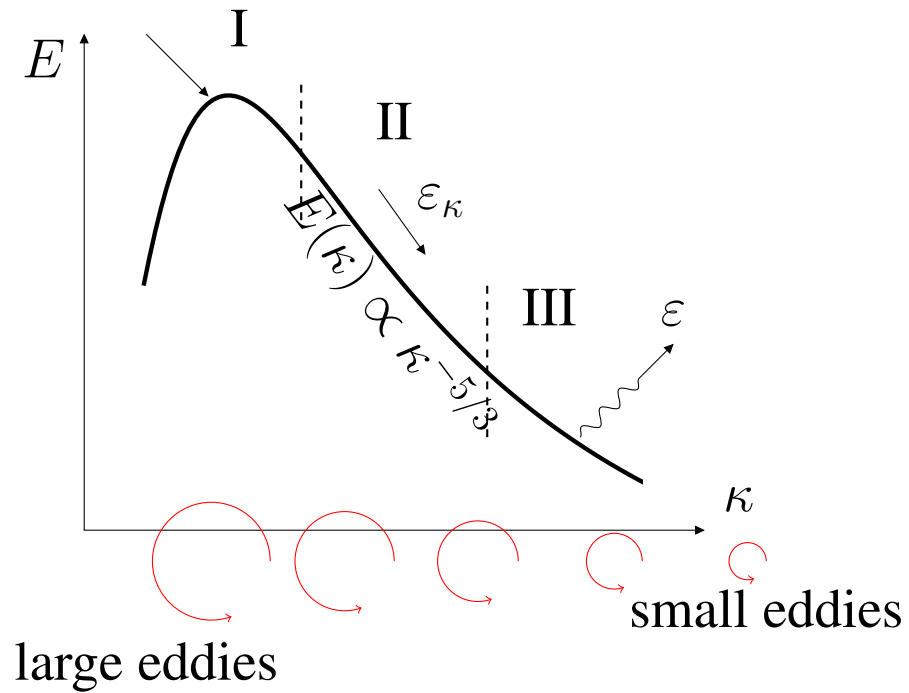
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► Turb. kinetic energy in Region II depends on: ► ϵ

► Turb. kinetic energy in Region II

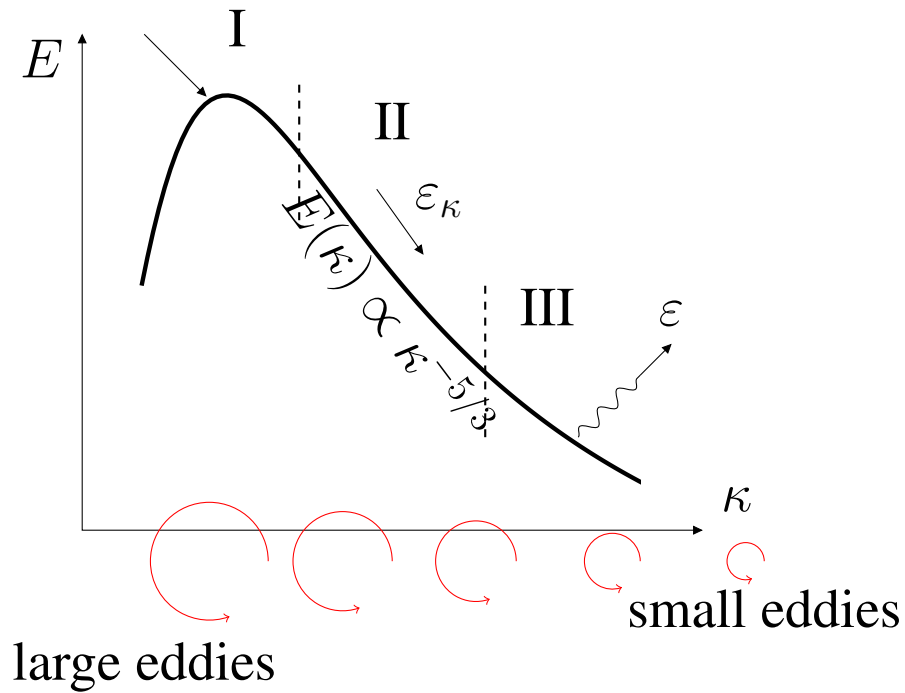
$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



► Turb. kinetic energy in Region II depends on: ► ϵ and ► eddy size $1/\kappa$

► Turb. kinetic energy in Region II

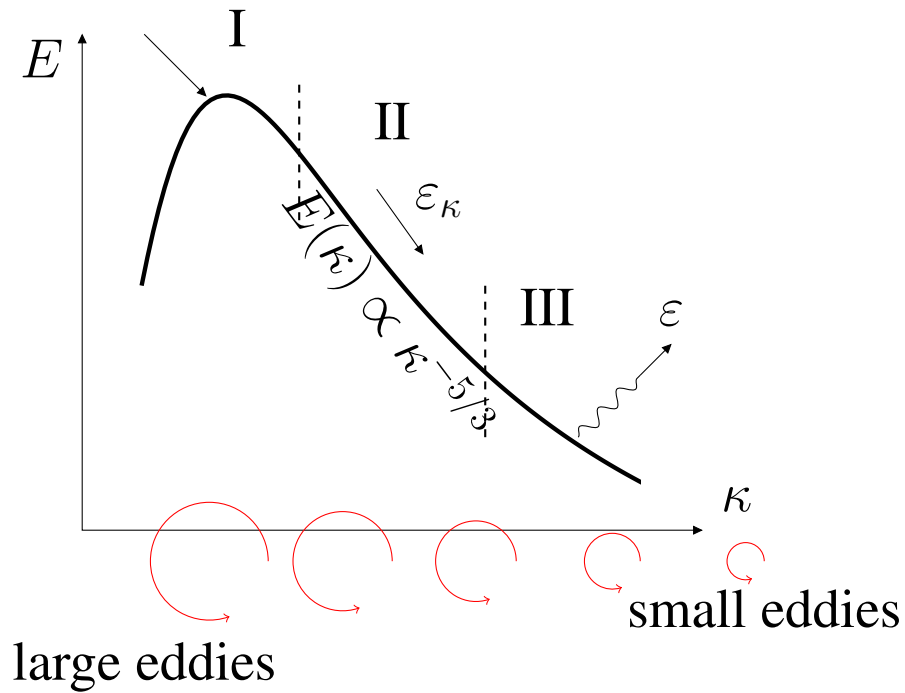
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► Turb. kinetic energy in Region II depends on: ► ϵ and ► eddy size $1/\kappa$ Recall: ► $k = \int_0^\infty E(\kappa) d\kappa$

► Turb. kinetic energy in Region II

$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$

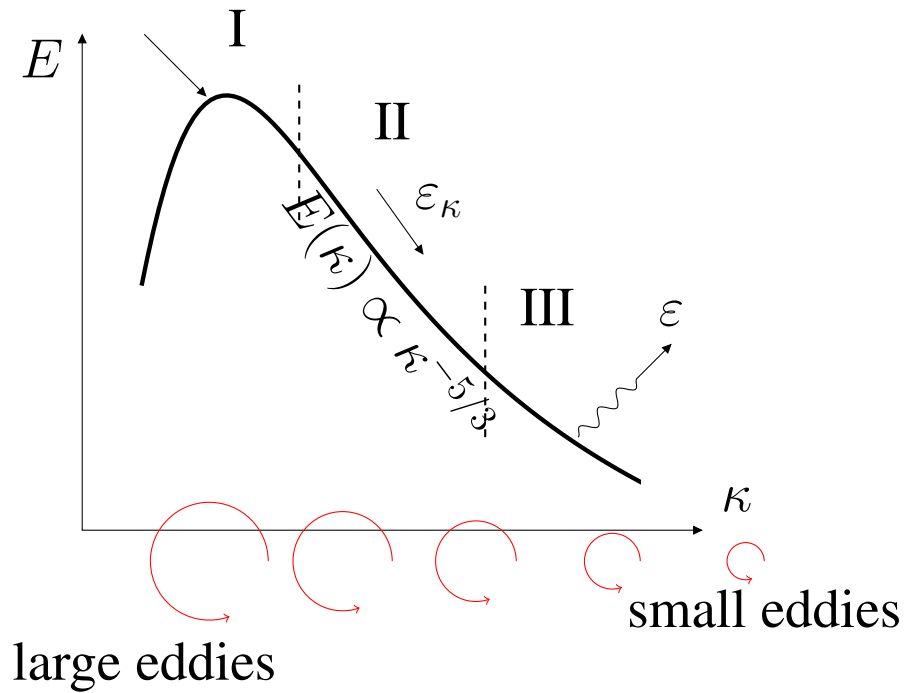


► Turb. kinetic energy in Region II depends on: ► ϵ and ► eddy size $1/k$ Recall: ► $k = \int_0^\infty E(k) dk$

E

► Turb. kinetic energy in Region II

$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$

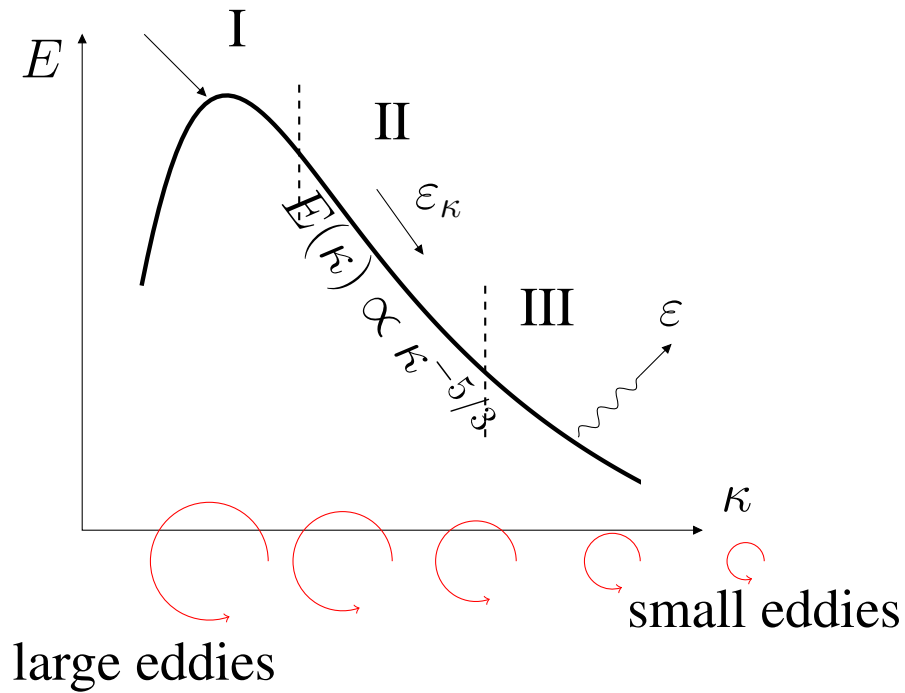


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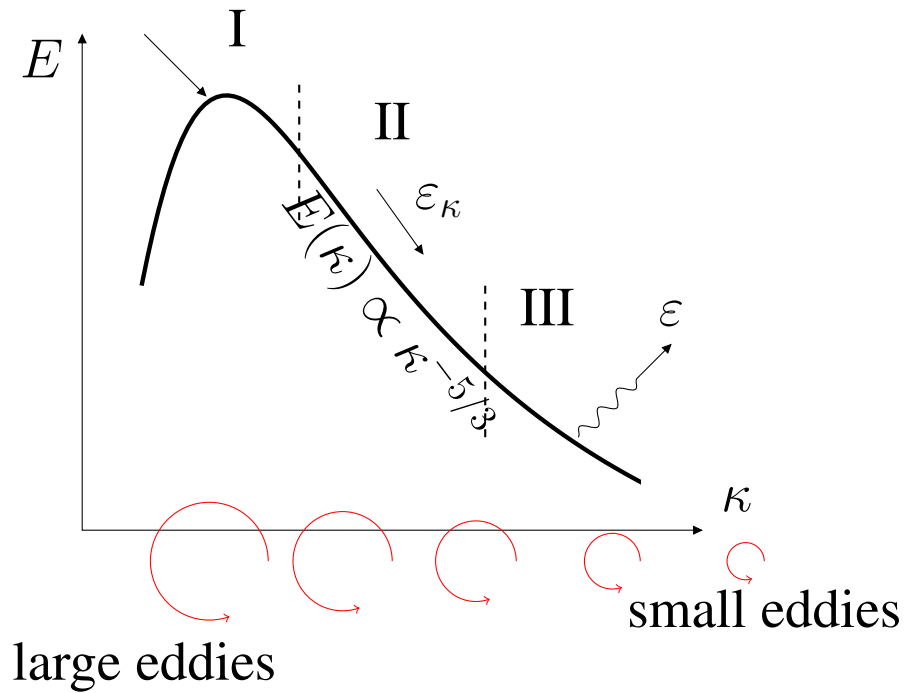


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$$E = \kappa^a$$

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$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$

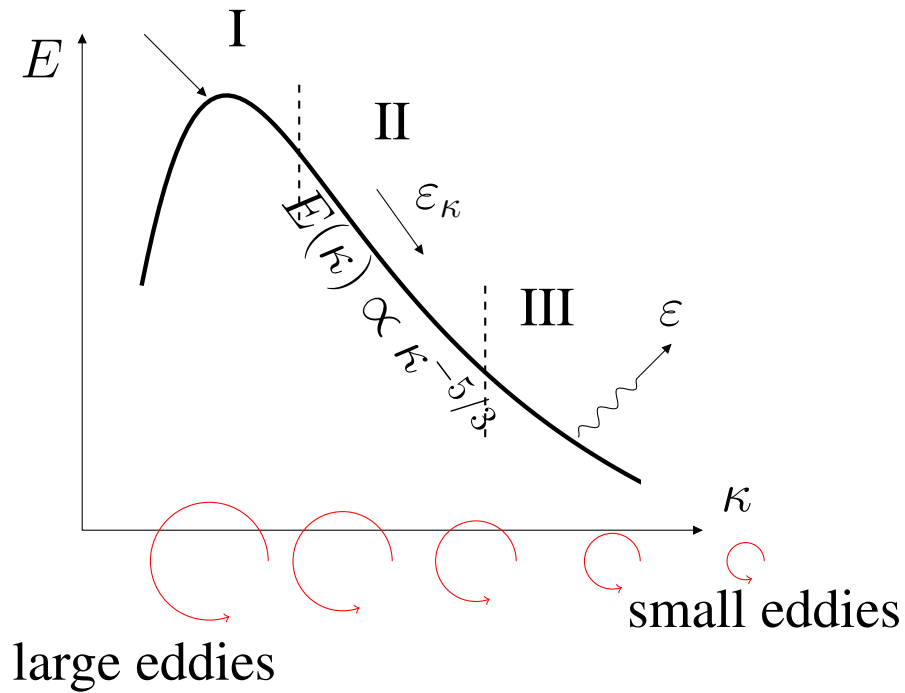


► Turb. kinetic energy in Region II depends on: ► ϵ and ► eddy size $1/\kappa$ Recall: ► $k = \int_0^\infty E(\kappa) d\kappa$

$$E = \kappa^a \epsilon^b$$

► Turb. kinetic energy in Region II

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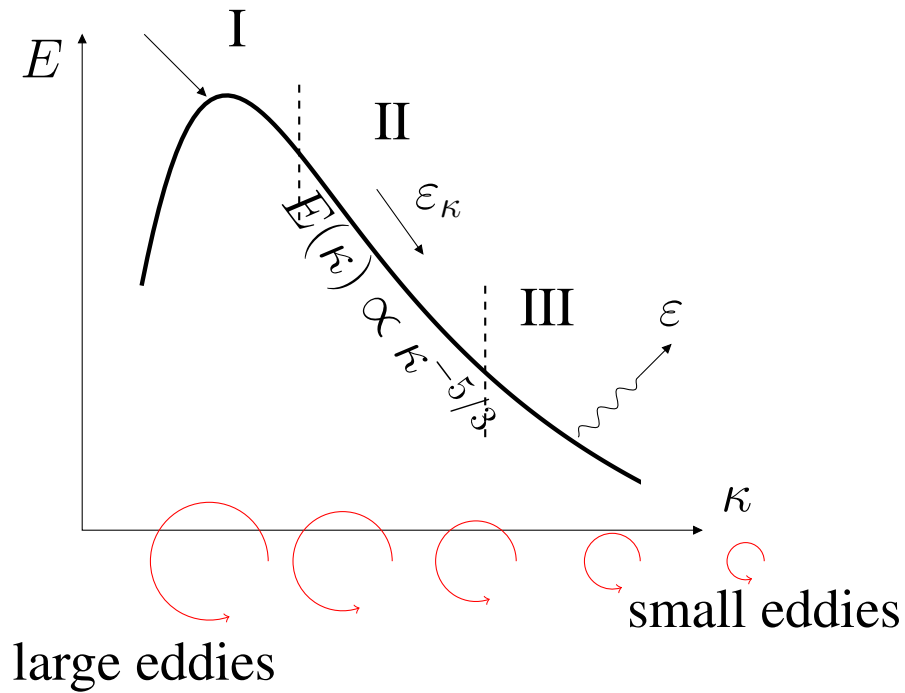
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$[m^3/s^2]$

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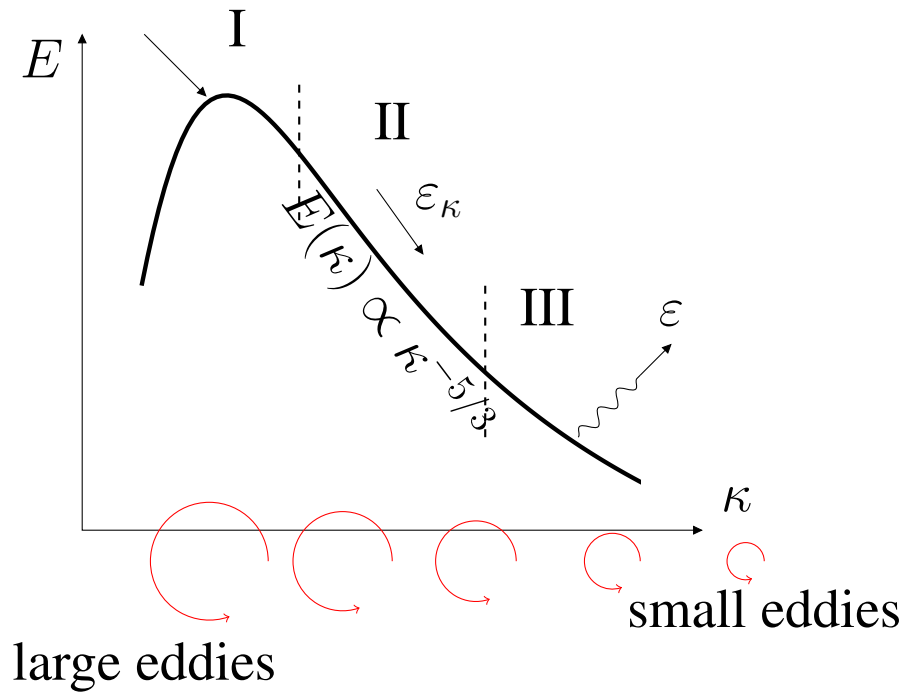


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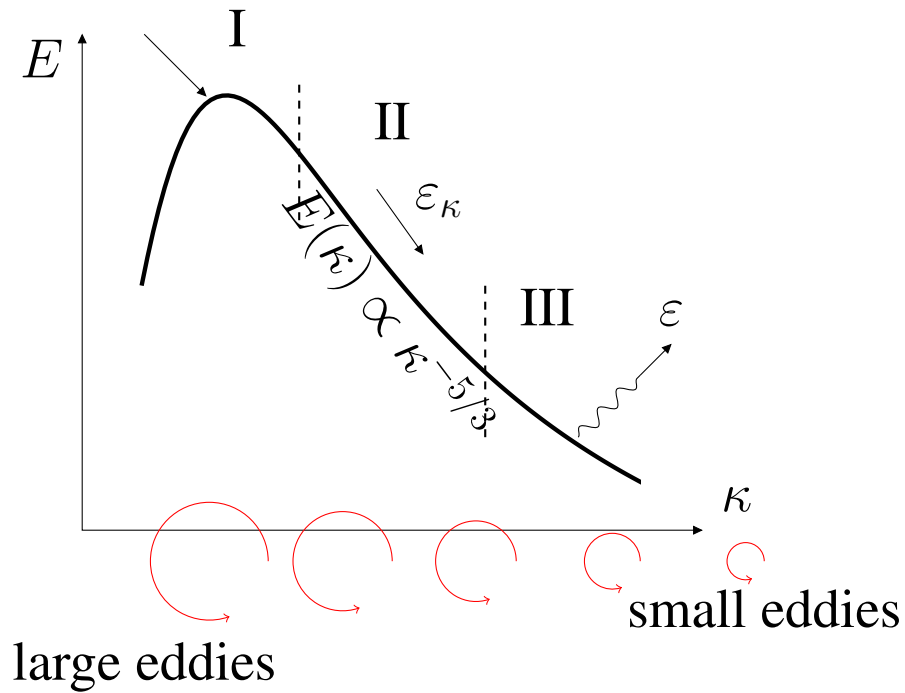


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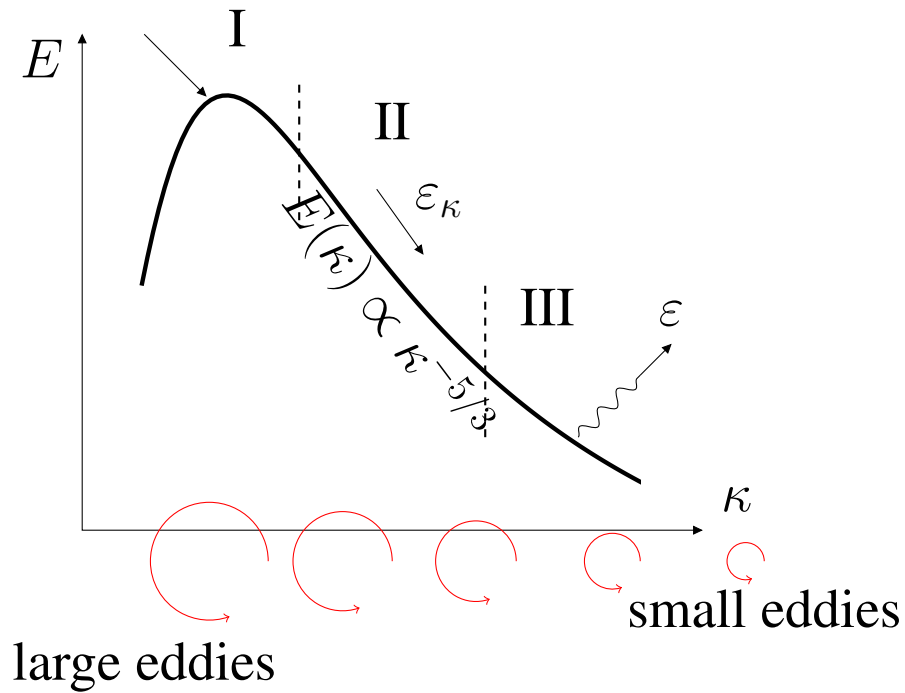


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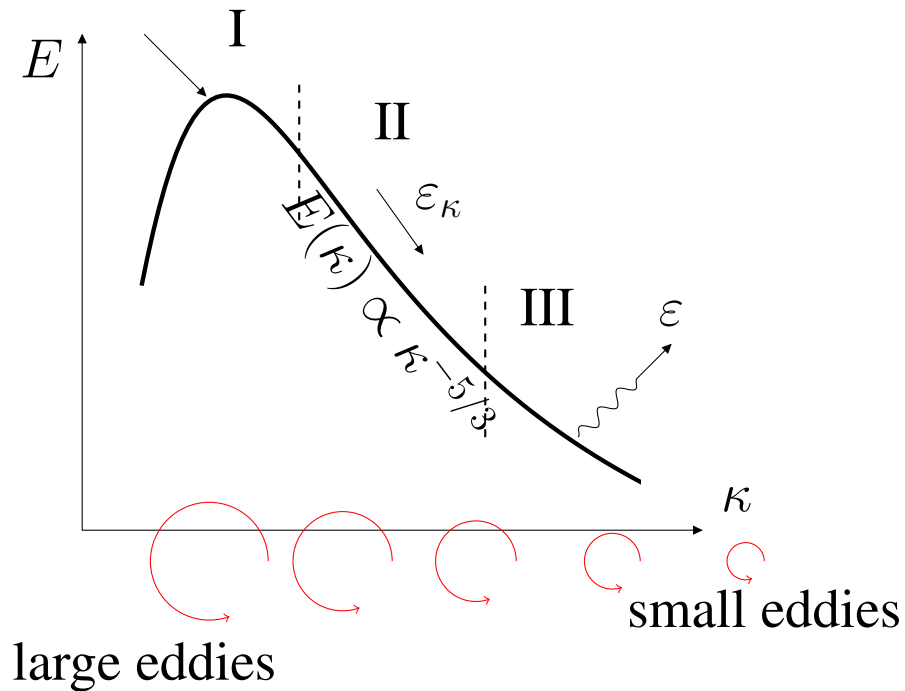
$$E = \kappa^a \epsilon^b$$

$$[m^3/s^2] = [1/m] [m^2/s^3]$$

$$[m]$$

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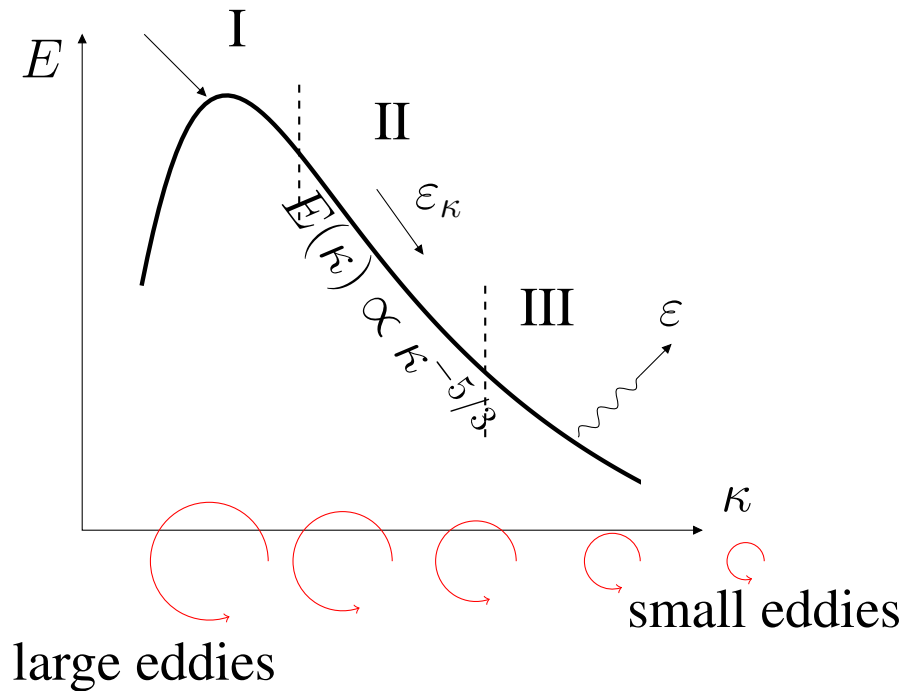
$$E = \kappa^a \epsilon^b$$

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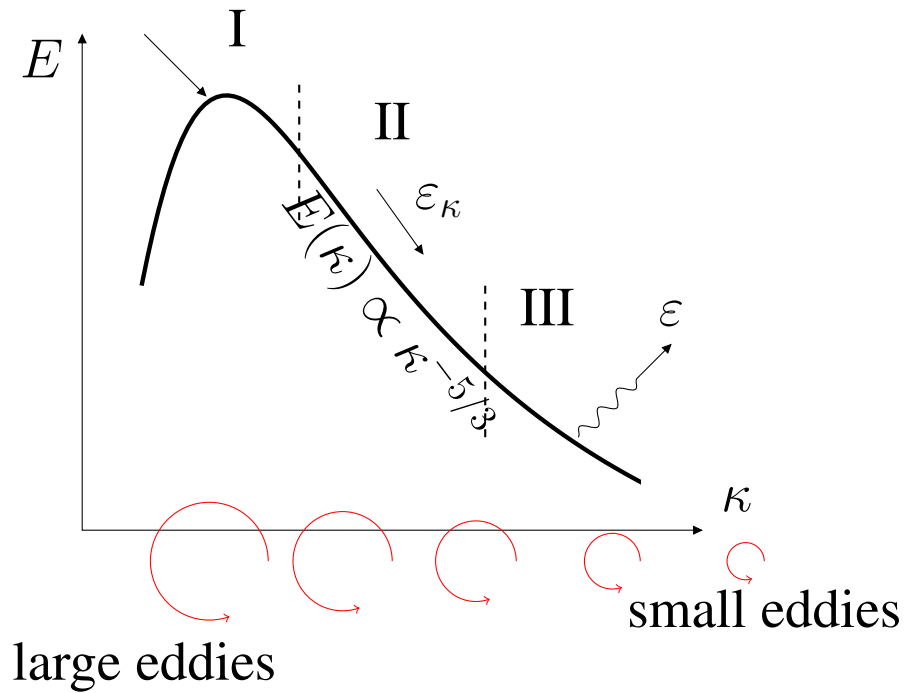
$$E = \kappa^a \epsilon^b$$

$$[m^3/s^2] = [1/m] [m^2/s^3]$$

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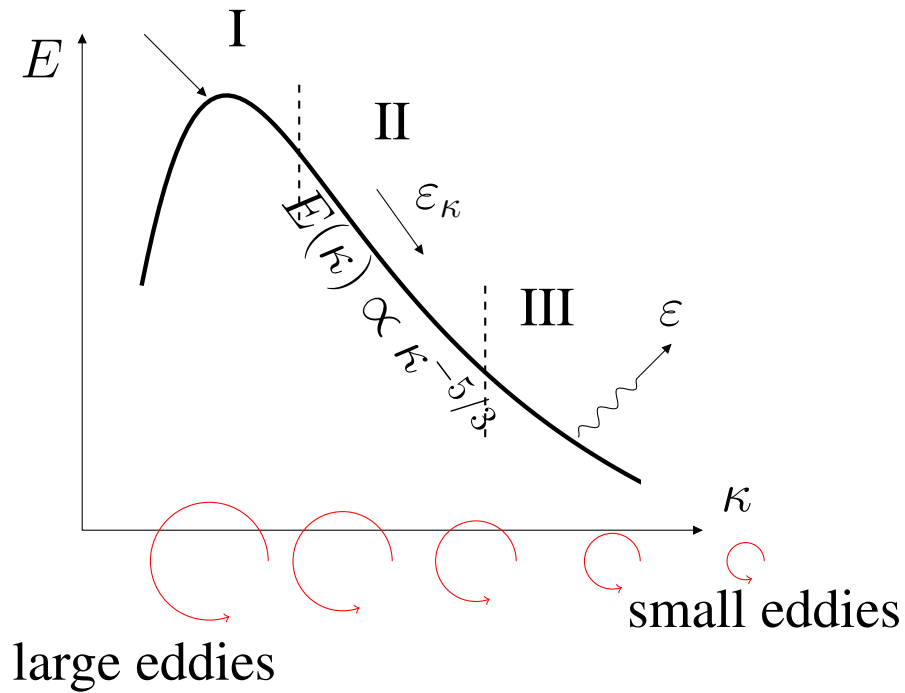
$$E = \kappa^a \epsilon^b$$

$$[m^3/s^2] = [1/m] [m^2/s^3]$$

$$[m] \quad 3 = -a +$$

► Turb. kinetic energy in Region II

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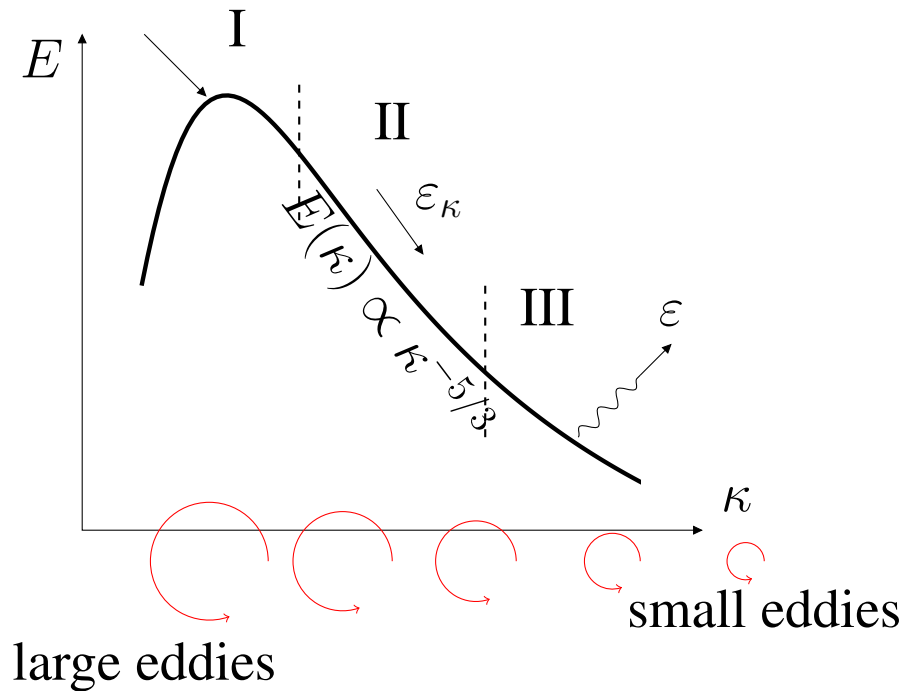
$$E = \kappa^a \epsilon^b$$

$$[m^3/s^2] = [1/m] [m^2/s^3]$$

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► Turb. kinetic energy in Region II

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► Turb. kinetic energy in Region II depends on: ► ϵ and ► eddy size $1/\kappa$ Recall: ► $k = \int_0^\infty E(\kappa) d\kappa$

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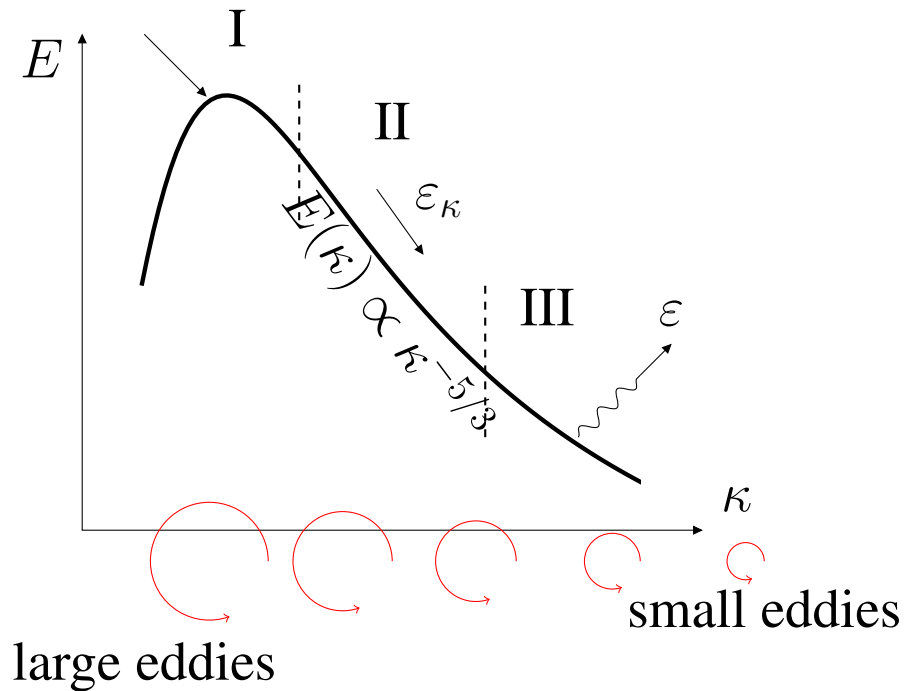
$$[m^3/s^2] = [1/m] [m^2/s^3]$$

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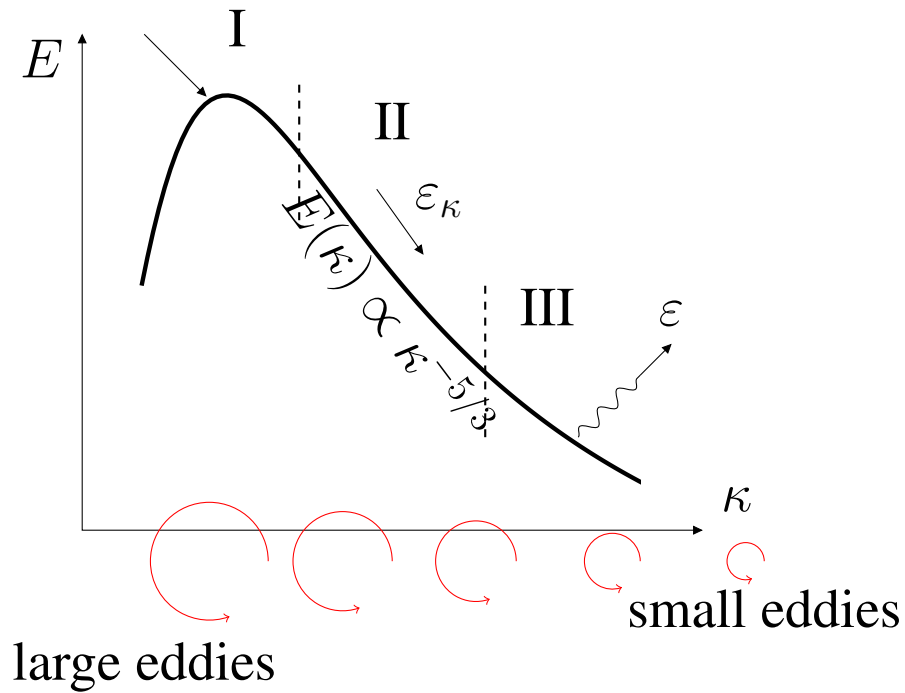
$$[m^3/s^2] = [1/m] [m^2/s^3]$$

$$[m] \quad 3 = -a + 2b$$

$$[s] \quad -2$$

► Turb. kinetic energy in Region II

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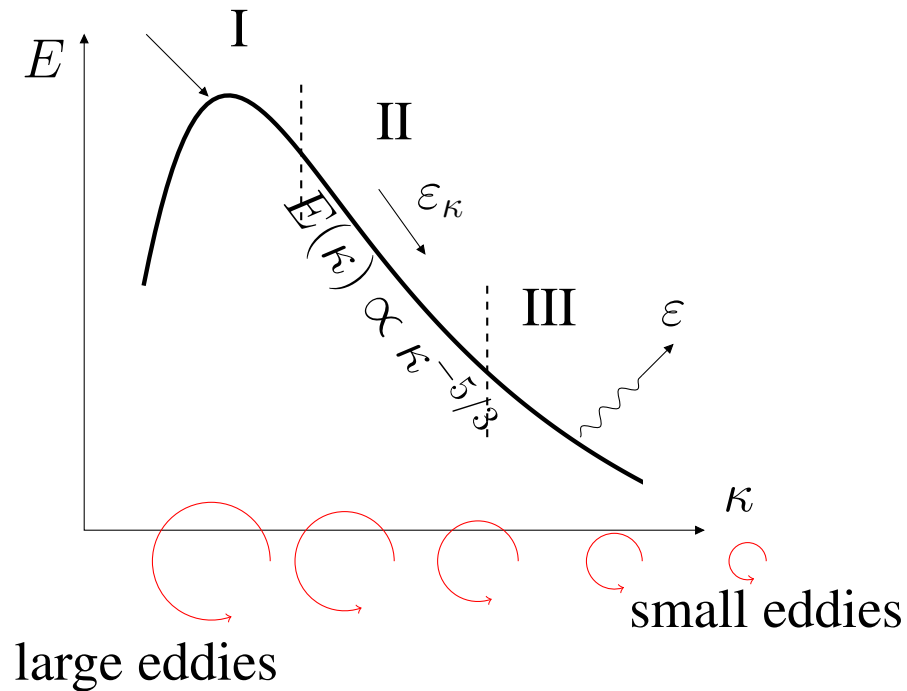
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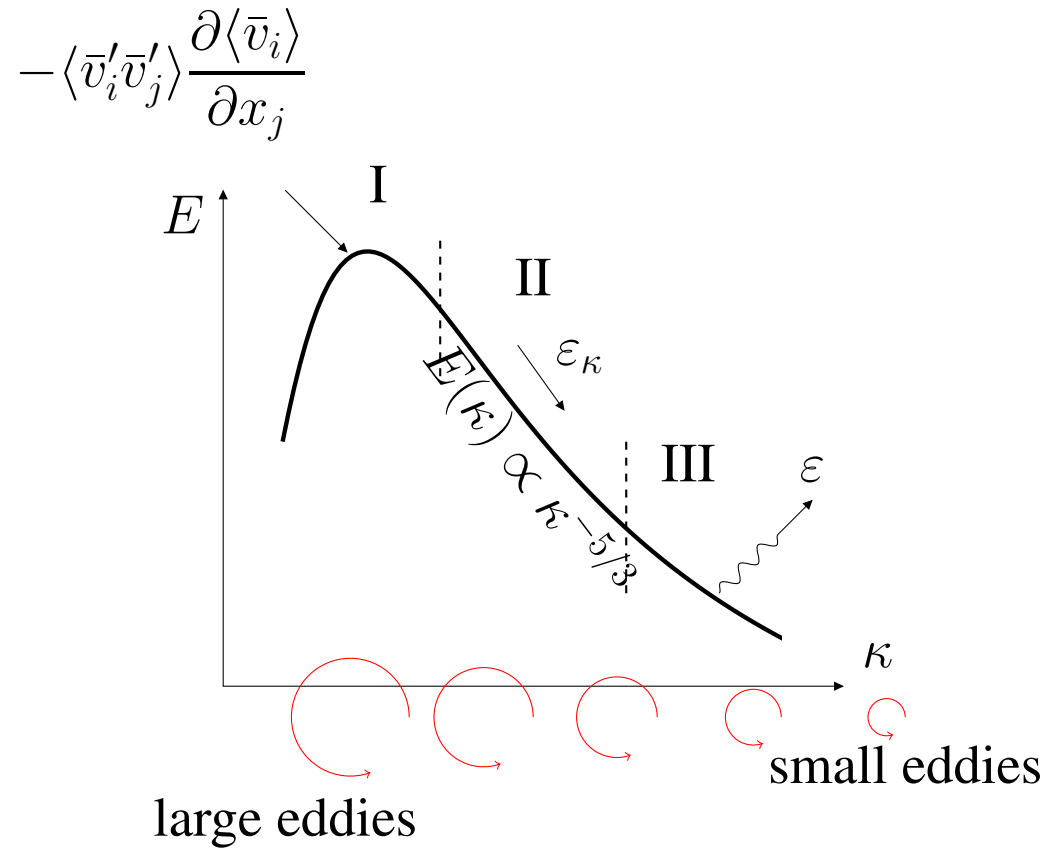
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$$[m] \quad 3 = -a + 2b$$

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► Turb. kinetic energy in Region II



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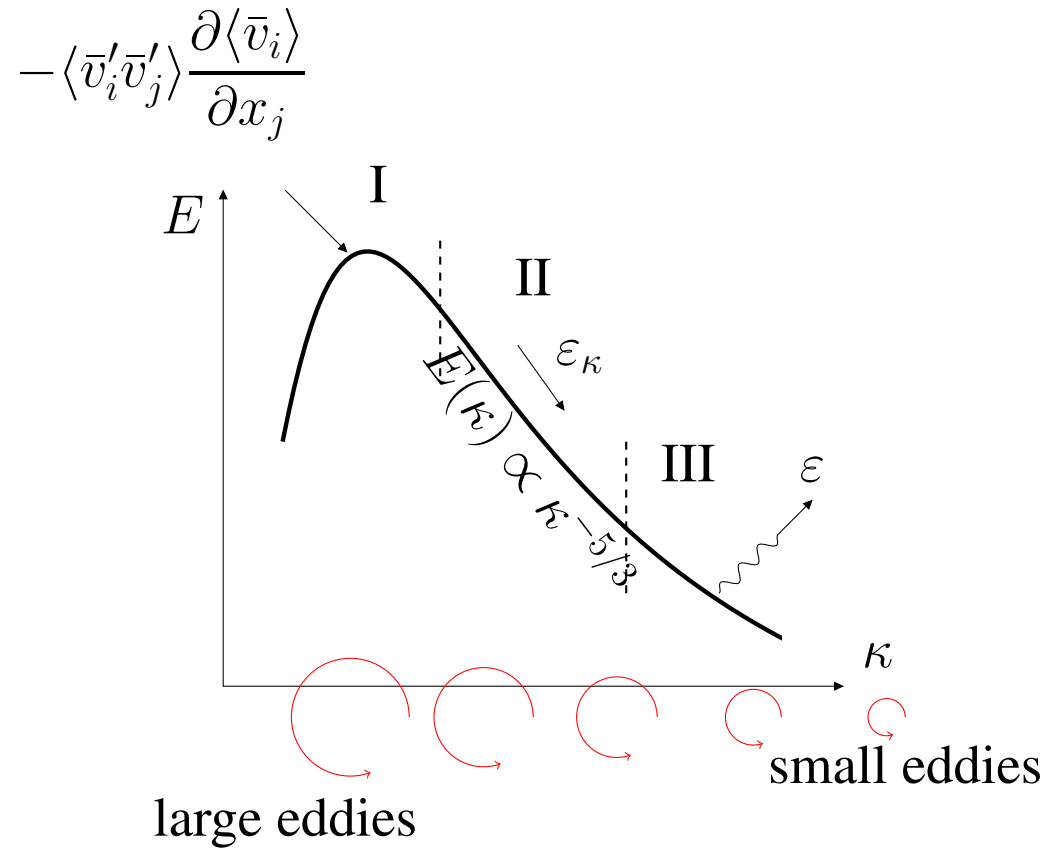
$$[m^3/s^2] = [1/m] [m^2/s^3]$$

$$[m] \quad 3 = -a + 2b$$

$$[s] \quad -2 = -3b$$

$b = 2/3, a = -5/3$ so that

► Turb. kinetic energy in Region II



► Turb. kinetic energy in Region II depends on: ► ϵ and ► eddy size $1/\kappa$ Recall: ► $k = \int_0^\infty E(\kappa) d\kappa$

$$E = \kappa^a \epsilon^b$$

$$[m^3/s^2] = [1/m] [m^2/s^3]$$

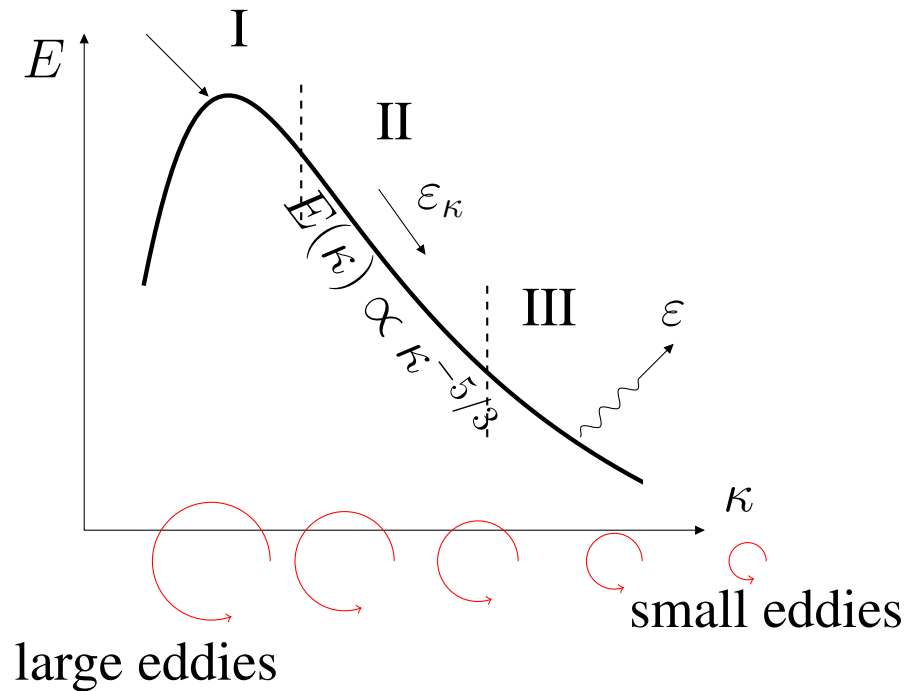
$$[m] \quad 3 = -a + 2b$$

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$b = 2/3, a = -5/3$ so that ► $E(\kappa) = C_K \epsilon^{2/3} \kappa^{-5/3}$

► Turb. kinetic energy in Region II

$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



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$$E = \kappa^a \epsilon^b$$

$$[m^3/s^2] = [1/m] [m^2/s^3]$$

$$[m] \quad 3 = -a + 2b$$

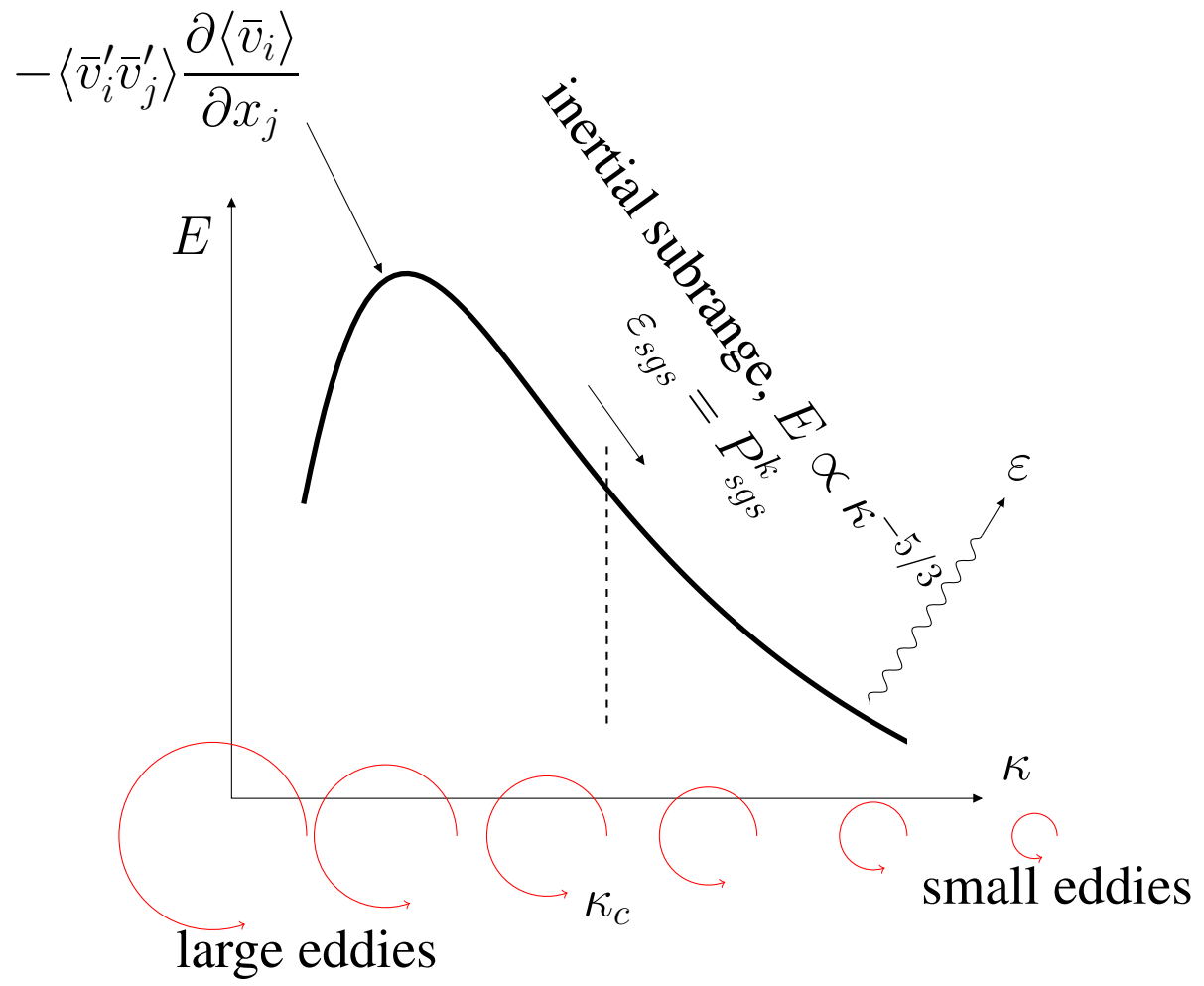
$$[s] \quad -2 = -3b$$

$b = 2/3, a = -5/3$ so that $\blacktriangleright E(\kappa) = C_K \varepsilon^{2/3} \kappa^{-5/3}$

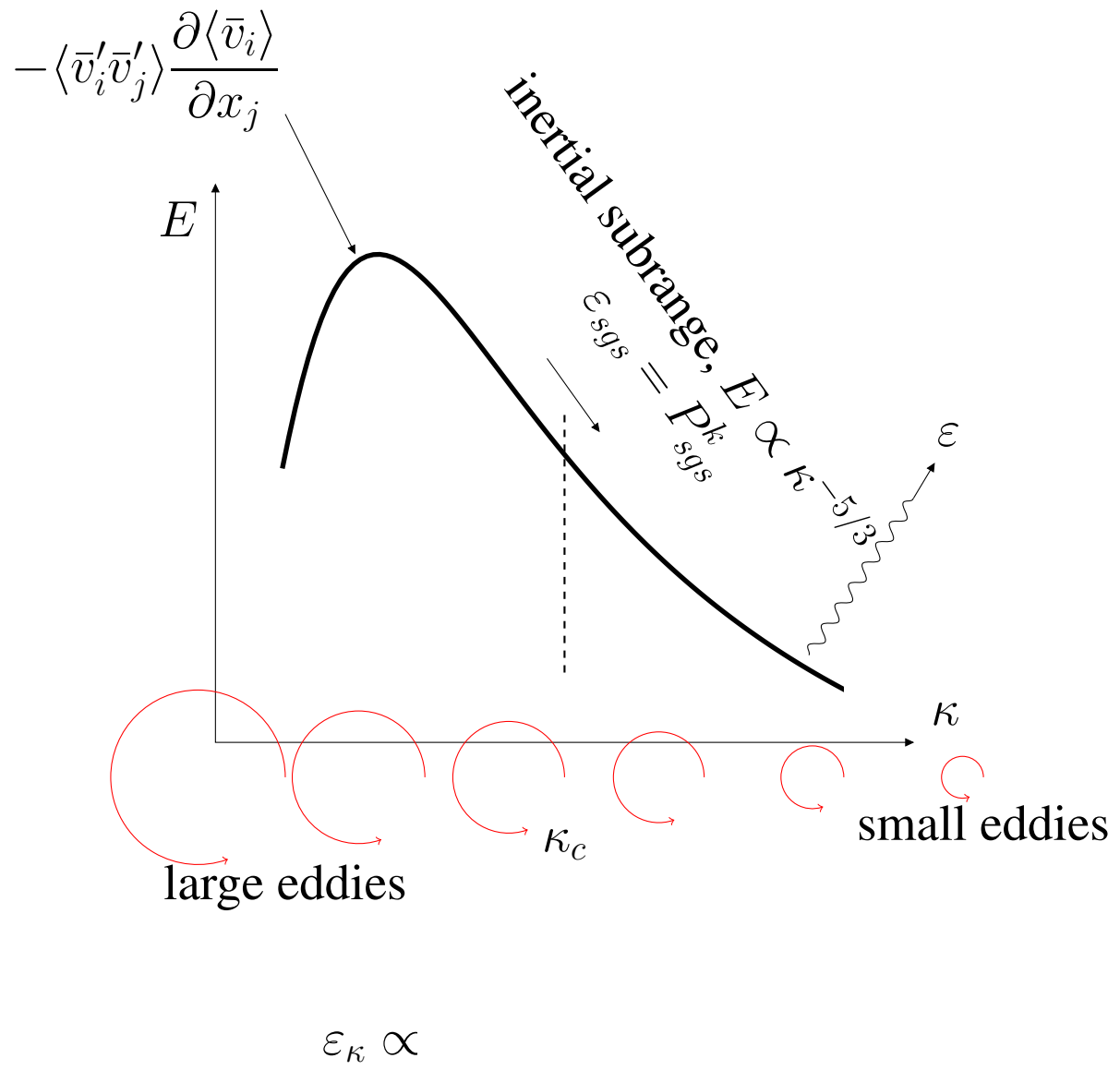
\blacktriangleright This is called **von Kármán spectrum** or **$-5/3$ law**

► Energy transfer from eddy-to-eddy

► Energy transfer from eddy-to-eddy

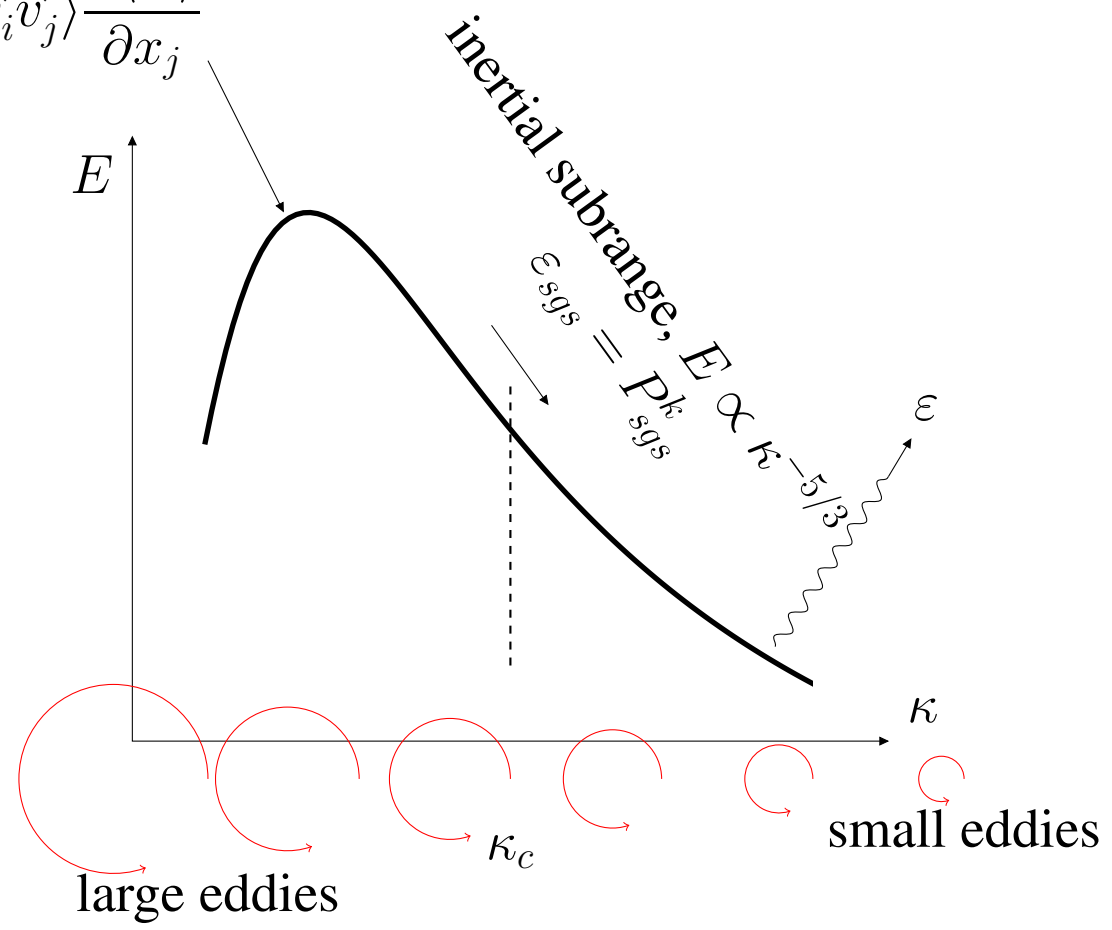


► Energy transfer from eddy-to-eddy



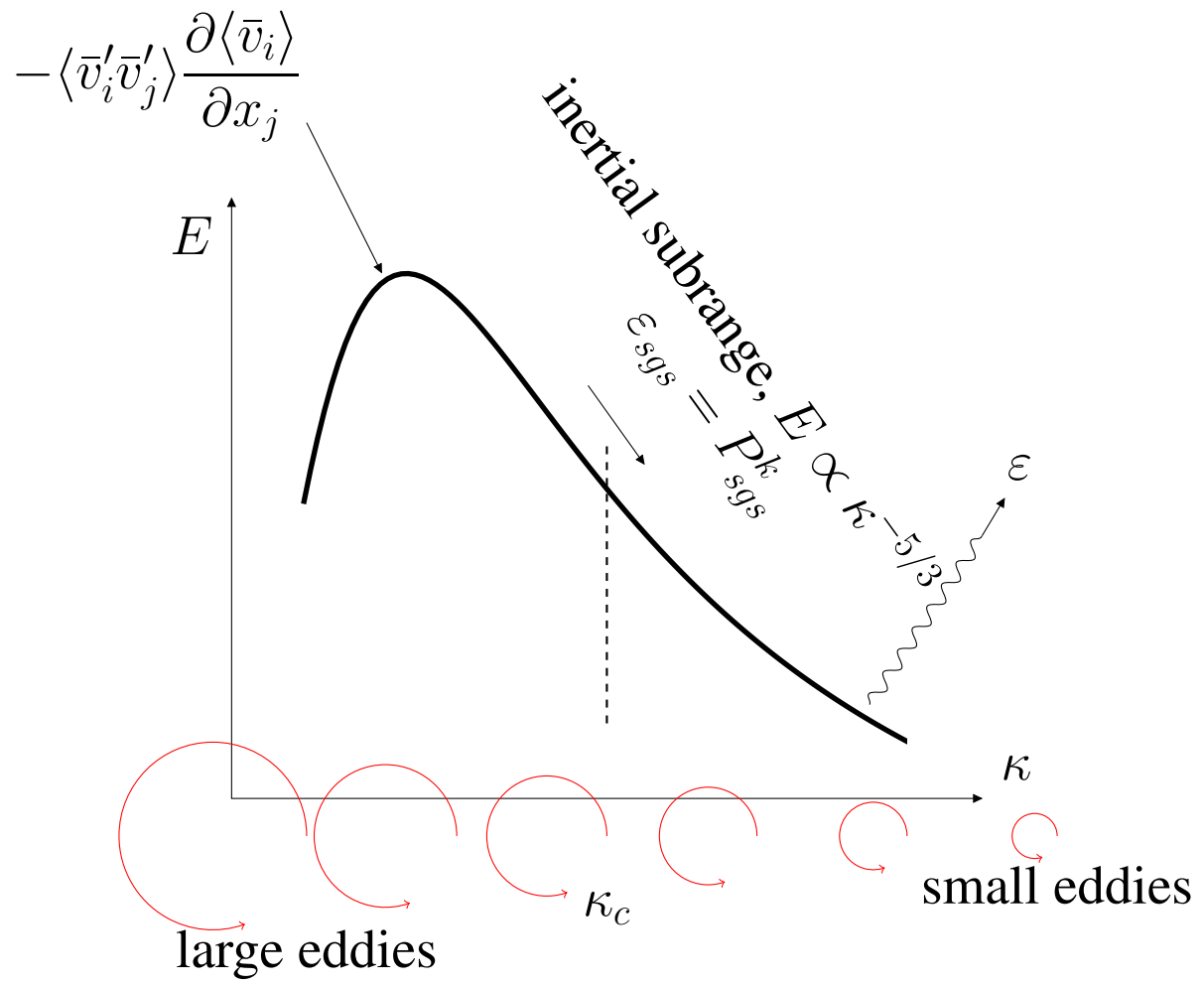
► Energy transfer from eddy-to-eddy

$$-\langle \bar{v}'_i \bar{v}'_j \rangle \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



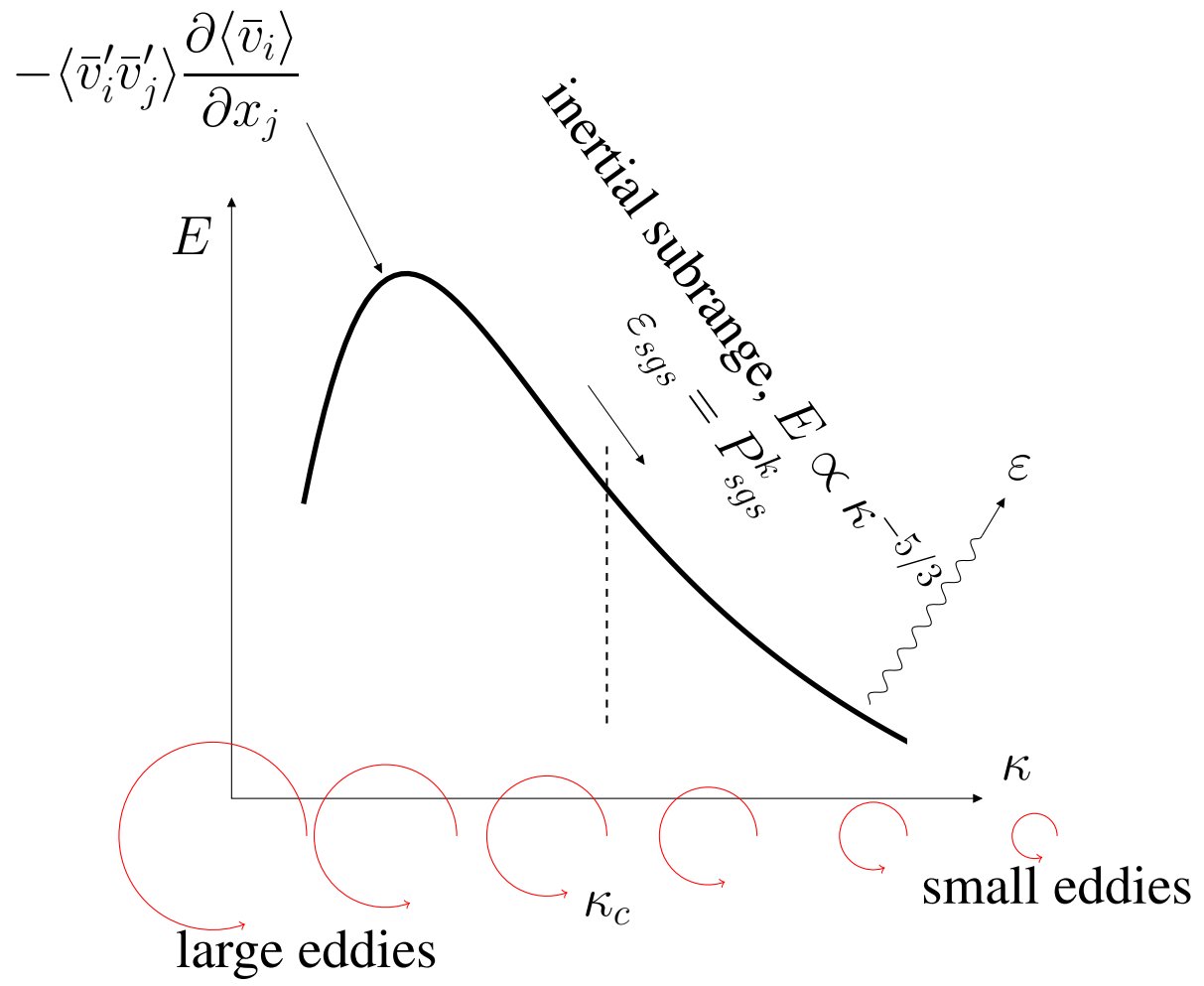
$$\epsilon_K \propto v_K^2 /$$

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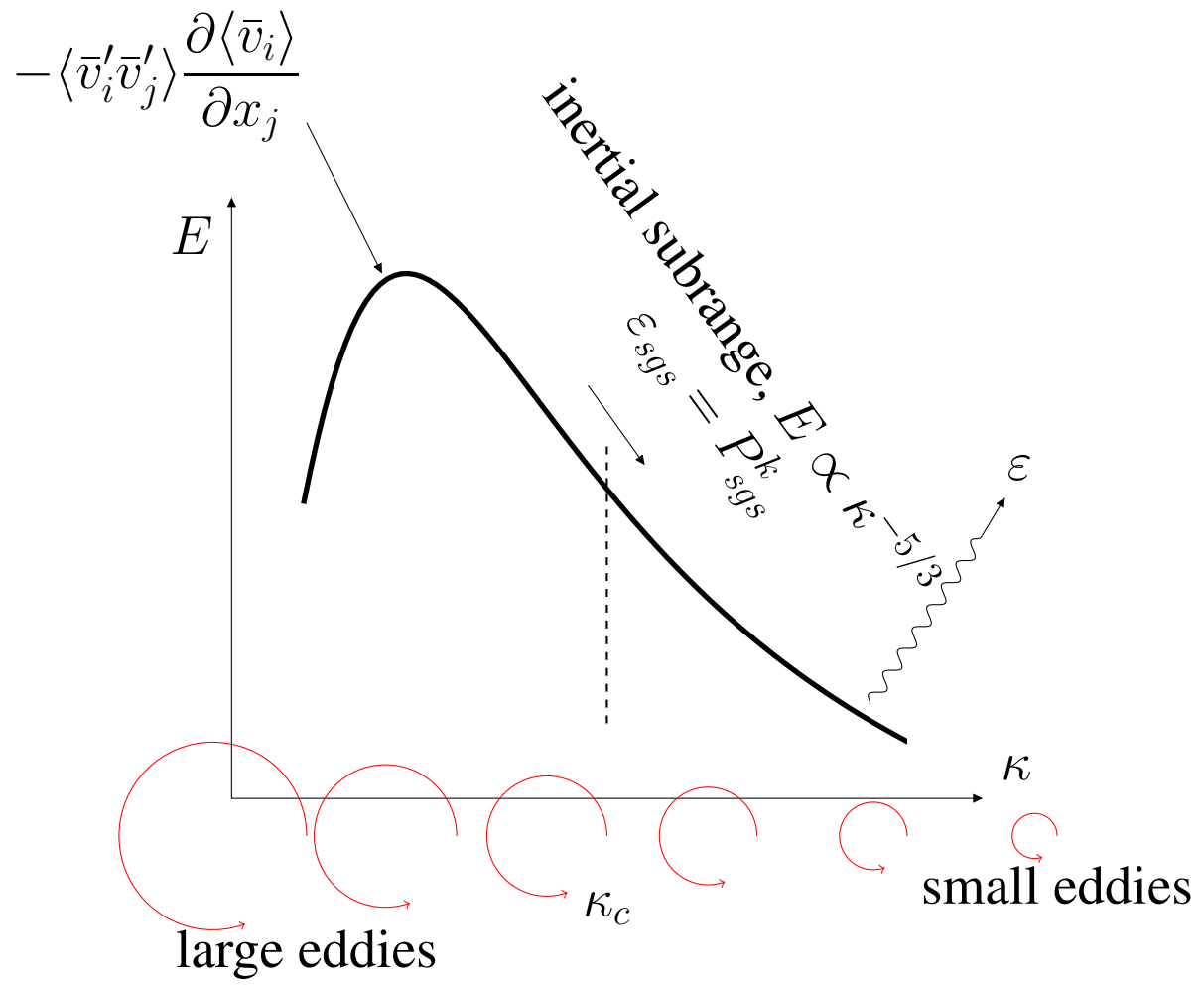
$$\epsilon_K \propto v_K^2 / (\ell_K / v_K) \propto$$

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► Energy spectrum: recall that k for wavenumber κ is $k \propto E \Delta \kappa$ (see Eq. 35.2). We get

$$E(\kappa) \propto k_{\kappa} / \kappa \propto v_{\kappa}^2 / \kappa \propto \kappa^{-5/3}$$

► Why dissipation only at small scale/eddies?

- Let's show that $\varepsilon = \nu \overline{\frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}}$ gets larger the smaller the scales/eddies.
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$$\left(\frac{\partial v}{\partial x} \right)_{\kappa} \propto \left(\kappa^{-2/3} \right)^{1/2} \kappa \propto \kappa^{-1/3} \kappa \propto \kappa^{2/3}$$

► Hence ε increases as κ increases, i.e. ε gets larger for small eddies.

On-line Lecture 7

¶ See Section 18, Large Eddy Simulations

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in RANS:

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$$\langle \Phi \rangle =$$

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$$\langle \Phi \rangle = \frac{1}{2T} \int_{-T}^T \Phi(t) dt$$

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$$\langle \Phi \rangle = \frac{1}{2T} \int_{-T}^T \Phi(t) dt, \quad \Phi = \langle \Phi \rangle + \Phi'$$

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$$\bar{\Phi}(x, t) = \frac{1}{\Delta x} \int_{x-0.5\Delta x}^{x+0.5\Delta x} \Phi(\xi, t) d\xi$$

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Momentum equations in DNS:

$$\frac{\partial v_i}{\partial t} + \frac{\partial}{\partial x_j} (v_i v_j) = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + \nu \frac{\partial^2 v_i}{\partial x_j \partial x_j} \quad (36.1)$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.2)$$

On-line Lecture 7

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► Filter pressure gradient in Eq. 36.1

Momentum equations in LES:

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$$\frac{\partial \bar{p}}{\partial x_i} =$$

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► Filter pressure gradient in Eq. 36.1

$$\overline{\frac{\partial p}{\partial x_i}} = \frac{1}{V} \int_V \frac{\partial p}{\partial x_i} dV$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\overline{\frac{\partial p}{\partial x_i}} = \frac{1}{V} \int_V \frac{\partial p}{\partial x_i} dV \stackrel{?}{=} \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) =$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

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► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{p}}{\partial x_i} = -\frac{1}{\rho} \frac{\partial}{\partial x_i} \int_V \rho \, dV = -\frac{1}{\rho} \frac{\partial}{\partial x_i} \int_V \rho \, dV = -\frac{\partial \bar{p}}{\partial x_i}$$

Momentum equations in LES:

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► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{p}}{\partial x_i} = -\frac{1}{\rho} \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) = -\frac{1}{\rho} \left(\frac{1}{V} \int_V \frac{\partial p}{\partial x_i} dV \right) = -\frac{\partial \bar{p}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) =$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{n}}{\partial x_i} = \frac{1}{V} \int_V \frac{\partial n}{\partial x_i} dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V n dV \right) = \frac{\partial \bar{n}}{\partial x_i}$$

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$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

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► Filter non-linear term in Eq. 36.1

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{n}}{\partial x_i} = \frac{1}{V} \frac{\partial}{\partial x_i} \int_V n dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V n dV \right) = \frac{\partial \bar{n}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} =$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{n}}{\partial x_i} = \frac{1}{V} \frac{\partial}{\partial x_i} \int_V n dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V n dV \right) = \frac{\partial \bar{n}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \mathcal{O}((\Delta x)^2)$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{n}}{\partial x_i} = \frac{1}{V} \frac{\partial n}{\partial x_i} dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int n dV \right) = \frac{\partial \bar{n}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \mathcal{O}((\Delta x)^2)$$

Left side :

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{n}}{\partial x_i} = \frac{1}{V} \int_V \frac{\partial n}{\partial x_i} dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V n dV \right) = \frac{\partial \bar{n}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \mathcal{O}((\Delta x)^2)$$

Left side : $\frac{\partial}{\partial x_j} (\overline{v_i v_j}) - \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) =$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{n}}{\partial x_i} = \frac{1}{V} \frac{\partial}{\partial x_i} \int_V n dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V n dV \right) = \frac{\partial \bar{n}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\overline{v_i v_j}) + \mathcal{O}((\Delta x)^2)$$

$$\text{Left side : } \frac{\partial}{\partial x_j} (\overline{v_i v_j}) - \frac{\partial}{\partial x_j} (\overline{v_i v_j}) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j)$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{1}{\rho} \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) = \frac{\partial}{\partial x_i} \left(\frac{1}{\rho} \frac{1}{V} \int_V p dV \right) = \frac{\partial \bar{p}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \mathcal{O}((\Delta x)^2)$$

$$\text{Left side : } \frac{\partial}{\partial x_j} (\overline{v_i v_j}) - \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j)$$

Right side :

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{p}}{\partial x_i} = -\frac{1}{\rho} \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) = -\frac{1}{\rho} \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) = -\frac{\partial \bar{p}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \mathcal{O}((\Delta x)^2)$$

$$\text{Left side : } \frac{\partial}{\partial x_j} (\overline{v_i v_j}) - \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j)$$

$$\text{Right side : } \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) =$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{p}}{\partial x_i} = -\frac{1}{\rho} \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) = -\frac{1}{\rho} \left(\frac{1}{V} \int_V \frac{\partial p}{\partial x_i} dV \right) = -\frac{\partial \bar{p}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \mathcal{O}((\Delta x)^2)$$

$$\text{Left side : } \frac{\partial}{\partial x_j} (\overline{v_i v_j}) - \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j)$$

$$\text{Right side : } -\frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{\partial \tau_{ij}}{\partial x_j}$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{m}}{\partial x_i} = \frac{1}{V} \frac{\partial}{\partial x_i} \int_V m dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V m dV \right) = \frac{\partial \bar{m}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \mathcal{O}((\Delta x)^2)$$

$$\text{Left side : } \frac{\partial}{\partial x_j} (\overline{v_i v_j}) - \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j)$$

$$\text{Right side : } \underbrace{-\frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j)} = -\frac{\partial \tau_{ij}}{\partial x_j}$$

$$\text{► } \frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) =$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{m}}{\partial x_i} = \frac{1}{V} \frac{\partial}{\partial x_i} \int_V m dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V m dV \right) = \frac{\partial \bar{m}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\overline{v_i v_j}) + \mathcal{O}((\Delta x)^2)$$

$$\text{Left side : } \frac{\partial}{\partial x_j} (\overline{v_i v_j}) - \frac{\partial}{\partial x_j} (\overline{v_i v_j}) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j)$$

$$\text{Right side : } -\frac{\partial}{\partial x_j} (\overline{v_i v_j}) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{\partial \tau_{ij}}{\partial x_j}$$

$$\text{► } \frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{m}}{\partial x_i} = \frac{1}{V} \int_V \frac{\partial m}{\partial x_i} dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V m dV \right) = \frac{\partial \bar{m}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \mathcal{O}((\Delta x)^2)$$

$$\text{Left side : } \frac{\partial}{\partial x_j} (\overline{v_i v_j}) - \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j)$$

$$\text{Right side : } -\frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{\partial \tau_{ij}}{\partial x_j}$$

$$\text{► } \frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j$$

Momentum equations in LES:

$$\frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad (36.3)$$

► Filter pressure gradient in Eq. 36.1

$$\frac{\partial \bar{m}}{\partial x_i} = \frac{1}{V} \int_V \frac{\partial m}{\partial x_i} dV = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V m dV \right) = \frac{\partial \bar{m}}{\partial x_i}$$

$$\frac{\partial \bar{p}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\frac{1}{V} \int_V p dV \right) + \mathcal{O}((\Delta x)^2) = \frac{\partial \bar{p}}{\partial x_i} + \mathcal{O}((\Delta x)^2)$$

► Filter non-linear term in Eq. 36.1

$$\frac{\partial \overline{v_i v_j}}{\partial x_j} = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \mathcal{O}((\Delta x)^2)$$

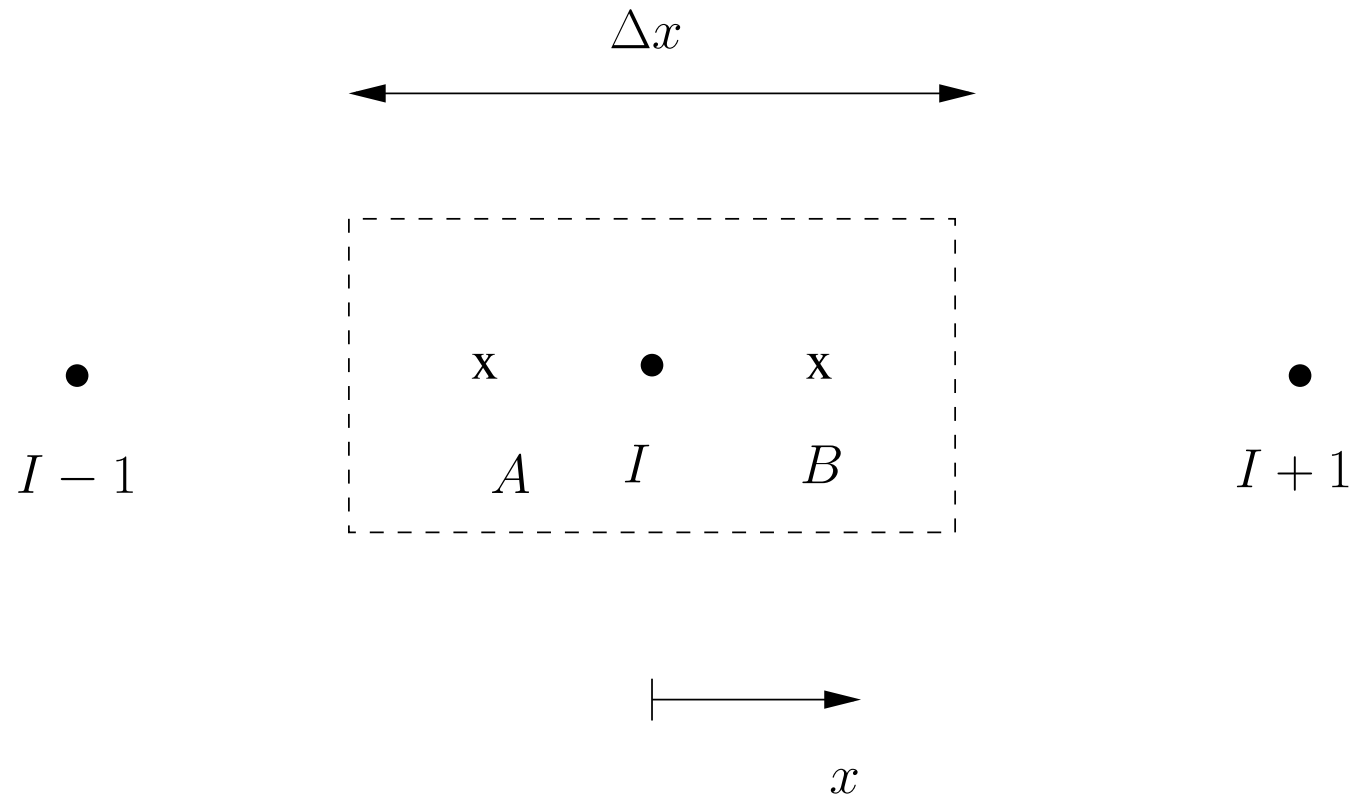
$$\text{Left side : } \frac{\partial}{\partial x_j} (\overline{v_i v_j}) - \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j)$$

$$\text{Right side : } -\frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{\partial \tau_{ij}}{\partial x_j}$$

$$\text{► } \frac{\partial \bar{v}_i}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_i \bar{v}_j) = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \nu \frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}, \quad \tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j$$

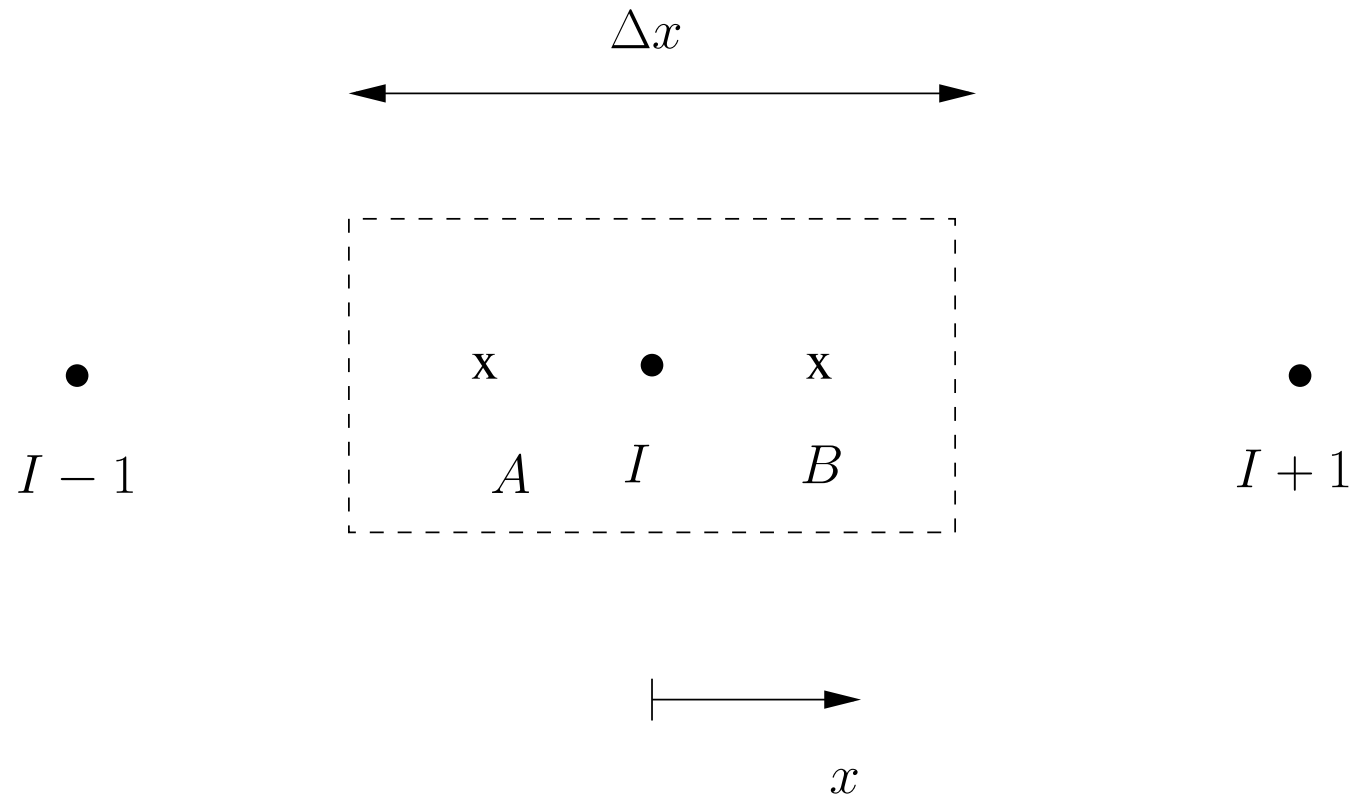
► Filtering twice (used for turbulence modeling)

► Filtering twice (used for turbulence modeling)



Control volume (dashed lines). $\bar{\bar{v}}_I \neq \bar{v}_I$

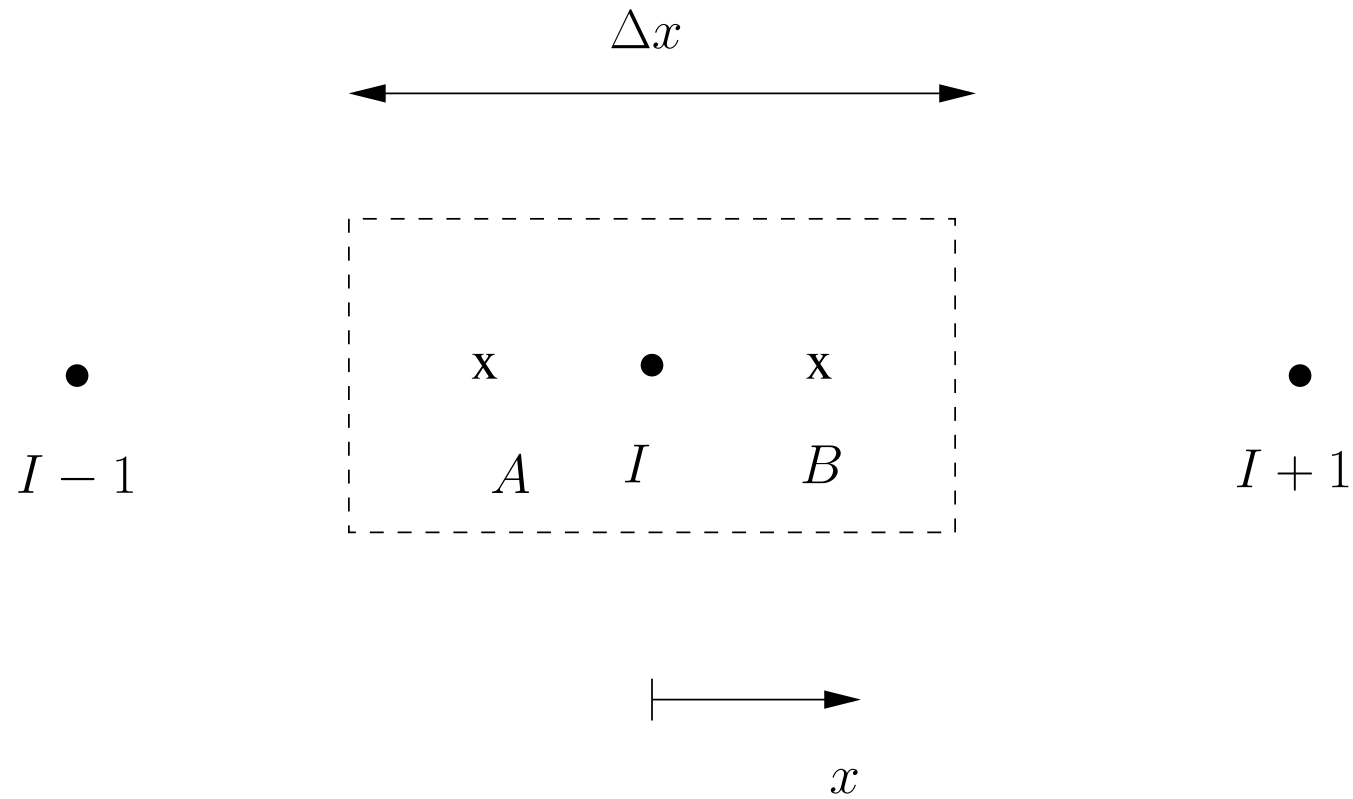
► Filtering twice (used for turbulence modeling)



Control volume (dashed lines). $\overline{\overline{v}}_I \neq \overline{v}_I$

$$\overline{\overline{v}}_I =$$

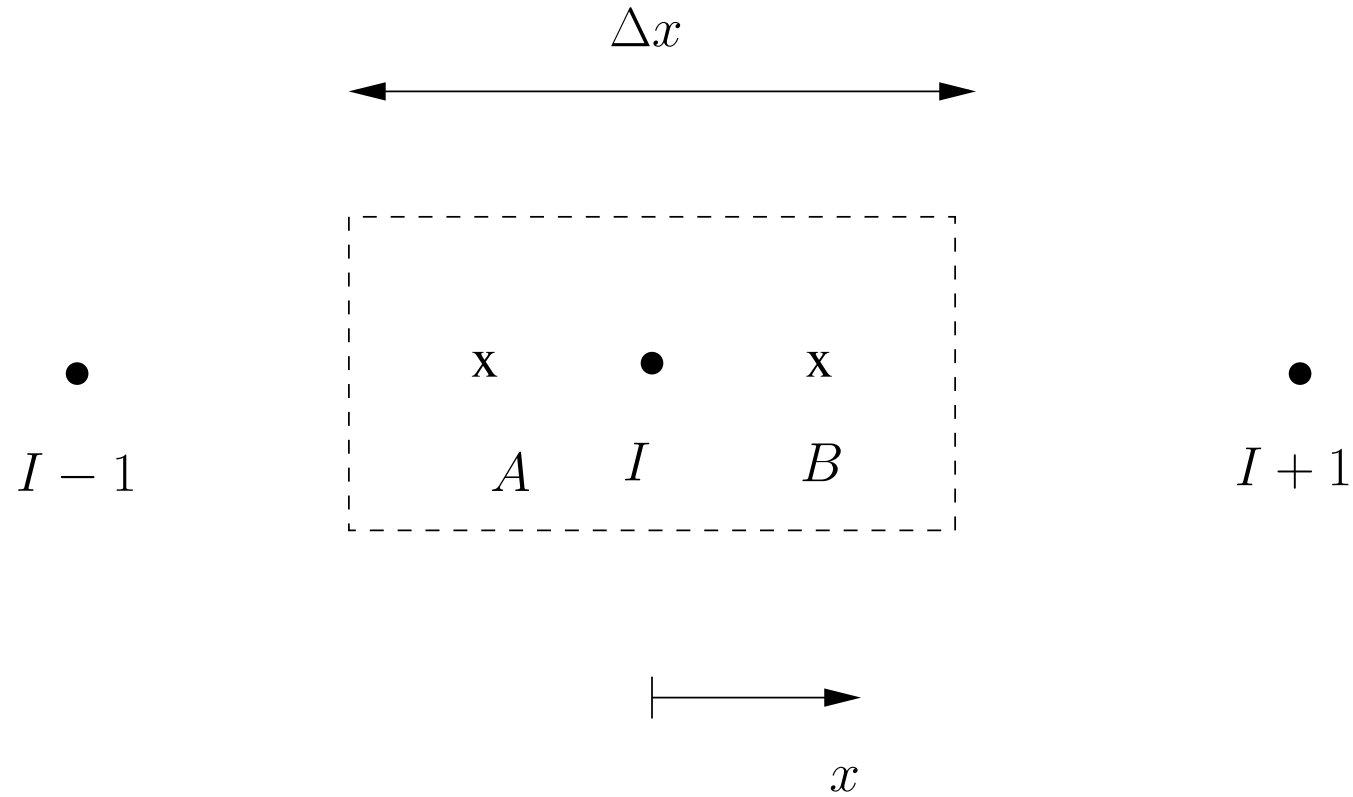
► Filtering twice (used for turbulence modeling)



Control volume (dashed lines). $\bar{\bar{v}}_I \neq \bar{v}_I$

$$\bar{\bar{v}}_I = \frac{1}{\Delta x} \int_{-\Delta x/2}^{\Delta x/2} \bar{v}(\xi) d\xi =$$

► Filtering twice (used for turbulence modeling)

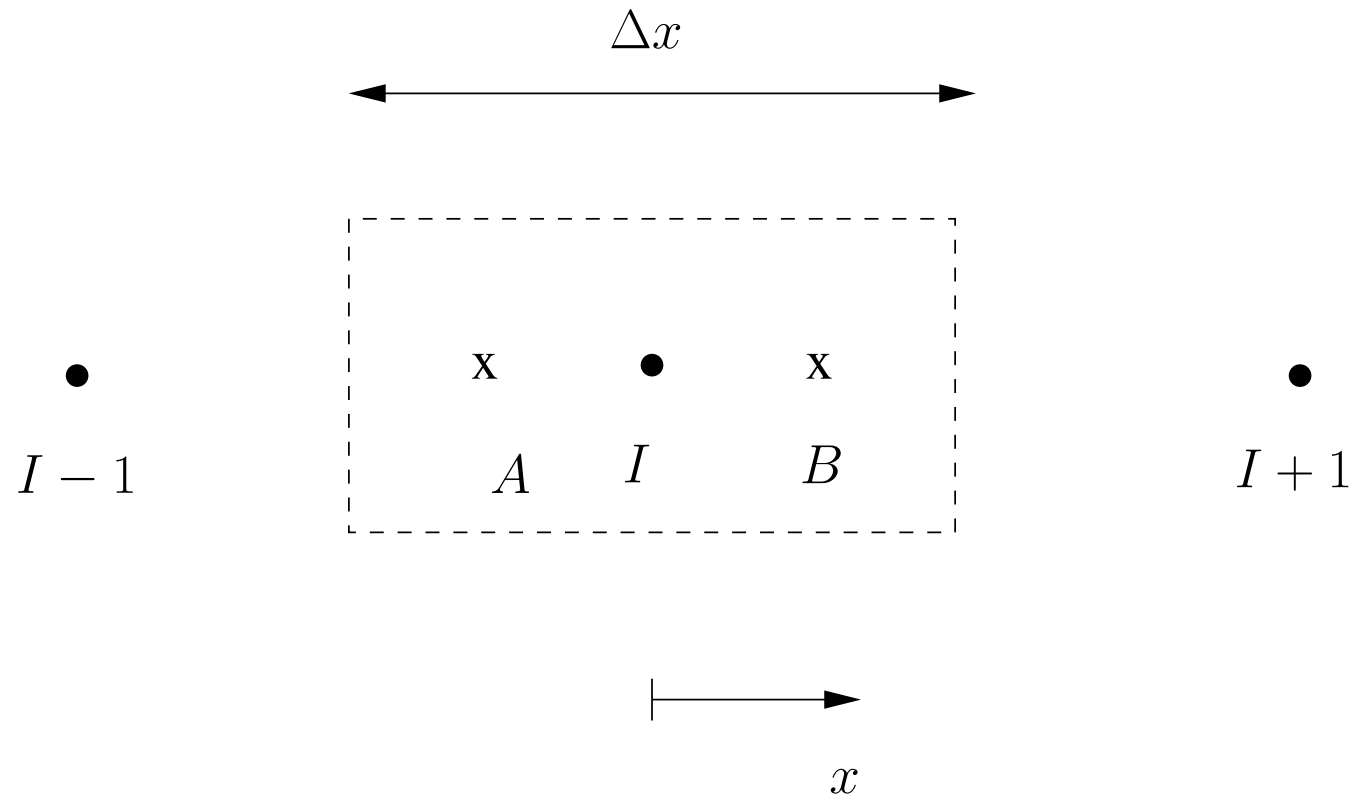


Control volume (dashed lines). $\bar{\bar{v}}_I \neq \bar{v}_I$

$$\bar{\bar{v}}_I = \frac{1}{\Delta x} \int_{-\Delta x/2}^{\Delta x/2} \bar{v}(\xi) d\xi = \frac{1}{\Delta x} \left(\int_{-\Delta x/2}^0 \bar{v}(\xi) d\xi + \int_0^{\Delta x/2} \bar{v}(\xi) d\xi \right) =$$

$$=$$

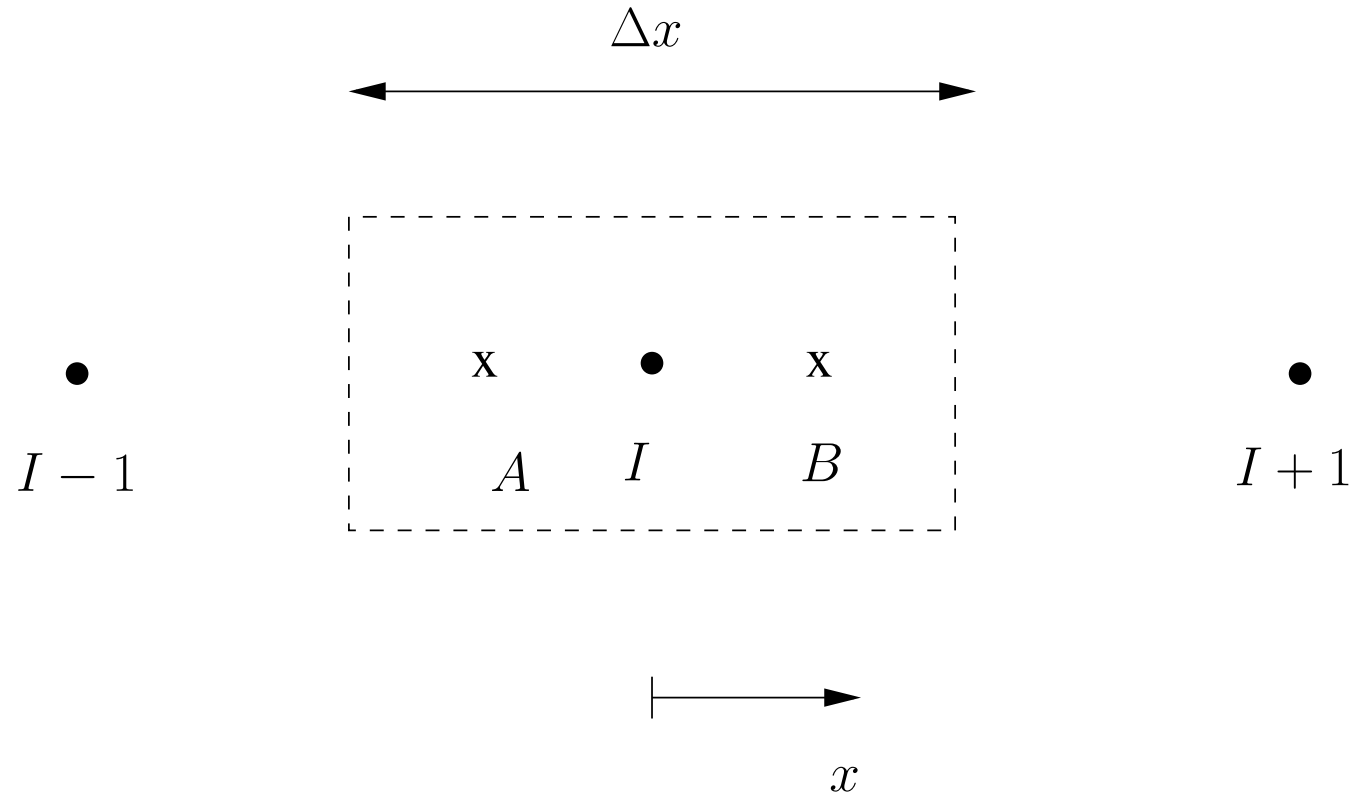
► Filtering twice (used for turbulence modeling)



Control volume (dashed lines). $\bar{\bar{v}}_I \neq \bar{v}_I$

$$\begin{aligned}
 \bar{\bar{v}}_I &= \frac{1}{\Delta x} \int_{-\Delta x/2}^{\Delta x/2} \bar{v}(\xi) d\xi = \frac{1}{\Delta x} \left(\int_{-\Delta x/2}^0 \bar{v}(\xi) d\xi + \int_0^{\Delta x/2} \bar{v}(\xi) d\xi \right) = \\
 &= \frac{1}{\Delta x} \left(\frac{\Delta x}{2} \bar{v}_A + \frac{\Delta x}{2} \bar{v}_B \right) =
 \end{aligned}$$

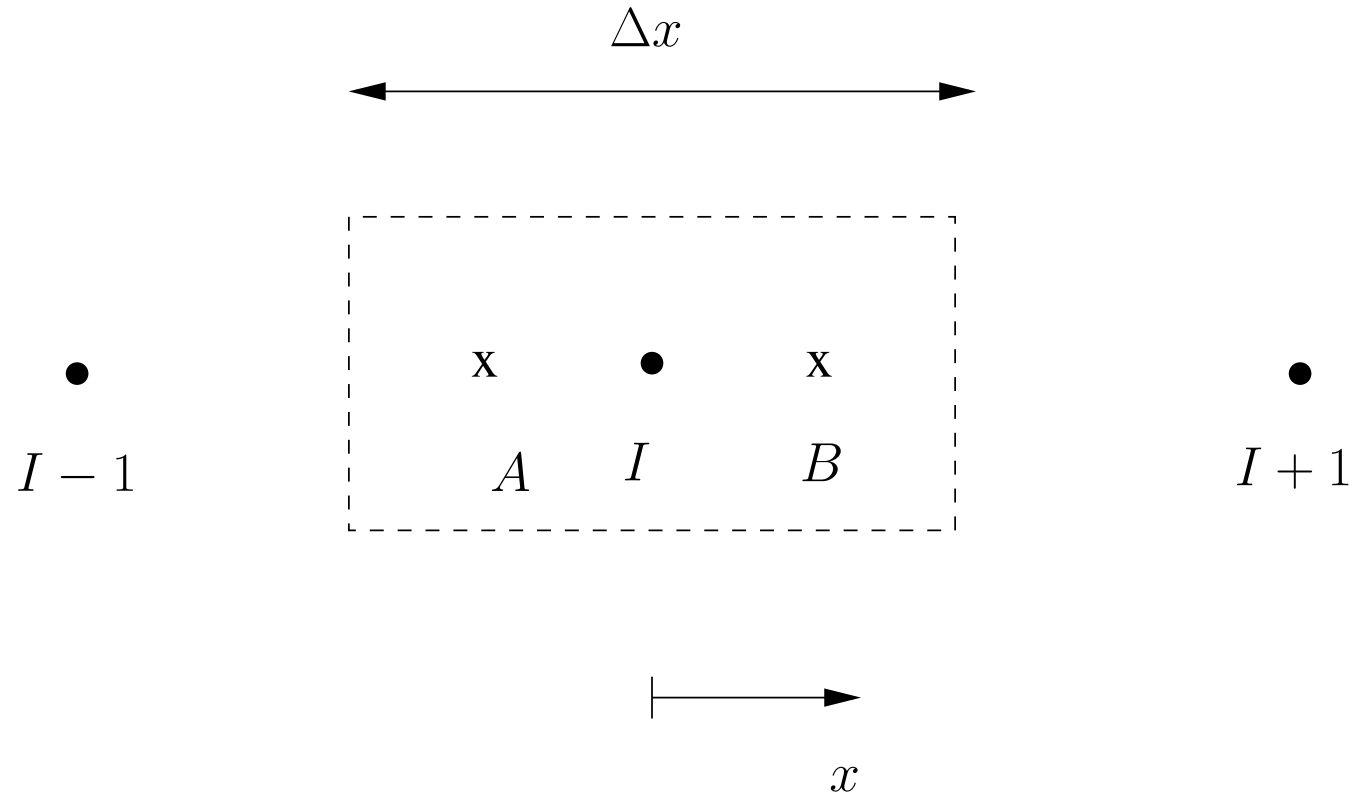
► Filtering twice (used for turbulence modeling)



Control volume (dashed lines). $\bar{\bar{v}}_I \neq \bar{v}_I$

$$\begin{aligned} \bar{\bar{v}}_I &= \frac{1}{\Delta x} \int_{-\Delta x/2}^{\Delta x/2} \bar{v}(\xi) d\xi = \frac{1}{\Delta x} \left(\int_{-\Delta x/2}^0 \bar{v}(\xi) d\xi + \int_0^{\Delta x/2} \bar{v}(\xi) d\xi \right) = \\ &= \frac{1}{\Delta x} \left(\frac{\Delta x}{2} \bar{v}_A + \frac{\Delta x}{2} \bar{v}_B \right) = \frac{1}{2} \left[\left(\frac{1}{4} \bar{v}_{I-1} + \frac{3}{4} \bar{v}_I \right) + \left(\frac{3}{4} \bar{v}_I + \frac{1}{4} \bar{v}_{I+1} \right) \right] = \end{aligned}$$

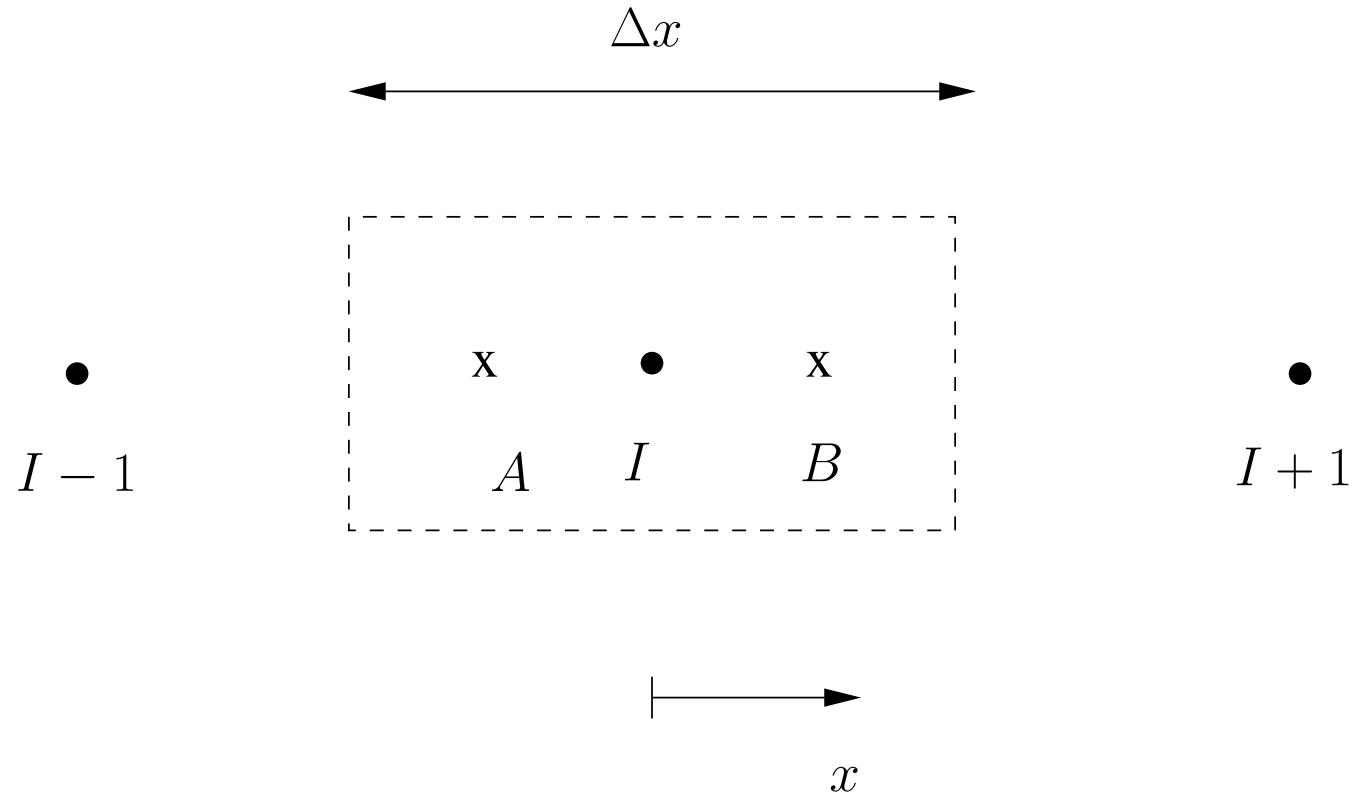
► Filtering twice (used for turbulence modeling)



Control volume (dashed lines). $\bar{\bar{v}}_I \neq \bar{v}_I$

$$\begin{aligned} \bar{\bar{v}}_I &= \frac{1}{\Delta x} \int_{-\Delta x/2}^{\Delta x/2} \bar{v}(\xi) d\xi = \frac{1}{\Delta x} \left(\int_{-\Delta x/2}^0 \bar{v}(\xi) d\xi + \int_0^{\Delta x/2} \bar{v}(\xi) d\xi \right) = \\ &= \frac{1}{\Delta x} \left(\frac{\Delta x}{2} \bar{v}_A + \frac{\Delta x}{2} \bar{v}_B \right) = \frac{1}{2} \left[\left(\frac{1}{4} \bar{v}_{I-1} + \frac{3}{4} \bar{v}_I \right) + \left(\frac{3}{4} \bar{v}_I + \frac{1}{4} \bar{v}_{I+1} \right) \right] = \frac{1}{8} (\bar{v}_{I-1} + 6\bar{v}_I + \bar{v}_{I+1}) \end{aligned}$$

► Filtering twice (used for turbulence modeling)

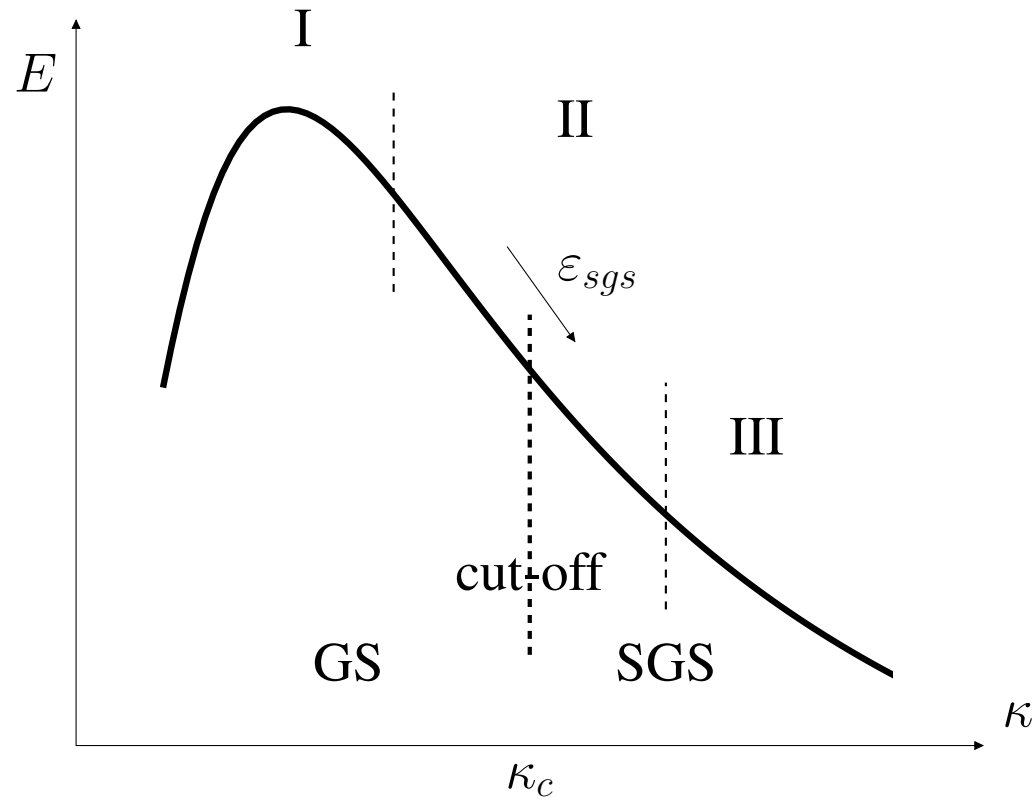


Control volume (dashed lines). $\bar{\bar{v}}_I \neq \bar{v}_I$

$$\begin{aligned}
 \bar{\bar{v}}_I &= \frac{1}{\Delta x} \int_{-\Delta x/2}^{\Delta x/2} \bar{v}(\xi) d\xi = \frac{1}{\Delta x} \left(\int_{-\Delta x/2}^0 \bar{v}(\xi) d\xi + \int_0^{\Delta x/2} \bar{v}(\xi) d\xi \right) = \\
 &= \frac{1}{\Delta x} \left(\frac{\Delta x}{2} \bar{v}_A + \frac{\Delta x}{2} \bar{v}_B \right) = \frac{1}{2} \left[\left(\frac{1}{4} \bar{v}_{I-1} + \frac{3}{4} \bar{v}_I \right) + \left(\frac{3}{4} \bar{v}_I + \frac{1}{4} \bar{v}_{I+1} \right) \right] = \frac{1}{8} (\bar{v}_{I-1} + 6\bar{v}_I + \bar{v}_{I+1}) \neq \bar{v}_I
 \end{aligned}$$

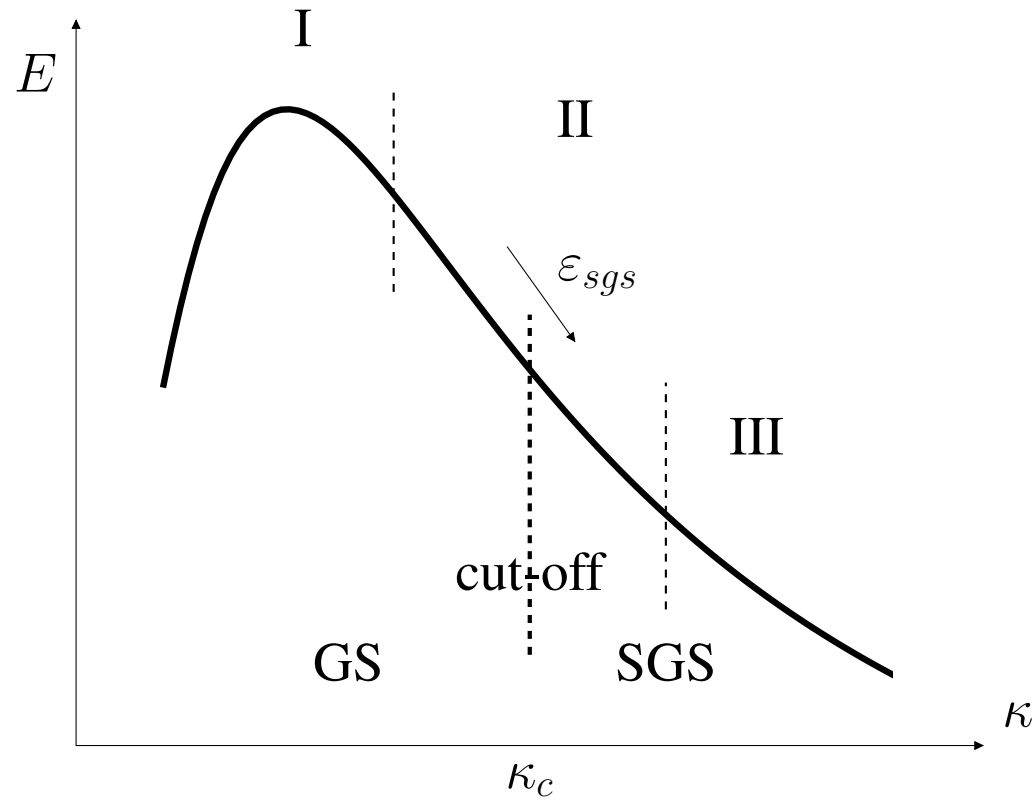
¶ See Section 18.3, Resolved & SGS scales (GS & SGS)

See Section 18.3, Resolved & SGS scales (GS & SGS)



$\kappa \leq \kappa_c$: Grid (=resolved) Scales; $\kappa > \kappa_c$ = Sub-Grid Scales

See Section 18.3, Resolved & SGS scales (GS & SGS)



$\kappa \leq \kappa_c$: Grid (=resolved) Scales; $\kappa > \kappa_c$ = Sub-Grid Scales

¶ See Section 18.5, [Highest resolved wavenumbers](#)

▶ A Fourier series (see [Appendix H](#))

¶ See Section 18.5, Highest resolved wavenumbers

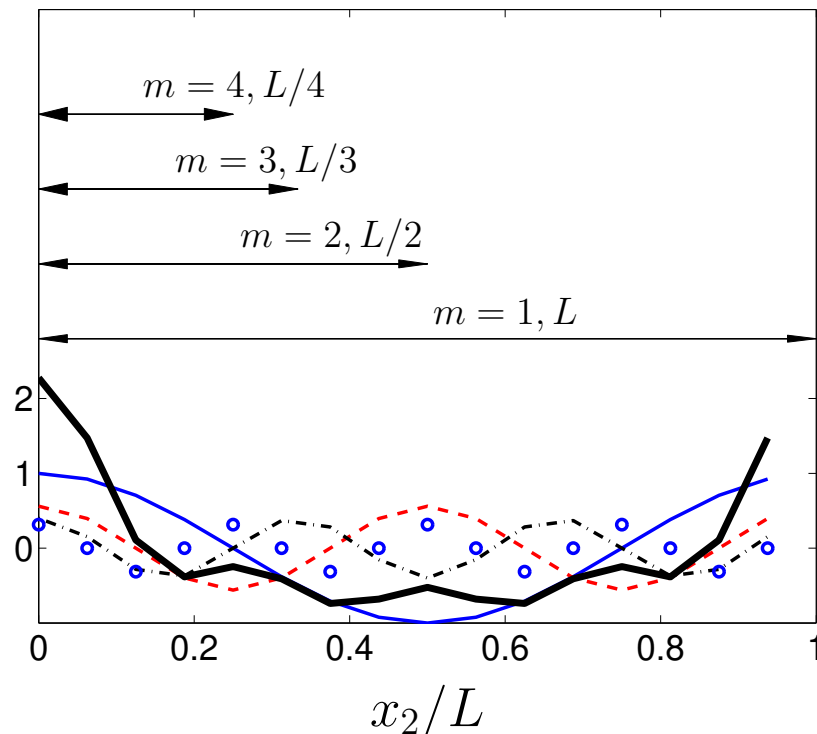
▶ A Fourier series (see Appendix H)

$$v_1'(x) = \sum_{n=-\infty}^{\infty} c_n \exp(i\kappa_n x_1)$$

¶ See Section 18.5, Highest resolved wavenumbers

► A Fourier series (see Appendix H)

$$v_1'(x) = \sum_{n=-\infty}^{\infty} c_n \exp(i\kappa_n x_1) \quad \text{only symmetric part, i.e. real}$$

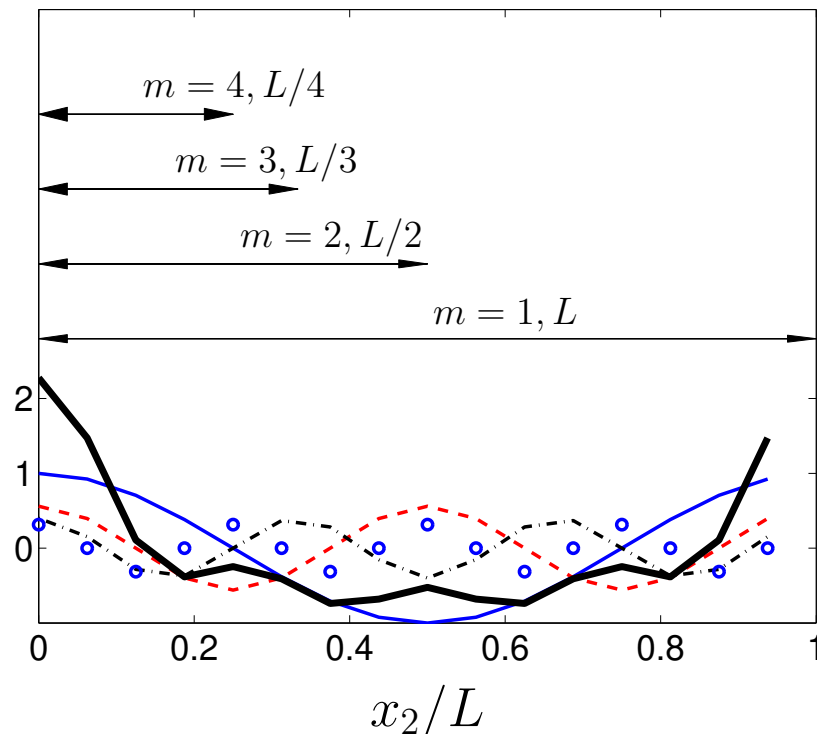


v_2' vs. x_2/L . —: term 1 ($m = 1$); - -: term 2 ($m = 2$); ···: term 3 ($m = 3$); ○: term 4 ($m = 4$); —: v_2'
Matlab code is given in Section I.3.

¶ See Section 18.5, Highest resolved wavenumbers

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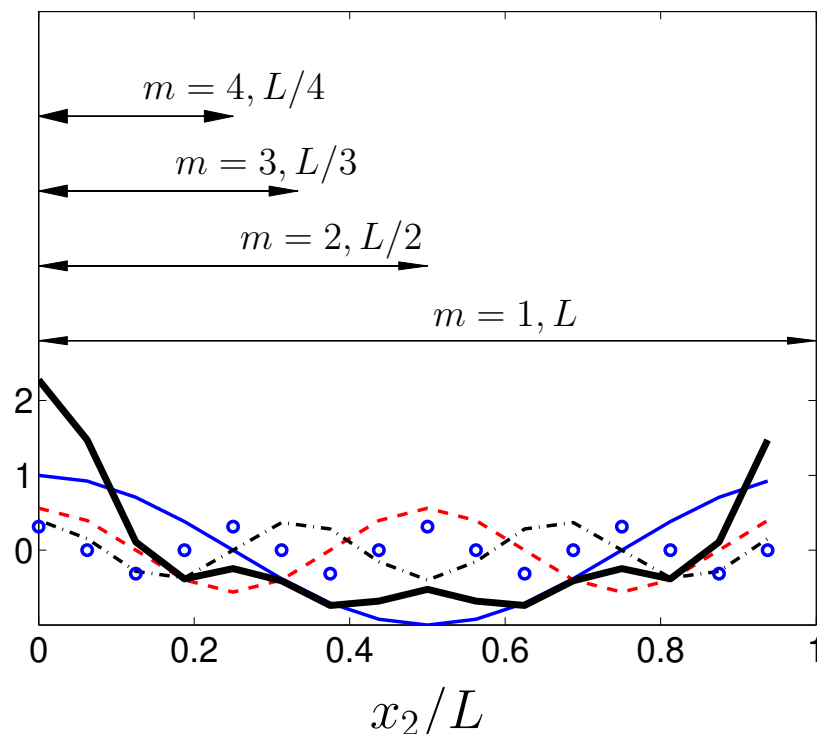
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Matlab code is given in Section I.3.

► We construct v_2' as a sum of four Fourier components

See Section 18.5, Highest resolved wavenumbers

► A Fourier series (see Appendix H)

$$v_1'(x) = \sum_{n=-\infty}^{\infty} c_n \exp(i\kappa_n x_1) \quad \text{only symmetric part, i.e. real}$$



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Matlab code is given in Section I.3.

► We construct v_2' as a sum of four Fourier components

$$v_2'(x_2) = b_1 \cos\left(\frac{2\pi}{L/1}x_2\right) + b_2 \cos\left(\frac{2\pi}{L/2}x_2\right) + b_3 \cos\left(\frac{2\pi}{L/3}x_2\right) + b_4 \cos\left(\frac{2\pi}{L/4}x_2\right)$$

▶ On the previous slide, we showed a couple of different wave number (Fourier) modes.

$$v'_1 = \sin(\kappa_c x_1)$$

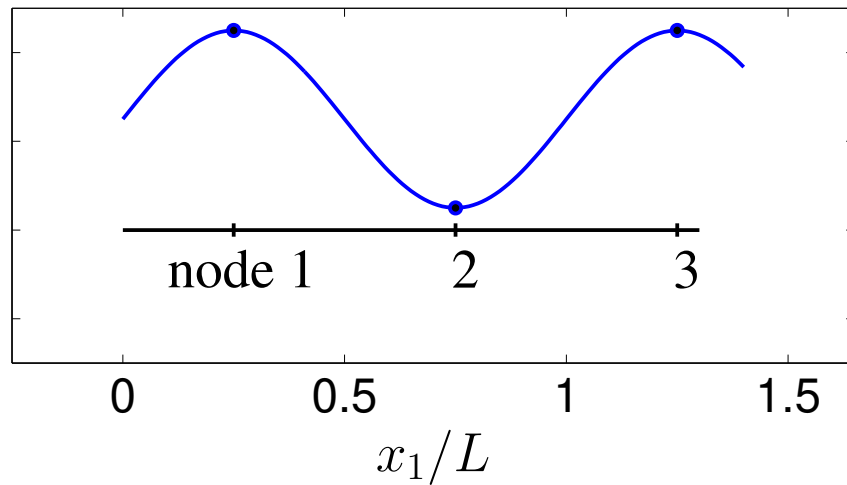
▶ How large wave numbers (i.e. how short wavelengths) can we resolve in an LES?

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► How large wave numbers (i.e. how short wavelengths) can we resolve in an LES?

One period=two cells

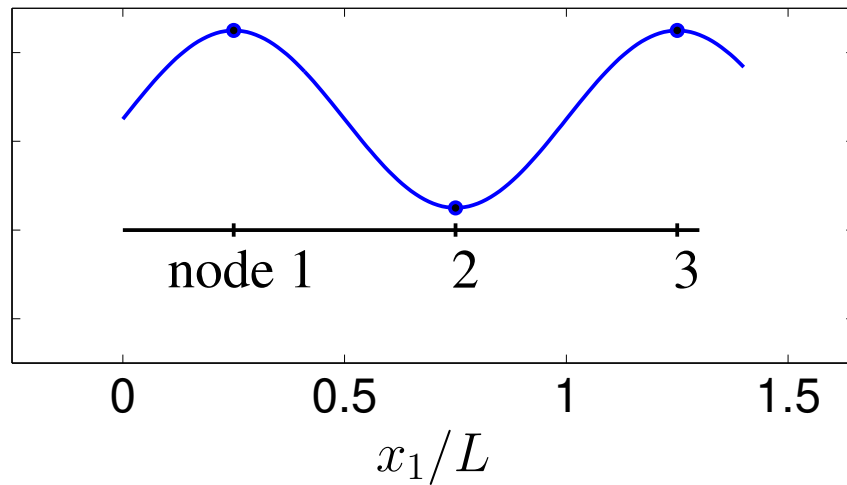


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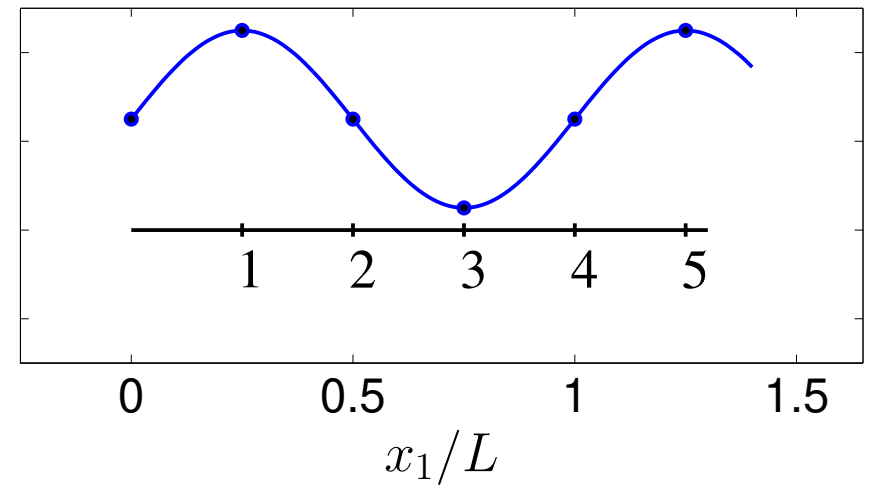
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One period=four cells

v'_1

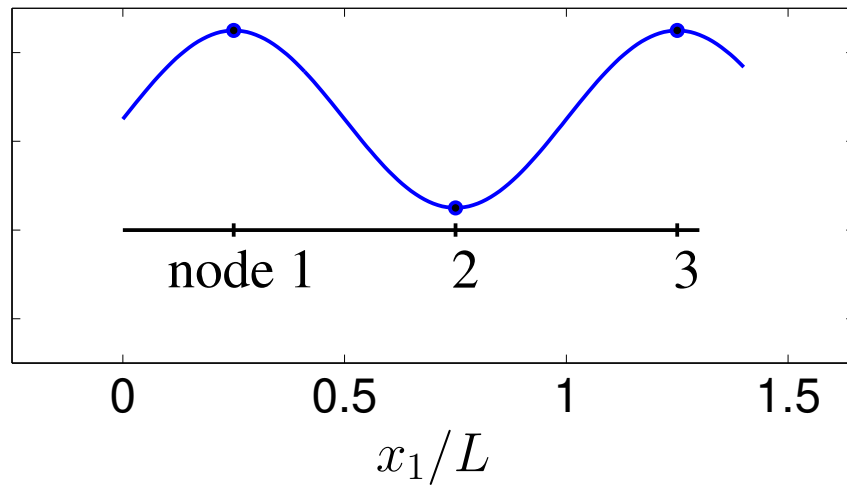


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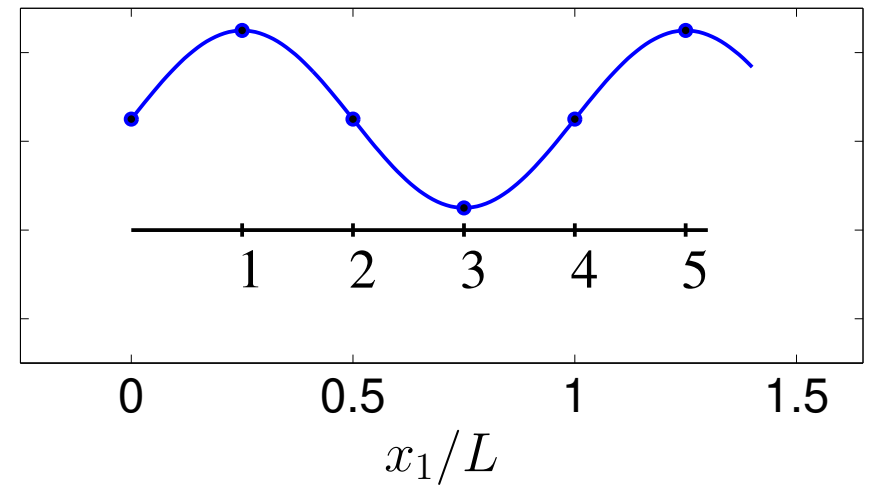
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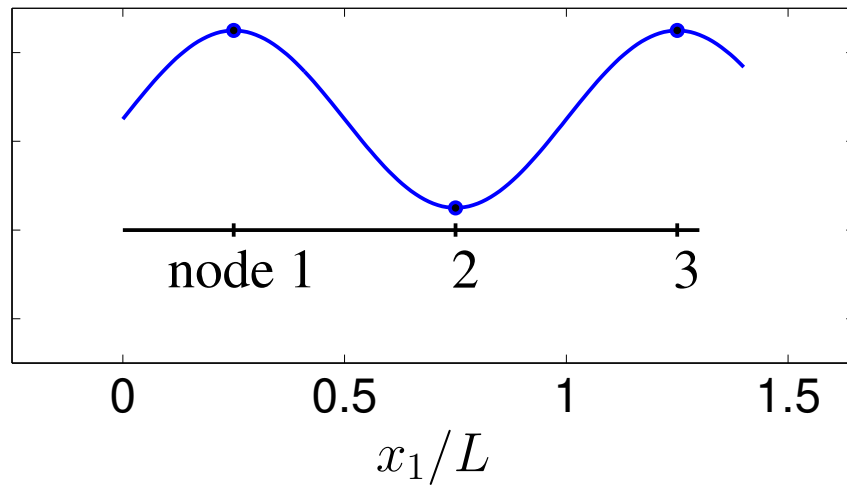
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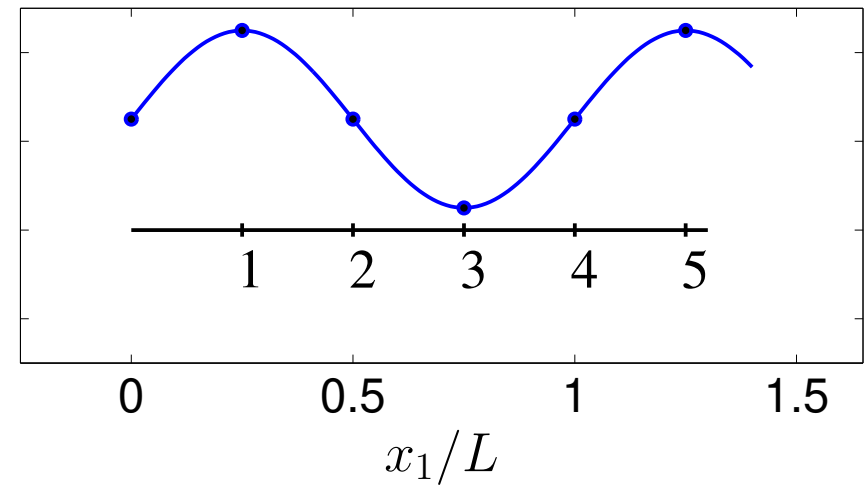
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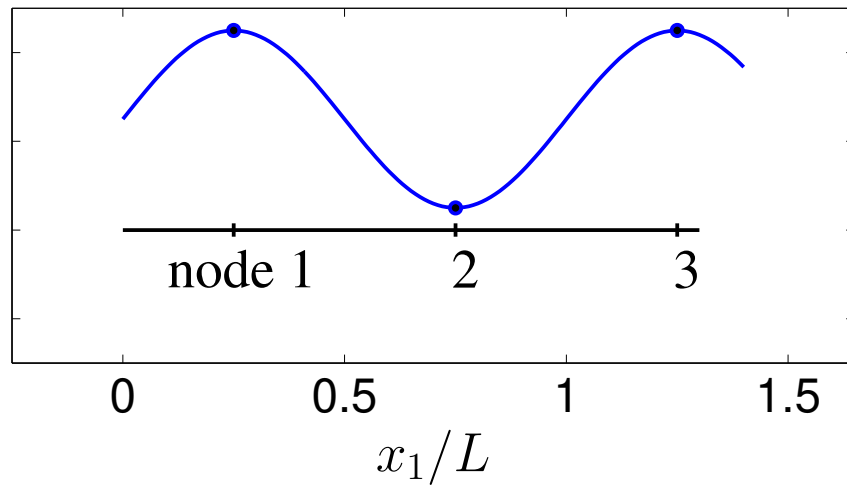
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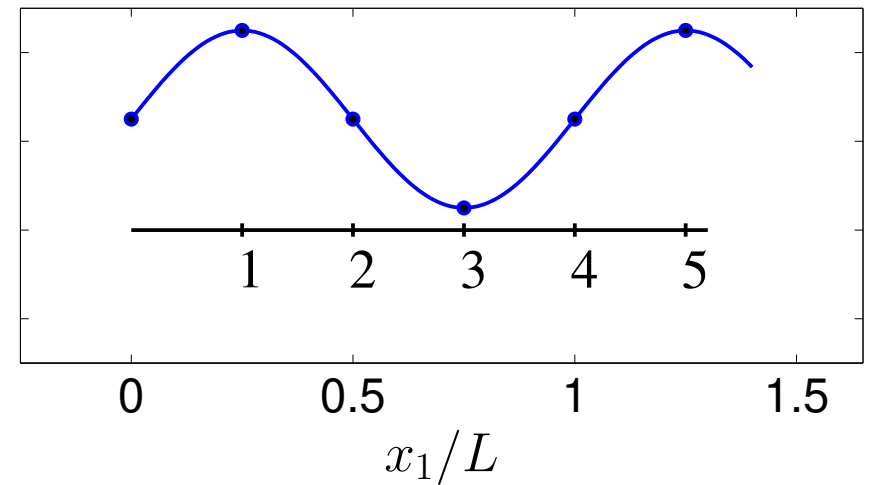
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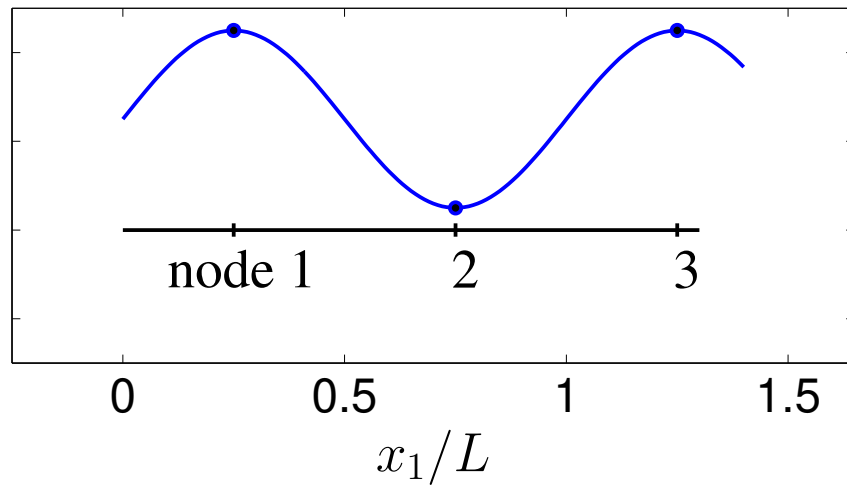
two cells : $\kappa_c 2\Delta x_1 = 2\pi$

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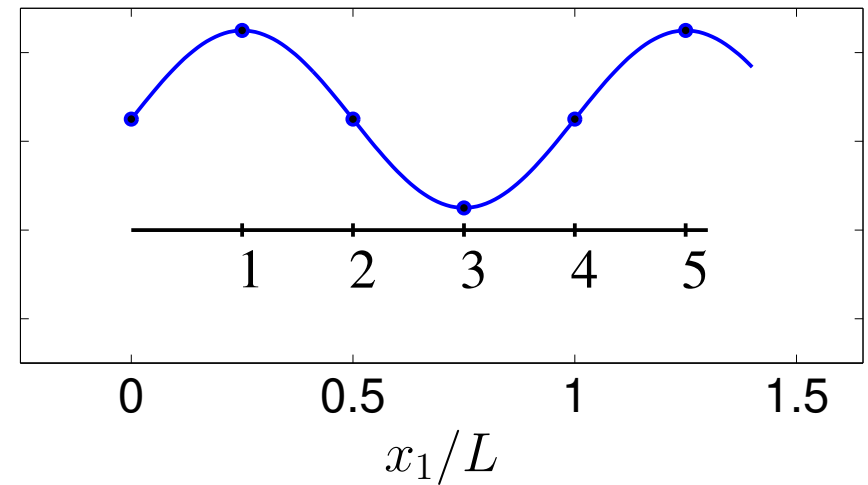
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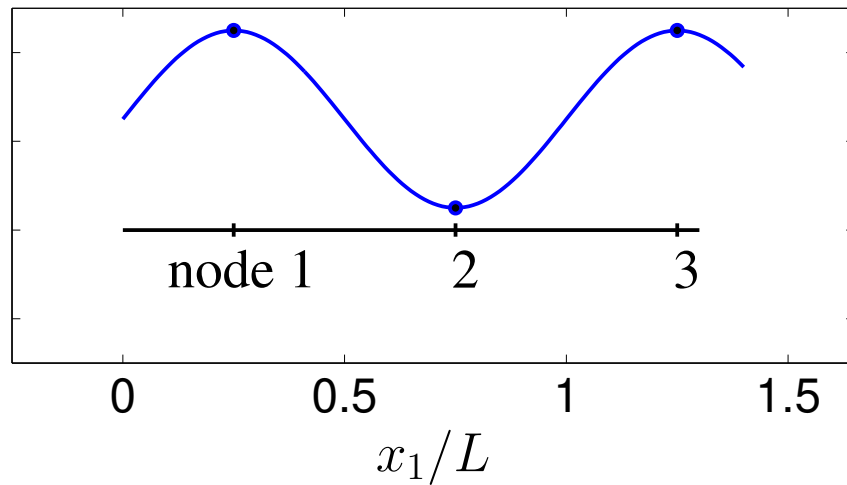
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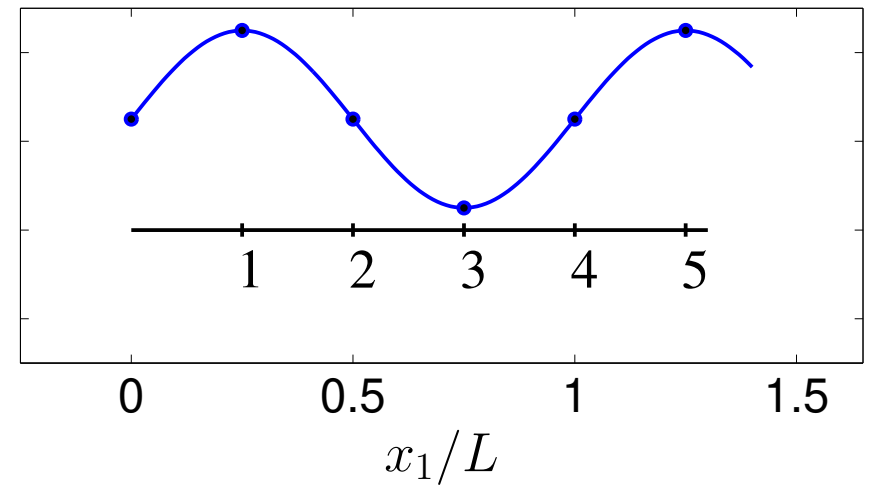
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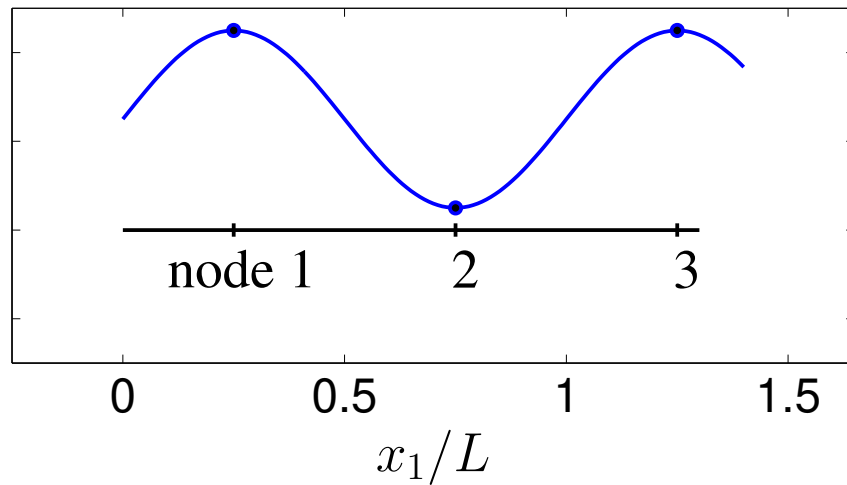
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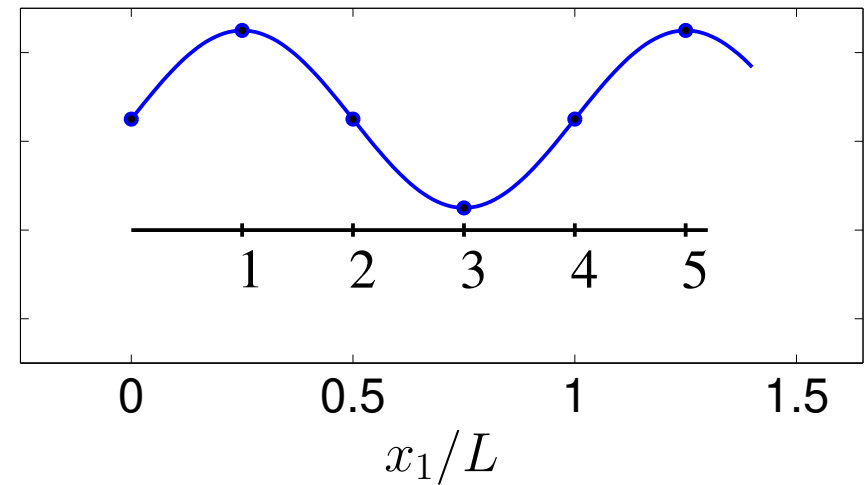
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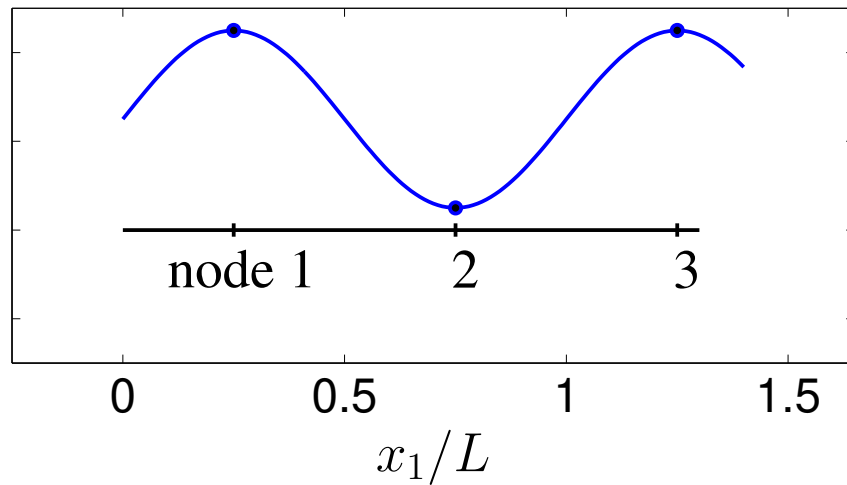
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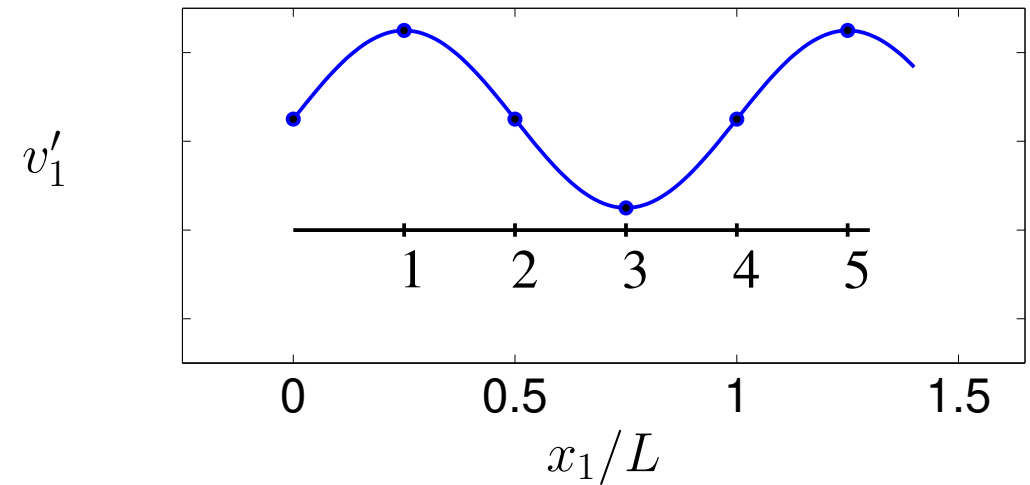
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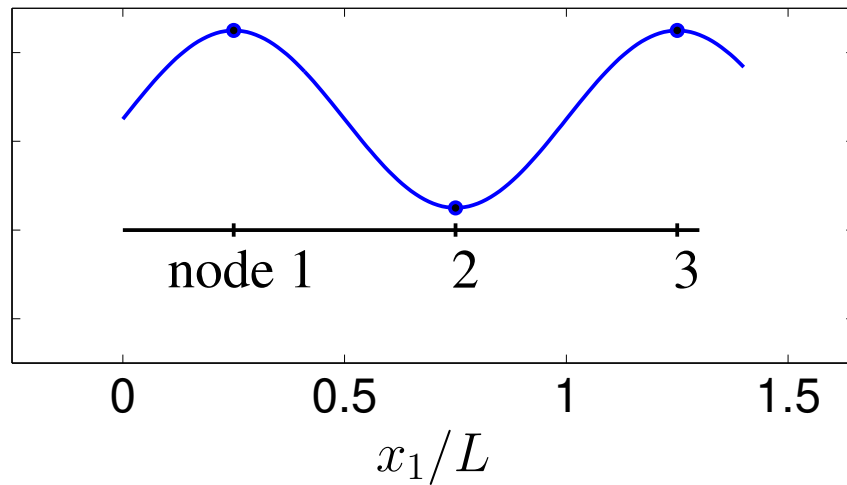
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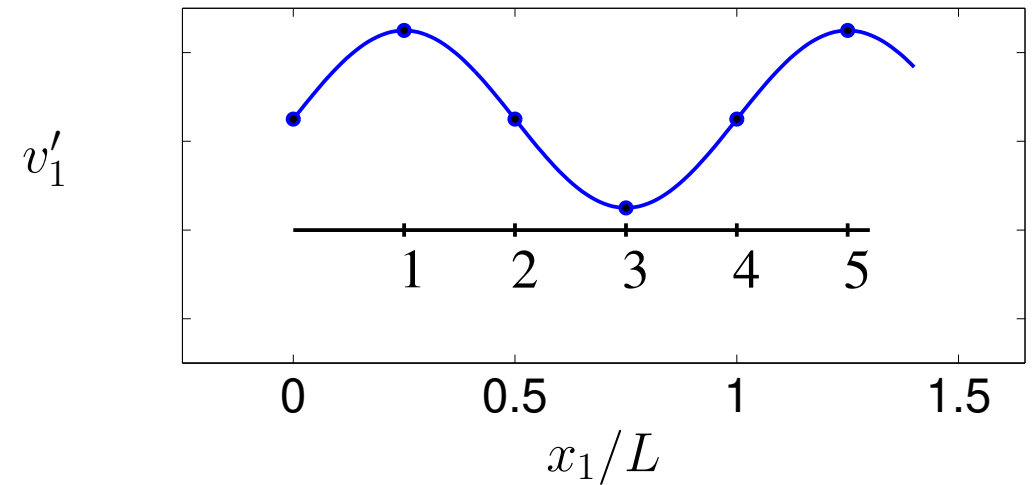
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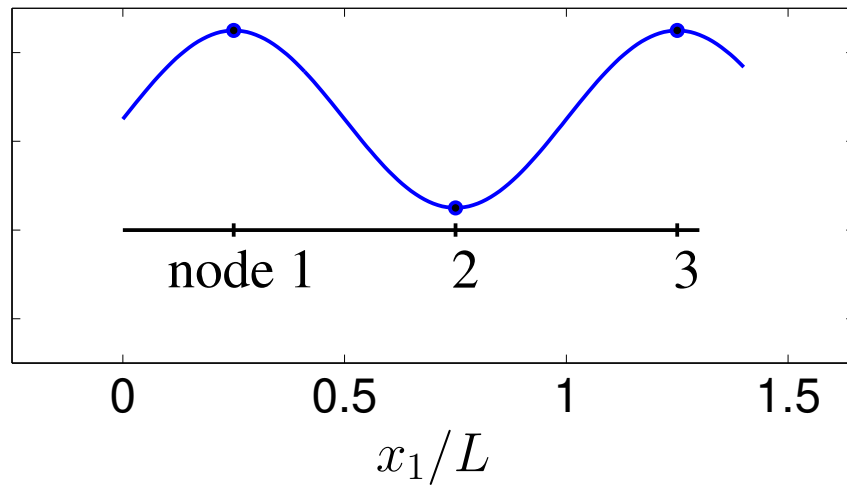
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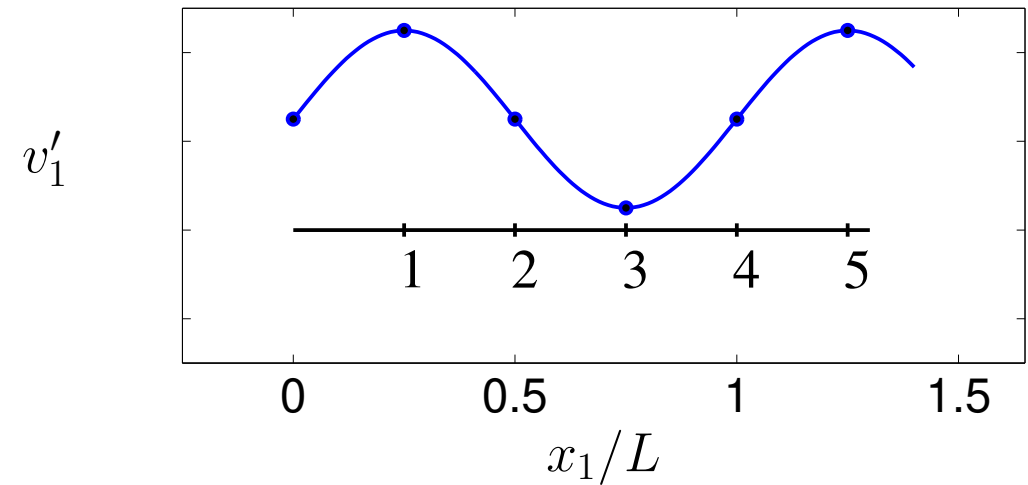
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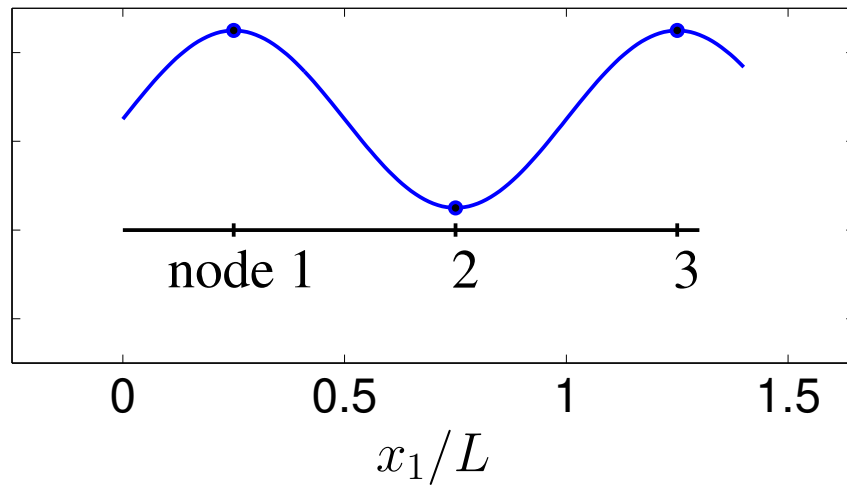
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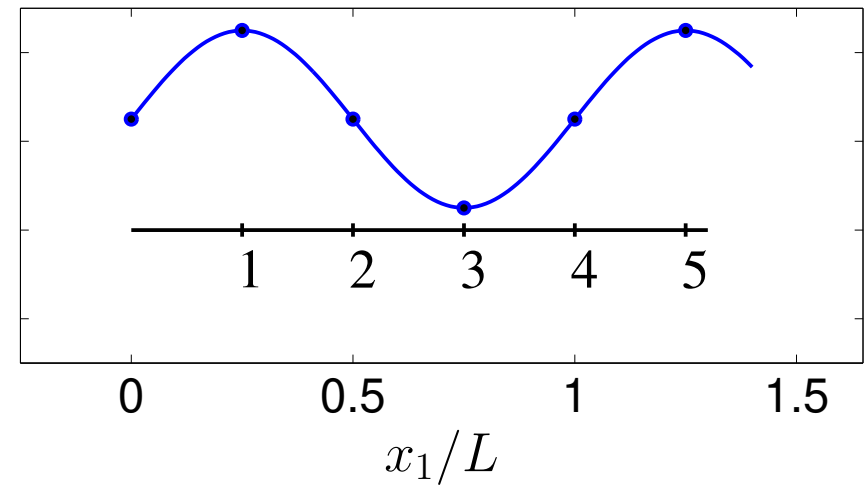
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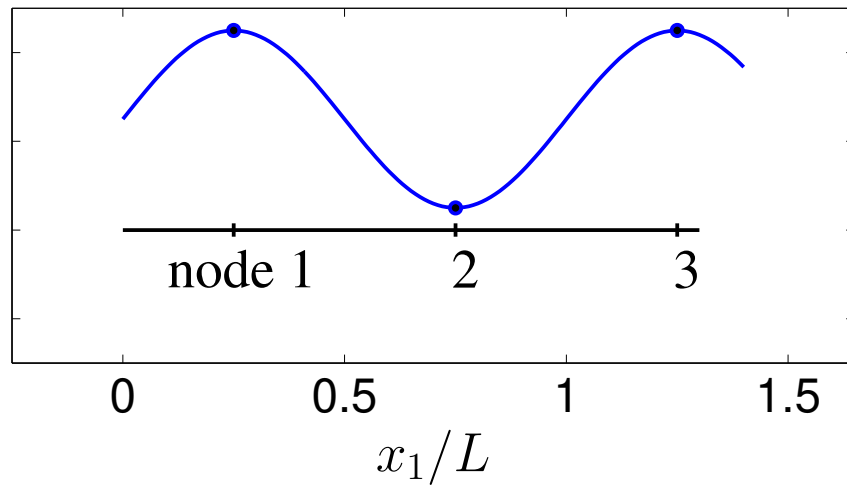
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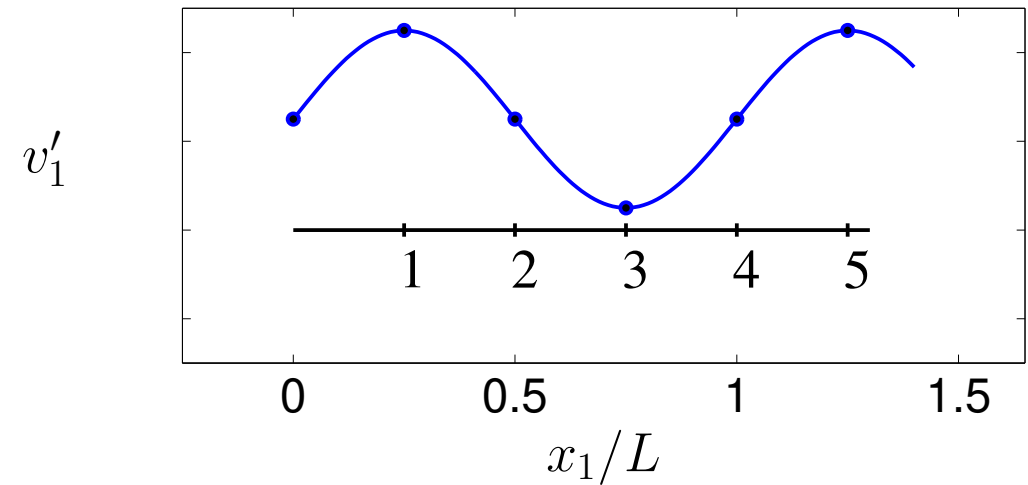
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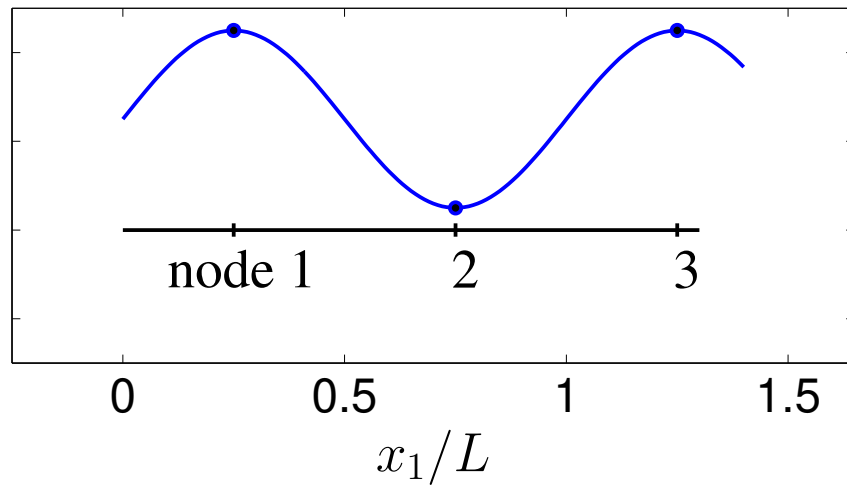
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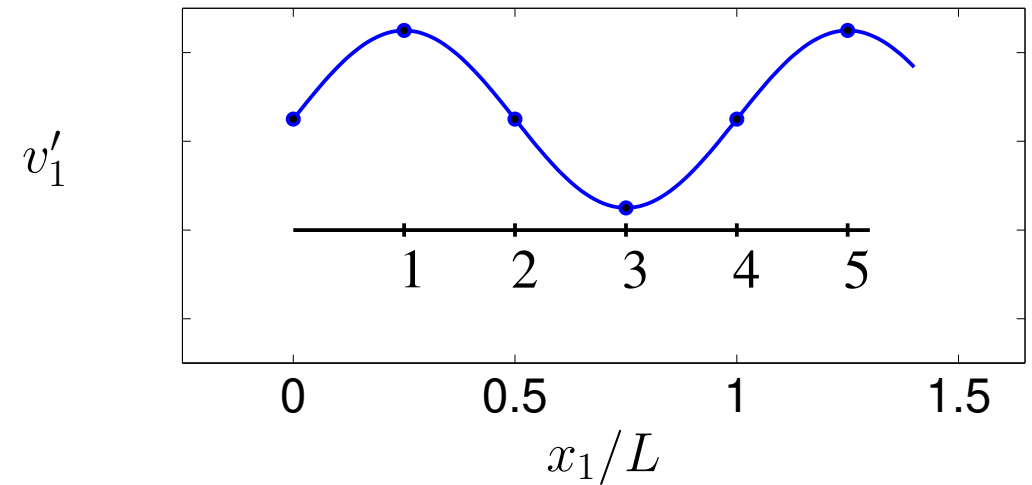
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▶ See Section 18.6, [Subgrid model](#)

▶ Smagorinsky Subgrid model

¶ See Section 18.6, Subgrid model

▶ Smagorinsky Subgrid model

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} =$$

¶ See Section 18.6, Subgrid model

► Smagorinsky Subgrid model

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -\nu_{sgs} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) =$$

¶ See Section 18.6, Subgrid model

► Smagorinsky Subgrid model

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -\nu_{sgs} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) = -2\nu_{sgs}\bar{S}_{ij}$$

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$$\nu_{sgs} \propto$$

¶ See Section 18.6, Subgrid model

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$$\nu_{sgs} \propto v'\ell \propto \left(\Delta x_1 \frac{\partial \bar{v}_1}{\partial x_1} \right) \Delta x_1 \propto$$

¶ See Section 18.6, Subgrid model

► Smagorinsky Subgrid model

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -\nu_{sgs} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) = -2\nu_{sgs}\bar{s}_{ij}$$

$$\nu_{sgs} \propto v'\ell \propto \left(\Delta x_1 \frac{\partial \bar{v}_1}{\partial x_1} \right) \Delta x_1 \propto \Delta x_1^2 \left(\frac{\partial \bar{v}_1}{\partial x_1} \right) \propto$$

¶ See Section 18.6, Subgrid model

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$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -\nu_{sgs} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) = -2\nu_{sgs}\bar{s}_{ij}$$

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$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -\nu_{sgs} \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) = -2\nu_{sgs}\bar{s}_{ij}$$

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$$\Delta = (\Delta V_{IJK})^{1/3}$$

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$$\Delta = (\Delta V_{IJK})^{1/3}$$

$|\bar{s}|$ stems from the production term in the k eq., $|\bar{s}^2| = 2\bar{s}_{ij}\bar{s}_{ij}$

¶ See Section 18.21, One-equation k_{sgs} model

See Section 18.21, One-equation k_{sgs} model

$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_{sgs}) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_{sgs}) \frac{\partial k_{sgs}}{\partial x_j} \right] + P_{k_{sgs}} - \varepsilon$$

See Section 18.21, One-equation k_{sgs} model

$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_{sgs}) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_{sgs}) \frac{\partial k_{sgs}}{\partial x_j} \right] + P_{k_{sgs}} - \varepsilon$$

ν_{sgs}

¶ See Section 18.21, One-equation k_{sgs} model

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$$\nu_{sgs} \propto l v' =$$

See Section 18.21, One-equation k_{sgs} model

$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_{sgs}) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_{sgs}) \frac{\partial k_{sgs}}{\partial x_j} \right] + P_{k_{sgs}} - \varepsilon$$

$$\nu_{sgs} \propto \ell v' = c_k \Delta k_{sgs}^{1/2}$$

See Section 18.21, One-equation k_{sgs} model

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$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_{sgs}) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_{sgs}) \frac{\partial k_{sgs}}{\partial x_j} \right] + P_{k_{sgs}} - \varepsilon$$

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$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_{sgs}) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_{sgs}) \frac{\partial k_{sgs}}{\partial x_j} \right] + P_{k_{sgs}} - \varepsilon$$

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$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial}{\partial x_j}(\bar{v}_j k_{sgs}) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_{sgs}) \frac{\partial k_{sgs}}{\partial x_j} \right] + P_{k_{sgs}} - \varepsilon$$

$$\nu_{sgs} \propto \ell v' = c_k \Delta k_{sgs}^{1/2}, \quad P_{k_{sgs}} = 2\nu_{sgs} \bar{s}_{ij} \bar{s}_{ij}, \quad \varepsilon \propto \frac{v'^3}{\ell} =$$

See Section 18.21, One-equation k_{sgs} model

$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_{sgs}) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_{sgs}) \frac{\partial k_{sgs}}{\partial x_j} \right] + P_{k_{sgs}} - \varepsilon$$

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¶ See Section 18.21, One-equation k_{sgs} model

$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_{sgs}) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_{sgs}) \frac{\partial k_{sgs}}{\partial x_j} \right] + P_{k_{sgs}} - \varepsilon$$
$$\nu_{sgs} \propto \ell v' = c_k \Delta k_{sgs}^{1/2}, \quad P_{k_{sgs}} = 2\nu_{sgs} \bar{s}_{ij} \bar{s}_{ij}, \quad \varepsilon \propto \frac{v'^3}{\ell} = C_\varepsilon \frac{k_{sgs}^{3/2}}{\Delta}$$

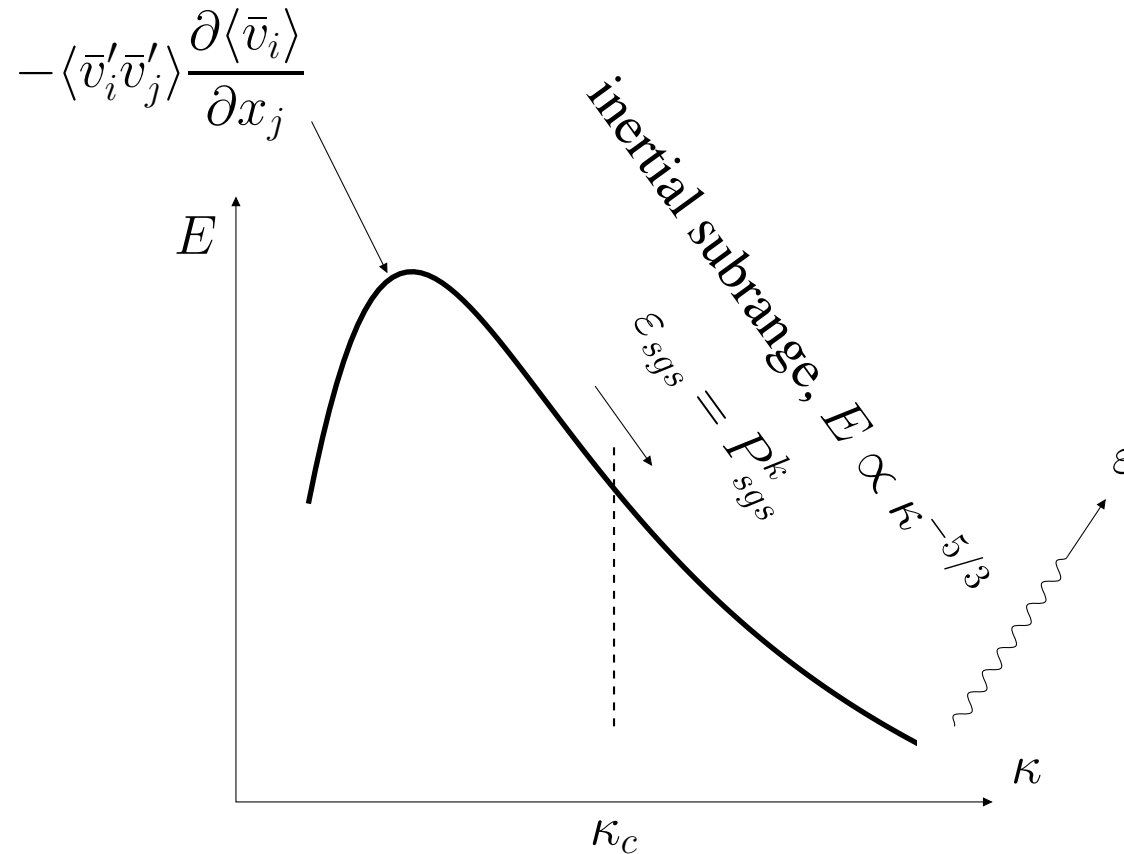
¶ See Section 18.8, Energy path

See Section 18.21, One-equation k_{sgs} model

$$\frac{\partial k_{sgs}}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_{sgs}) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_{sgs}) \frac{\partial k_{sgs}}{\partial x_j} \right] + P_{k_{sgs}} - \varepsilon$$

$$\nu_{sgs} \propto \ell v' = c_k \Delta k_{sgs}^{1/2}, \quad P_{k_{sgs}} = 2\nu_{sgs} \bar{s}_{ij} \bar{s}_{ij}, \quad \varepsilon \propto \frac{v'^3}{\ell} = C_\varepsilon \frac{k_{sgs}^{3/2}}{\Delta}$$

See Section 18.8, Energy path



See Section 18.9, SGS kinetic energy

See Section 18.9, SGS kinetic energy

$$v_i =$$

See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v_i'$$

¶ See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v'_i, \quad v_i = \bar{v}_i + v''_i =$$

¶ See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v'_i, \quad v_i = \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i$$

¶ See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v'_i, \quad v_i = \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i$$

$$k \equiv$$

¶ See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v'_i, \quad v_i = \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i$$
$$k \equiv \frac{1}{2} \langle v'_i v'_i \rangle$$

¶ See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v'_i, \quad v_i = \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i$$
$$k \equiv \frac{1}{2} \langle v'_i v'_i \rangle = \int_0^\infty E(\kappa) d\kappa$$

¶ See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v'_i, \quad v_i = \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i$$
$$k \equiv \frac{1}{2} \langle v'_i v'_i \rangle = \int_0^\infty E(\kappa) d\kappa, \quad k_{sgs} \equiv$$

¶ See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v'_i, \quad v_i = \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i$$
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¶ See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v'_i, \quad v_i = \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i$$
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See Section 18.9, SGS kinetic energy

$$v_i = \langle v_i \rangle + v'_i, \quad v_i = \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i$$
$$k \equiv \frac{1}{2} \langle v'_i v'_i \rangle = \int_0^\infty E(\kappa) d\kappa, \quad k_{sgs} \equiv \frac{1}{2} \langle v''_i v''_i \rangle = \int_{\kappa_c}^\infty E(\kappa) d\kappa$$

$$\bar{k} \equiv$$

¶ See Section 18.9, SGS kinetic energy

$$\begin{aligned}v_i &= \langle v_i \rangle + v'_i, & v_i &= \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i \\k &\equiv \frac{1}{2} \langle v'_i v'_i \rangle = \int_0^\infty E(\kappa) d\kappa, & k_{sgs} &\equiv \frac{1}{2} \langle v''_i v''_i \rangle = \int_{\kappa_c}^\infty E(\kappa) d\kappa \\ \bar{k} &\equiv \frac{1}{2} \langle \bar{v}'_i \bar{v}'_i \rangle =\end{aligned}$$

¶ See Section 18.9, SGS kinetic energy

$$\begin{aligned}v_i &= \langle v_i \rangle + v'_i, & v_i &= \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i \\k &\equiv \frac{1}{2} \langle v'_i v'_i \rangle = \int_0^\infty E(\kappa) d\kappa, & k_{sgs} &\equiv \frac{1}{2} \langle v''_i v''_i \rangle = \int_{\kappa_c}^\infty E(\kappa) d\kappa \\ \bar{k} &\equiv \frac{1}{2} \langle \bar{v}'_i \bar{v}'_i \rangle = \int_0^{\kappa_c} E(\kappa) d\kappa\end{aligned}$$

See Section 18.9, SGS kinetic energy

$$\begin{aligned}v_i &= \langle v_i \rangle + v'_i, & v_i &= \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i \\k &\equiv \frac{1}{2} \langle v'_i v'_i \rangle = \int_0^\infty E(\kappa) d\kappa, & k_{sgs} &\equiv \frac{1}{2} \langle v''_i v''_i \rangle = \int_{\kappa_c}^\infty E(\kappa) d\kappa \\ \bar{k} &\equiv \frac{1}{2} \langle \bar{v}'_i \bar{v}'_i \rangle = \int_0^{\kappa_c} E(\kappa) d\kappa, & \bar{K} &\equiv\end{aligned}$$

See Section 18.9, SGS kinetic energy

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See Section 18.9, SGS kinetic energy

$$\begin{aligned}v_i &= \langle v_i \rangle + v'_i, & v_i &= \bar{v}_i + v''_i = \langle \bar{v}_i \rangle + \bar{v}'_i + v''_i \\k &\equiv \frac{1}{2} \langle v'_i v'_i \rangle = \int_0^\infty E(\kappa) d\kappa, & k_{sgs} &\equiv \frac{1}{2} \langle v''_i v''_i \rangle = \int_{\kappa_c}^\infty E(\kappa) d\kappa \\ \bar{k} &\equiv \frac{1}{2} \langle \bar{v}'_i \bar{v}'_i \rangle = \int_0^{\kappa_c} E(\kappa) d\kappa, & \bar{K} &\equiv \frac{1}{2} \langle \bar{v}_i \rangle \langle \bar{v}_i \rangle\end{aligned}$$

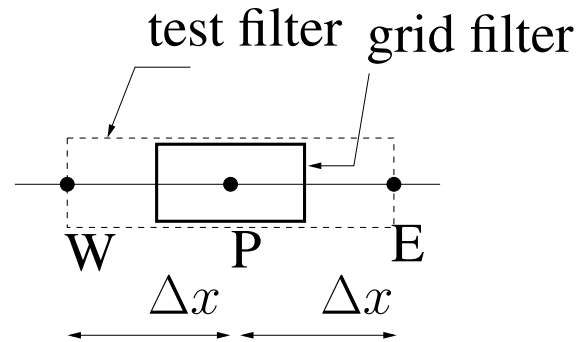
On-line Lecture 8

¶ See Section 18.11, The dynamic model

On-line Lecture 8

¶ See Section 18.11, The dynamic model

► The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$

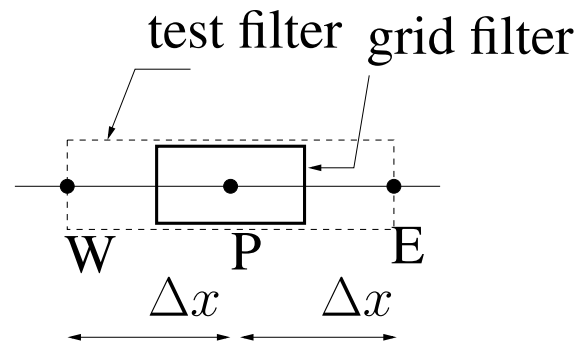


Control volume for grid and test filter.

On-line Lecture 8

¶ See Section 18.11, The dynamic model

► The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



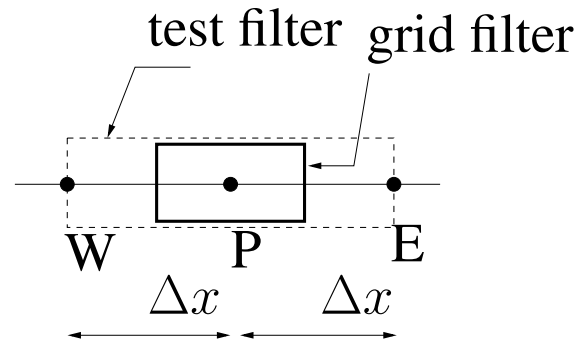
Control volume for grid and test filter.

► First, grid and test filter the Navier-Stokes (DNS)

On-line Lecture 8

¶ See Section 18.11, The dynamic model

► The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

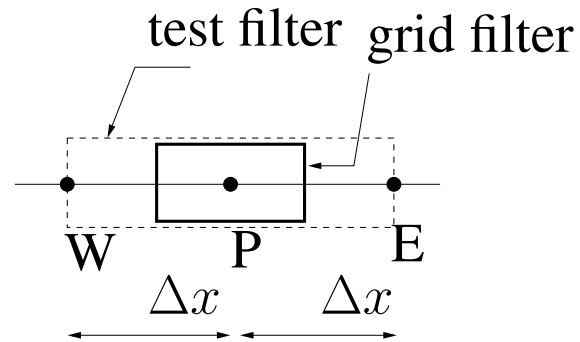
► First, grid and test filter the Navier-Stokes (DNS)

$$\frac{\partial \widehat{v}_i}{\partial t} +$$

On-line Lecture 8

¶ See Section 18.11, The dynamic model

► The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

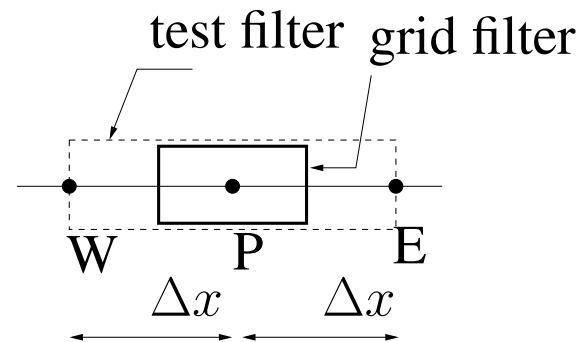
► First, grid and test filter the Navier-Stokes (DNS)

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) =$$

On-line Lecture 8

¶ See Section 18.11, The dynamic model

► The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

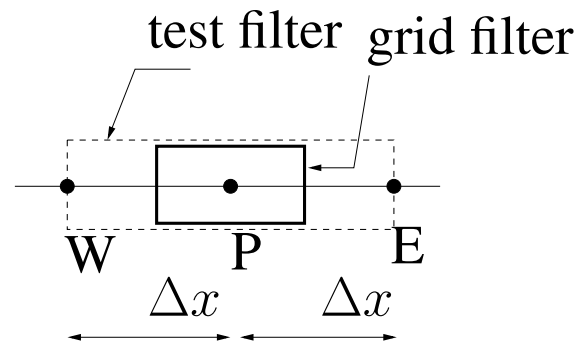
► First, grid and test filter the Navier-Stokes (DNS)

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} +$$

On-line Lecture 8

¶ See Section 18.11, The dynamic model

► The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

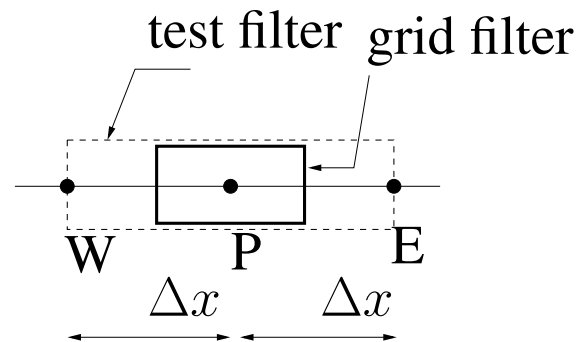
► First, grid and test filter the Navier-Stokes (DNS)

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

On-line Lecture 8

¶ See Section 18.11, The dynamic model

► The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

► First, grid and test filter the Navier-Stokes (DNS)

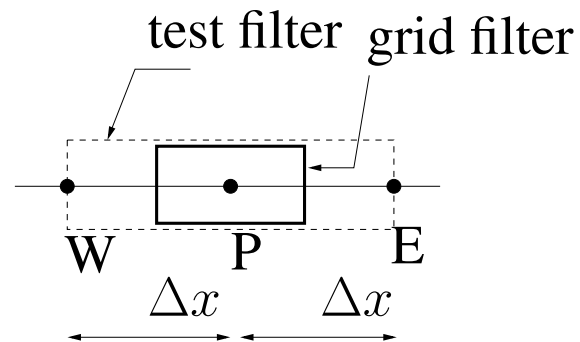
$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

Left side :

On-line Lecture 8

¶ See Section 18.11, The dynamic model

► The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

► First, grid and test filter the Navier-Stokes (DNS)

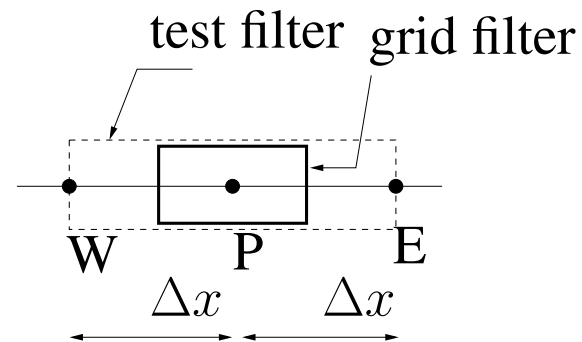
$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

Left side : $\frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right)$

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See Section 18.11, The dynamic model

The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

First, grid and test filter the Navier-Stokes (DNS)

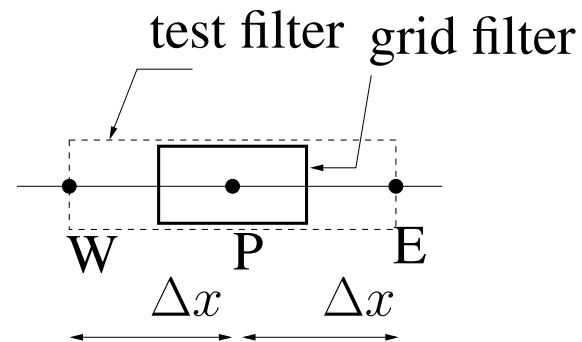
$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

Left side : $\frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) - \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) +$

On-line Lecture 8

See Section 18.11, The dynamic model

The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

First, grid and test filter the Navier-Stokes (DNS)

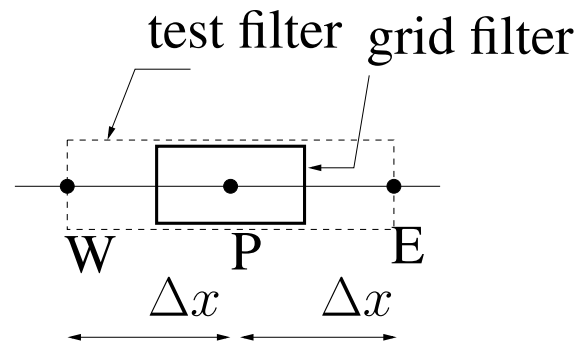
$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

Left side : $\frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) - \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) =$

On-line Lecture 8

See Section 18.11, The dynamic model

The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

First, grid and test filter the Navier-Stokes (DNS)

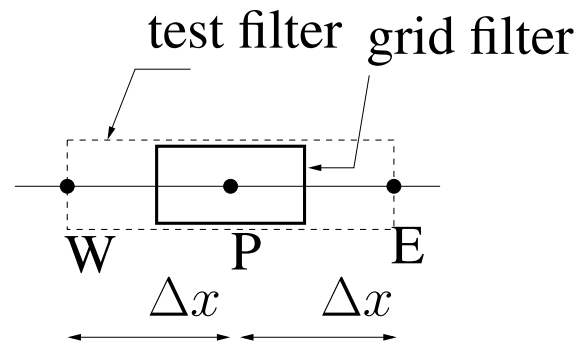
$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

Left side : $\frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) - \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right)$

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See Section 18.11, The dynamic model

The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

First, grid and test filter the Navier-Stokes (DNS)

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

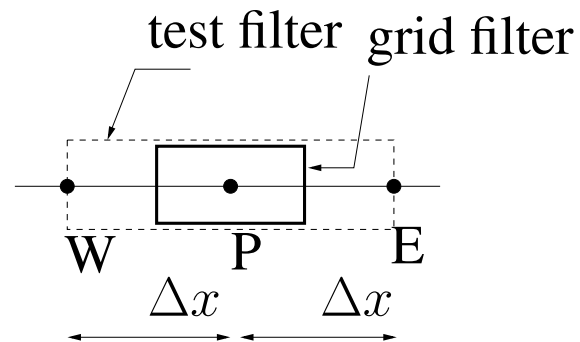
Left side : $\frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) - \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right)$

Right side :

On-line Lecture 8

See Section 18.11, The dynamic model

The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

First, grid and test filter the Navier-Stokes (DNS)

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

$$\text{Left side : } \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) - \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right)$$

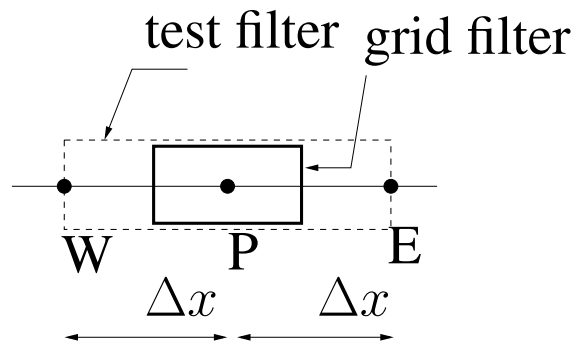
$$\text{Right side : } -\frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right)$$

We get

On-line Lecture 8

See Section 18.11, The dynamic model

The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

First, grid and test filter the Navier-Stokes (DNS)

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

$$\text{Left side} : \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) - \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right)$$

$$\text{Right side} : -\frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right)$$

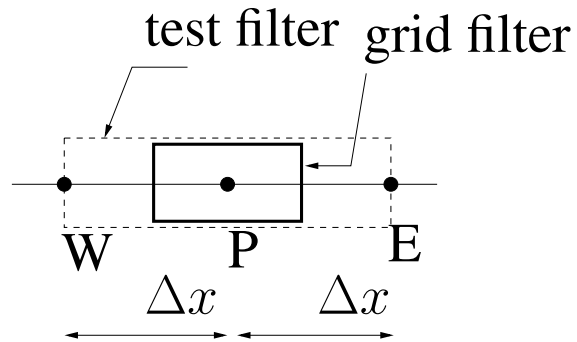
We get

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

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See Section 18.11, The dynamic model

The dynamic model. C is computed. Test filter, $\widehat{\Delta} = 2\Delta$



Control volume for grid and test filter.

First, grid and test filter the Navier-Stokes (DNS)

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j}$$

$$\text{Left side} : \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) - \frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right)$$

$$\text{Right side} : -\frac{\partial}{\partial x_j} \left(\overline{v_i v_j} \right) + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right)$$

We get

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{v_i v_j}}{\partial x_j}$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{v_i v_j}}{\partial x_j} =$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{v_i v_j}}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j}$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{v_i v_j}}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}$$

Left side :

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}$$

$$\text{Left side} : \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j}$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j}$$

$$\text{Left side} : \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} - \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} +$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j}$$

$$\text{Left side} : \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} - \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} =$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j}$$

Left side : $\frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} - \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} = \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j}$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}$$

$$\text{Left side : } \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} = \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} = \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j}$$

Right side :

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\begin{aligned} \frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{v_i v_j}}{\partial x_j} &= -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \overline{\tau}_{ij}}{\partial x_j} \\ \text{Left side} &: \frac{\partial \overline{v_i v_j}}{\partial x_j} - \frac{\partial \overline{v_i v_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} = \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} \\ \text{Right side} &: \underbrace{-\frac{\partial \overline{v_i v_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j}}_{-\partial \mathcal{L}_{ij} / \partial x_j} \end{aligned}$$

► We get

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\begin{aligned} \frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} &= -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} \\ \text{Left side} &: \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} - \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} = \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} \\ \text{Right side} &: \underbrace{-\frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j}}_{-\partial \mathcal{L}_{ij} / \partial x_j} \end{aligned}$$

► We get

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} - \frac{\partial \mathcal{L}_{ij}}{\partial x_j} \quad (37.2)$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\begin{aligned} \frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} &= -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} \\ \text{Left side} &: \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} - \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} = \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} \\ \text{Right side} &: \underbrace{-\frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j}}_{-\partial \mathcal{L}_{ij} / \partial x_j} \end{aligned}$$

► We get

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} - \frac{\partial \mathcal{L}_{ij}}{\partial x_j} \quad (37.2)$$

Identification of Eqs. 37.1 and 37.2 gives

$$(37.3)$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\begin{aligned} \frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} &= -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} \\ \text{Left side} &: \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} - \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} = \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} \\ \text{Right side} &: \underbrace{-\frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j}}_{-\partial \mathcal{L}_{ij} / \partial x_j} \end{aligned}$$

► We get

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} - \frac{\partial \mathcal{L}_{ij}}{\partial x_j} \quad (37.2)$$

Identification of Eqs. 37.1 and 37.2 gives

$$T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j + \widehat{\tau}_{ij} = \quad (37.3)$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\begin{aligned} \frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} &= -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} \\ \text{Left side} &: \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} - \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} = \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} \\ \text{Right side} &: \underbrace{-\frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j}}_{-\partial \mathcal{L}_{ij} / \partial x_j} \end{aligned}$$

► We get

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} - \frac{\partial \mathcal{L}_{ij}}{\partial x_j} \quad (37.2)$$

Identification of Eqs. 37.1 and 37.2 gives

$$T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j + \widehat{\tau}_{ij} = \mathcal{L}_{ij} + \widehat{\tau}_{ij} \quad (37.3)$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\begin{aligned} \frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} &= -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} \\ \text{Left side} &: \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} - \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} = \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} \\ \text{Right side} &: \underbrace{-\frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j}}_{-\partial \mathcal{L}_{ij} / \partial x_j} \end{aligned}$$

► We get

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} - \frac{\partial \mathcal{L}_{ij}}{\partial x_j} \quad (37.2)$$

Identification of Eqs. 37.1 and 37.2 gives

$$T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j + \widehat{\tau}_{ij} = \mathcal{L}_{ij} + \widehat{\tau}_{ij}, \quad \frac{1}{3} \delta_{ij} T_{kk} = \quad (37.3)$$

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial T_{ij}}{\partial x_j}, \quad T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j \quad (37.1)$$

► Second, we test filter the LES equations

$$\begin{aligned} \frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} &= -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} \\ \text{Left side} &: \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} - \frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} = \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j} \\ \text{Right side} &: \underbrace{-\frac{\partial \overline{\widehat{v}_i \widehat{v}_j}}{\partial x_j} + \frac{\partial \widehat{v}_i \widehat{v}_j}{\partial x_j}}_{-\partial \mathcal{L}_{ij} / \partial x_j} \end{aligned}$$

► We get

$$\frac{\partial \widehat{v}_i}{\partial t} + \frac{\partial}{\partial x_j} \left(\widehat{v}_i \widehat{v}_j \right) = -\frac{1}{\rho} \frac{\partial \widehat{p}}{\partial x_i} + \nu \frac{\partial^2 \widehat{v}_i}{\partial x_j \partial x_j} - \frac{\partial \widehat{\tau}_{ij}}{\partial x_j} - \frac{\partial \mathcal{L}_{ij}}{\partial x_j} \quad (37.2)$$

Identification of Eqs. 37.1 and 37.2 gives

$$T_{ij} = \overline{v_i v_j} - \widehat{v}_i \widehat{v}_j + \widehat{\tau}_{ij} = \mathcal{L}_{ij} + \widehat{\tau}_{ij}, \quad \frac{1}{3} \delta_{ij} T_{kk} = \frac{1}{3} \delta_{ij} \mathcal{L}_{kk} + \frac{1}{3} \delta_{ij} \widehat{\tau}_{kk} \quad (37.3)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\mathcal{T}}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\mathcal{T}}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

► Smagorinsky model for both grid and test level SGS stresses:

$$(37.5)$$

$$(37.6)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

► Smagorinsky model for both grid and test level SGS stresses:

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = \quad (37.5)$$

$$(37.6)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

► Smagorinsky model for both grid and test level SGS stresses:

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -2C\Delta^2|\bar{s}|\bar{s}_{ij} \quad (37.5)$$

$$(37.6)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

► Smagorinsky model for both grid and test level SGS stresses:

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -2C\Delta^2|\bar{s}|\bar{s}_{ij} \quad (37.5)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} = \quad (37.6)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

► Smagorinsky model for both grid and test level SGS stresses:

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -2C\Delta^2|\bar{s}|\bar{s}_{ij} \quad (37.5)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} = -2C\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} \quad (37.6)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

► Smagorinsky model for both grid and test level SGS stresses:

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -2C\Delta^2|\bar{s}|\bar{s}_{ij} \quad (37.5)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} = -2C\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} \quad (37.6)$$

where

$$\widehat{s}_{ij} = \frac{1}{2} \left(\frac{\partial \widehat{v}_i}{\partial x_j} + \frac{\partial \widehat{v}_j}{\partial x_i} \right), \quad |\widehat{s}| = \left(2\widehat{s}_{ij}\widehat{s}_{ij} \right)^{1/2}$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

► Smagorinsky model for both grid and test level SGS stresses:

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -2C\Delta^2|\bar{s}|\bar{s}_{ij} \quad (37.5)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} = -2C\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} \quad (37.6)$$

where

$$\widehat{s}_{ij} = \frac{1}{2} \left(\frac{\partial \widehat{v}_i}{\partial x_j} + \frac{\partial \widehat{v}_j}{\partial x_i} \right), \quad |\widehat{s}| = \left(2\widehat{s}_{ij}\widehat{s}_{ij} \right)^{1/2}$$

► Three equations, three unknowns!

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

► Smagorinsky model for both grid and test level SGS stresses:

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -2C\Delta^2|\bar{s}|\bar{s}_{ij} \quad (37.5)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} = -2C\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} \quad (37.6)$$

where

$$\widehat{s}_{ij} = \frac{1}{2} \left(\frac{\partial \widehat{v}_i}{\partial x_j} + \frac{\partial \widehat{v}_j}{\partial x_i} \right), \quad |\widehat{s}| = \left(2\widehat{s}_{ij}\widehat{s}_{ij} \right)^{1/2}$$

► Three equations, three unknowns!

► Eqs. 37.5. 37.6 into Eq. 37.4 gives

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} = -2 \left(C\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} - \overline{C\Delta^2|\bar{s}|\bar{s}_{ij}} \right)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

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► Three equations, three unknowns!

► Eqs. 37.5. 37.6 into Eq. 37.4 gives

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} = -2 \left(C\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} - \overline{C\Delta^2|\bar{s}|\bar{s}_{ij}} \right)$$

► We need to yank C out of the test filter;

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

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► Three equations, three unknowns!

► Eqs. 37.5. 37.6 into Eq. 37.4 gives

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► We need to yank C out of the test filter; ► If not, it's very difficult to solve for C .

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

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► Eqs. 37.5. 37.6 into Eq. 37.4 gives

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► We need to yank C out of the test filter; ► If not, it's very difficult to solve for C . ► We get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} = -2C \left(\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} - \overline{\Delta^2|\bar{s}|\bar{s}_{ij}} \right)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} + \widehat{\tau}_{ij} - \frac{1}{3}\delta_{ij}\widehat{\tau}_{kk} = \mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} \quad (37.4)$$

► Smagorinsky model for both grid and test level SGS stresses:

$$\tau_{ij} - \frac{1}{3}\delta_{ij}\tau_{kk} = -2C\Delta^2|\bar{s}|\bar{s}_{ij} \quad (37.5)$$

$$T_{ij} - \frac{1}{3}\delta_{ij}T_{kk} = -2C\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} \quad (37.6)$$

where

$$\widehat{s}_{ij} = \frac{1}{2} \left(\frac{\partial \widehat{v}_i}{\partial x_j} + \frac{\partial \widehat{v}_j}{\partial x_i} \right), \quad |\widehat{s}| = \left(2\widehat{s}_{ij}\widehat{s}_{ij} \right)^{1/2}$$

► Three equations, three unknowns!

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$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} = -2 \left(C\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} - \overline{C\Delta^2|\bar{s}|\bar{s}_{ij}} \right)$$

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$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} = -2C \left(\widehat{\Delta}^2|\widehat{s}|\widehat{s}_{ij} - \overline{\Delta^2|\bar{s}|\bar{s}_{ij}} \right)$$

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \tag{37.7}$$

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

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► This cannot be satisfied for all i, j

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

► This cannot be satisfied for all i, j ► Least-square problem:

$$Q = \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right)^2$$

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

► This cannot be satisfied for all i, j ► Least-square problem:

$$Q = \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right)^2$$

► Find a minimum of Q which best satisfies Eq. 37.7 for all i, j

(37.8)

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

► This cannot be satisfied for all i, j ► Least-square problem:

$$Q = \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right)^2$$

► Find a minimum of Q which best satisfies Eq. 37.7 for all i, j

$$\frac{\partial Q}{\partial C} = \quad (37.8)$$

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

► This cannot be satisfied for all i, j ► Least-square problem:

$$Q = \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right)^2$$

► Find a minimum of Q which best satisfies Eq. 37.7 for all i, j

$$\frac{\partial Q}{\partial C} = 4M_{ij} \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right) = \quad (37.8)$$

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

► This cannot be satisfied for all i, j ► Least-square problem:

$$Q = \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right)^2$$

► Find a minimum of Q which best satisfies Eq. 37.7 for all i, j

$$\frac{\partial Q}{\partial C} = 4M_{ij} \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right) = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0 \quad (37.8)$$

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

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$$\frac{\partial Q}{\partial C} = 4M_{ij} \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right) = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0 \quad (37.8)$$

since $\frac{1}{3}\delta_{ij}\mathcal{L}_{kk}M_{ij} = \frac{1}{3}\mathcal{L}_{kk}M_{ii} = 0$ since $\widehat{\bar{s}}_{ii} = \bar{s}_{ii} = 0$ thanks to continuity.

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

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► Find a minimum of Q which best satisfies Eq. 37.7 for all i, j

$$\frac{\partial Q}{\partial C} = 4M_{ij} \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right) = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0 \quad (37.8)$$

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Eq. 37.8: Minimum or maximum?

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

► This cannot be satisfied for all i, j ► Least-square problem:

$$Q = \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right)^2$$

► Find a minimum of Q which best satisfies Eq. 37.7 for all i, j

$$\frac{\partial Q}{\partial C} = 4M_{ij} \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right) = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0 \quad (37.8)$$

since $\frac{1}{3}\delta_{ij}\mathcal{L}_{kk}M_{ij} = \frac{1}{3}\mathcal{L}_{kk}M_{ii} = 0$ since $\widehat{\bar{s}}_{ii} = \bar{s}_{ii} = 0$ thanks to continuity.

Eq. 37.8: Minimum or maximum?

► $\partial^2 Q / \partial C^2 = 8M_{ij}M_{ij} > 0$

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

► This cannot be satisfied for all i, j ► Least-square problem:

$$Q = \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right)^2$$

► Find a minimum of Q which best satisfies Eq. 37.7 for all i, j

$$\frac{\partial Q}{\partial C} = 4M_{ij} \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right) = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0 \quad (37.8)$$

since $\frac{1}{3}\delta_{ij}\mathcal{L}_{kk}M_{ij} = \frac{1}{3}\mathcal{L}_{kk}M_{ii} = 0$ since $\widehat{\bar{s}}_{ii} = \bar{s}_{ii} = 0$ thanks to continuity.

Eq. 37.8: Minimum or maximum?

► $\partial^2 Q / \partial C^2 = 8M_{ij}M_{ij} > 0$ ► Hence, minimum

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2C \underbrace{\left(\widehat{\Delta}^2 | \widehat{\bar{s}} | \widehat{\bar{s}}_{ij} - \Delta^2 \overline{|\bar{s}| \bar{s}_{ij}} \right)}_{M_{ij}} = 0$$

► Now we get

$$\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} = 0 \quad (37.7)$$

► This cannot be satisfied for all i, j ► Least-square problem:

$$Q = \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right)^2$$

► Find a minimum of Q which best satisfies Eq. 37.7 for all i, j

$$\frac{\partial Q}{\partial C} = 4M_{ij} \left(\mathcal{L}_{ij} - \frac{1}{3}\delta_{ij}\mathcal{L}_{kk} + 2CM_{ij} \right) = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0 \quad (37.8)$$

since $\frac{1}{3}\delta_{ij}\mathcal{L}_{kk}M_{ij} = \frac{1}{3}\mathcal{L}_{kk}M_{ii} = 0$ since $\widehat{\bar{s}}_{ii} = \bar{s}_{ii} = 0$ thanks to continuity.

Eq. 37.8: Minimum or maximum?

► $\partial^2 Q / \partial C^2 = 8M_{ij}M_{ij} > 0$ ► Hence, minimum (fortunately)

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}$$

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

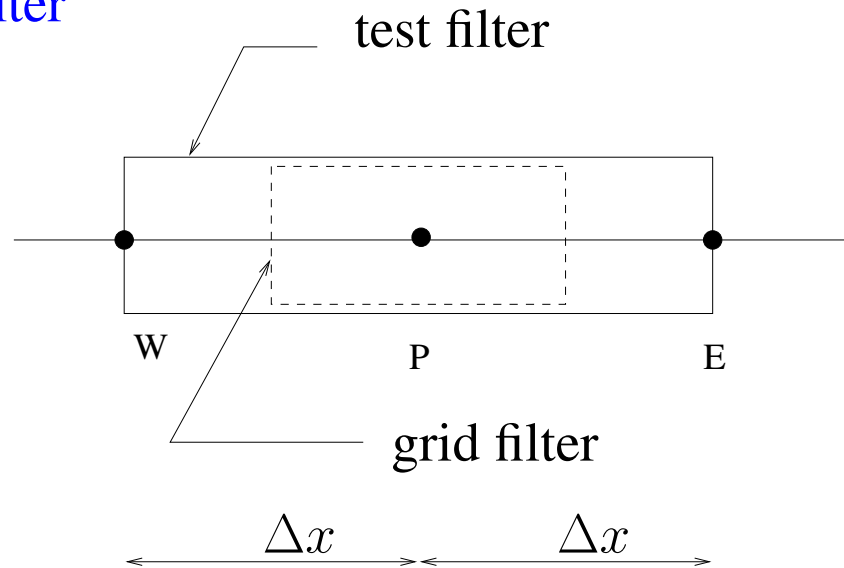
¶ See Section [18.12](#), [The test filter](#)

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

¶ See Section 18.12, The test filter

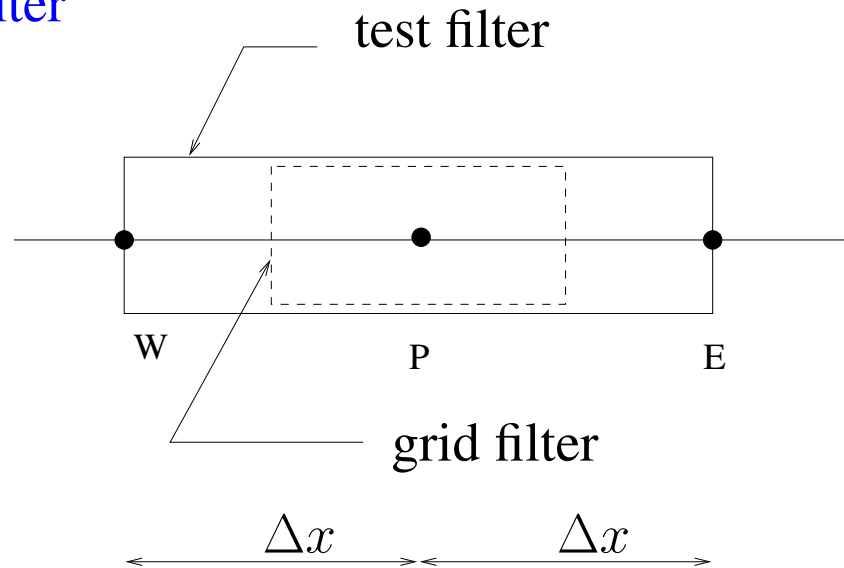


$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

¶ See Section 18.12, The test filter



\widehat{v}_P is computed as $(\widehat{\Delta x} = 2\Delta x)$

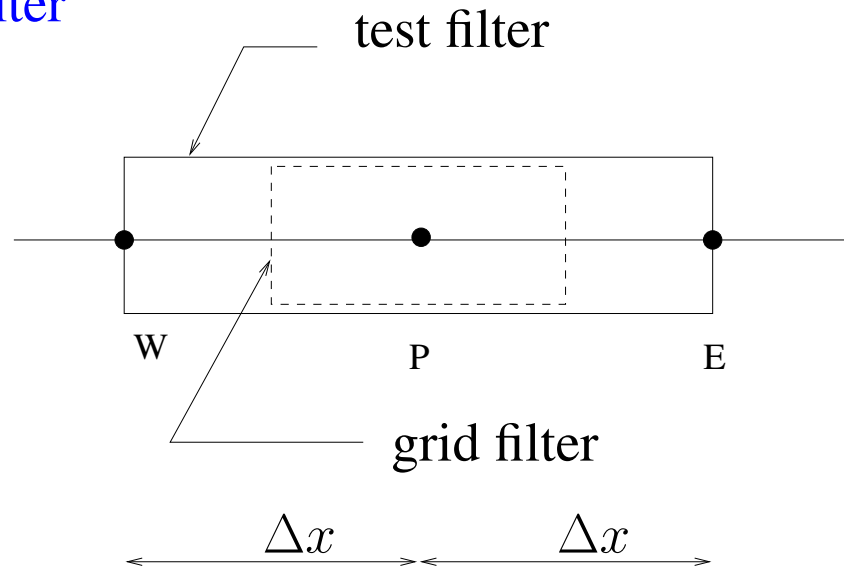
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$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

¶ See Section 18.12, The test filter



\widehat{v}_P is computed as $(\widehat{\Delta x} = 2\Delta x)$

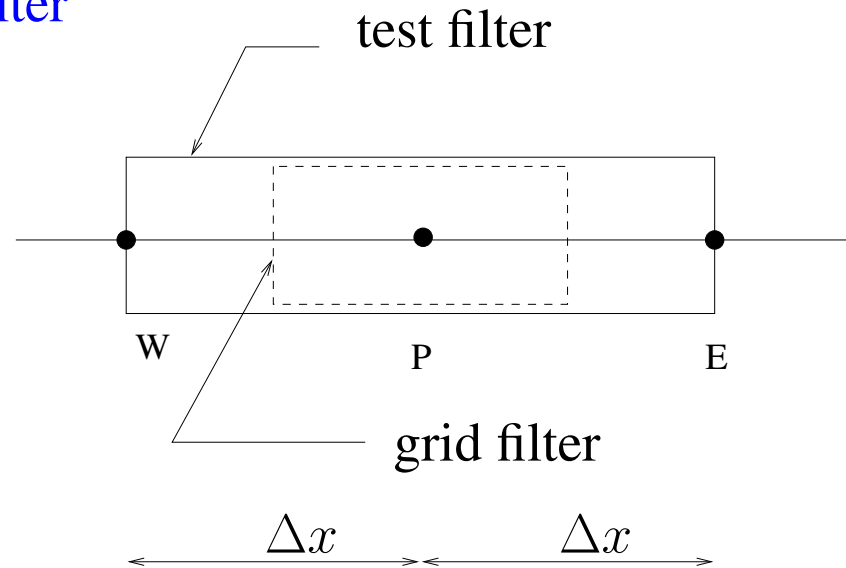
$$\widehat{v}_P =$$

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

¶ See Section 18.12, The test filter



\widehat{v}_P is computed as ($\widehat{\Delta x} = 2\Delta x$)

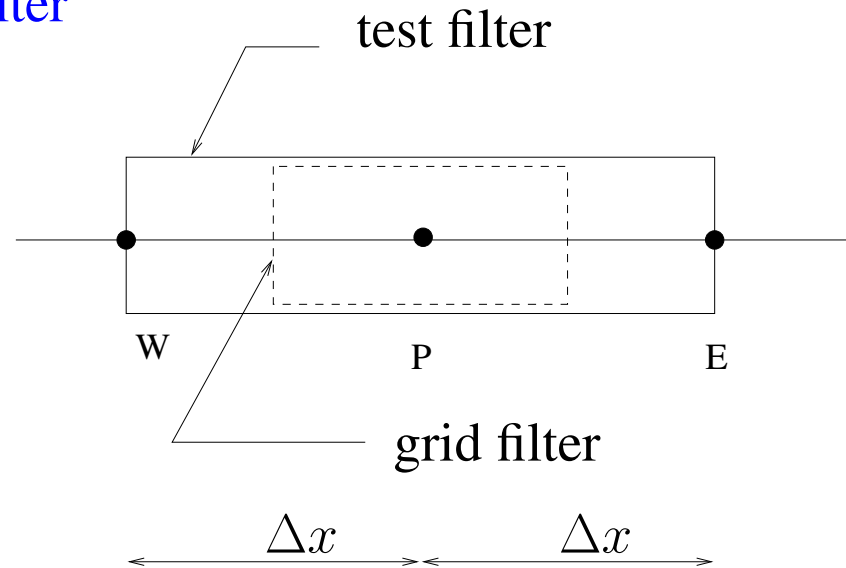
$$\widehat{v}_P = \frac{1}{2\Delta x} \int_W^E \bar{v} dx =$$

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

¶ See Section 18.12, The test filter



\widehat{v}_P is computed as ($\widehat{\Delta x} = 2\Delta x$)

$$\widehat{v}_P = \frac{1}{2\Delta x} \int_W^E \bar{v} dx = \frac{1}{2\Delta x} \left(\int_W^P \bar{v} dx + \int_P^E \bar{v} dx \right)$$

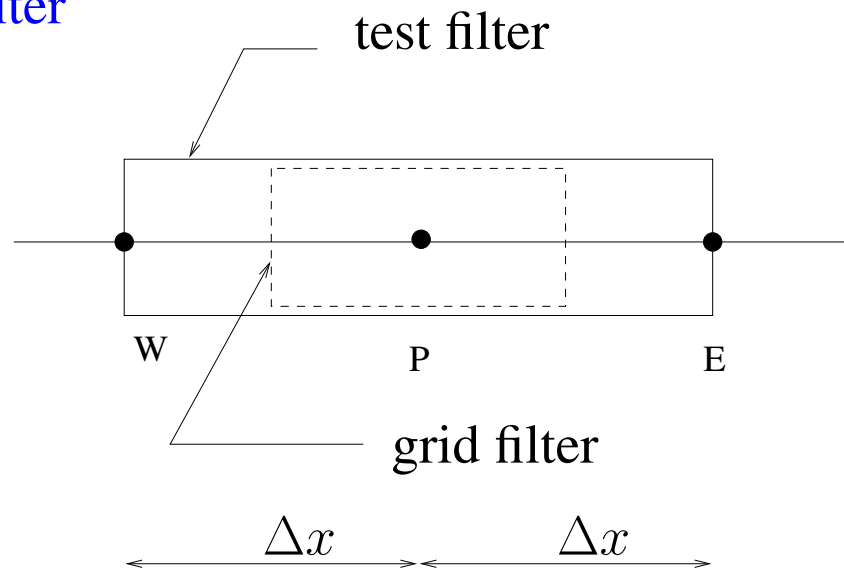
=

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

¶ See Section 18.12, The test filter



\widehat{v}_P is computed as ($\widehat{\Delta x} = 2\Delta x$)

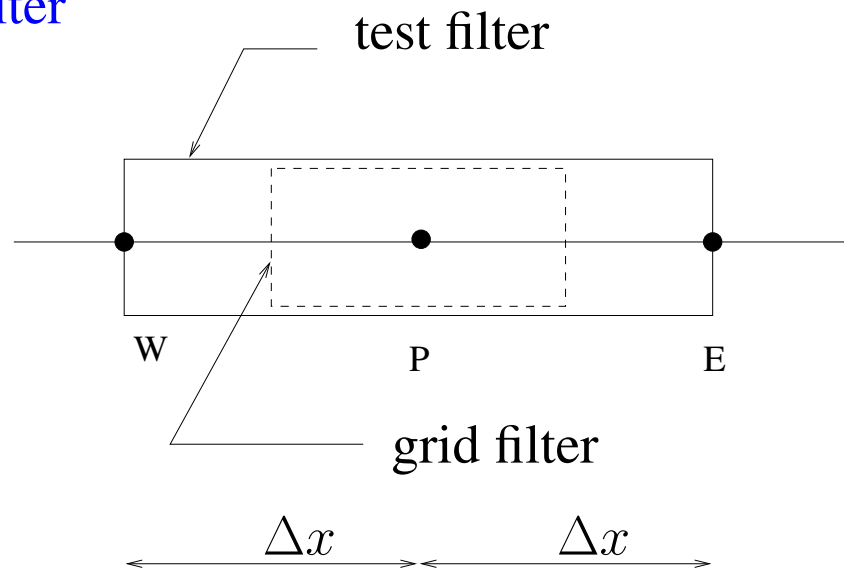
$$\begin{aligned} \widehat{v}_P &= \frac{1}{2\Delta x} \int_W^E \bar{v} dx = \frac{1}{2\Delta x} \left(\int_W^P \bar{v} dx + \int_P^E \bar{v} dx \right) \\ &= \frac{1}{2\Delta x} (\bar{v}_w \Delta x + \bar{v}_e \Delta x) = \end{aligned}$$

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

¶ See Section 18.12, The test filter



\widehat{v}_P is computed as ($\widehat{\Delta x} = 2\Delta x$)

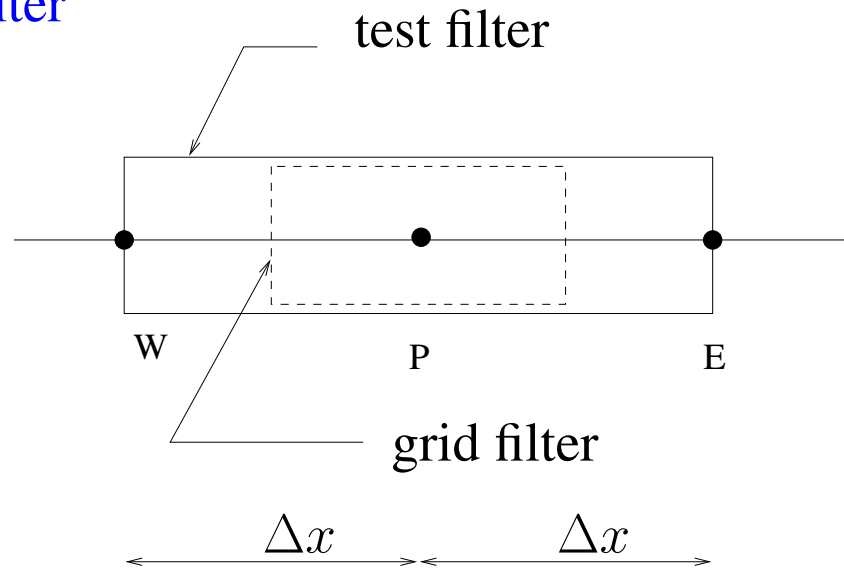
$$\begin{aligned} \widehat{v}_P &= \frac{1}{2\Delta x} \int_W^E \bar{v} dx = \frac{1}{2\Delta x} \left(\int_W^P \bar{v} dx + \int_P^E \bar{v} dx \right) \\ &= \frac{1}{2\Delta x} (\bar{v}_w \Delta x + \bar{v}_e \Delta x) = \frac{1}{2} \left(\frac{\bar{v}_W + \bar{v}_P}{2} + \frac{\bar{v}_P + \bar{v}_E}{2} \right) = \end{aligned}$$

$$\frac{\partial Q}{\partial C} = 4M_{ij} (\mathcal{L}_{ij} + 2CM_{ij}) = 0$$

► We get

$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \text{stability problems: needs smoothing}$$

¶ See Section 18.12, The test filter



\widehat{v}_P is computed as ($\widehat{\Delta x} = 2\Delta x$)

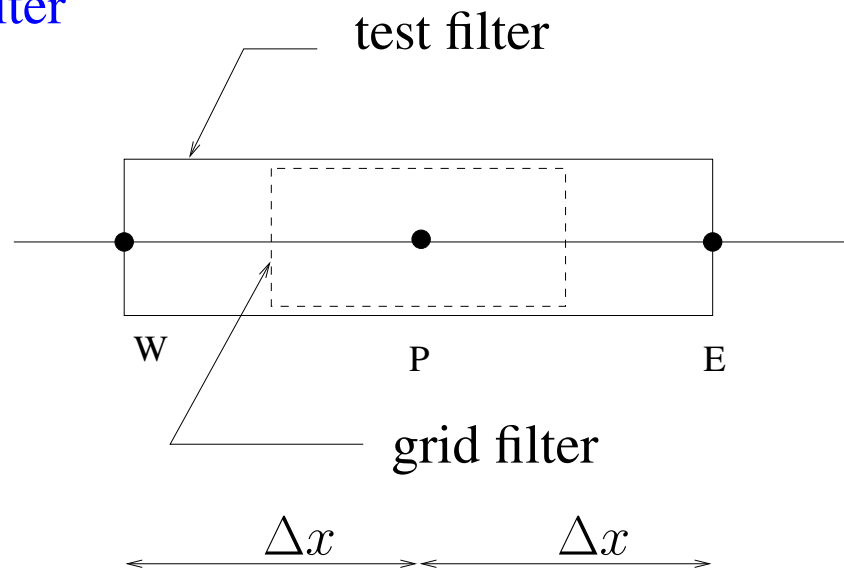
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$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \nu_{sgs} = C\Delta^2|\bar{s}|$$

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► Is C positive?

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► Is C positive? ► Do we want it to stay positive?

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$$\nu_{tot} =$$

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$$\nu_{tot} = \nu + \nu_{sgs} =$$

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$$\nu_{tot} = \nu + \nu_{sgs} = \nu + C\Delta^2|\bar{s}| > 0$$

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$$C = -\frac{\mathcal{L}_{ij}M_{ij}}{2M_{ij}M_{ij}}, \quad \nu_{sgs} = C\Delta^2|\bar{s}|$$

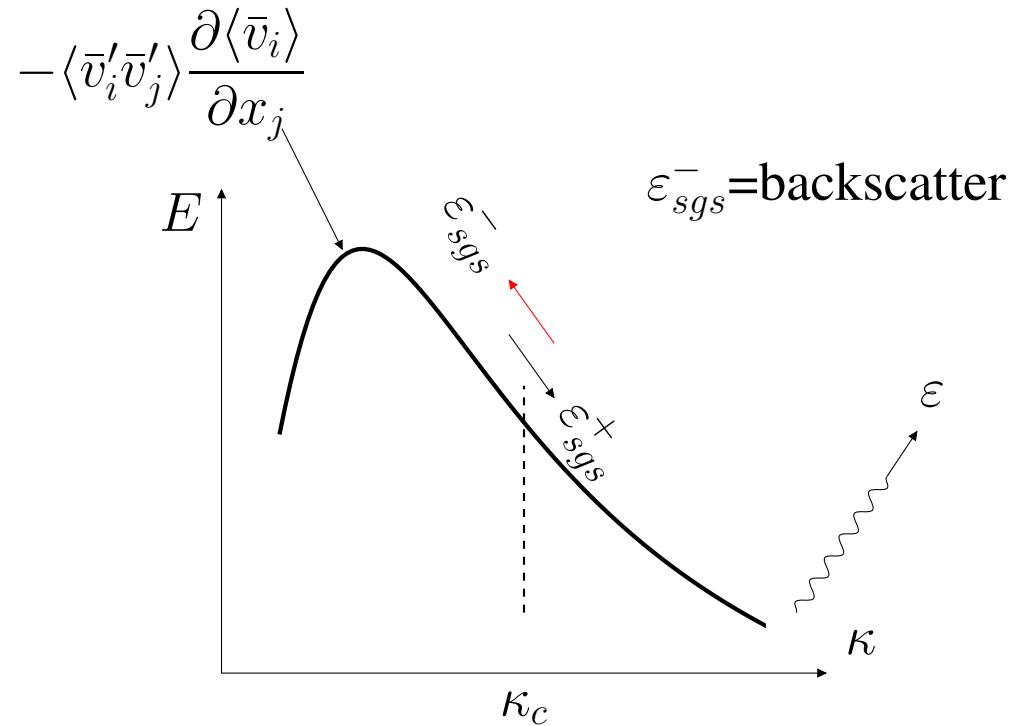
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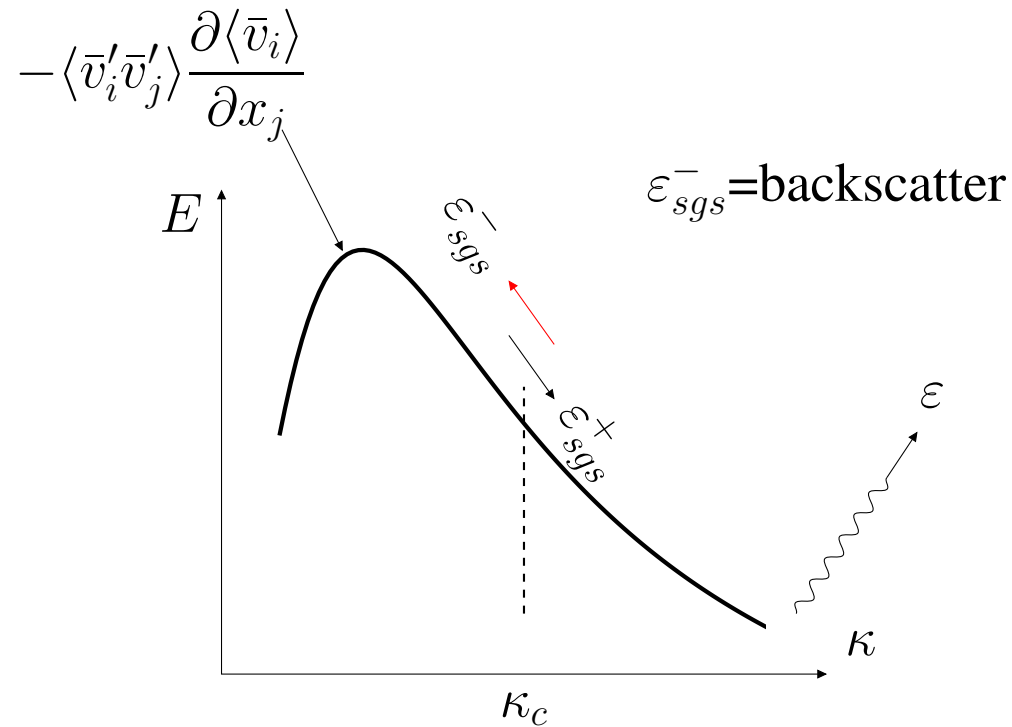
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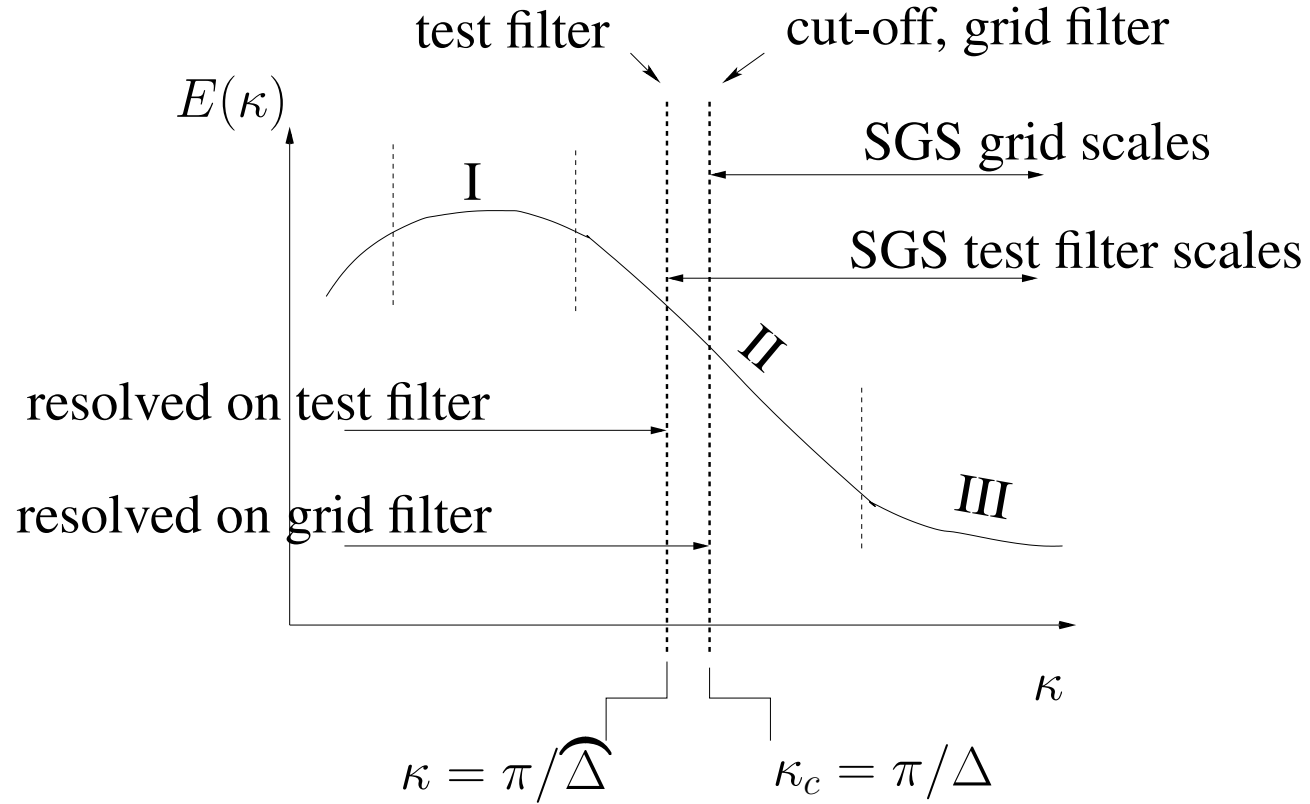
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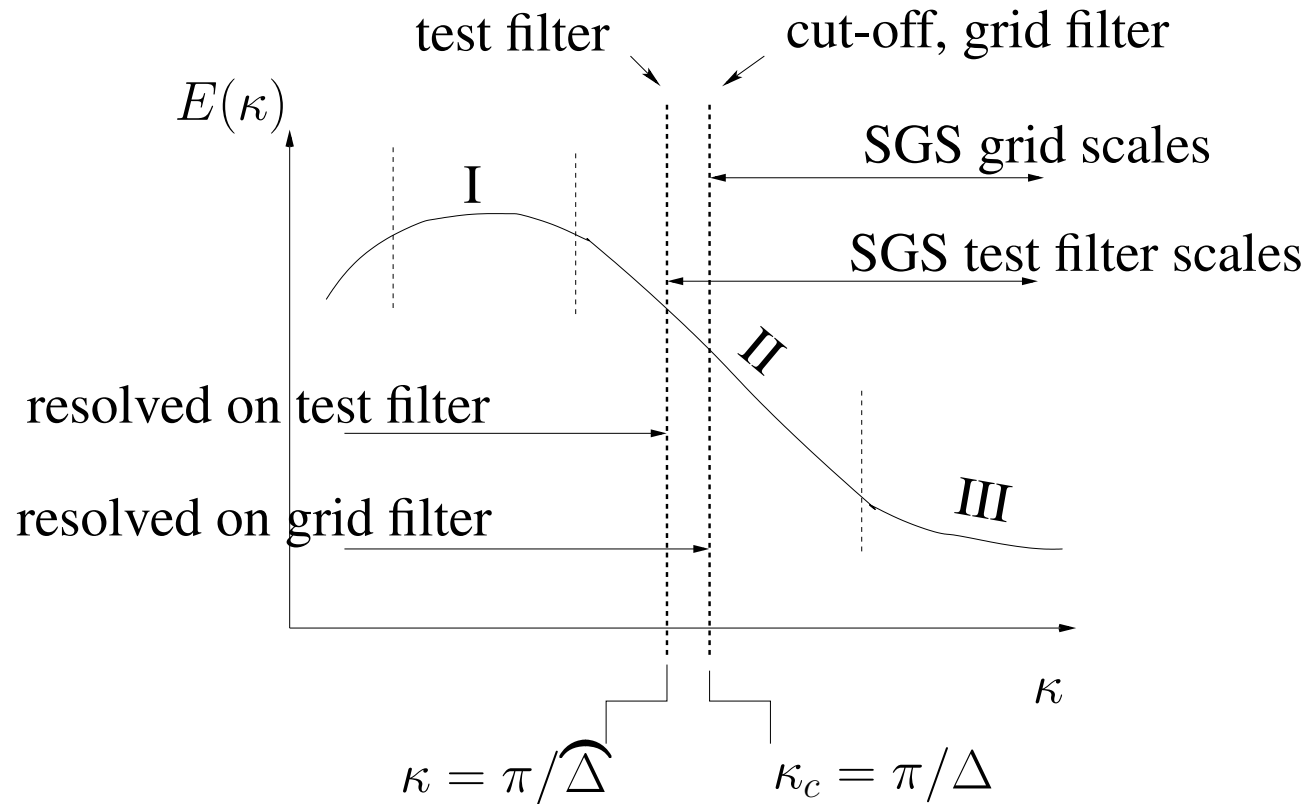
$$\epsilon_{sgs} = 2\nu_{sgs}\bar{s}_{ij}\bar{s}_{ij} = \epsilon_{sgs}^+ + \epsilon_{sgs}^-$$

¶ See Section 18.13, Stresses on grid, test and intermediate level

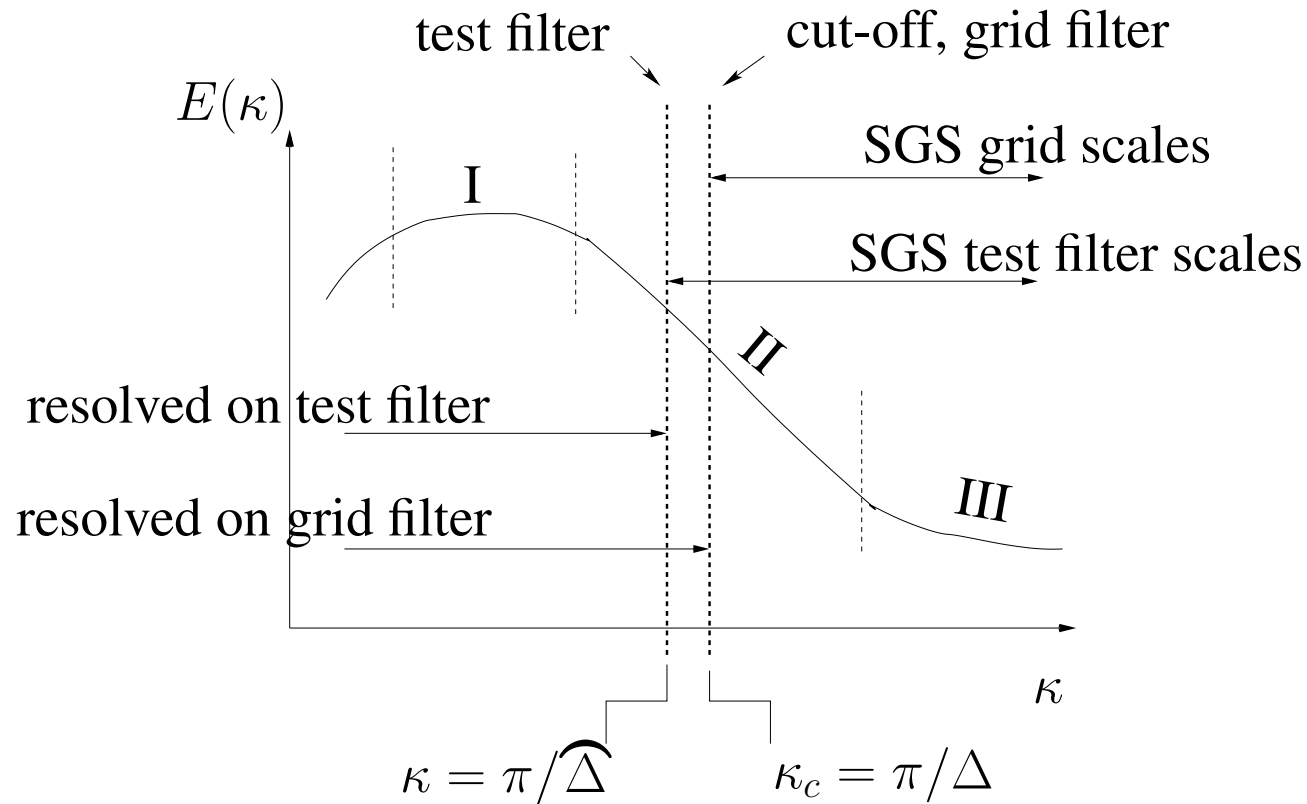
See Section 18.13, Stresses on grid, test and intermediate level



See Section 18.13, Stresses on grid, test and intermediate level

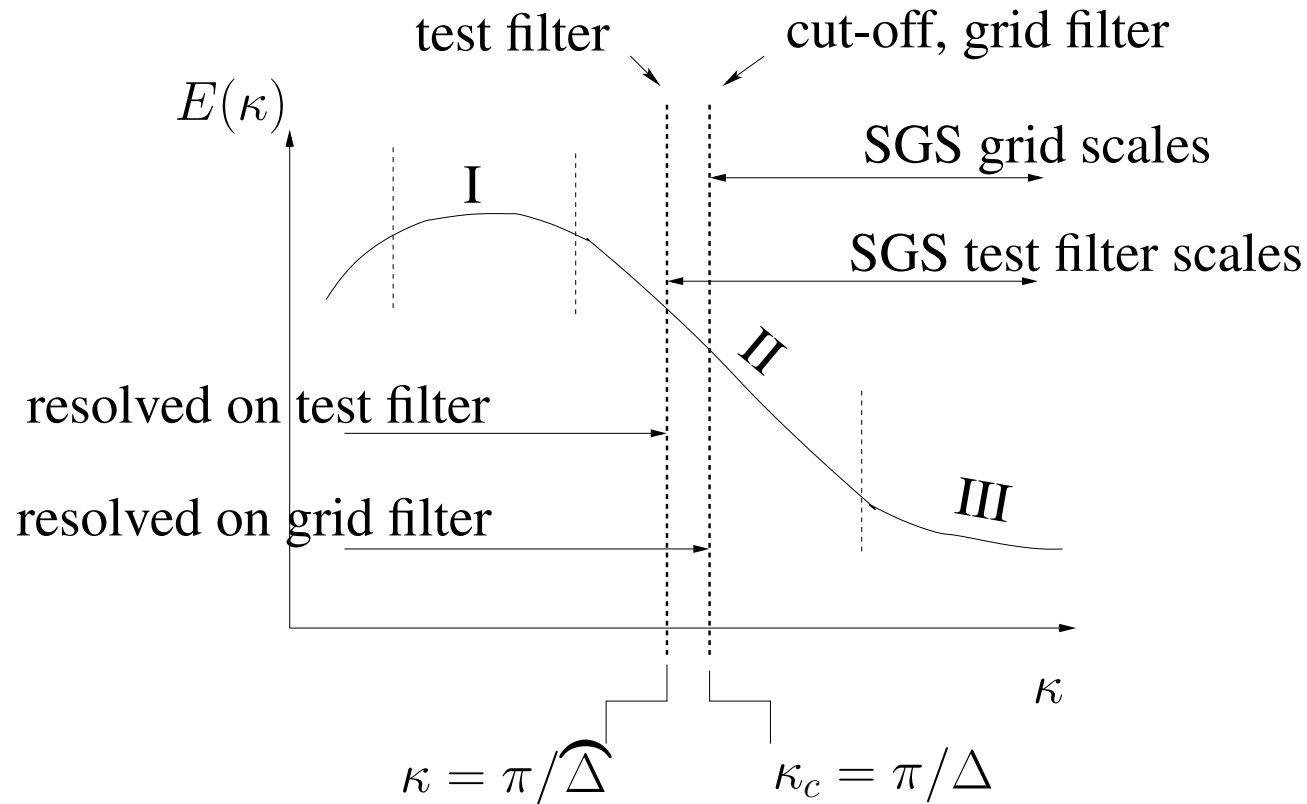


See Section 18.13, Stresses on grid, test and intermediate level



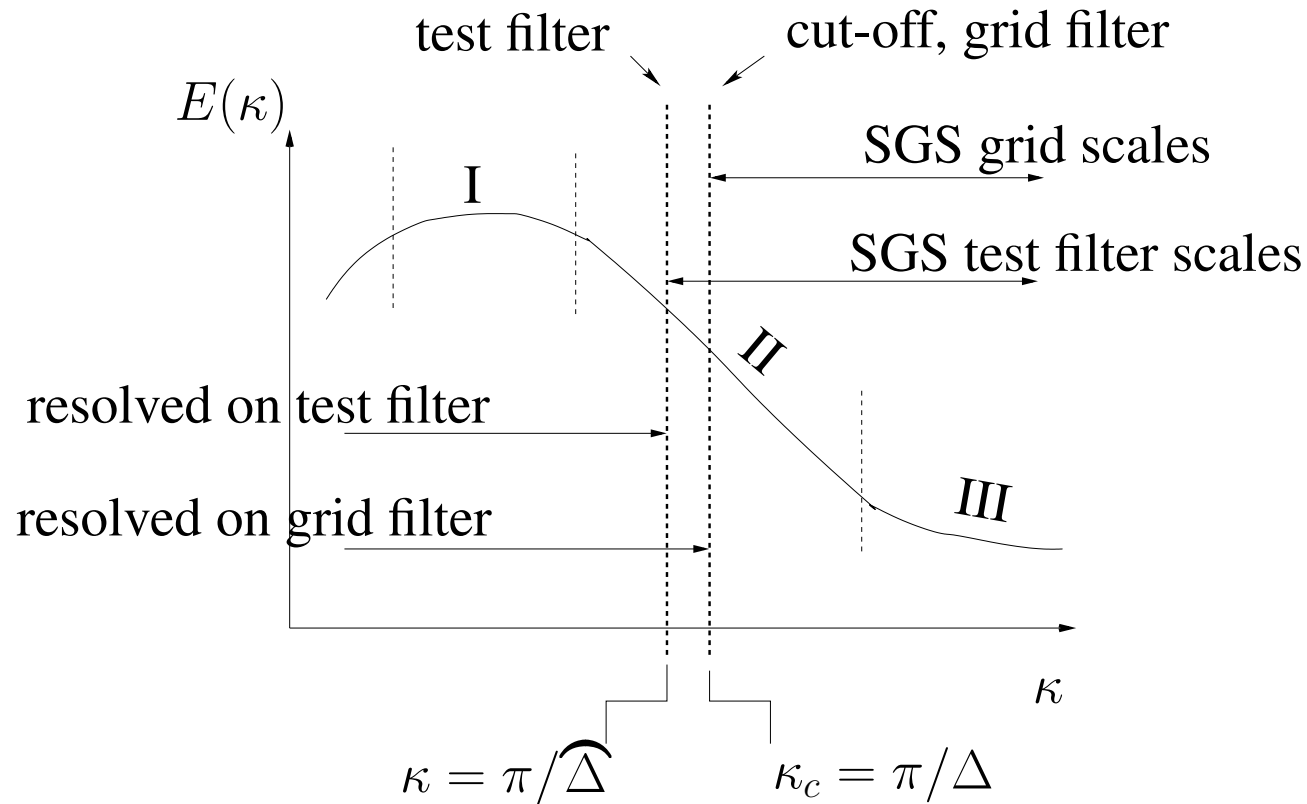
$$\tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j$$

See Section 18.13, Stresses on grid, test and intermediate level



$$\tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad \text{stresses with } \ell < \Delta$$

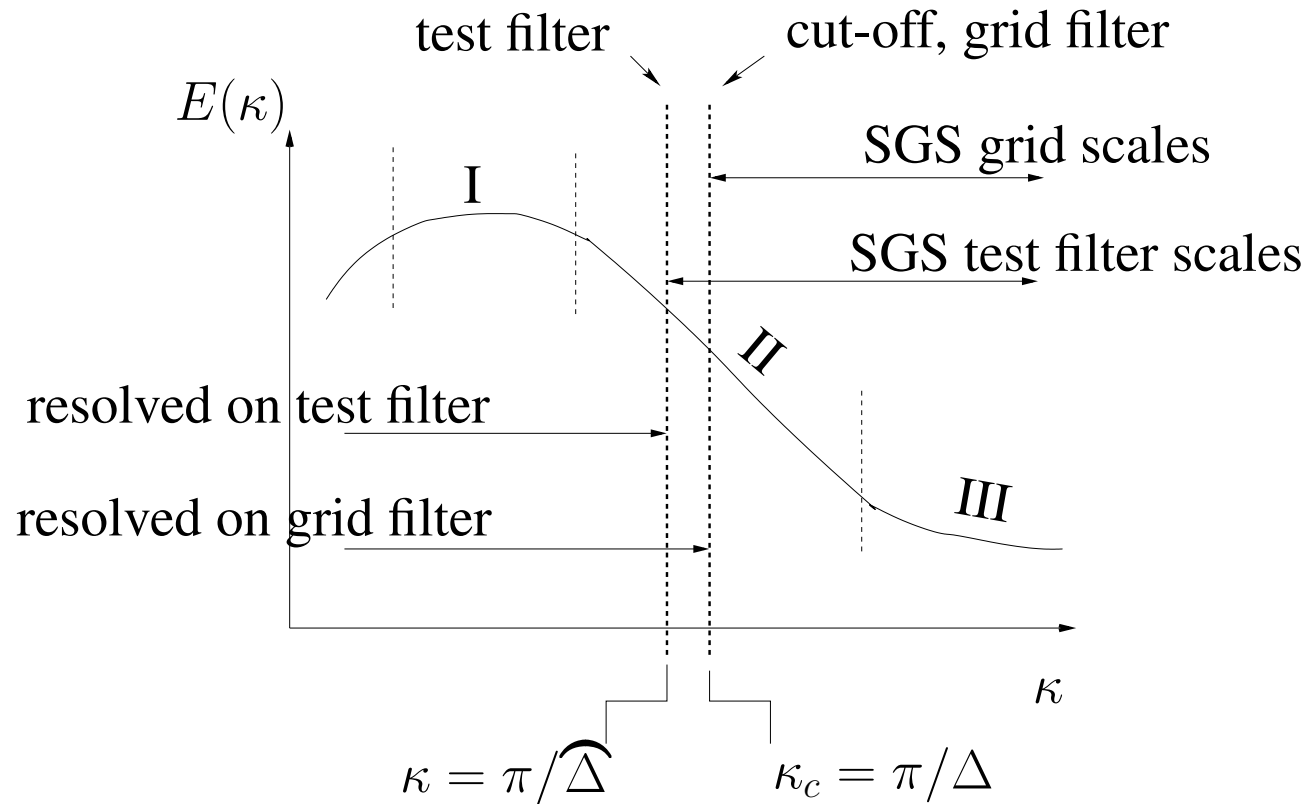
See Section 18.13, Stresses on grid, test and intermediate level



$$\tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j \quad \text{stresses with } \ell < \Delta$$

$$T_{ij} = \widehat{\overline{v_i v_j}} - \widehat{\bar{v}}_i \widehat{\bar{v}}_j$$

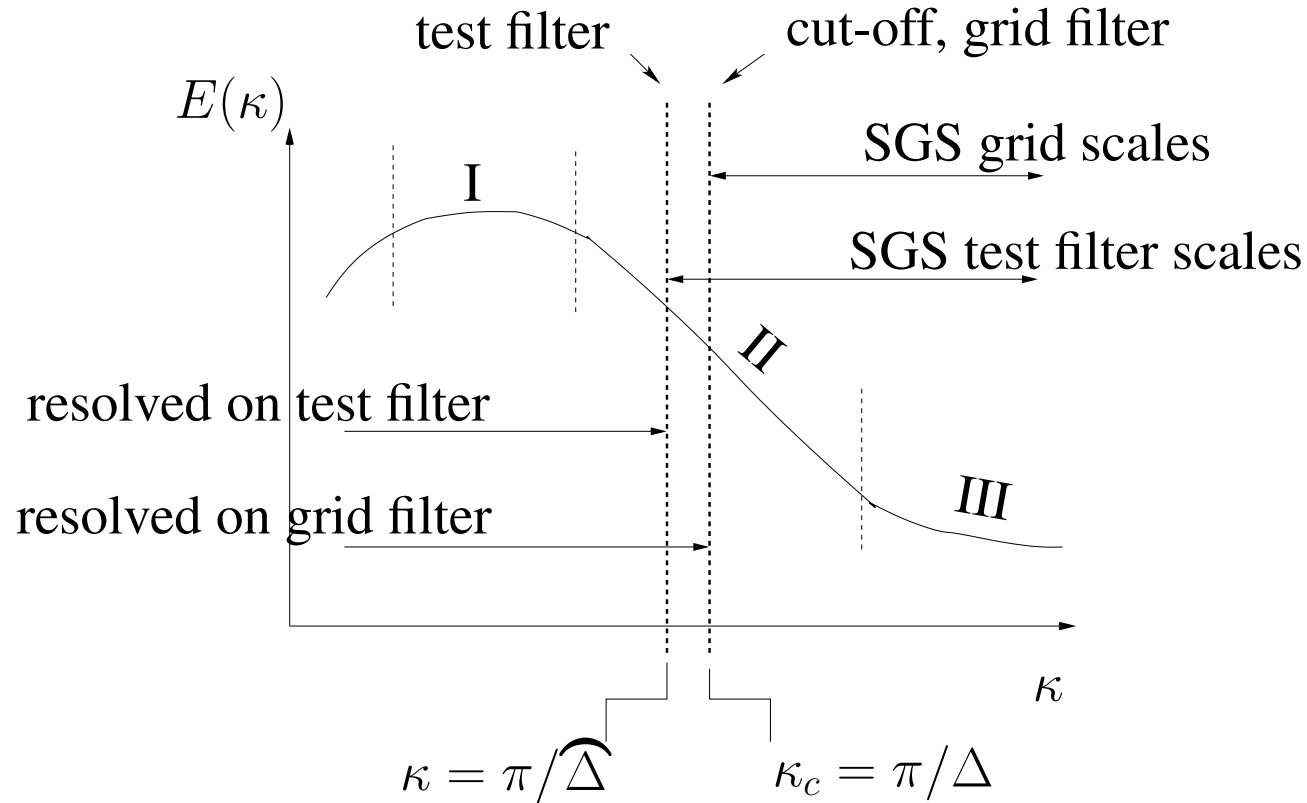
See Section 18.13, Stresses on grid, test and intermediate level



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See Section 18.13, Stresses on grid, test and intermediate level

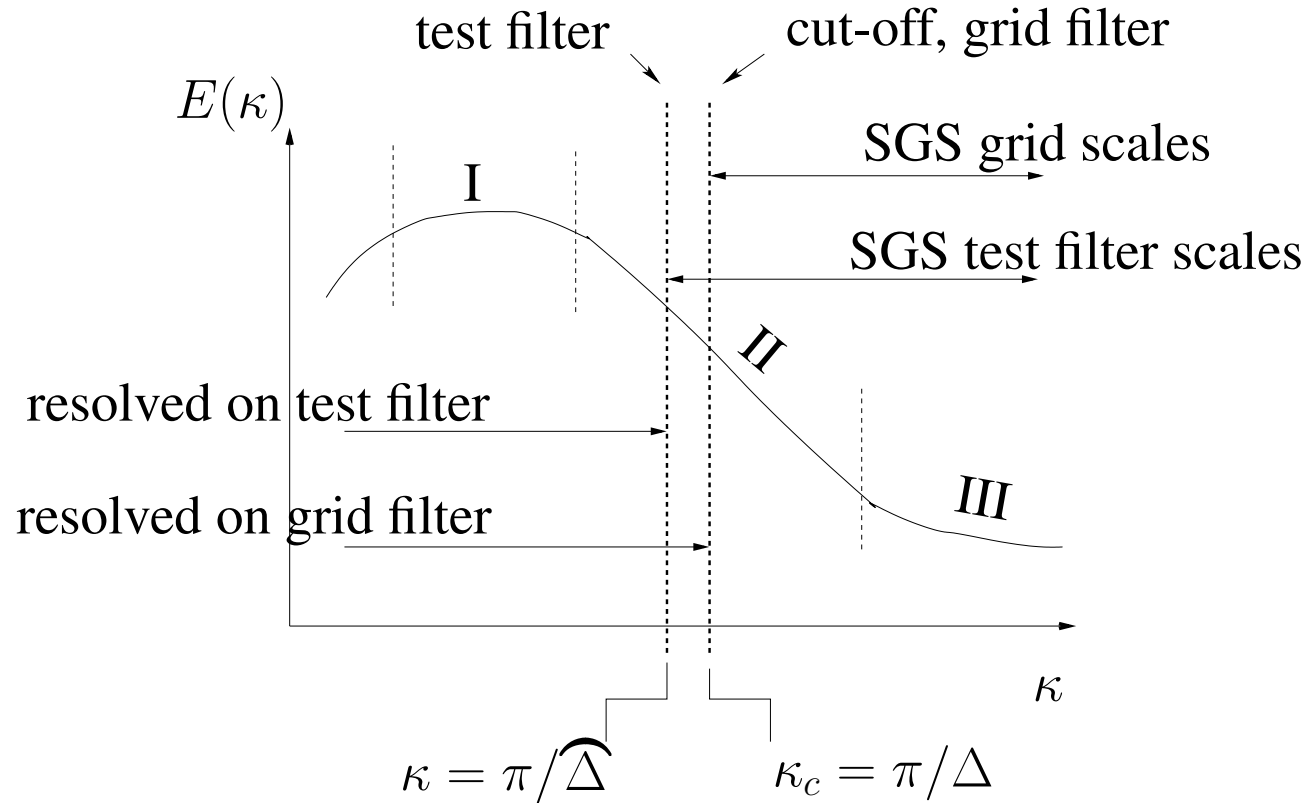


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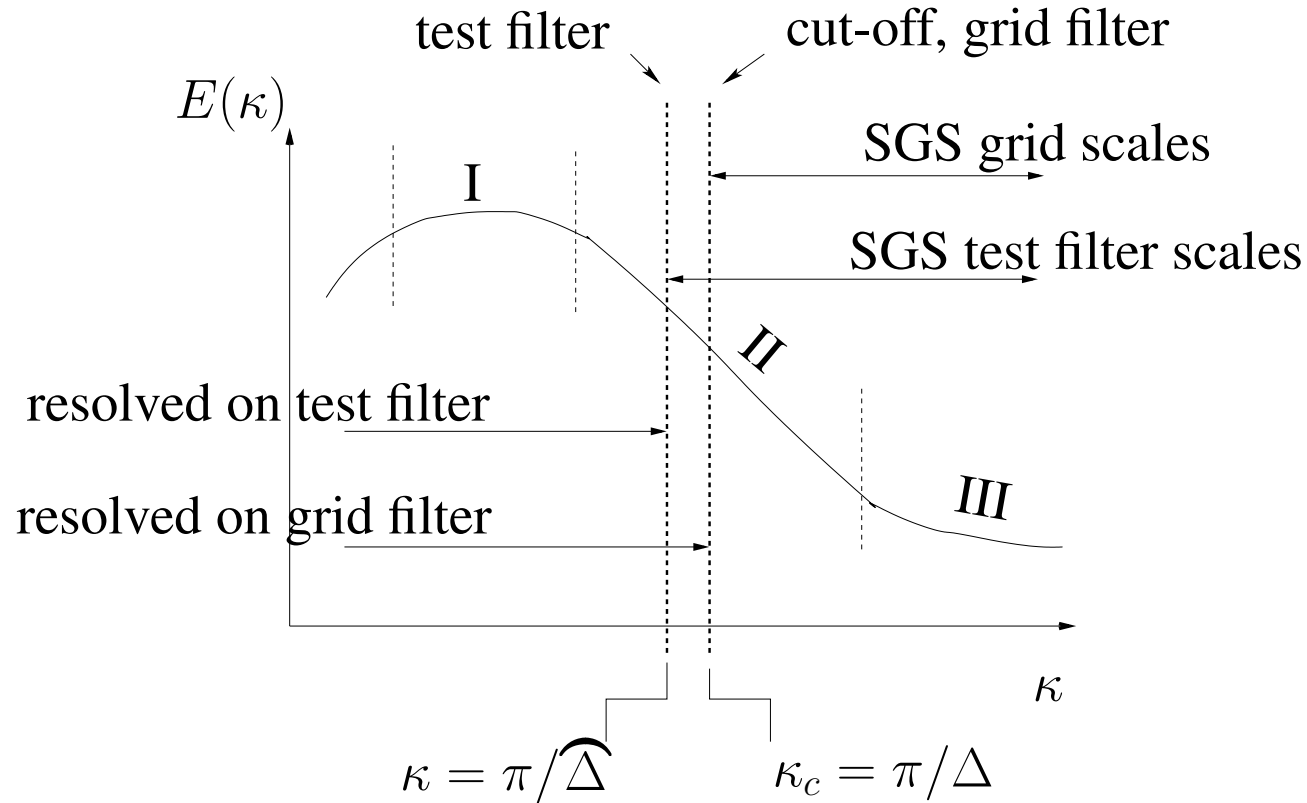
$$\mathcal{L}_{ij} = T_{ij} - \widehat{\tau}_{ij}$$

See Section 18.13, Stresses on grid, test and intermediate level



$$\begin{aligned} \tau_{ij} &= \overline{v_i v_j} - \bar{v}_i \bar{v}_j && \text{stresses with } \ell < \Delta \\ T_{ij} &= \widehat{\overline{v_i v_j}} - \widehat{\bar{v}}_i \widehat{\bar{v}}_j && \text{stresses with } \ell < \widehat{\Delta} \\ \mathcal{L}_{ij} &= T_{ij} - \widehat{\tau}_{ij} && \text{stresses with } \Delta < \ell < \widehat{\Delta} \end{aligned}$$

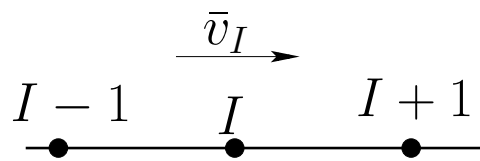
See Section 18.13, Stresses on grid, test and intermediate level



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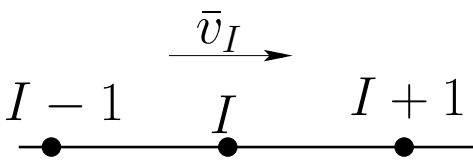
¶ See Section 18.20, Numerical method

See Section 18.20, Numerical method



(37.9)

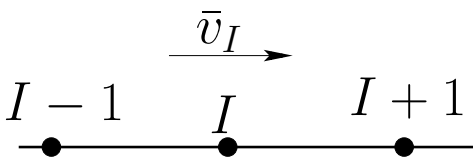
See Section 18.20, Numerical method

$$\bar{v}_I \left(\frac{\partial \bar{v}}{\partial x} \right)_{exact} =$$


The diagram shows a horizontal line representing a 1D grid. Three nodes are marked with black dots on the line, labeled $I-1$, I , and $I+1$ from left to right. Above the line, an arrow points from the node at I to the node at $I+1$, and is labeled \bar{v}_I .

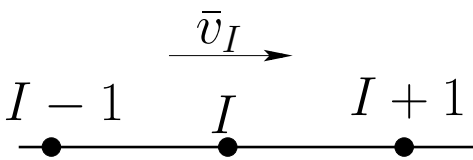
(37.9)

¶ See Section 18.20, Numerical method


$$\bar{v}_I \left(\frac{\partial \bar{v}}{\partial x} \right)_{exact} = \bar{v}_I \left(\frac{\bar{v}_I - \bar{v}_{I-1}}{\Delta x} + \mathcal{O}(\Delta x) \right) \quad (37.9)$$

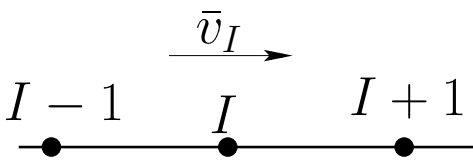
(37.10)

See Section 18.20, Numerical method


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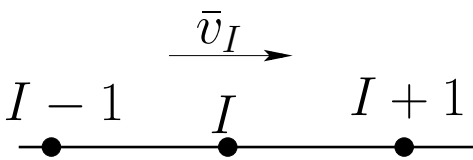
$$\bar{v}_{I-1} = \quad (37.10)$$

See Section 18.20, Numerical method


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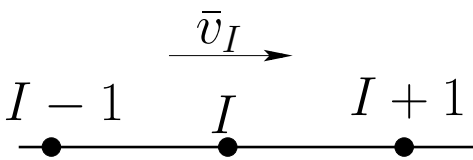
$$\bar{v}_{I-1} = \bar{v}_I - \Delta x \left(\frac{\partial \bar{v}}{\partial x} \right)_I + \quad (37.10)$$

See Section 18.20, Numerical method


$$\bar{v}_I \left(\frac{\partial \bar{v}}{\partial x} \right)_{exact} = \bar{v}_I \left(\frac{\bar{v}_I - \bar{v}_{I-1}}{\Delta x} + \mathcal{O}(\Delta x) \right) \quad (37.9)$$

$$\bar{v}_{I-1} = \bar{v}_I - \Delta x \left(\frac{\partial \bar{v}}{\partial x} \right)_I + \frac{1}{2} (\Delta x)^2 \left(\frac{\partial^2 \bar{v}}{\partial x^2} \right)_I + \quad (37.10)$$

See Section 18.20, Numerical method


$$\bar{v}_I \left(\frac{\partial \bar{v}}{\partial x} \right)_{exact} = \bar{v}_I \left(\frac{\bar{v}_I - \bar{v}_{I-1}}{\Delta x} + \mathcal{O}(\Delta x) \right) \quad (37.9)$$

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See Section 18.20, Numerical method

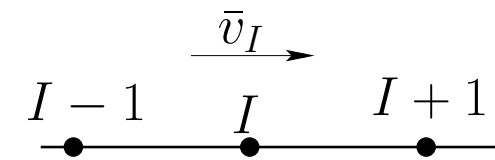
$$\begin{array}{c}
 \bar{v}_I \rightarrow \\
 I-1 \quad I \quad I+1 \\
 \bullet \quad \bullet \quad \bullet \\
 \hline
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 \end{array} \tag{37.9}$$

$$\bar{v}_{I-1} = \bar{v}_I - \Delta x \left(\frac{\partial \bar{v}}{\partial x} \right)_I + \frac{1}{2} (\Delta x)^2 \left(\frac{\partial^2 \bar{v}}{\partial x^2} \right)_I + \mathcal{O}((\Delta x)^3) \tag{37.10}$$

► Insert Eq. 37.9 into Eq. 37.9

$$\bar{v} \left(\frac{\partial \bar{v}}{\partial x} \right)_{exact} = \bar{v} \frac{\partial \bar{v}}{\partial x} - \frac{1}{2} \frac{\Delta x \bar{v} \frac{\partial^2 \bar{v}}{\partial x^2}}{\mathcal{O}(\Delta x)} + \bar{v} \mathcal{O}((\Delta x)^2)$$

See Section 18.20, Numerical method


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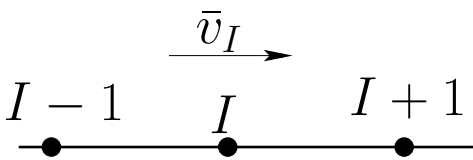
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► $\Delta x \bar{v} / 2$ acts as an additional **numerical** viscosity

See Section 18.20, Numerical method


$$\bar{v}_I \left(\frac{\partial \bar{v}}{\partial x} \right)_{exact} = \bar{v}_I \left(\frac{\bar{v}_I - \bar{v}_{I-1}}{\Delta x} + \mathcal{O}(\Delta x) \right) \quad (37.9)$$

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► $\Delta x \bar{v} / 2$ acts as an additional **numerical** viscosity

► The total diffusion now consists of

See Section 18.20, Numerical method

$$\begin{array}{c}
 \bar{v}_I \rightarrow \\
 I-1 \quad I \quad I+1 \\
 \bullet \quad \bullet \quad \bullet \\
 \hline
 \bar{v}_I \left(\frac{\partial \bar{v}}{\partial x} \right)_{exact} = \bar{v}_I \left(\frac{\bar{v}_I - \bar{v}_{I-1}}{\Delta x} + \mathcal{O}(\Delta x) \right)
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► $\Delta x \bar{v} / 2$ acts as an additional **numerical** viscosity

► The total diffusion now consists of

$$\text{diffusion term} = \frac{\partial}{\partial x} \left\{ (\nu + \nu_{sgs} + \nu_{num}) \frac{\partial \bar{v}}{\partial x} \right\}$$

See Section 18.20, Numerical method

$$\begin{array}{c}
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► Insert Eq. 37.9 into Eq. 37.9

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► And the total dissipation

See Section 18.20, Numerical method

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 \bar{v}_I \rightarrow \\
 I-1 \quad I \quad I+1 \\
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► The total diffusion now consists of

$$\text{diffusion term} = \frac{\partial}{\partial x} \left\{ (\nu + \nu_{sgs} + \nu_{num}) \frac{\partial \bar{v}}{\partial x} \right\}$$

► And the total dissipation

$$\varepsilon_{tot} = 2(\nu + \nu_{sgs} + \nu_{num}) \bar{s}_{ij} \bar{s}_{ij}$$

On-line Lecture 9

¶ See Section 18.15, Scale-similarity Models

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$$\tau_{ij} =$$

On-line Lecture 9

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On-line Lecture 9

¶ See Section 18.15, Scale-similarity Models

$$\tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j = \overline{(\bar{v}_i + v_i'')(\bar{v}_j + v_j'')} -$$

On-line Lecture 9

¶ See Section 18.15, Scale-similarity Models

$$\tau_{ij} = \overline{v_i v_j} - \bar{v}_i \bar{v}_j = \overline{(\bar{v}_i + v_i'')(\bar{v}_j + v_j'')} - \bar{v}_i \bar{v}_j$$

On-line Lecture 9

¶ See Section 18.15, Scale-similarity Models

$$\begin{aligned}\tau_{ij} &= \overline{v_i v_j} - \bar{v}_i \bar{v}_j = \overline{(\bar{v}_i + v_i'')(\bar{v}_j + v_j'')} - \bar{v}_i \bar{v}_j \\ &= \end{aligned}$$

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On-line Lecture 9

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On-line Lecture 9

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On-line Lecture 9

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- Small isotropic scales:

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► Replace ε by ν_{sgs} and Δ .

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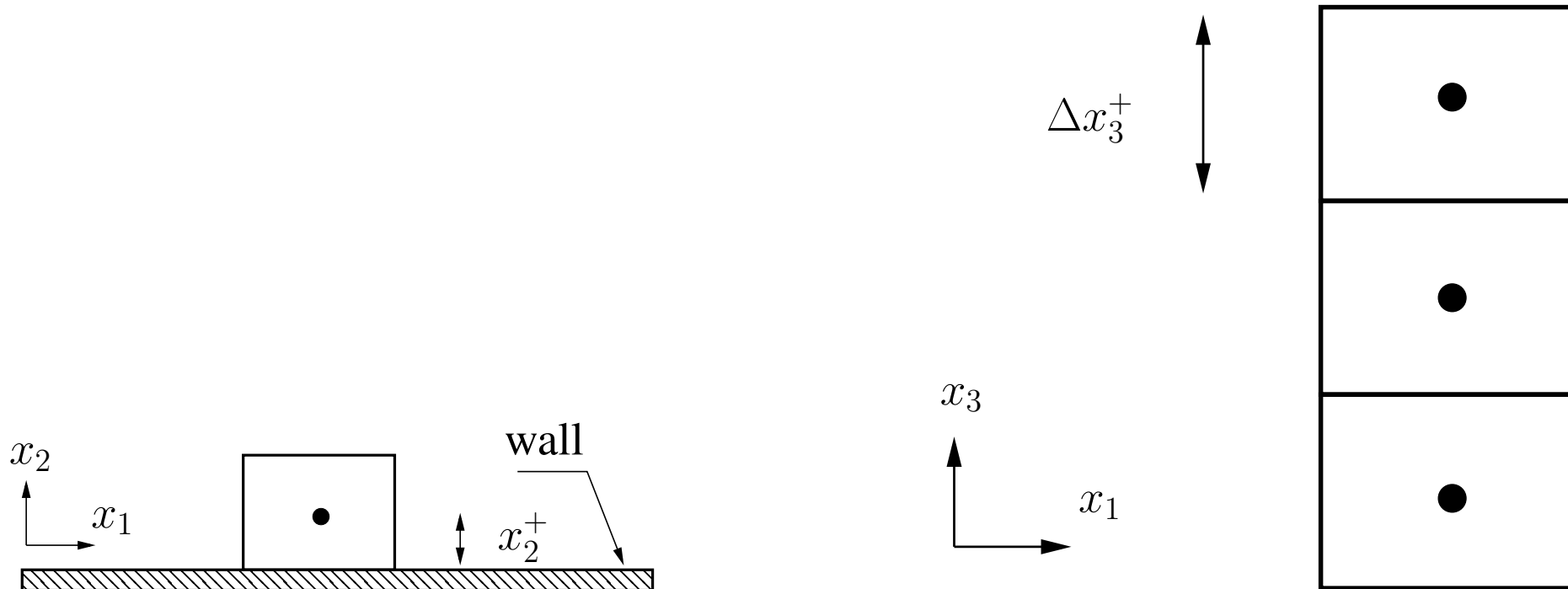
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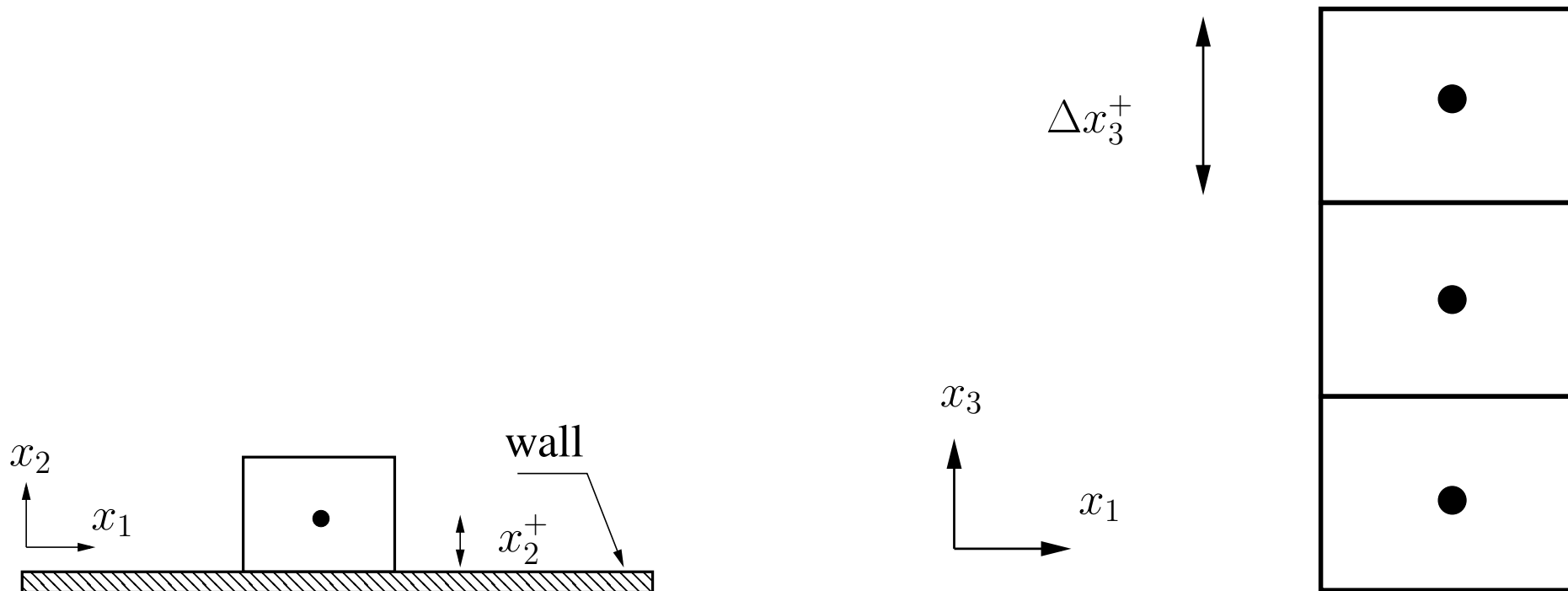


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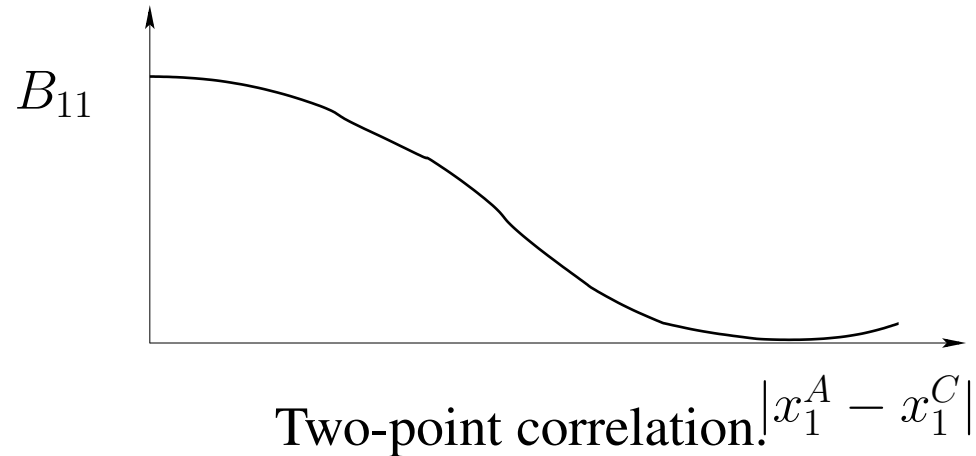
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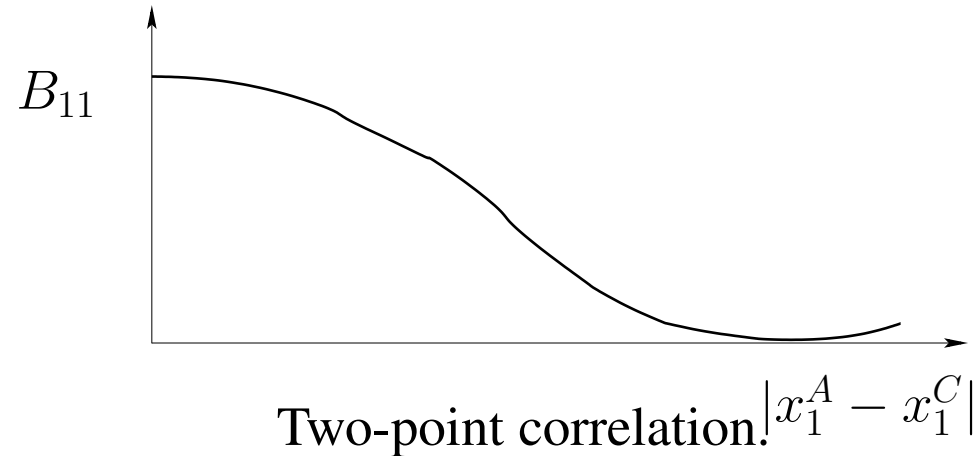
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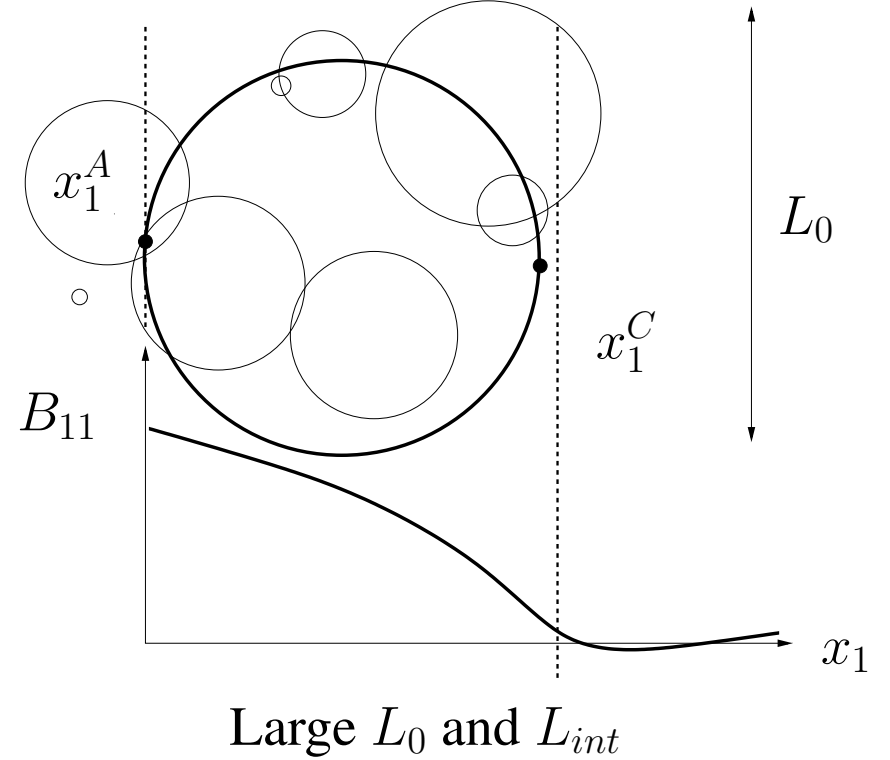
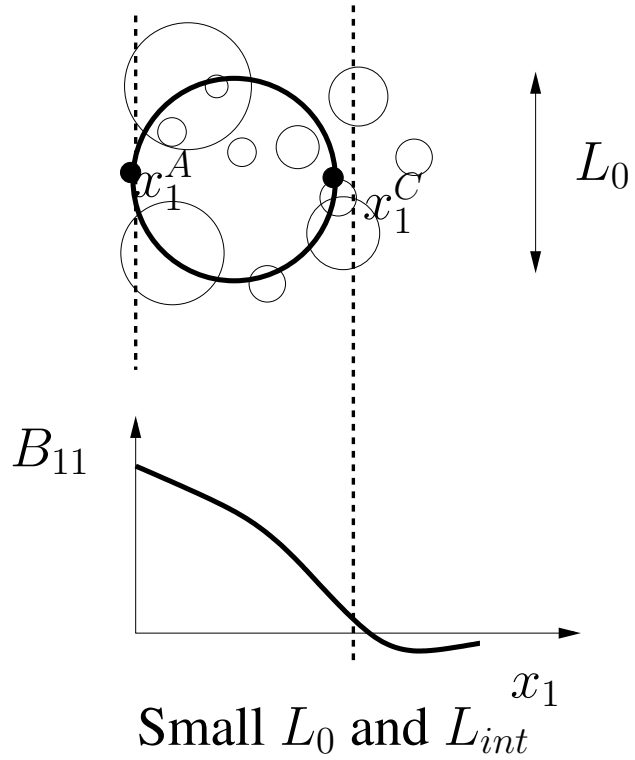
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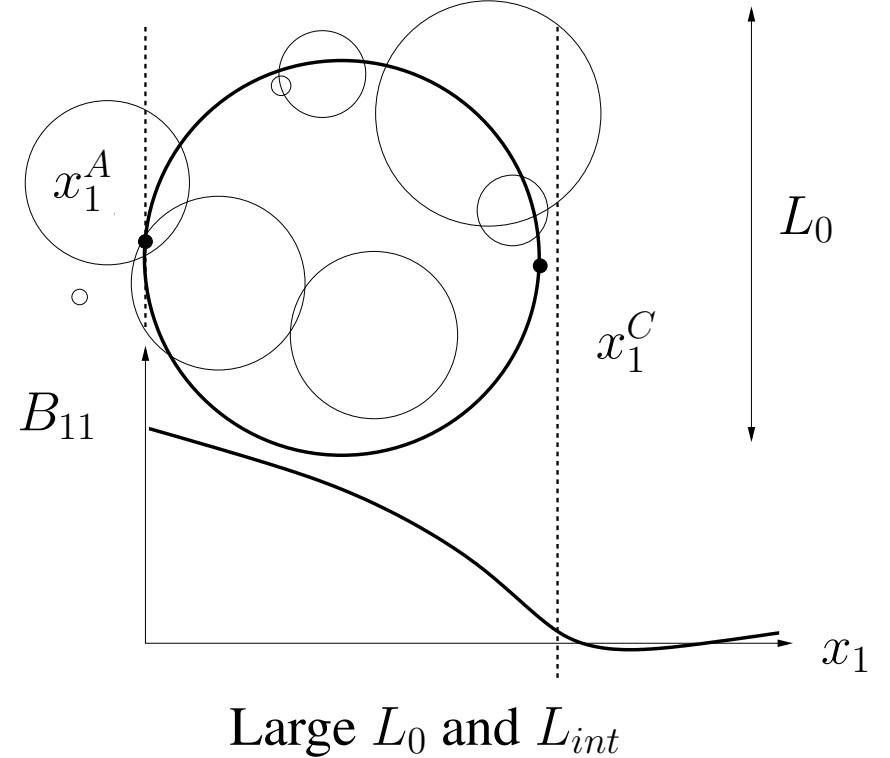
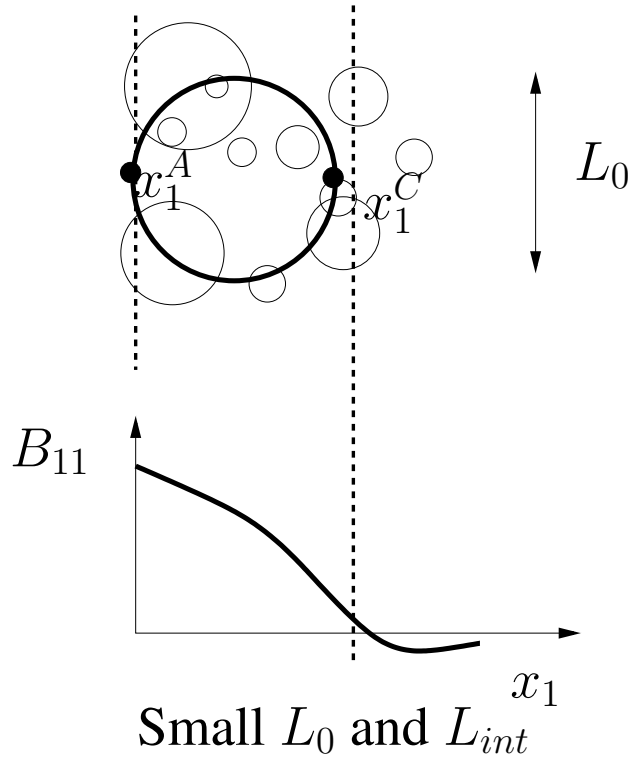
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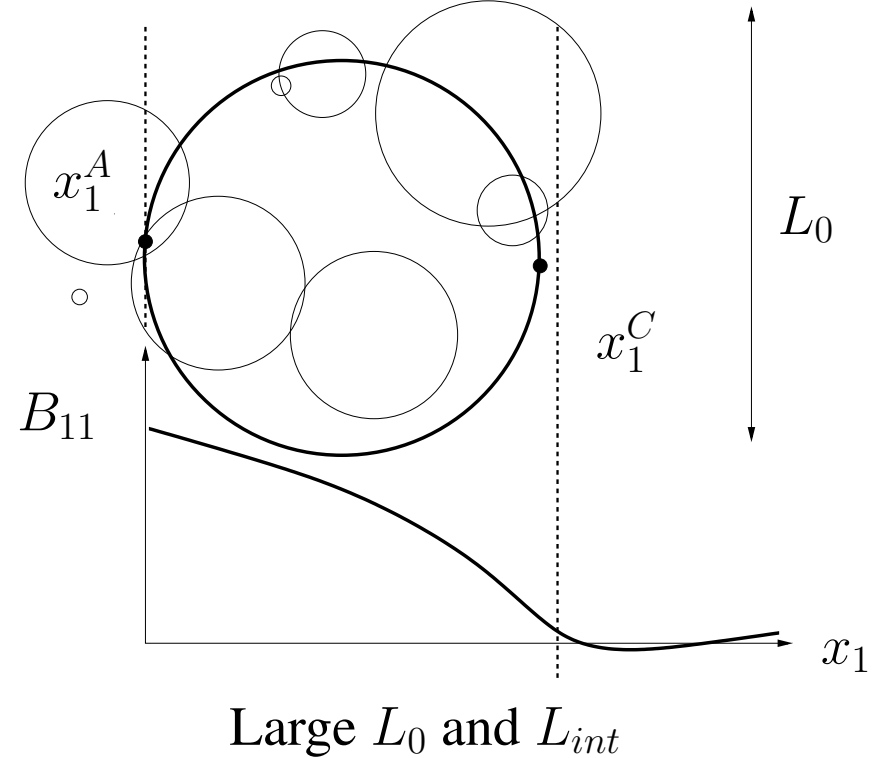
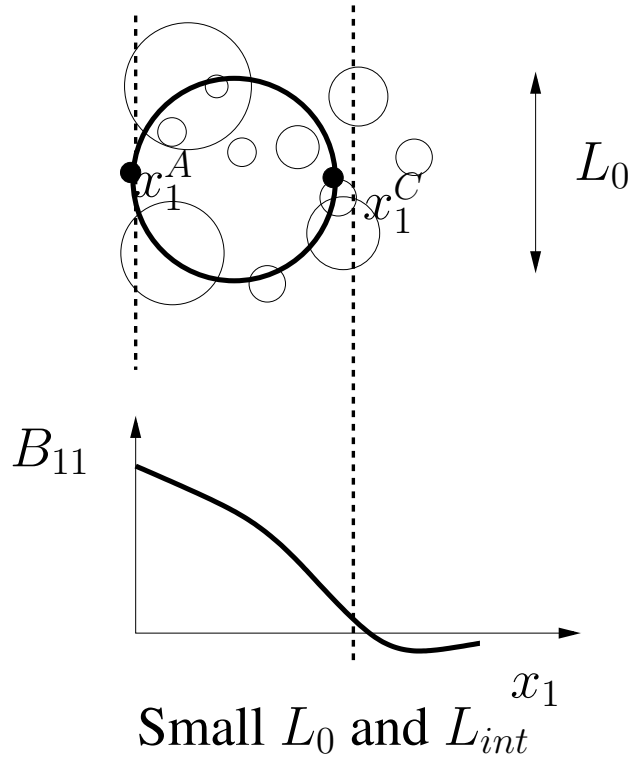


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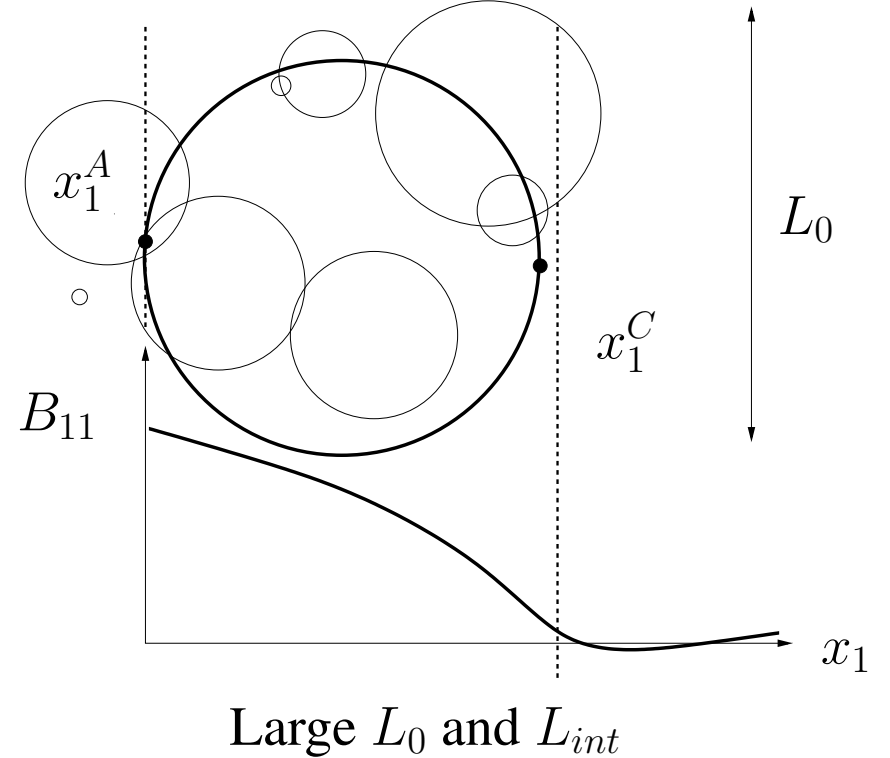
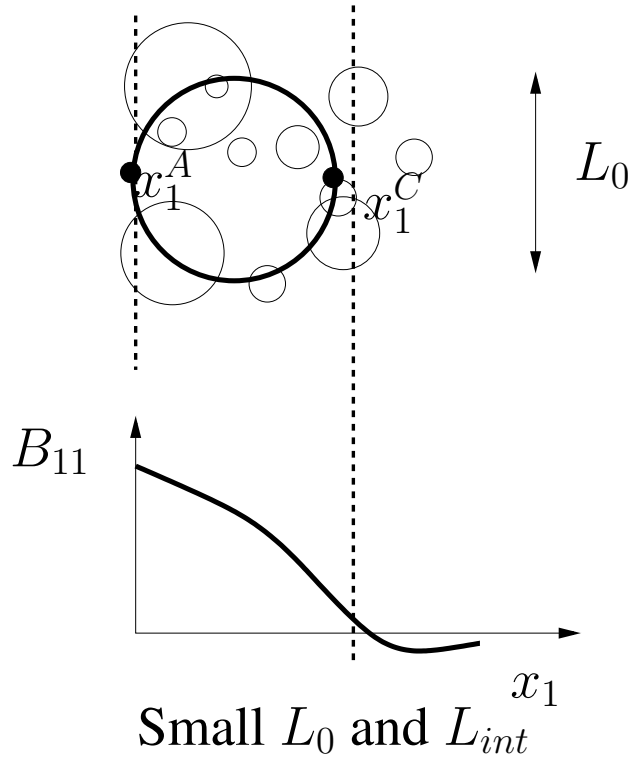
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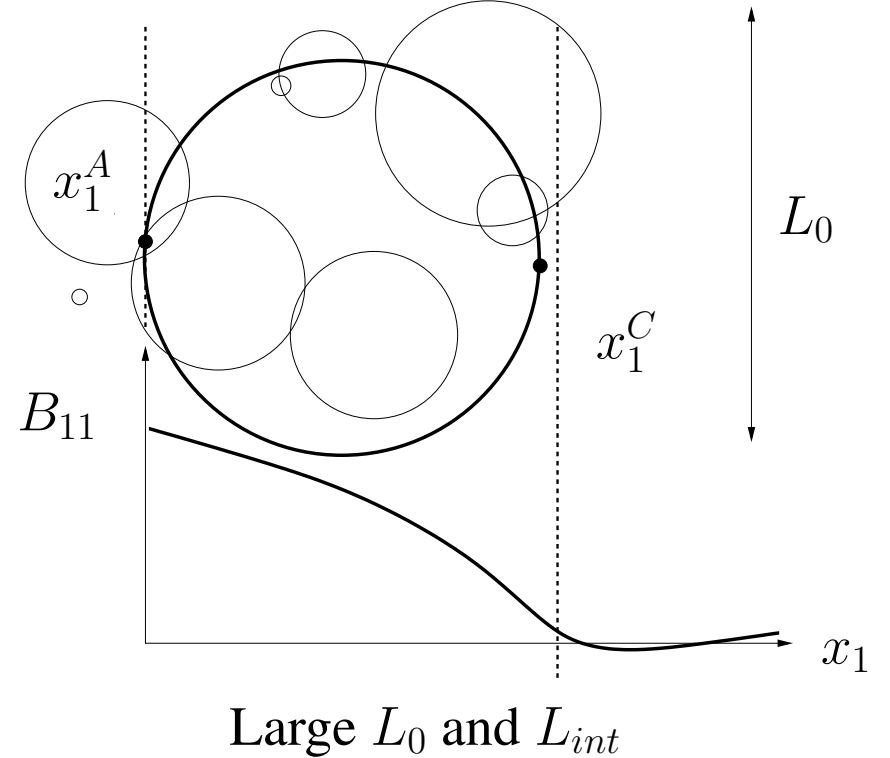
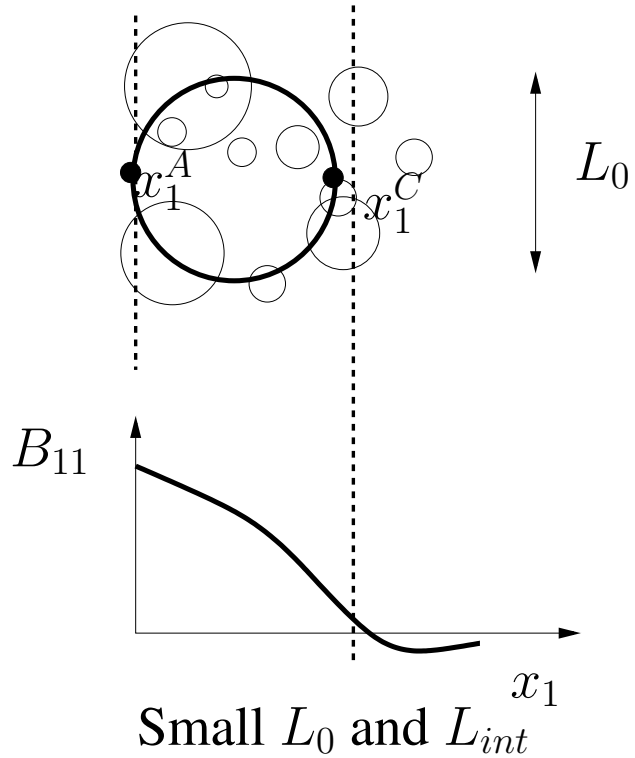
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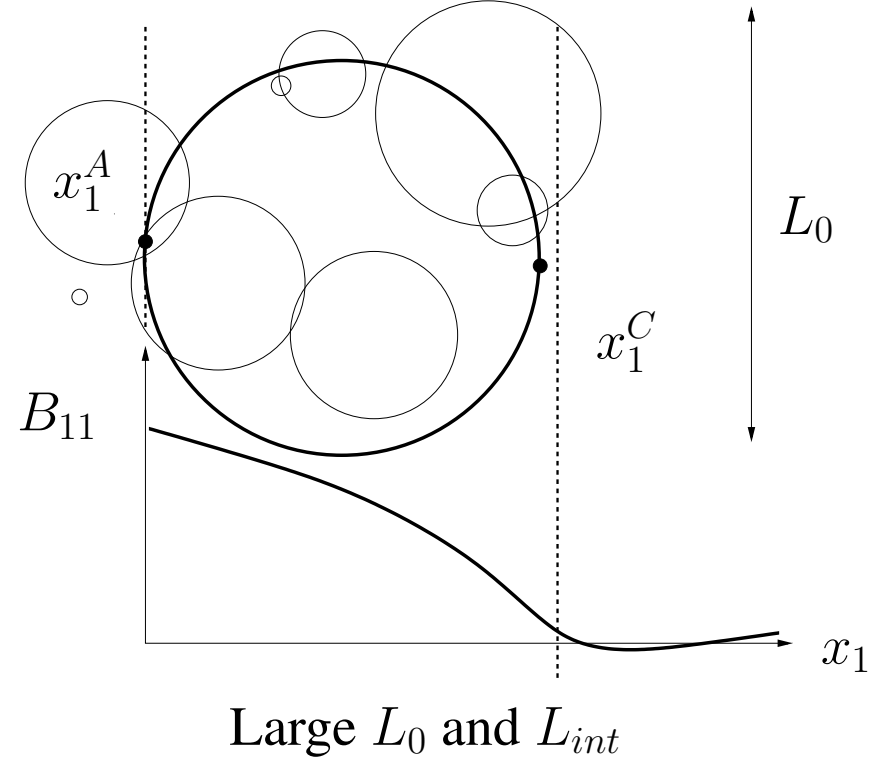
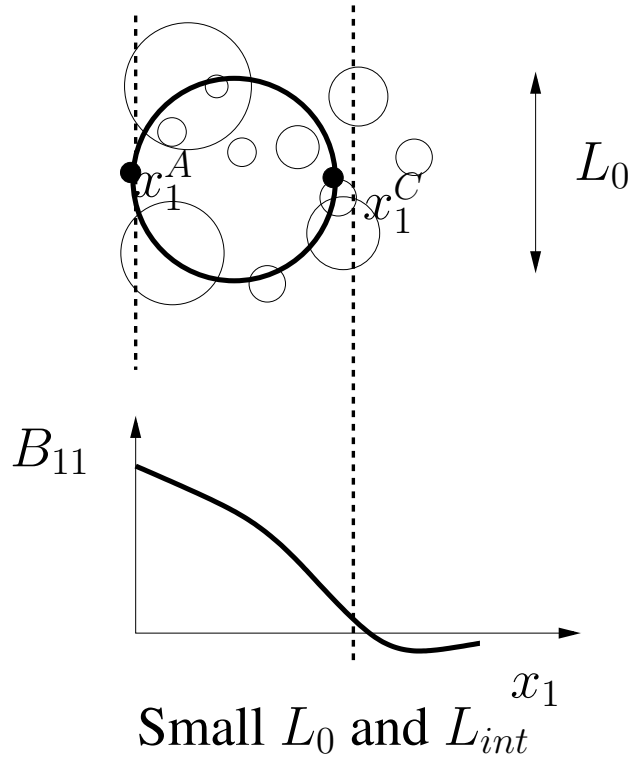
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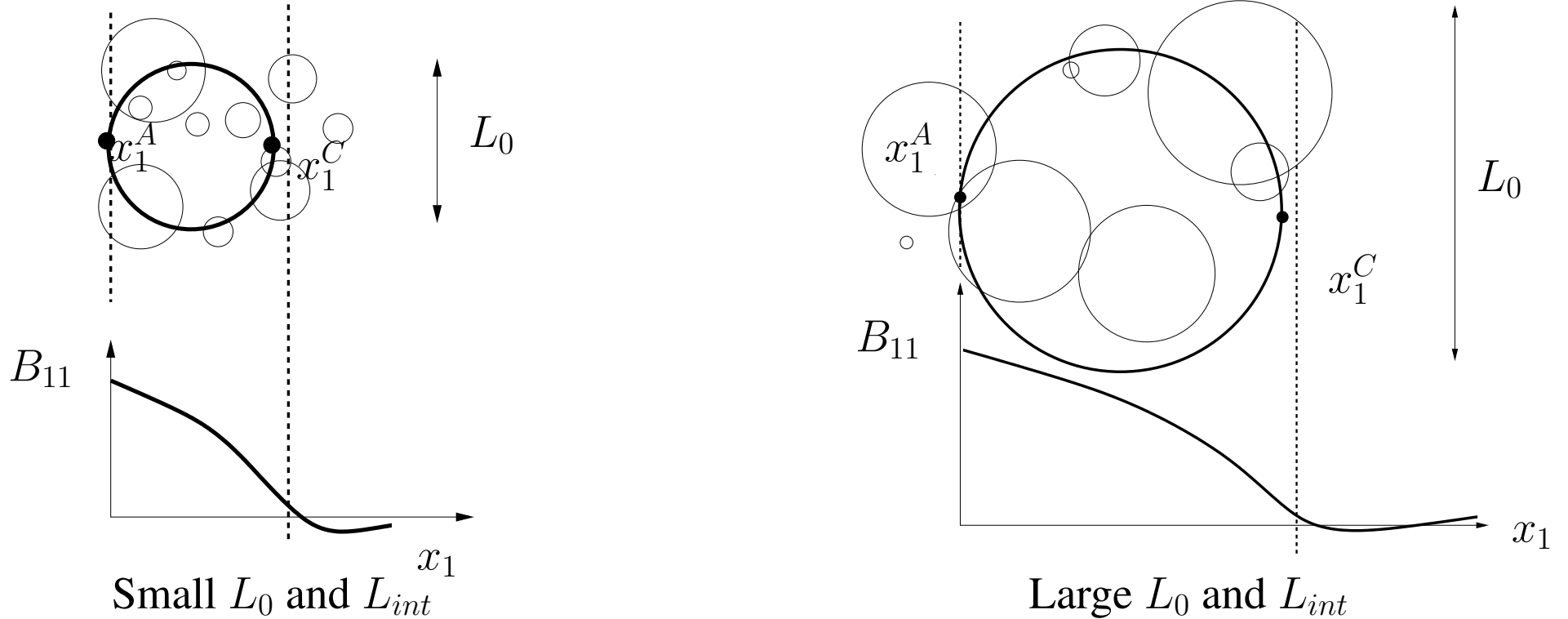
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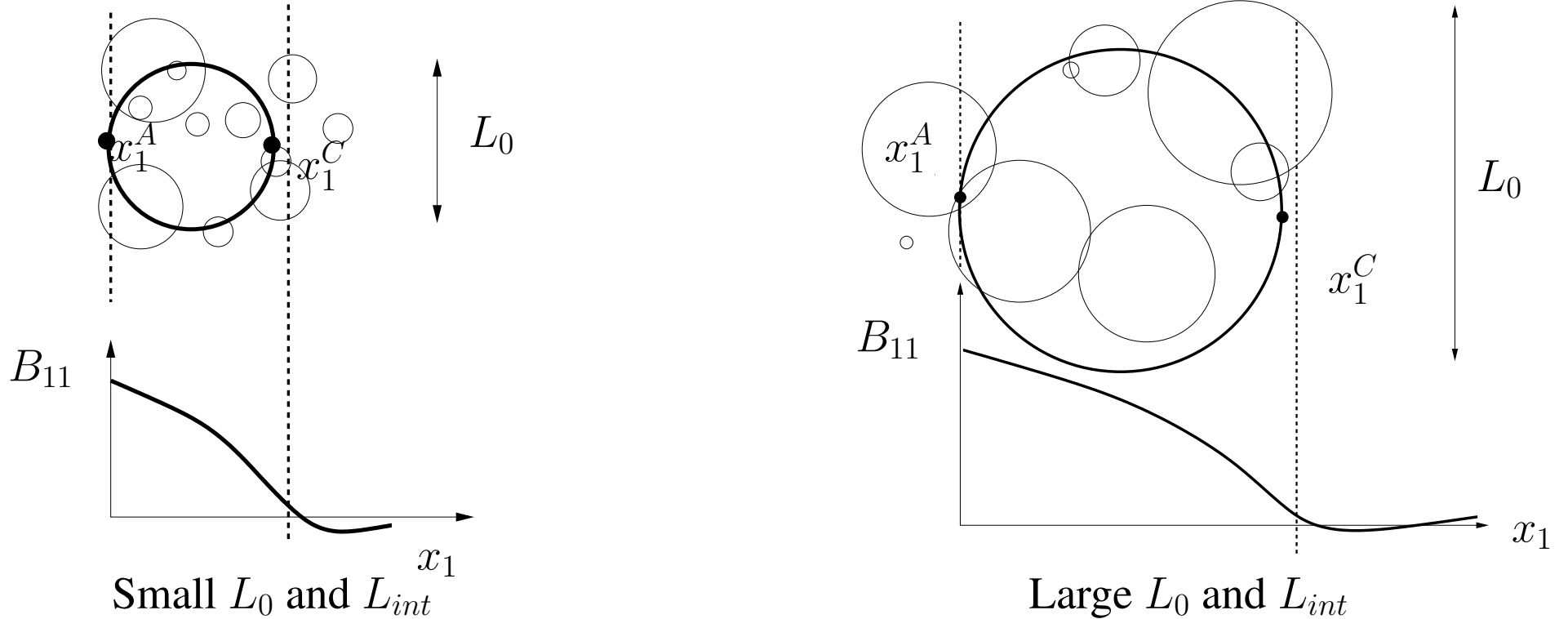
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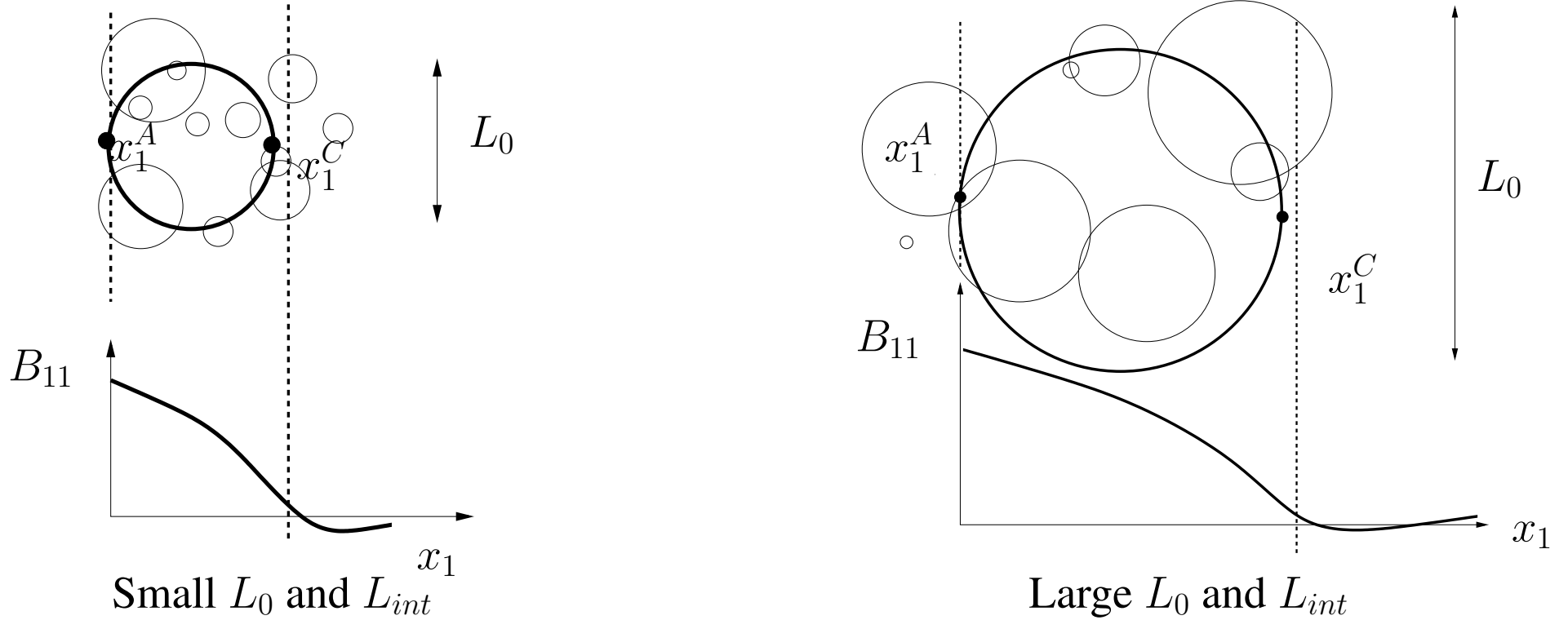
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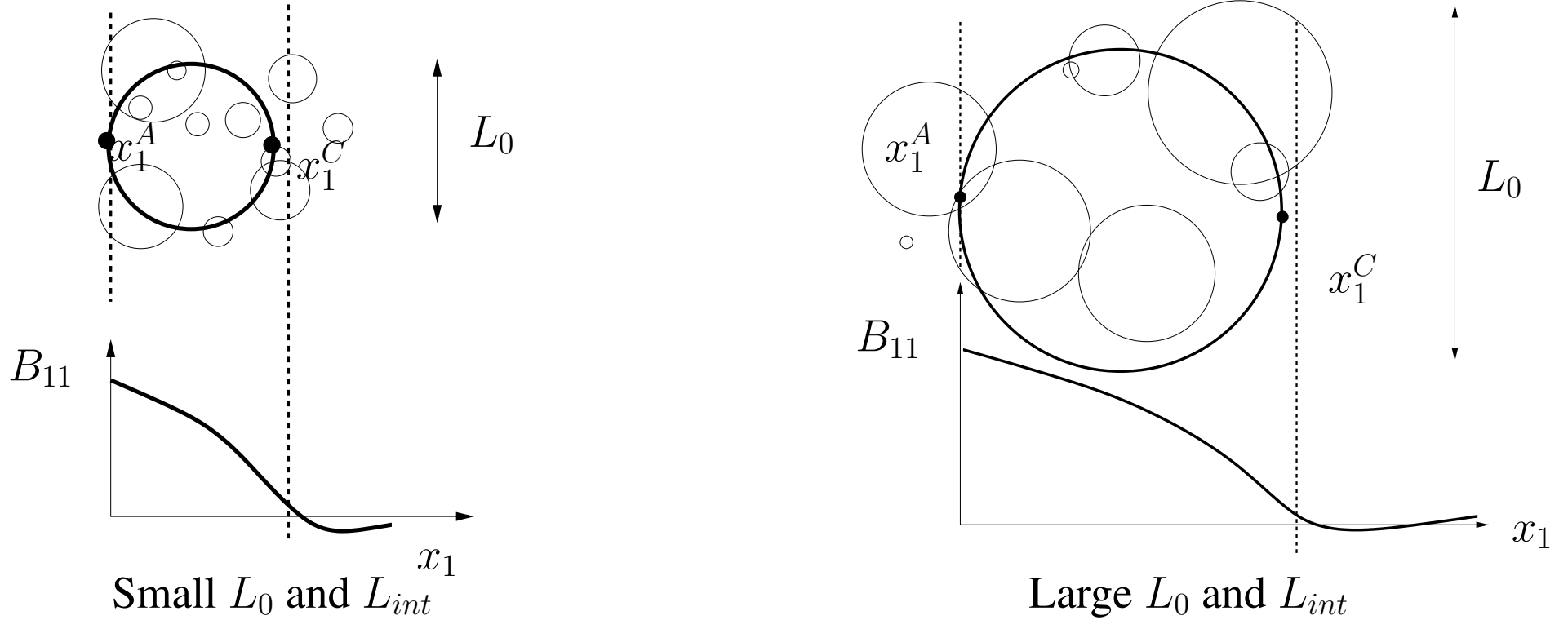


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$$T_{int} = \int_0^{\infty} B_{11}^{norm}(\hat{t}) d\hat{t}$$

▶ Integral timescale is used in Assignment 2a for finding time samples that are *independent* (i.e. the time between the samples is at least one integral timescale).

¶ See Section 18.20.1, RANS vs. LES

¶ See Section [18.20.1](#), [RANS vs. LES](#)

▶ Numerical method: RANS vs. LES



¶ See Section 18.20.1, [RANS vs. LES](#)

▶ Numerical method: RANS vs. LES

	RANS	

¶ See Section [18.20.1](#), [RANS vs. LES](#)

▶ Numerical method: RANS vs. LES

	RANS	LES

¶ See Section [18.20.1](#), [RANS vs. LES](#)

▶ Numerical method: RANS vs. LES

	RANS	LES
Domain		

¶ See Section [18.20.1](#), [RANS vs. LES](#)

► Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	

¶ See Section [18.20.1](#), [RANS vs. LES](#)

▶ Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D

¶ See Section 18.20.1, RANS vs. LES

▶ Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D
Time domain		

See Section 18.20.1, RANS vs. LES

► Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D
Time domain	steady or unsteady	

¶ See Section [18.20.1](#), [RANS vs. LES](#)

▶ Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D
Time domain	steady or unsteady	always unsteady

¶ See Section 18.20.1, [RANS vs. LES](#)

▶ Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D
Time domain	steady or unsteady	always unsteady
Space discretization		

¶ See Section 18.20.1, [RANS vs. LES](#)

▶ Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D
Time domain	steady or unsteady	always unsteady
Space discretization	2nd order upwind	

See Section 18.20.1, RANS vs. LES

► Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D
Time domain	steady or unsteady	always unsteady
Space discretization	2nd order upwind	central differencing

See Section 18.20.1, RANS vs. LES

► Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D
Time domain	steady or unsteady	always unsteady
Space discretization	2nd order upwind	central differencing
Time discretization		

See Section 18.20.1, RANS vs. LES

► Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D
Time domain	steady or unsteady	always unsteady
Space discretization	2nd order upwind	central differencing
Time discretization	1st order	

See Section 18.20.1, RANS vs. LES

► Numerical method: RANS vs. LES

	RANS	LES
Domain	2D or 3D	always 3D
Time domain	steady or unsteady	always unsteady
Space discretization	2nd order upwind	central differencing
Time discretization	1st order	2nd order (e.g. C-N)

See Section 18.20.1, RANS vs. LES

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Domain	2D or 3D	always 3D
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Turbulence model		

See Section 18.20.1, RANS vs. LES

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Turbulence model	\geq two-equations	

See Section 18.20.1, RANS vs. LES

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Domain	2D or 3D	always 3D
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Turbulence model	\geq two-equations	zero- or one-equation

See Section 18.20.1, RANS vs. LES

► Numerical method: RANS vs. LES

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Domain	2D or 3D	always 3D
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► **Start** and **end** time averaging.

See Section 18.20.1, RANS vs. LES

► Numerical method: RANS vs. LES

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Turbulence model	\geq two-equations	zero- or one-equation

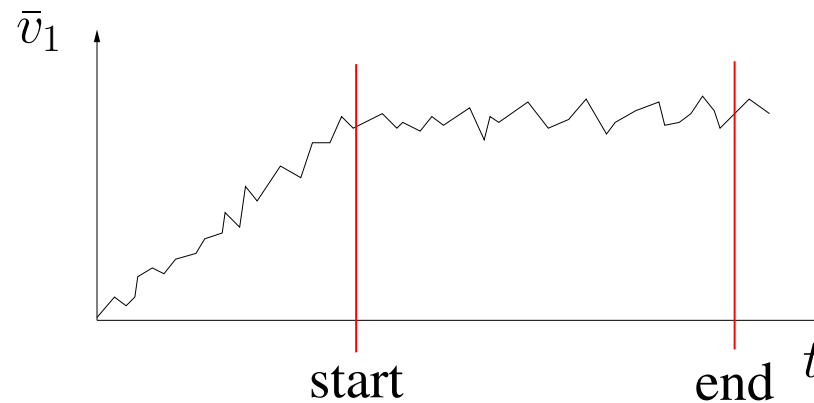
► **Start** and **end** time averaging. $t_{end} - t_{start} \simeq 100H / \langle \bar{v} \rangle_{center}$

See Section 18.20.1, RANS vs. LES

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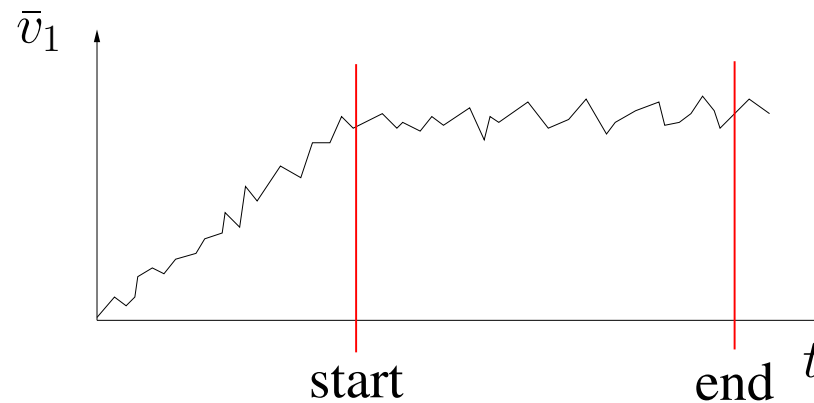


See Section 18.20.1, RANS vs. LES

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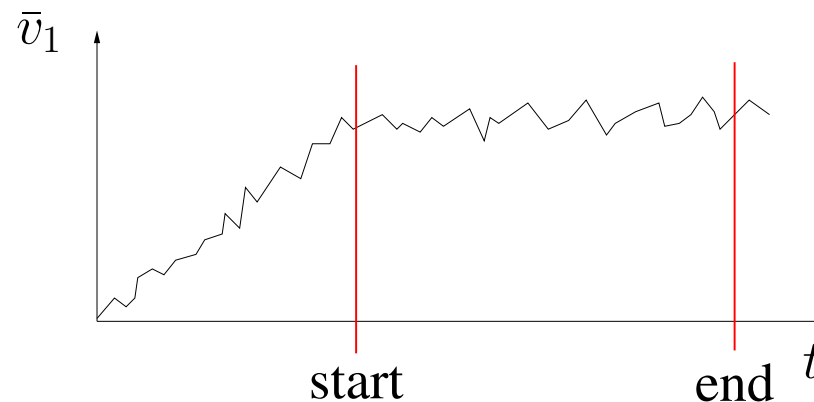
• Say that we want to store 3D inst. fields

See Section 18.20.1, RANS vs. LES

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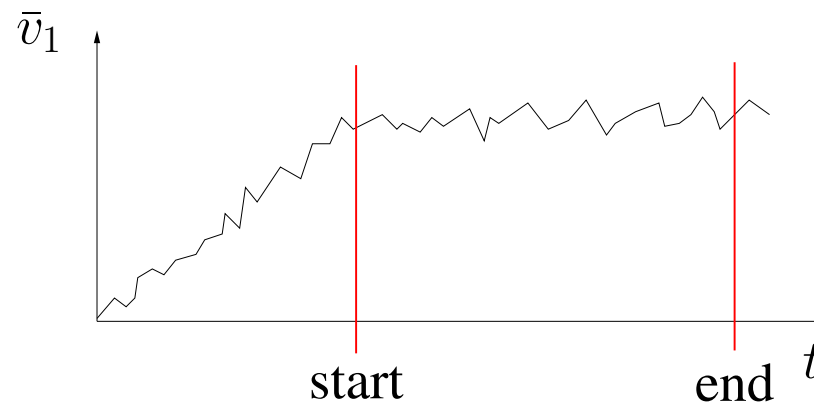
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See Section 18.20.1, RANS vs. LES

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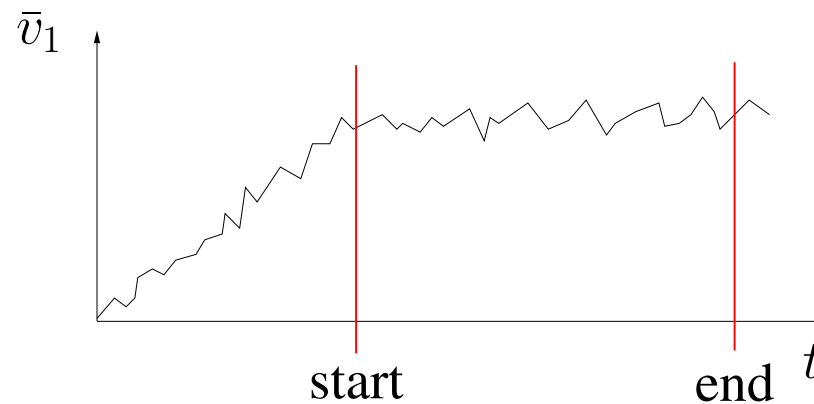
- Say that we want to store 3D inst. fields \Rightarrow we can post-proc, e.g., two-point corr anywhere
- Then we want to store as few 3D fields as possible

See Section 18.20.1, RANS vs. LES

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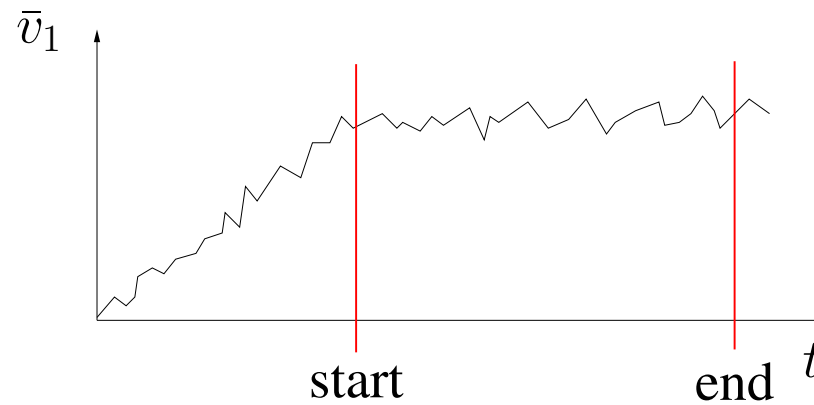
- Say that we want to store 3D inst. fields \Rightarrow we can post-proc, e.g., two-point corr anywhere
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See Section 18.20.1, RANS vs. LES

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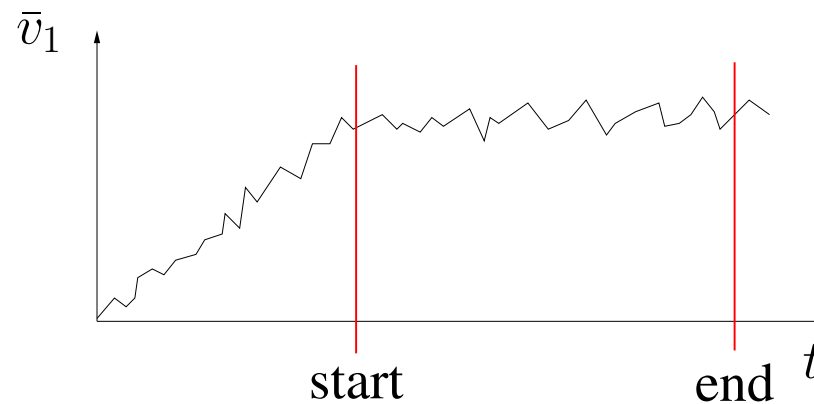
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- Answer: store only every T_{int} second:

See Section 18.20.1, RANS vs. LES

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¶ See Section 19, URANS: Unsteady RANS

¶ See Section 19, [URANS: Unsteady RANS](#)

▶ The usual Reynolds decomposition is employed

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¶ See Section 19, [URANS: Unsteady RANS](#)

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$$\bar{v}(t) = \frac{1}{2T} \int_{t-T}^{t+T} v(t) dt$$

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$$\bar{v}(t) = \frac{1}{2T} \int_{t-T}^{t+T} v(t) dt, \quad v = \bar{v} + v''$$

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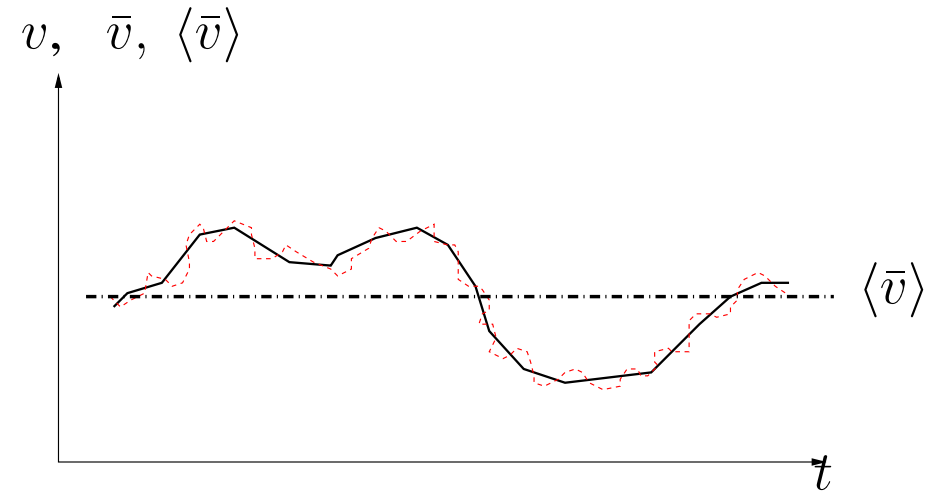
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Decomposition in URANS. —: \bar{v} ; - - : v ; - · - : $\langle \bar{v} \rangle$.

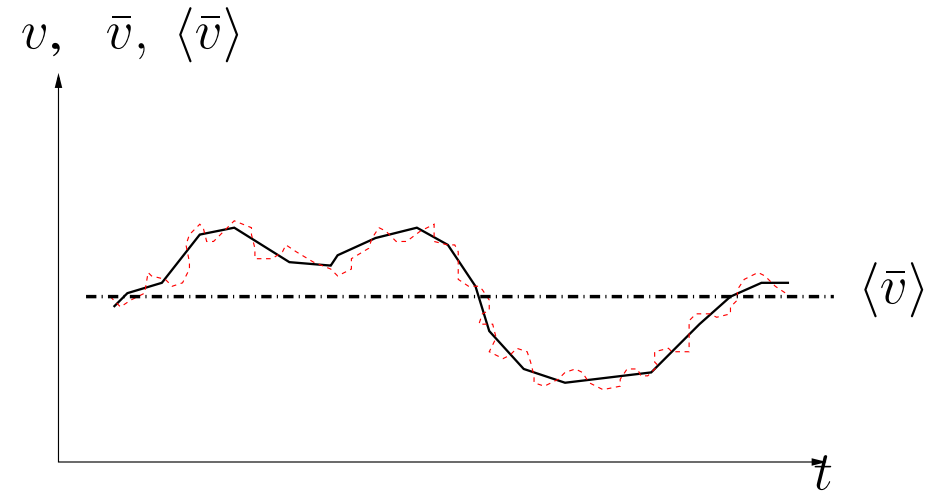


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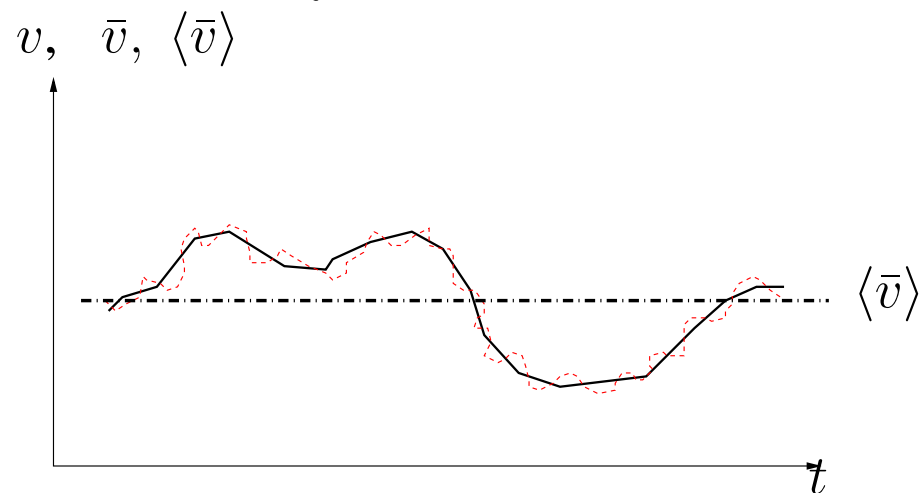
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See Section 19, URANS: Unsteady RANS

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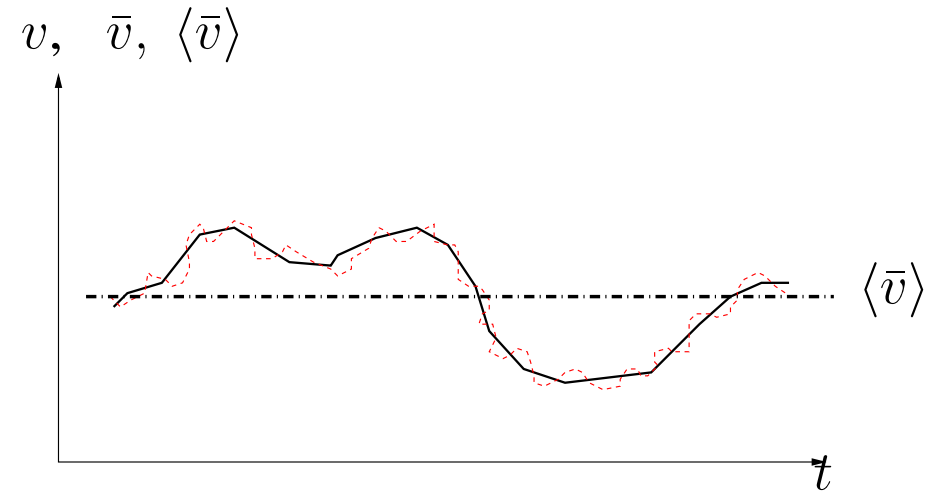
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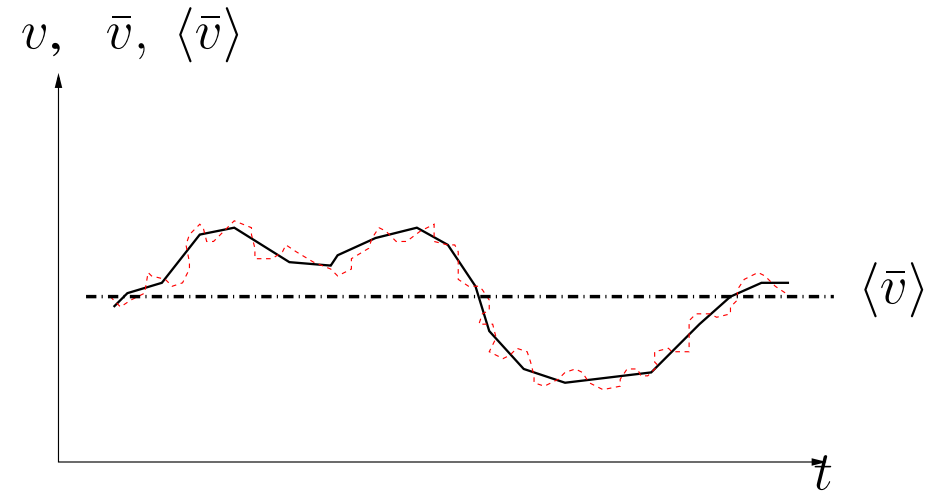
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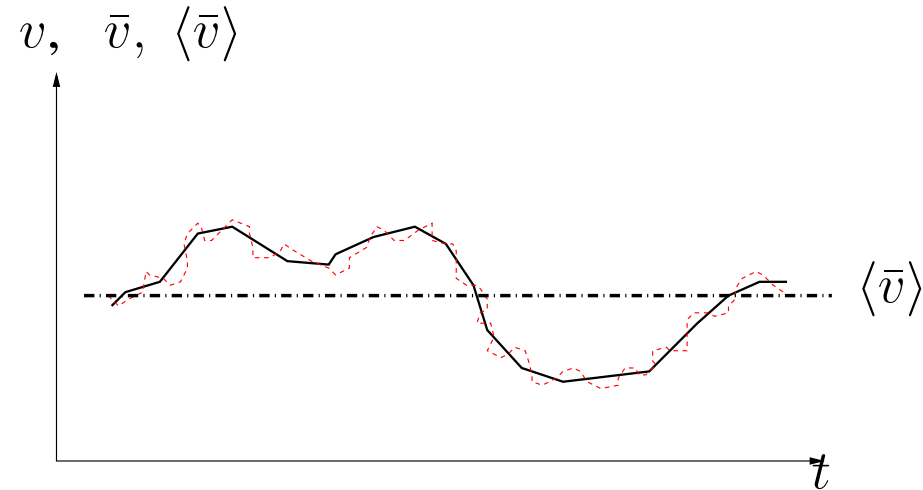
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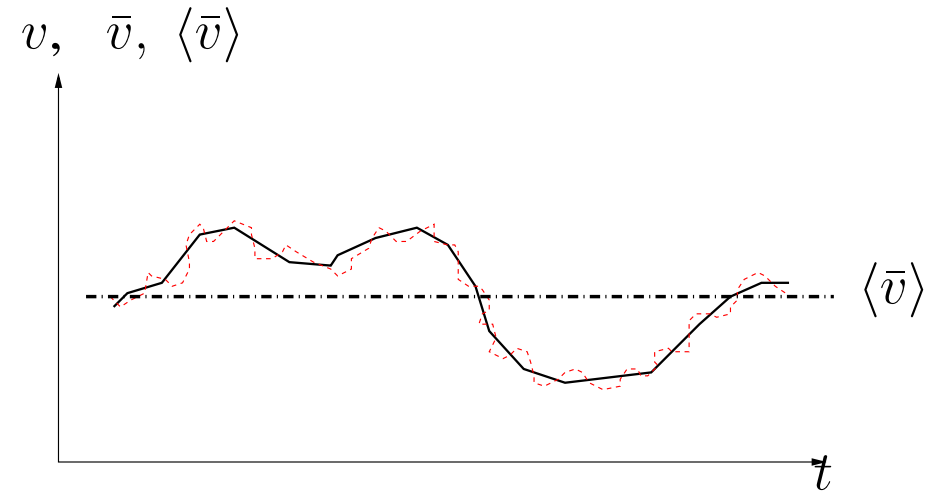
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¶ See Section 20, DES: Detached-Eddy-Simulations

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¶ See Section 20, [DES: Detached-Eddy-Simulations](#)

▶ DES=Detached Eddy Simulations:

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▶ DES=Detached Eddy Simulations: ▶ Use RANS near walls and LES away from walls

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¶ See Section 20, [DES: Detached-Eddy-Simulations](#)

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¶ See Section 20, [DES: Detached-Eddy-Simulations](#)

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▶ Replace d with \tilde{d} :

(38.2)

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$$\frac{d\rho\tilde{\nu}_t}{dt} = \frac{\partial}{\partial x_j} \left(\frac{\mu + \mu_t}{\sigma_{\tilde{\nu}_t}} \frac{\partial \tilde{\nu}_t}{\partial x_j} \right) + \text{cr. term} + P - C_{w1}\rho f_w \left(\frac{\tilde{\nu}_t}{d} \right)^2, \quad d = x_n$$

▶ Replace d with \tilde{d} :

$$\left(\frac{\tilde{\nu}_t}{d} \right)^2 \Rightarrow$$

(38.2)

¶ See Section 20, [DES: Detached-Eddy-Simulations](#)

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¶ See Section 20.1, DES based on two-equation models

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▶ $k - \varepsilon$ RANS

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On-line Lecture 10

¶ See Section 20.2, DES based on the $k - \omega$ SST model

On-line Lecture 10

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$k - \omega$ SST DES (modify $\beta^* k \omega$)

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$$C^k = D^k + P^k - F_{DES} \beta^* k \omega$$

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$k - \omega$ SST DES (modify $\beta^* k \omega$)

$$C^k = D^k + P^k - F_{DES} \beta^* k \omega, \quad F_{DES} = \max \left\{ \frac{L_t}{C_{DES} \Delta}, 1 \right\} =$$

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On-line Lecture 10

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On-line Lecture 10

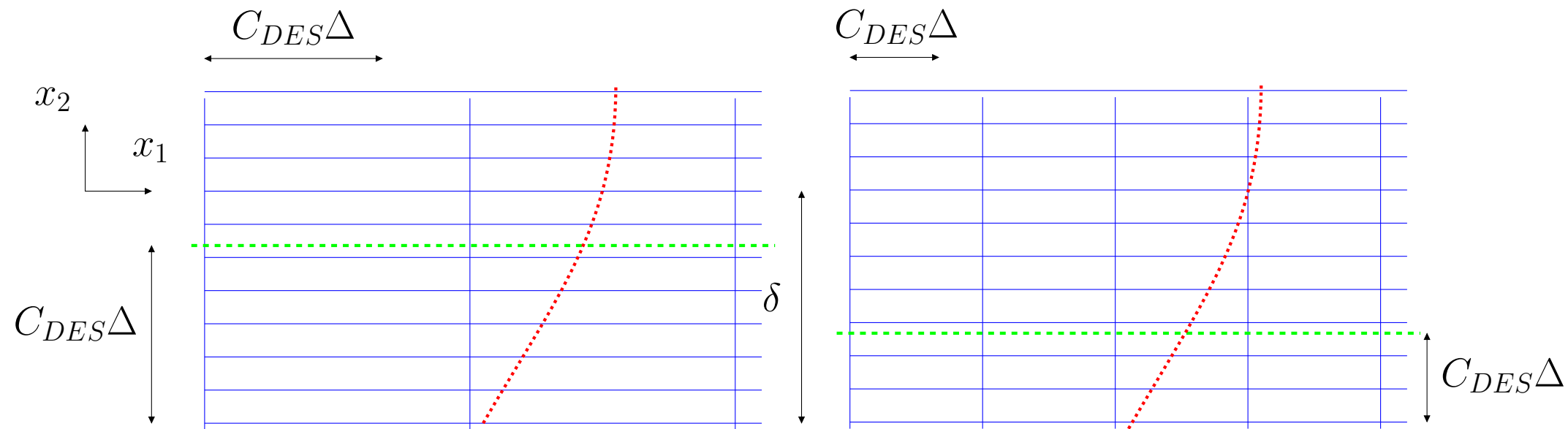
¶ See Section 20.2, DES based on the $k - \omega$ SST model

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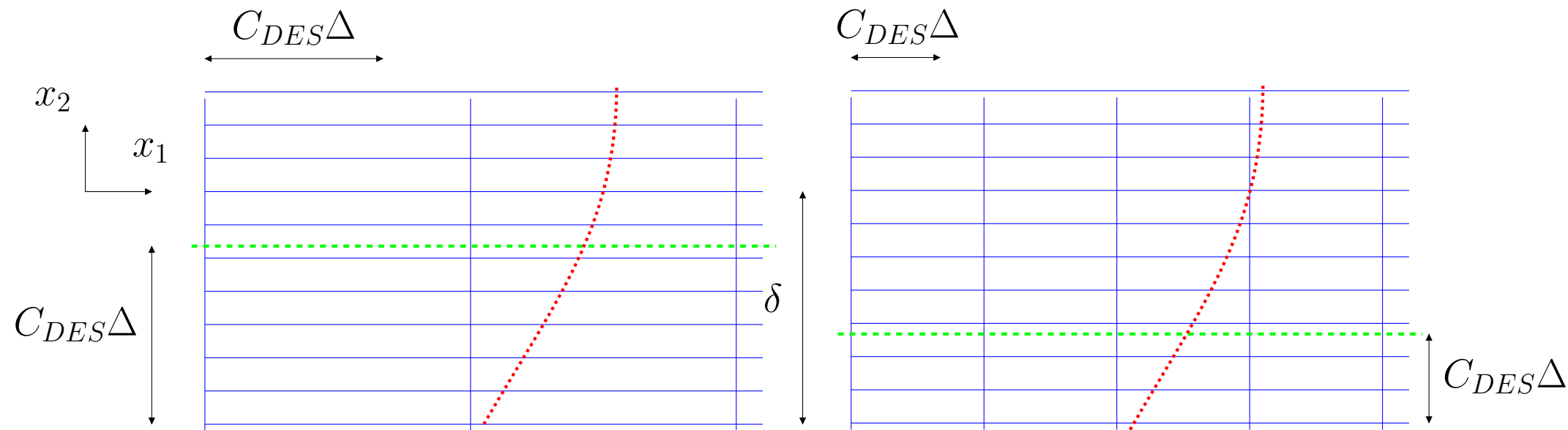
• See Section 20.3, DDES



Grid (solid lines) and a velocity profile (dotted line). RANS-LES interface: dashed line. $C_{DES} = 0.67$

•

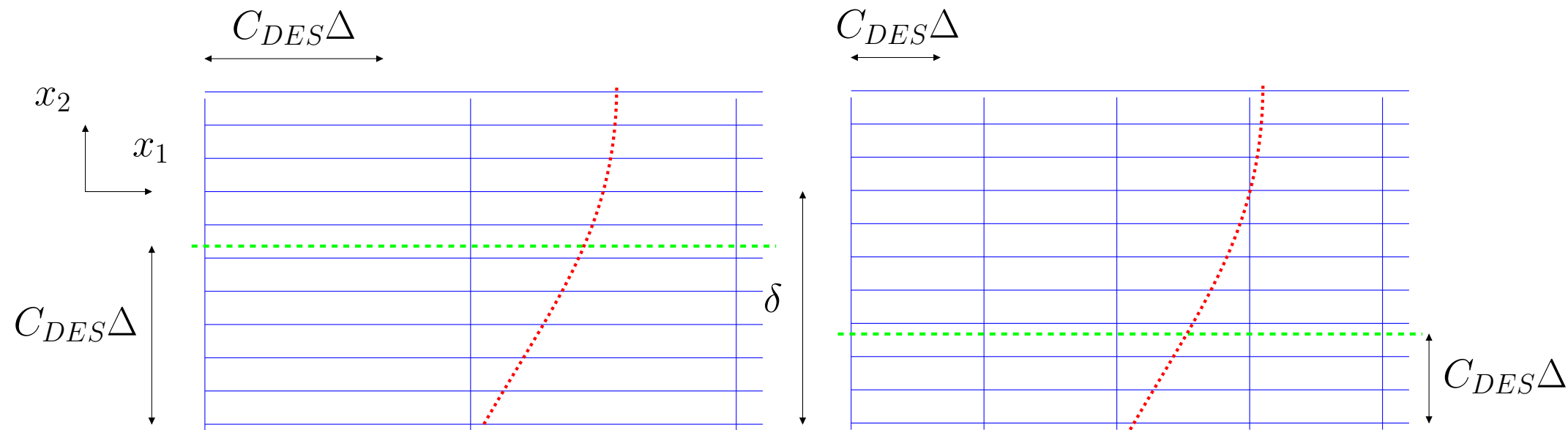
See Section 20.3, DDES



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- Consider the S-A DES (see Eq. 38.2). It may occur that the \tilde{d} switches to LES in the boundary layer because Δx_1 is too small (Δx_3 is usually smaller than Δx_1).

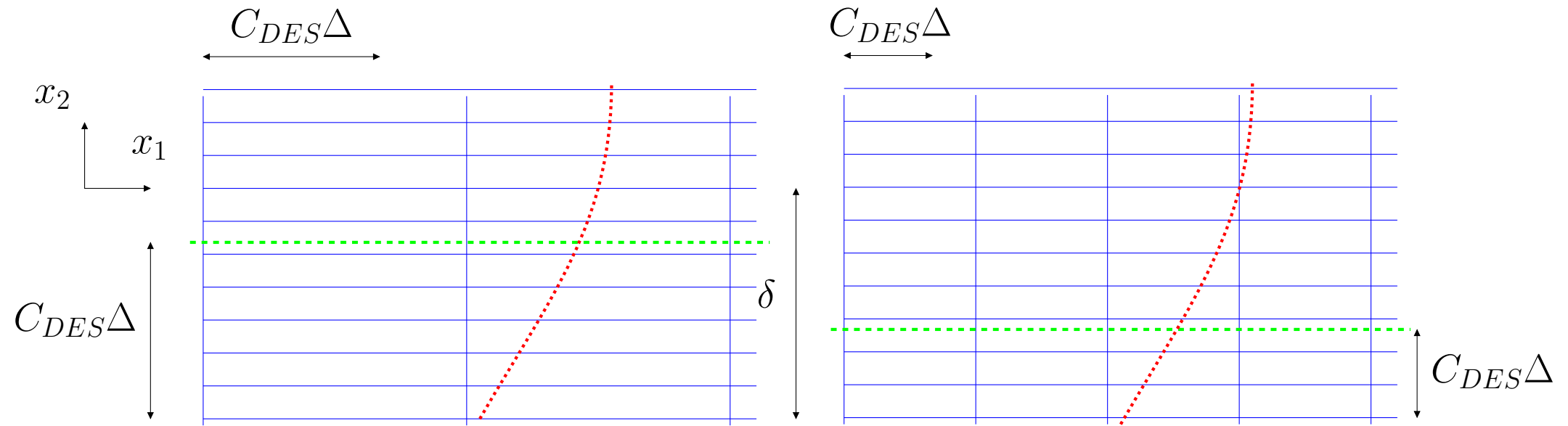
See Section 20.3, DDES



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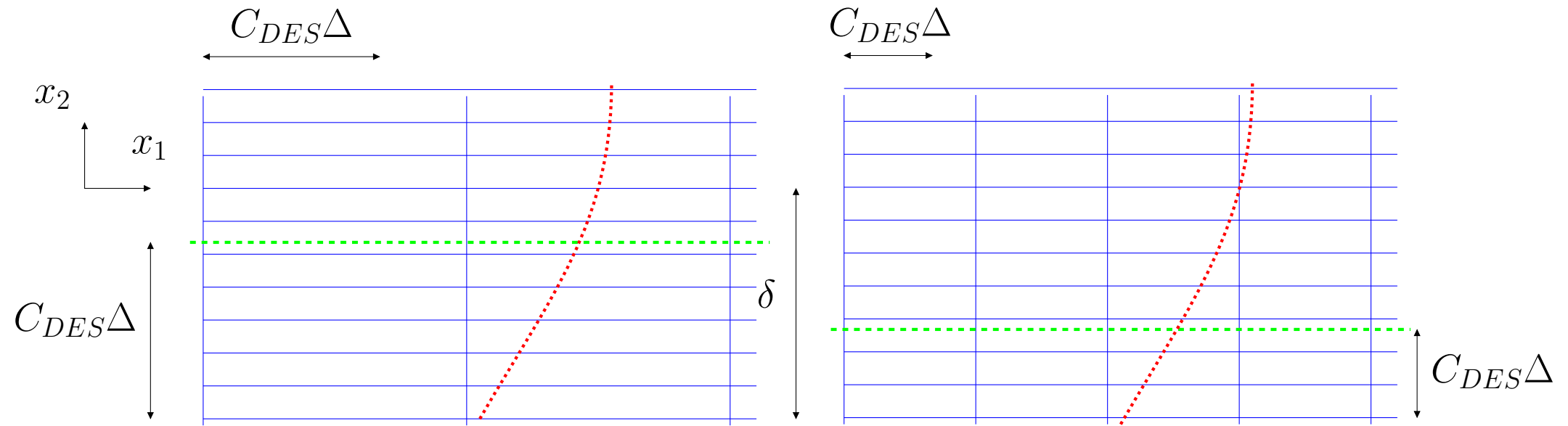
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- Hence boundary layer is treated in LES mode with too a coarse mesh

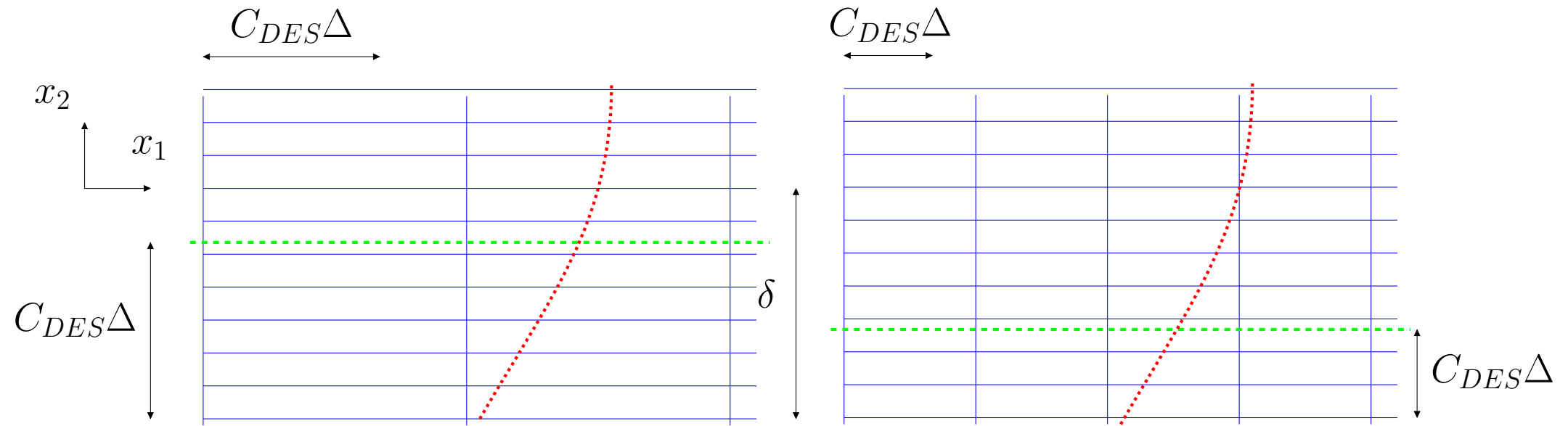
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- Hence boundary layer is treated in LES mode with too a coarse mesh \Rightarrow poorly resolved LES

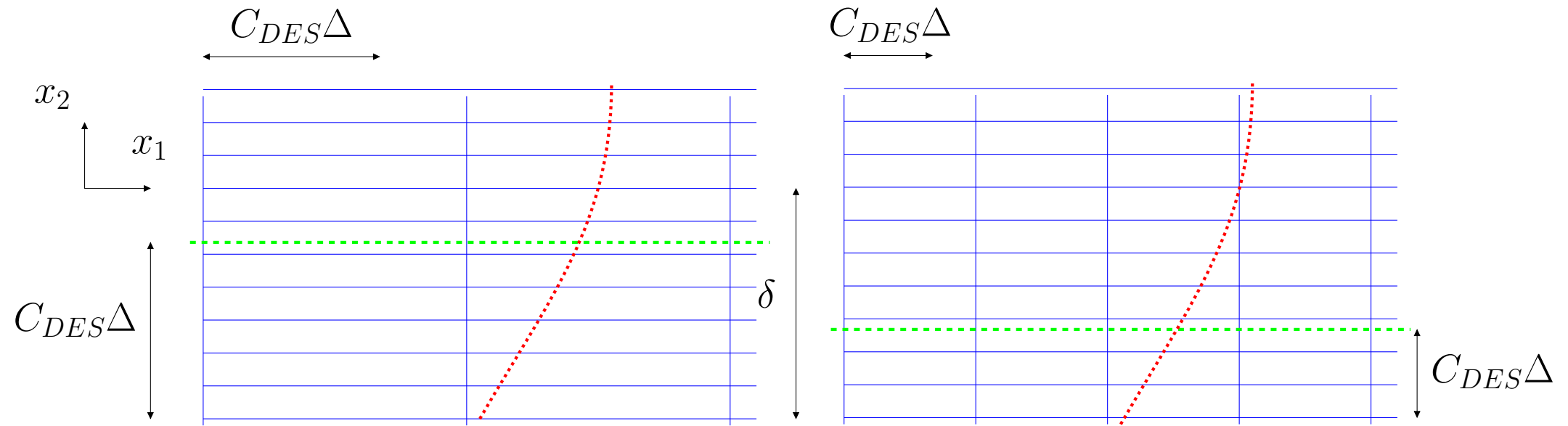
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- Hence boundary layer is treated in LES mode with too a coarse mesh \Rightarrow poorly resolved LES \Rightarrow inaccurate predictions.

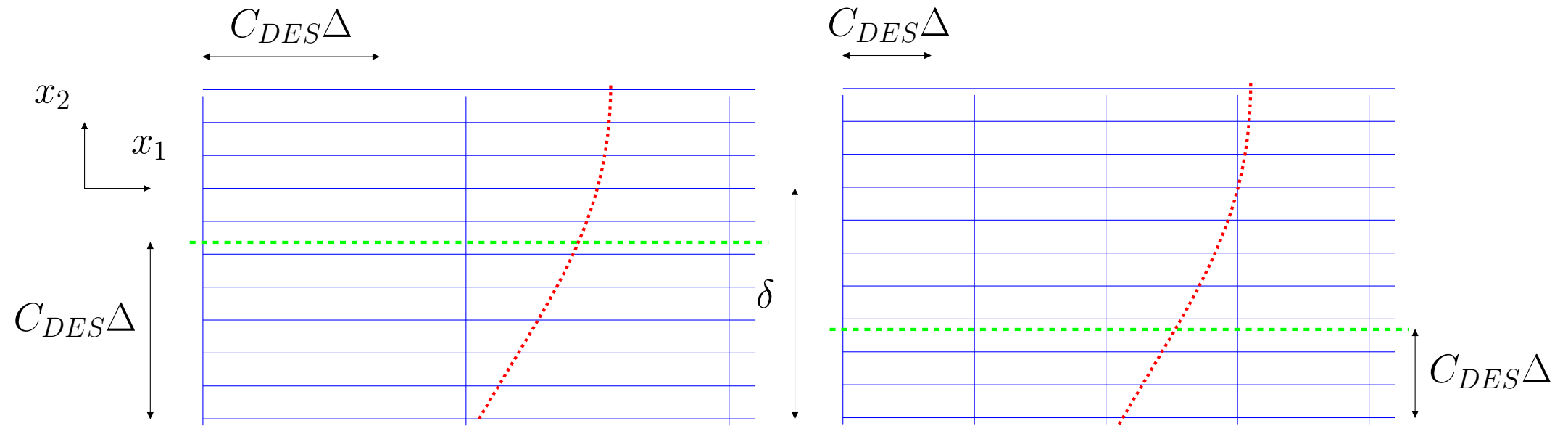
See Section 20.3, DDES



Grid (solid lines) and a velocity profile (dotted line). RANS-LES interface: dashed line. $C_{DES} = 0.67$

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- The left grid above is a good DES mesh because at the RANS-LES interface

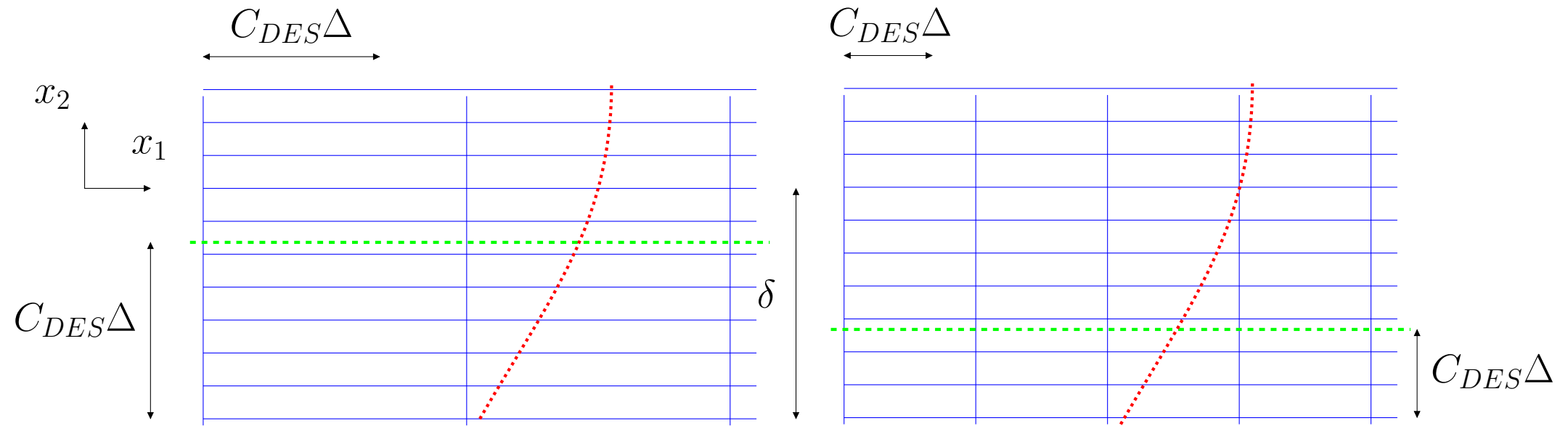
See Section 20.3, DDES



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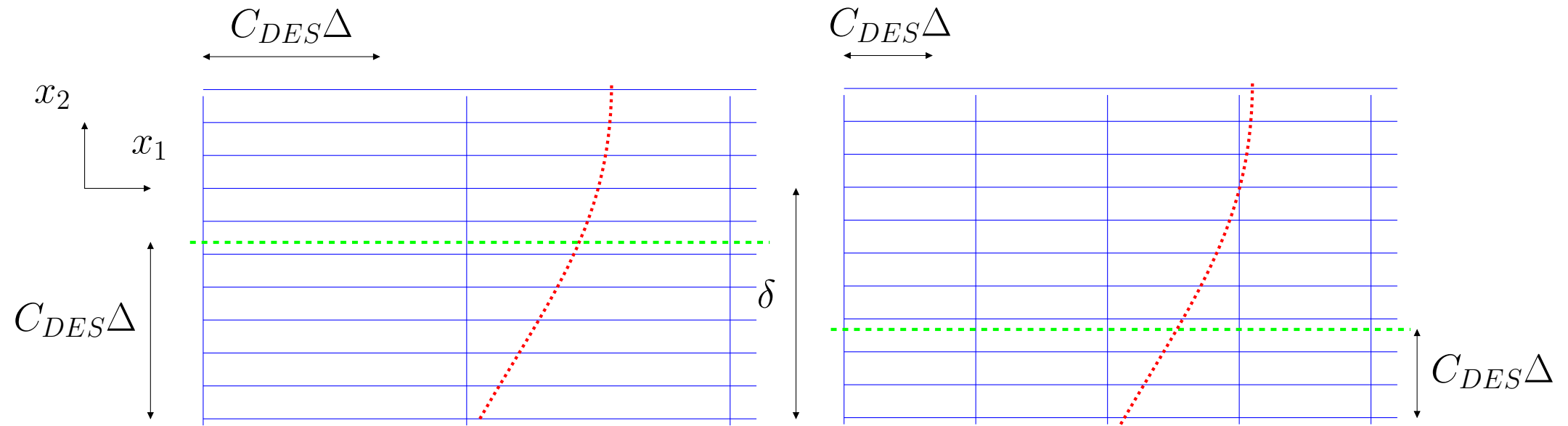
See Section 20.3, DDES



Grid (solid lines) and a velocity profile (dotted line). RANS-LES interface: dashed line. $C_{DES} = 0.67$

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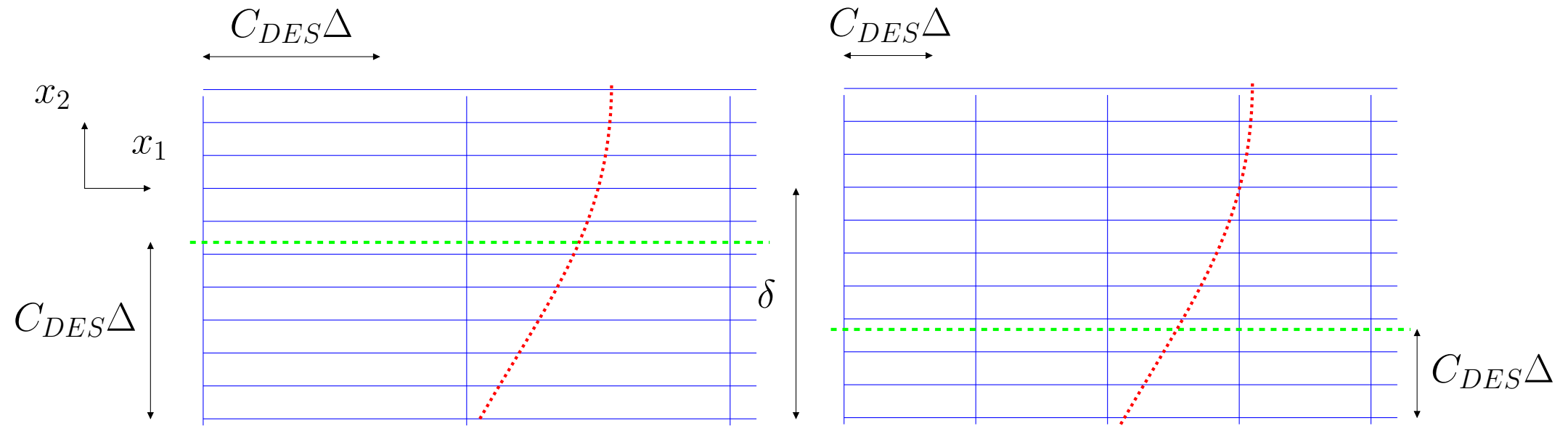
See Section 20.3, DDES



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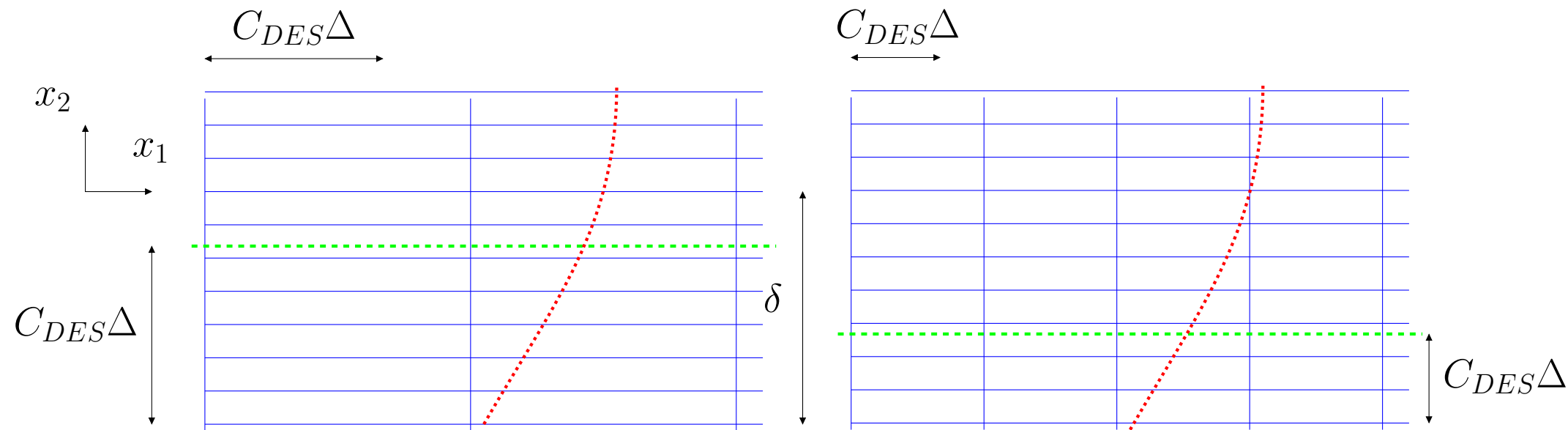
See Section 20.3, DDES



Grid (solid lines) and a velocity profile (dotted line). RANS-LES interface: dashed line. $C_{DES} = 0.67$

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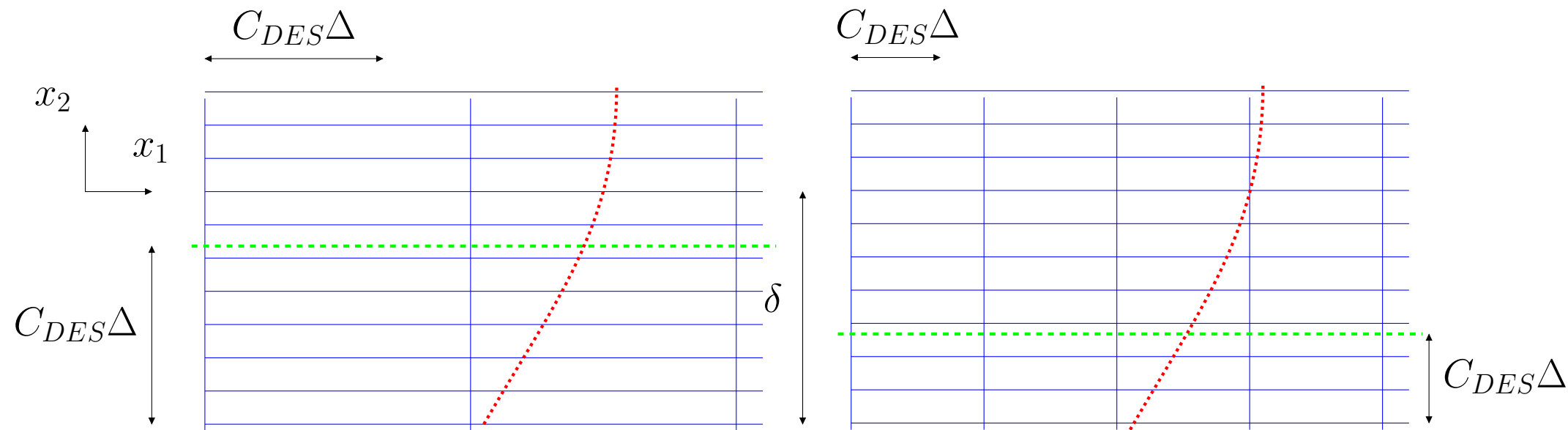
See Section 20.3, DDES



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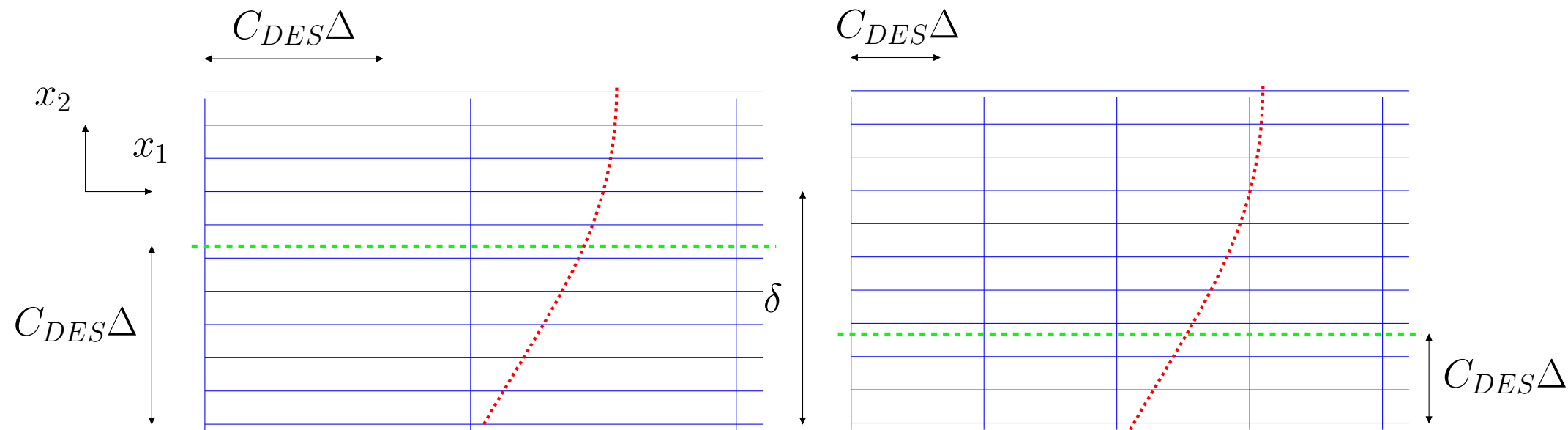
See Section 20.3, DDES



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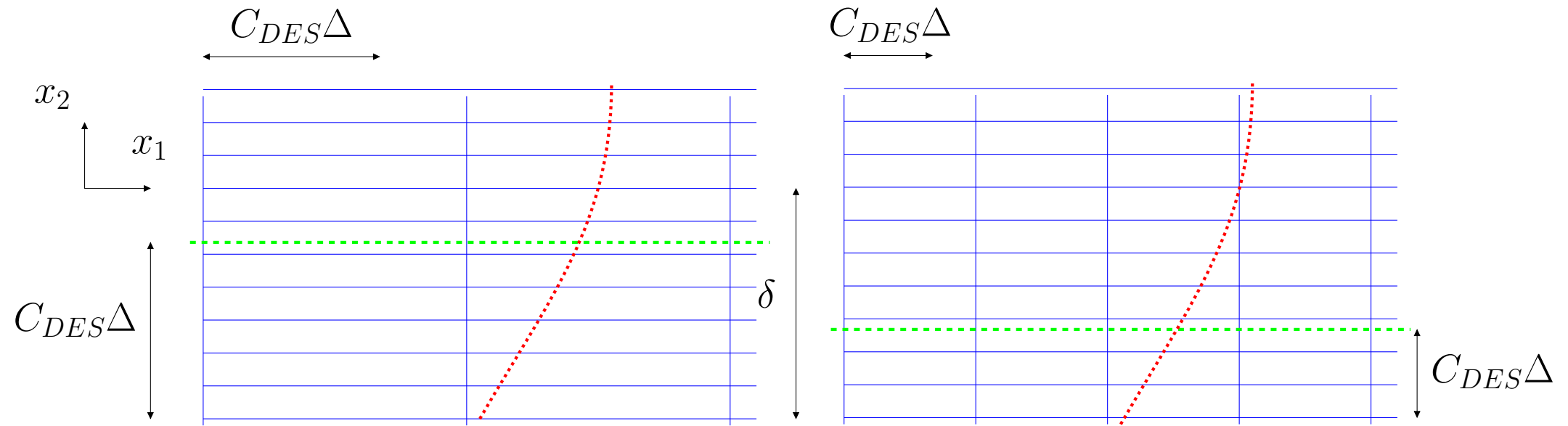
See Section 20.3, DDES



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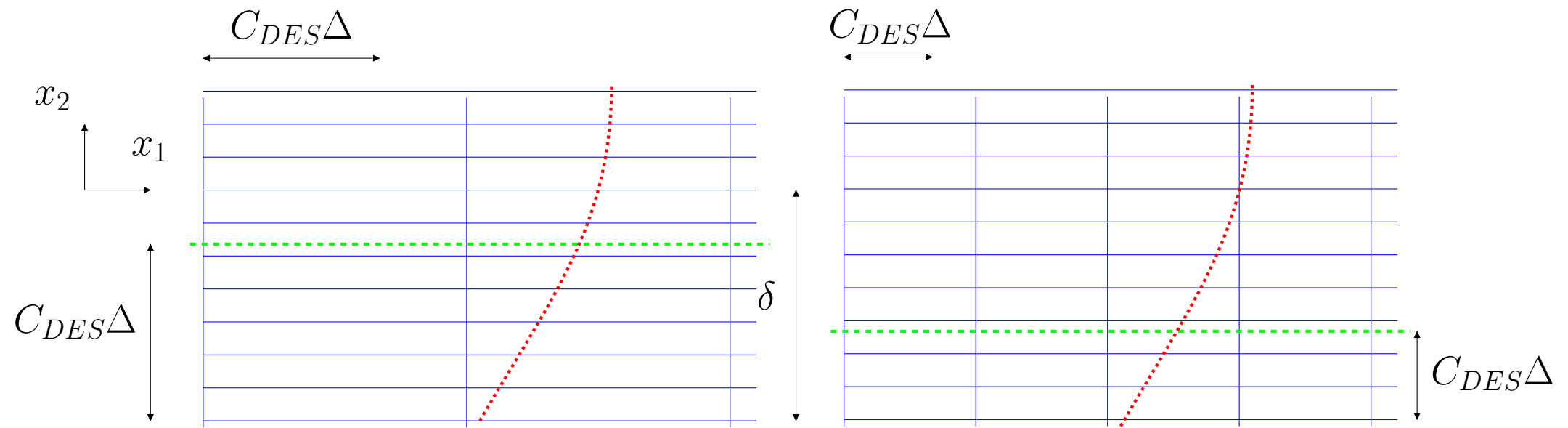
See Section 20.3, DDES



Grid (solid lines) and a velocity profile (dotted line). RANS-LES interface: dashed line. $C_{DES} = 0.67$

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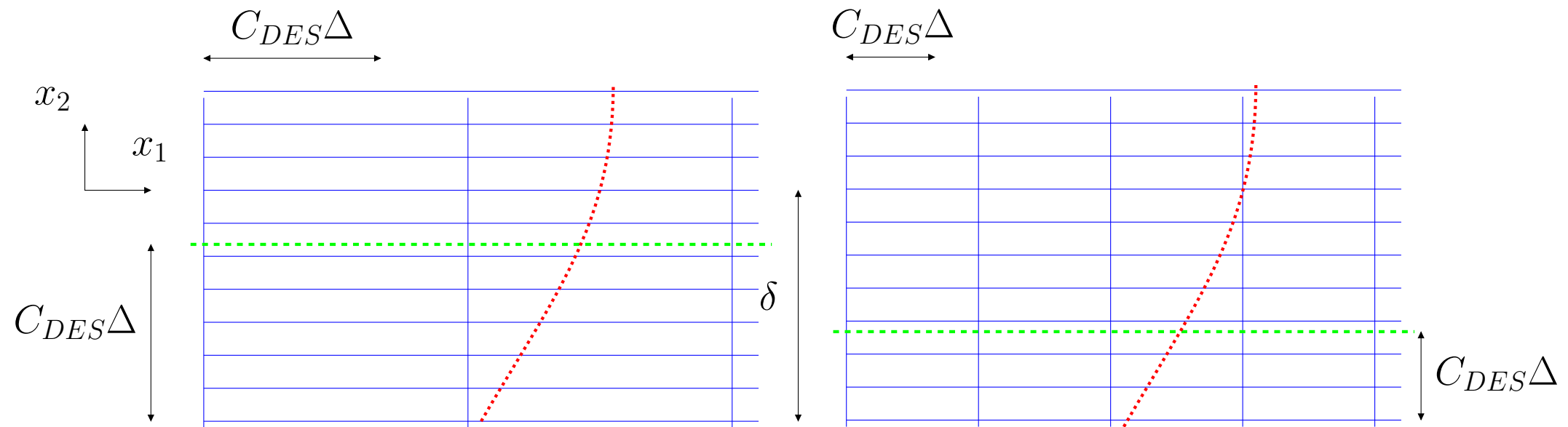
See Section 20.3, DDES



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See Section 20.3, DDES



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► The solution is **DDES** (Delayed DES)

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► In DDES

$$F_{DES} = \max \left\{ \frac{L_t}{C_{DES}\Delta}, 1 \right\}$$

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$$F_{DES} = \max \left\{ \frac{L_t}{C_{DES}\Delta}, 1 \right\}$$

is replaced by

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$$F_{DES} = \max \left\{ \frac{L_t}{C_{DES}\Delta}, 1 \right\}$$

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$$F_{DDES} = \max \left\{ \frac{L_t}{C_{DES}\Delta} (1 - F_S), 1 \right\}$$

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where F_S ($F_S = 1$ in the boundary layer) is taken as F_1 or F_2 of the SST model.

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► F_S is called the **shielding** function: ► it **protects** the boundary layer from LES

¶ See Section 21, Hybrid LES-RANS

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▶ DES:

¶ See Section 21, [Hybrid LES-RANS](#)

▶ **DES:** The entire boundary layer is modelled with URANS

¶ See Section 21, [Hybrid LES-RANS](#)

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Hybrid LES-RANS:

¶ See Section 21, [Hybrid LES-RANS](#)

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Hybrid LES-RANS: Only the inner part of the log region is modelled with URANS.

¶ See Section 21, [Hybrid LES-RANS](#)

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Hybrid LES-RANS: Only the inner part of the log region is modelled with URANS.

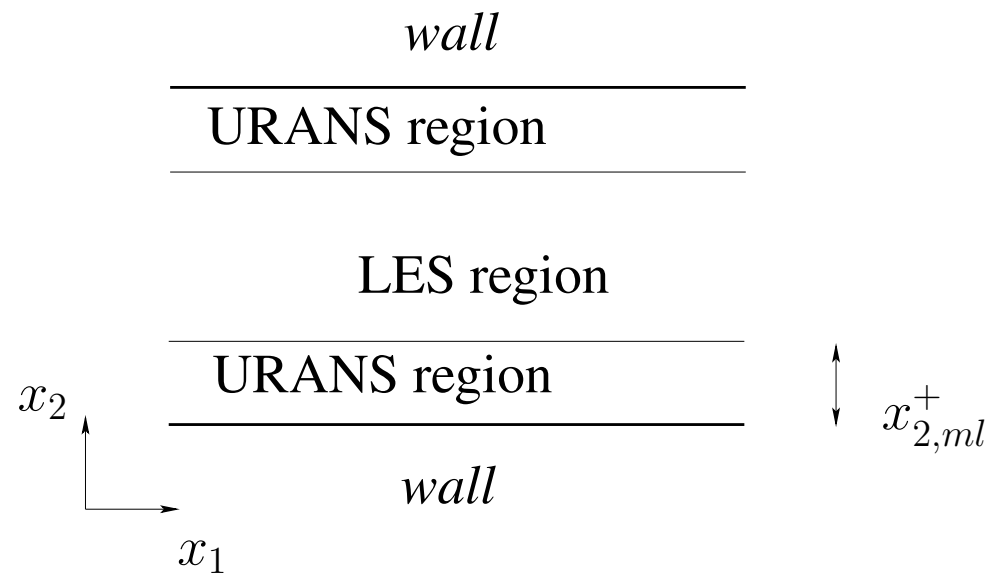
▶ Hybrid LES-RANS is also called **WM-LES** (WM=**W**all-**M**odelled)

¶ See Section 21, [Hybrid LES-RANS](#)

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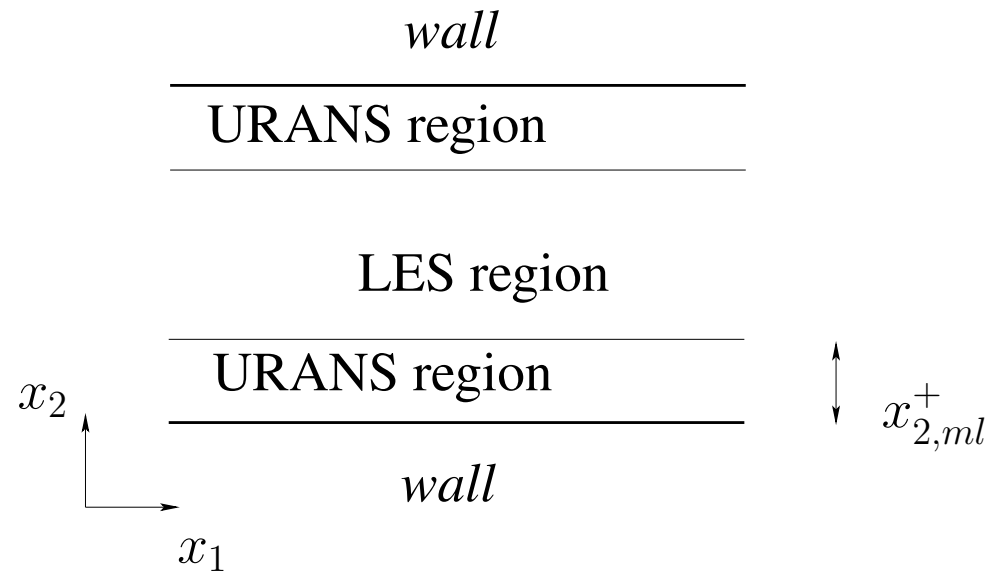


¶ See Section 21, [Hybrid LES-RANS](#)

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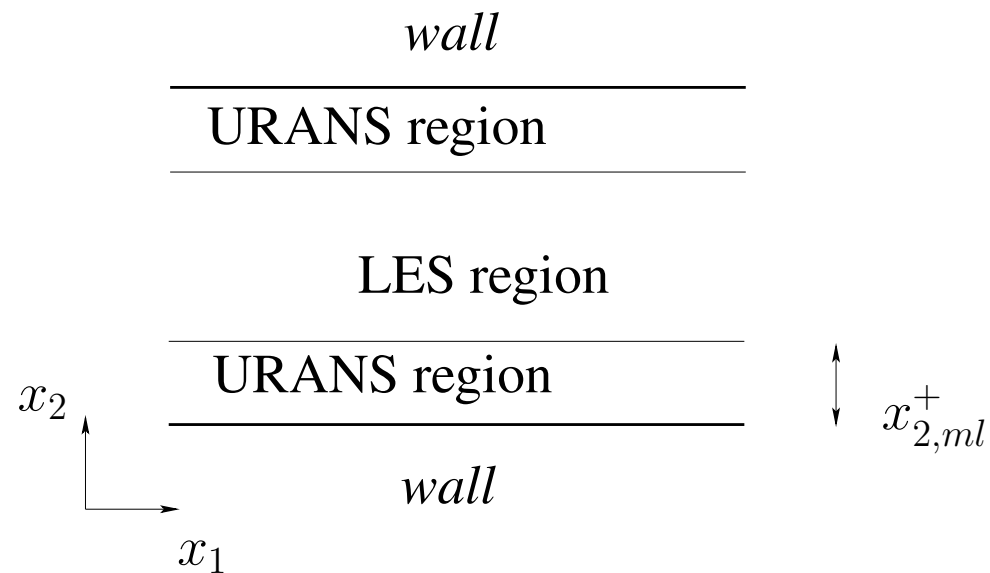
▶ One-equation model in both URANS and LES region

¶ See Section 21, Hybrid LES-RANS

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► One-equation model in both URANS and LES region

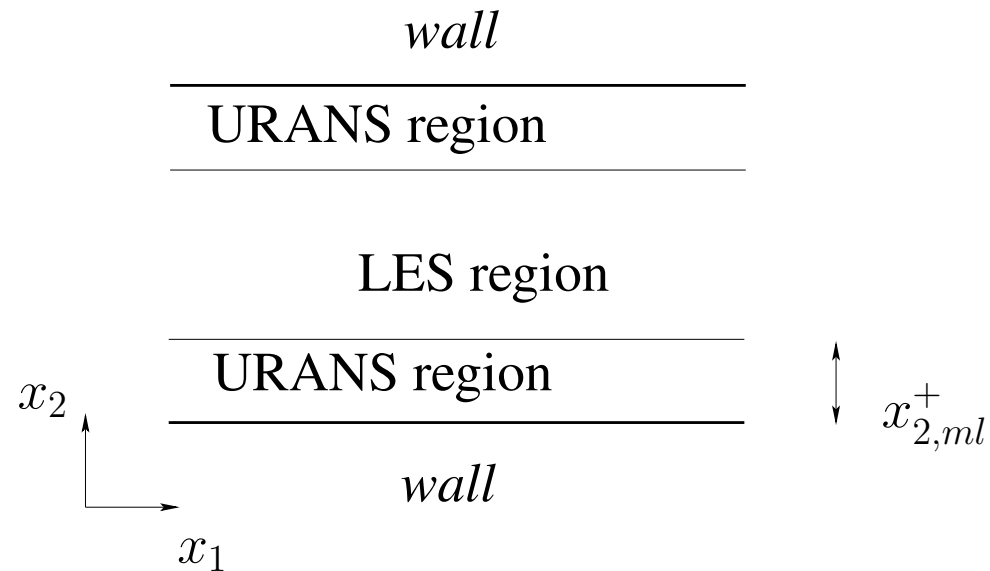
$$\frac{\partial k_T}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_T) =$$

¶ See Section 21, [Hybrid LES-RANS](#)

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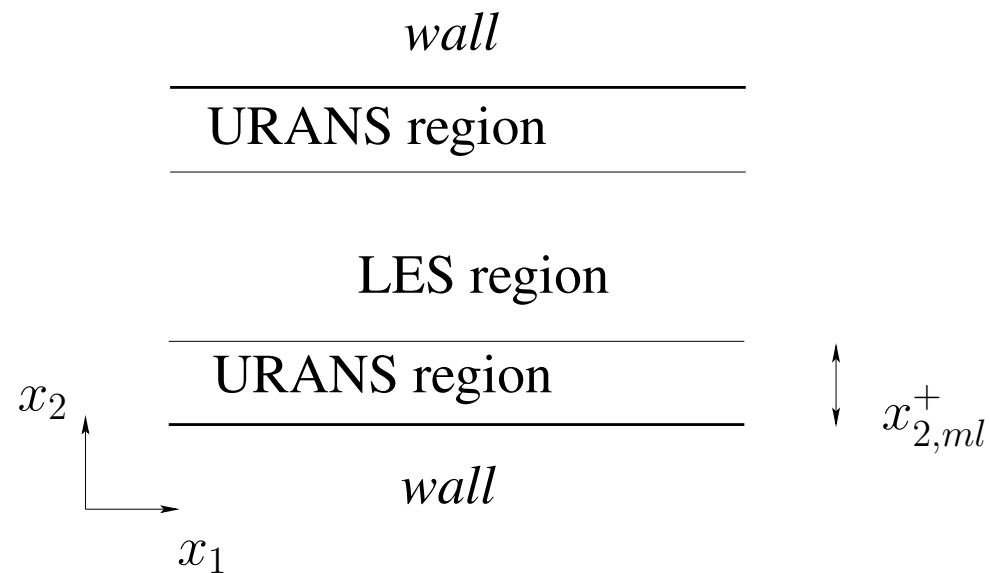
$$\frac{\partial k_T}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_T) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_T) \frac{\partial k_T}{\partial x_j} \right] +$$

¶ See Section 21, Hybrid LES-RANS

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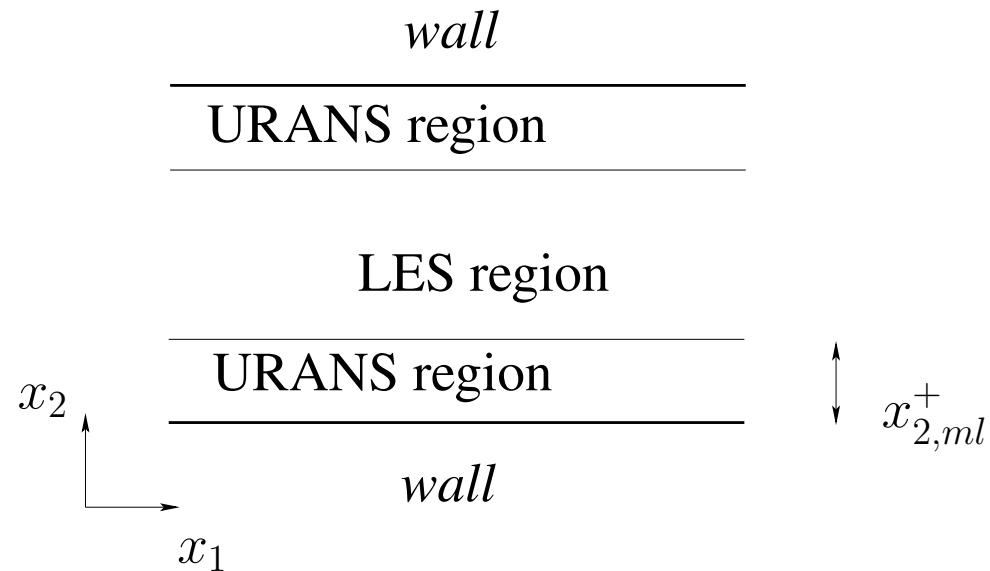
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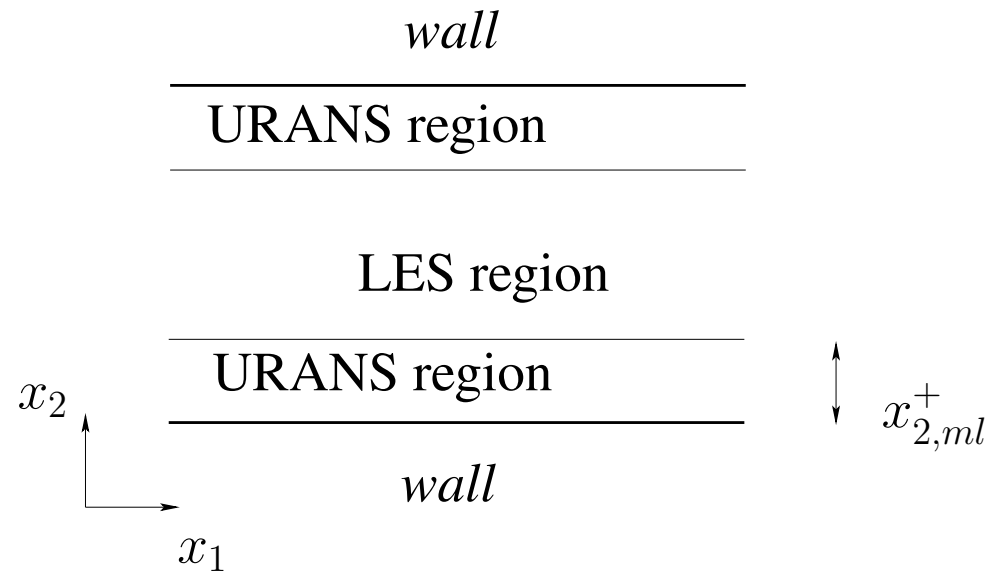
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¶ See Section 21, [Hybrid LES-RANS](#)

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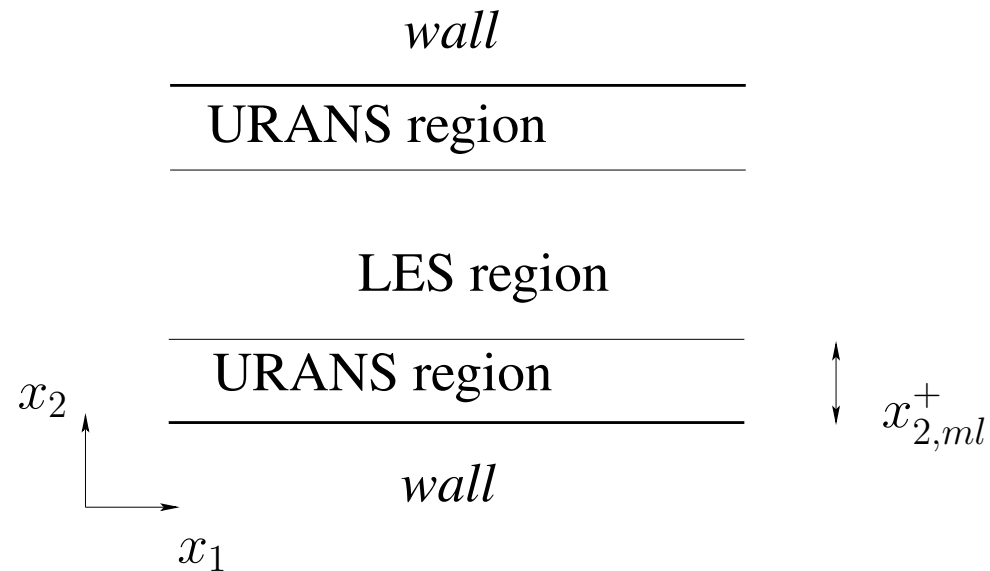
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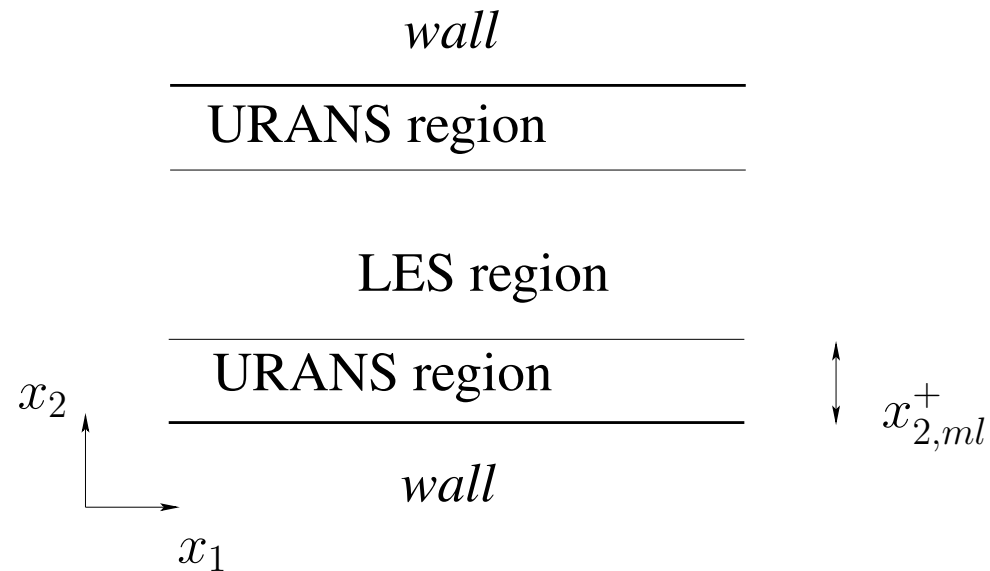
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¶ See Section 21, [Hybrid LES-RANS](#)

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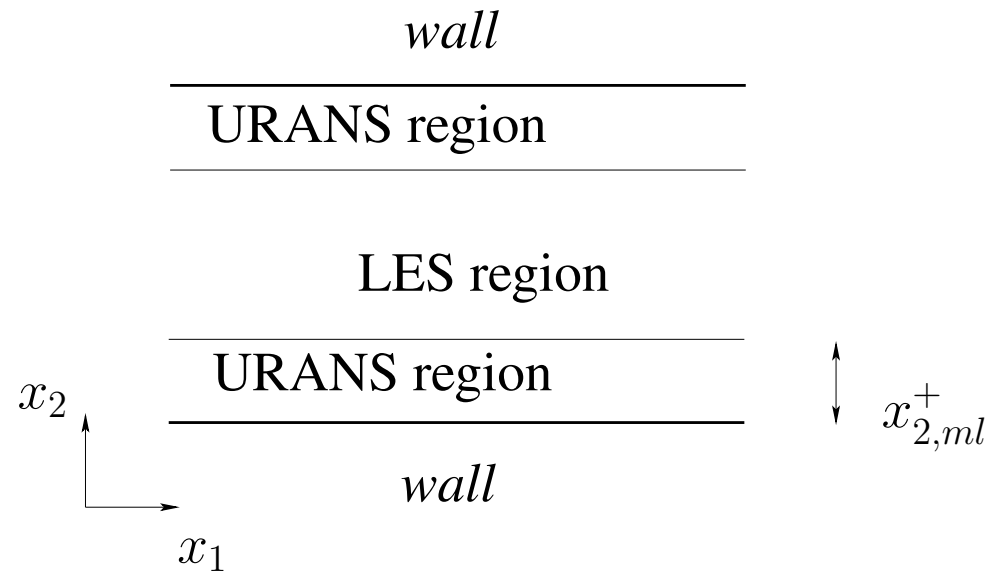
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¶ See Section 21, Hybrid LES-RANS

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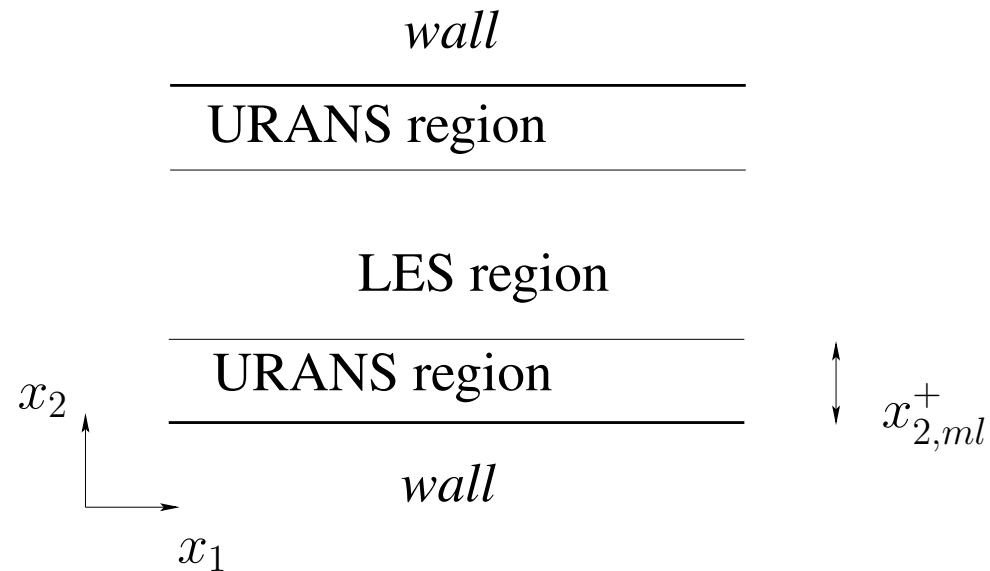
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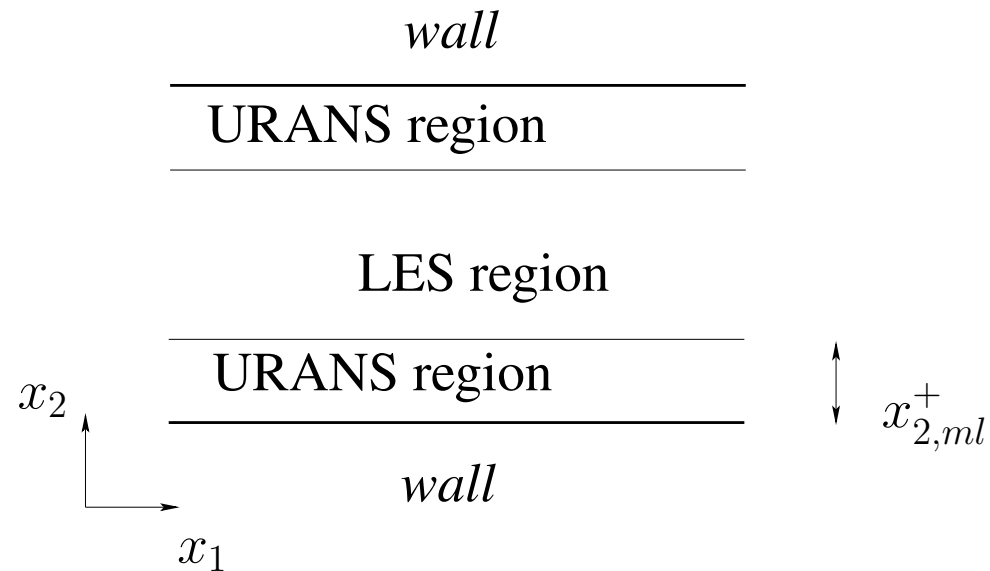
► Inner region ($x_2 \leq x_{2,ml}$):

¶ See Section 21, [Hybrid LES-RANS](#)

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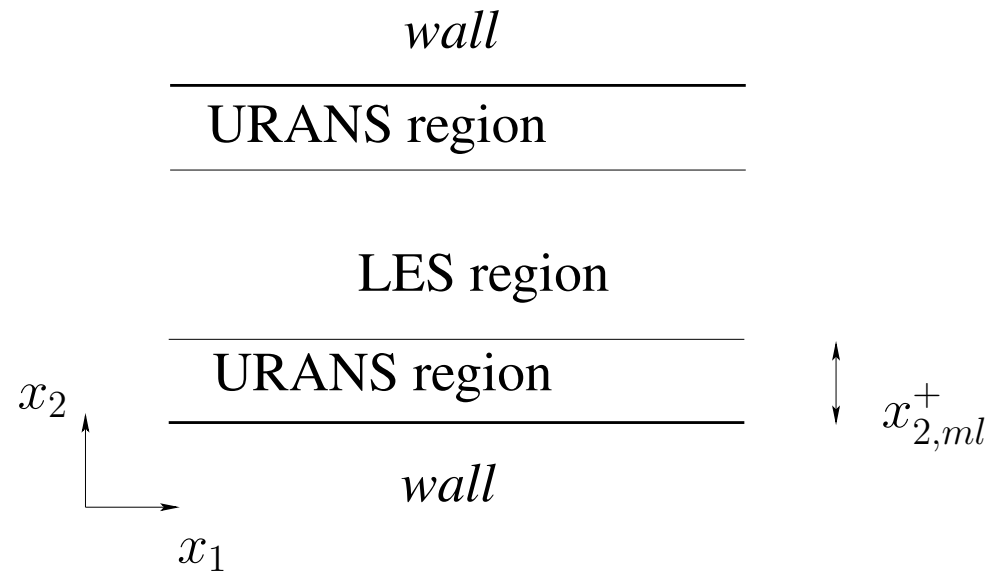
► Inner region ($x_2 \leq x_{2,ml}$): $\ell \propto \kappa x_2$

¶ See Section 21, [Hybrid LES-RANS](#)

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$$\frac{\partial k_T}{\partial t} + \frac{\partial}{\partial x_j} (\bar{v}_j k_T) = \frac{\partial}{\partial x_j} \left[(\nu + \nu_T) \frac{\partial k_T}{\partial x_j} \right] + P_{k_T} - C_\varepsilon \frac{k_T^{3/2}}{\ell}$$
$$P_{k_T} = 2\nu_T \bar{s}_{ij} \bar{s}_{ij}, \quad \nu_T \propto k^{1/2} \ell$$

► Inner region ($x_2 \leq x_{2,ml}$): $\ell \propto \kappa x_2$

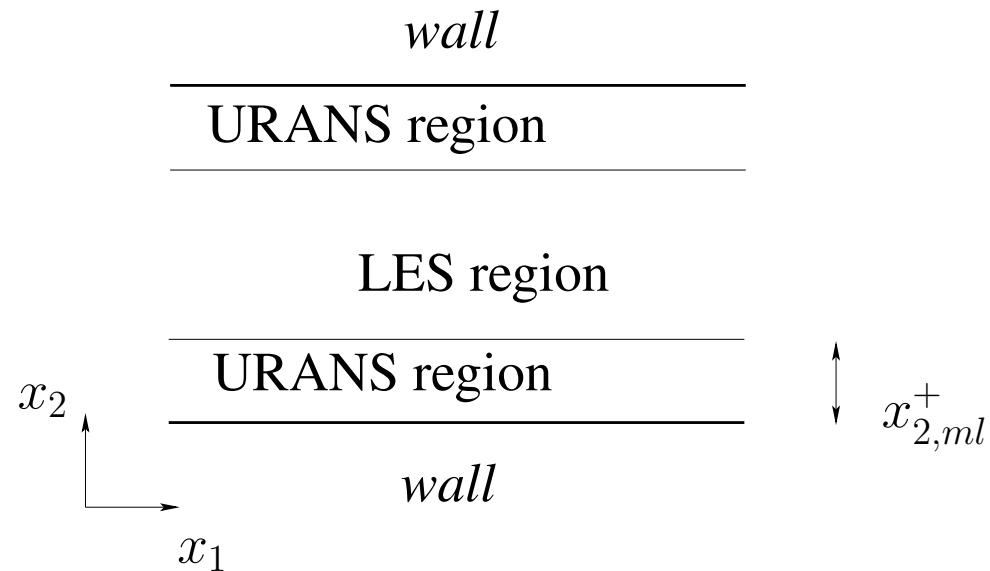
► outer region:

¶ See Section 21, [Hybrid LES-RANS](#)

► **DES**: The entire boundary layer is modelled with URANS

Hybrid LES-RANS: Only the inner part of the log region is modelled with URANS.

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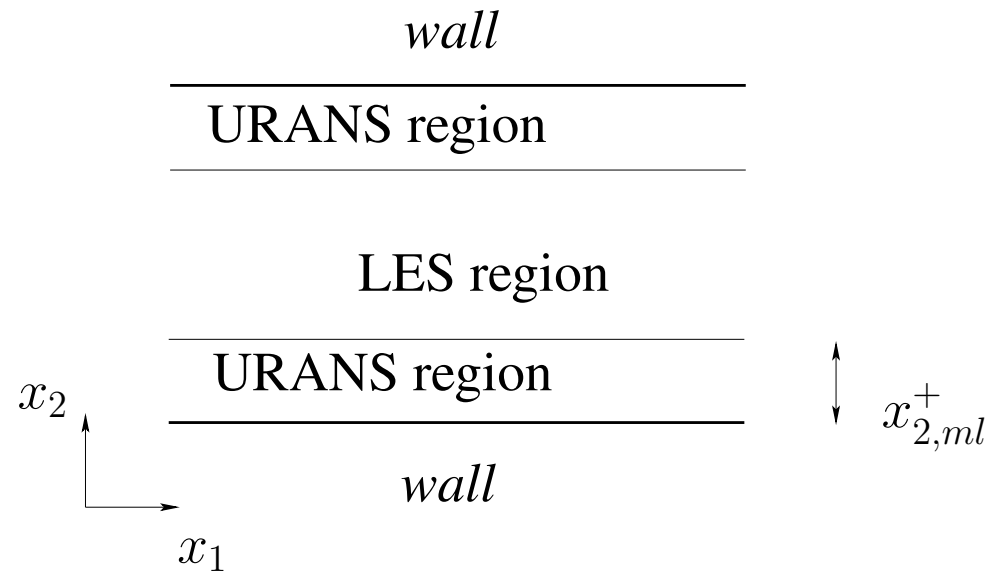
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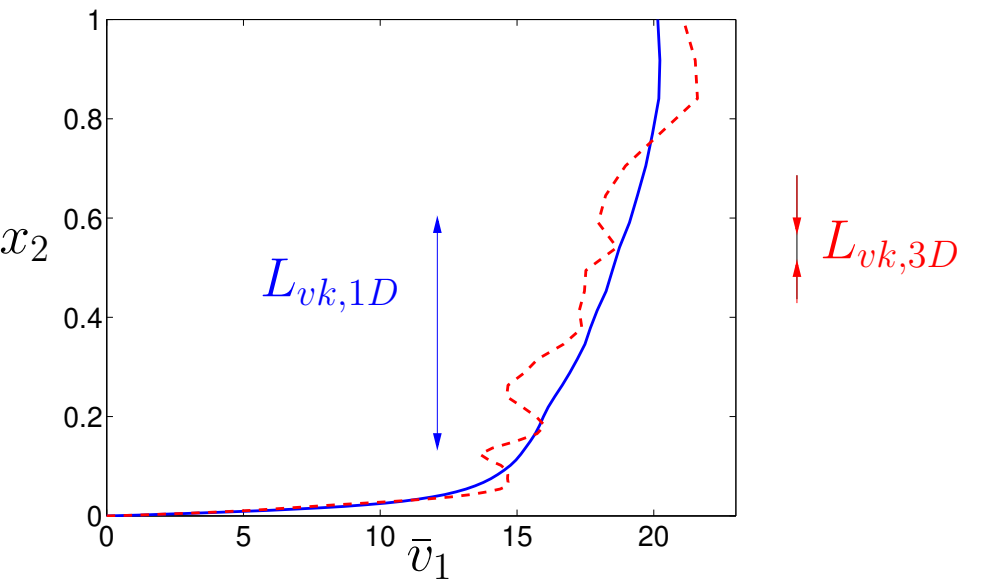
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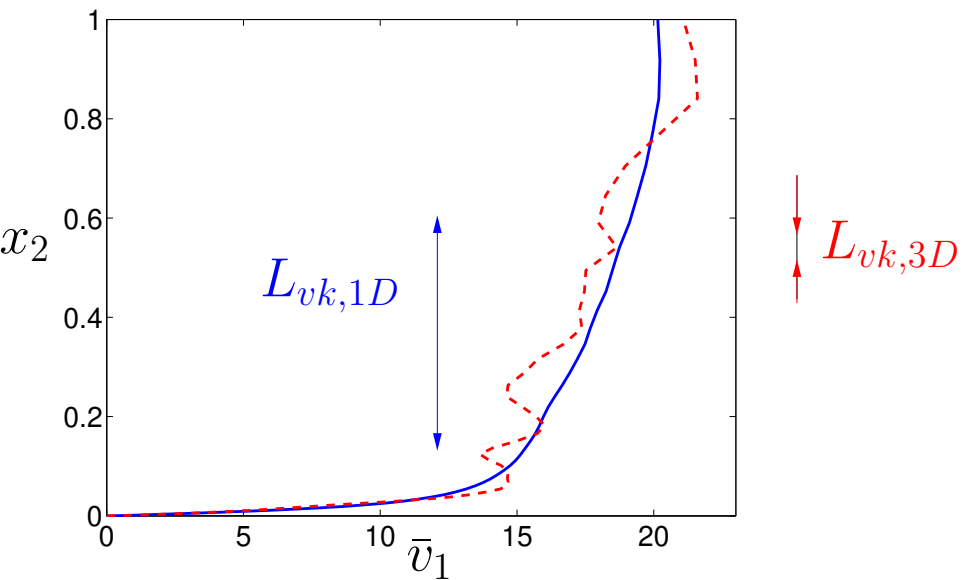
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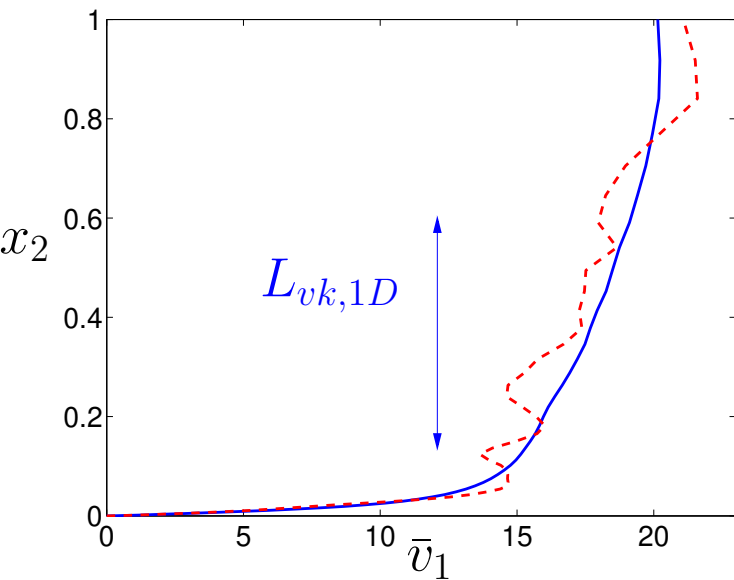
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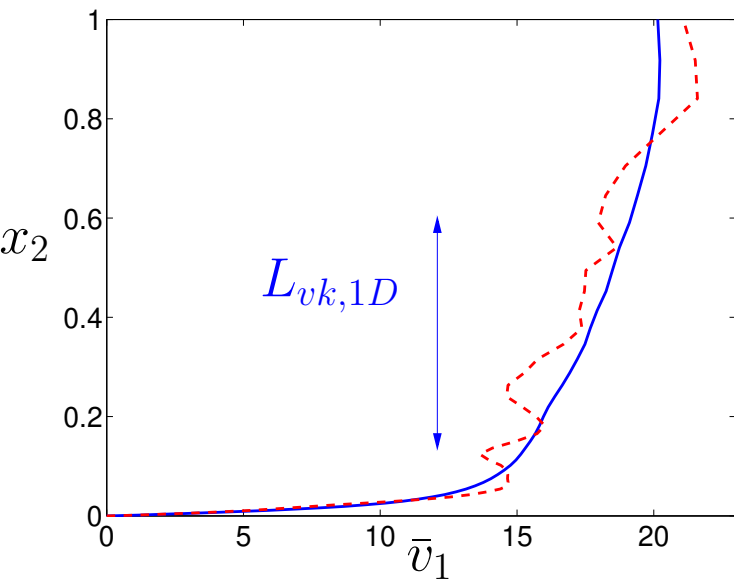
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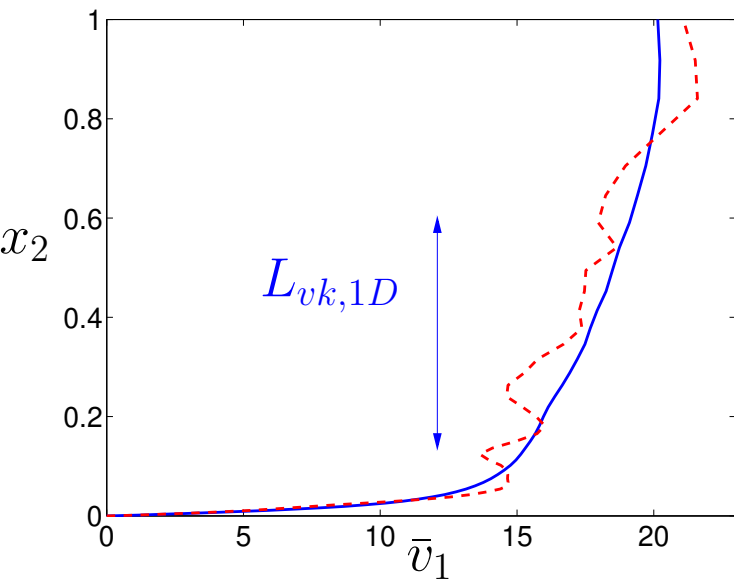
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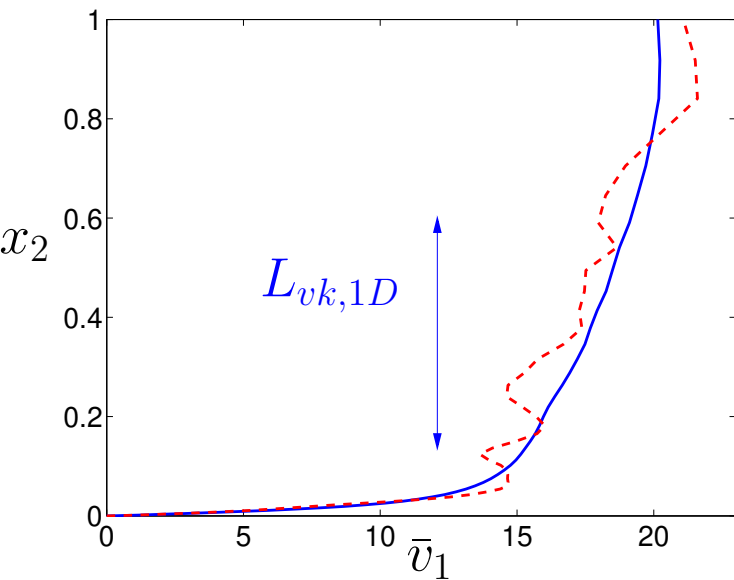
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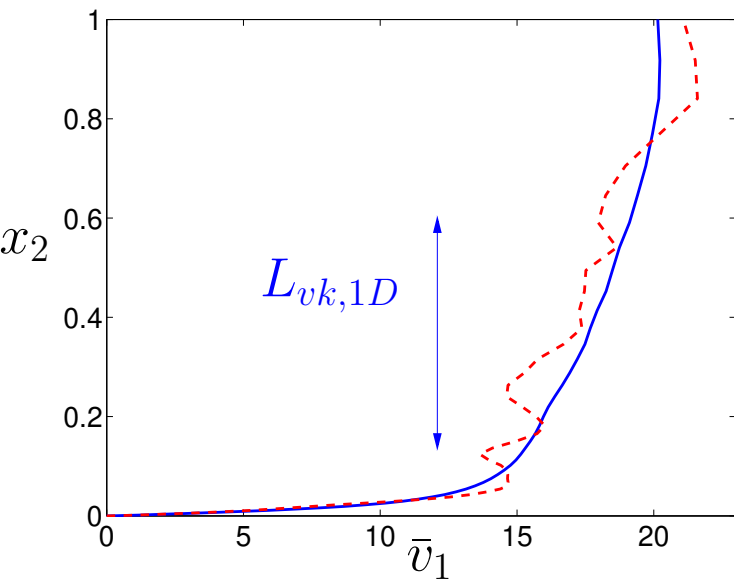
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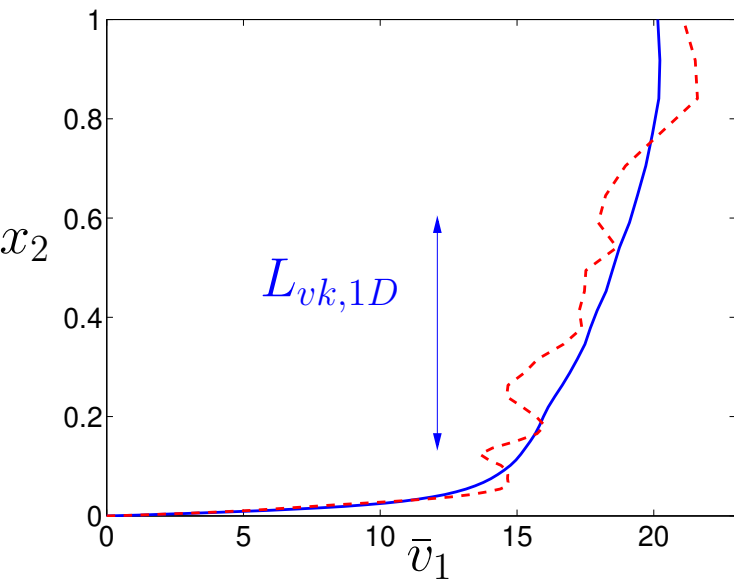
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- In URANS (without SAS), resolved fluctuations are damped.

On-line Lecture 11

¶ See Section 23, The PANS Model

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- LES: it is in-between ► $0 < f_k \lesssim 0.5$

On-line Lecture 11

¶ See Section 23, The PANS Model

► PANS: Partial-Averaging Navier-Stokes. It is a hybrid LES-RANS model based on the $k - \varepsilon$ model.

- $f_k = k/k_{tot}$ and $f_\varepsilon = \varepsilon/\varepsilon_{tot}$: ratio of modelled to total $k_{tot} = k + k_{res}$, $\varepsilon_{tot} = \varepsilon + \varepsilon_{res}$.

- $f_\varepsilon < 1$ means that part of the dissipation is resolved.

- This occurs only for DNS-like resolution.

- Hence, in practice $f_\varepsilon = 1$

- $0 < f_k \leq 1$

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- LES: it is in-between ► $0 < f_k \lesssim 0.5$

► Derivation of PANS k equation

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$$f_\varepsilon \left\{ \frac{\partial \varepsilon_{tot}}{\partial t} + \bar{V}_j \frac{\partial \varepsilon_{tot}}{\partial x_j} \right\} = \frac{\partial \varepsilon}{\partial t} + \bar{V}_j \frac{\partial \varepsilon}{\partial x_j} \simeq \frac{\partial \varepsilon}{\partial t} + \bar{v}_j \frac{\partial \varepsilon}{\partial x_j}$$

► Right side, diffusion term

$$f_\varepsilon \left\{ \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_{t,tot}}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon_{tot}}{\partial x_j} \right] \right\} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_{t,tot}}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_j} \right] = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon}{\partial x_j} \right]$$

► Production and destruction terms

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► use Eq. 40.1, $k_{tot} = k/f_k$, $\varepsilon_{tot} = \varepsilon/f_\varepsilon$

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where

$$C_{\varepsilon 2}^* = C_{\varepsilon 1} + \frac{f_k}{f_\varepsilon}(C_{\varepsilon 2} - C_{\varepsilon 1}) =$$

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where

$$C_{\varepsilon 2}^* = C_{\varepsilon 1} + \frac{f_k}{f_\varepsilon}(C_{\varepsilon 2} - C_{\varepsilon 1}) = 1.5 + \frac{f_k}{f_\varepsilon}(1.9 - 1.5)$$

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► The ε eqn can now be written

► Production and destruction terms ► use Eq. 40.1, $k_{tot} = k/f_k$, $\varepsilon_{tot} = \varepsilon/f_\varepsilon$

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► The ε eqn can now be written

$$\frac{\partial \varepsilon}{\partial t} + \frac{\partial(\varepsilon \bar{v}_j)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{\varepsilon 1} P^k \frac{\varepsilon}{k} - C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$$

► Production and destruction terms ► use Eq. 40.1, $k_{tot} = k/f_k$, $\varepsilon_{tot} = \varepsilon/f_\varepsilon$

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► When $f_k = 1$, the PANS eqns are in RANS mode

$$\frac{\partial \varepsilon}{\partial t} + \frac{\partial(\varepsilon \bar{v}_j)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{\varepsilon 1} P^k \frac{\varepsilon}{k} - C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$$

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► When $f_k = 1$, the PANS eqns are in RANS mode

• When $f_k < 1$ (say, $f_k = 0.4$) then:

$$\frac{\partial \varepsilon}{\partial t} + \frac{\partial(\varepsilon \bar{v}_j)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{\varepsilon 1} P^k \frac{\varepsilon}{k} - C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$$

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► When $f_k = 1$, the PANS eqns are in RANS mode

• When $f_k < 1$ (say, $f_k = 0.4$) then:

$C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$ is reduced

$$\frac{\partial \varepsilon}{\partial t} + \frac{\partial(\varepsilon \bar{v}_j)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{\varepsilon 1} P^k \frac{\varepsilon}{k} - C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$$

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► When $f_k = 1$, the PANS eqns are in RANS mode

• When $f_k < 1$ (say, $f_k = 0.4$) then:

$C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$ is reduced
 $\Rightarrow \varepsilon$ is increased

$$\frac{\partial \varepsilon}{\partial t} + \frac{\partial(\varepsilon \bar{v}_j)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{\varepsilon 1} P^k \frac{\varepsilon}{k} - C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$$

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• When $f_k < 1$ (say, $f_k = 0.4$) then:

$C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$ is reduced

⇒ ε is increased

⇒ k is decreased

$$\frac{\partial \varepsilon}{\partial t} + \frac{\partial(\varepsilon \bar{v}_j)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{\varepsilon 1} P^k \frac{\varepsilon}{k} - C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$$

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► When $f_k = 1$, the PANS eqns are in RANS mode

• When $f_k < 1$ (say, $f_k = 0.4$) then:

$C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$ is reduced

⇒ ε is increased

⇒ k is decreased

⇒ ν_t is decreased (both small k and large ε)

$$\frac{\partial \varepsilon}{\partial t} + \frac{\partial(\varepsilon \bar{v}_j)}{\partial x_j} = \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_{\varepsilon u}} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{\varepsilon 1} P^k \frac{\varepsilon}{k} - C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$$

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▶ When $f_k = 1$, the PANS eqns are in RANS mode

• When $f_k < 1$ (say, $f_k = 0.4$) then:

$C_{\varepsilon 2}^* \frac{\varepsilon^2}{k}$ is reduced

⇒ ε is increased

⇒ k is decreased

⇒ ν_t is decreased (both small k and large ε)

⇒ the momentum eqns go into LES mode.

¶ See Section 23.2, Zonal PANS: different treatments of the RANS-LES interface

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► In the previous slides we assumed that f_k is constant. ($f_k = k/k_{tot}$, $k_{tot} = k_{res} + k$)

(40.2)

¶ See Section 23.2, Zonal PANS: different treatments of the RANS-LES interface

► In the previous slides we assumed that f_k is constant. ($f_k = k/k_{tot}$, $k_{tot} = k_{res} + k$)

$$f_k \frac{dk_{tot}}{dt} = \tag{40.2}$$

¶ See Section 23.2, Zonal PANS: different treatments of the RANS-LES interface

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$$f_k \frac{dk_{tot}}{dt} = \frac{d(f_k k_{tot})}{dt} = \quad (40.2)$$

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$$f_k \frac{dk_{tot}}{dt} = \frac{d(f_k k_{tot})}{dt} = \frac{dk}{dt} \quad (40.2)$$

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► PANS as a hybrid RANS-LES model ($f_k = 1$ in RANS region, and $0 < f_k < 0.5$ in LES region)

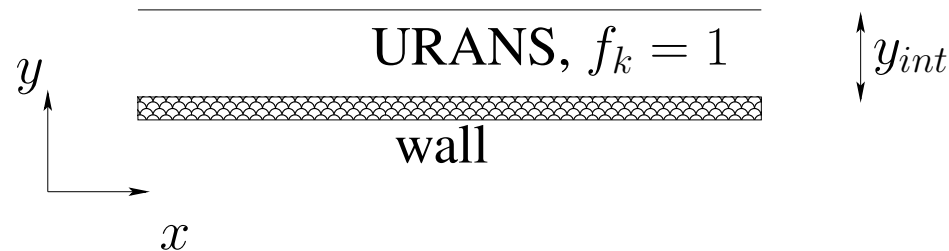
¶ See Section 23.2, Zonal PANS: different treatments of the RANS-LES interface

► In the previous slides we assumed that f_k is constant. ($f_k = k/k_{tot}$, $k_{tot} = k_{res} + k$)

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► PANS as a hybrid RANS-LES model ($f_k = 1$ in RANS region, and $0 < f_k < 0.5$ in LES region)

LES, $f_k = 0.4$ or computed



The URANS and the LES regions near a wall (horizontal interface).

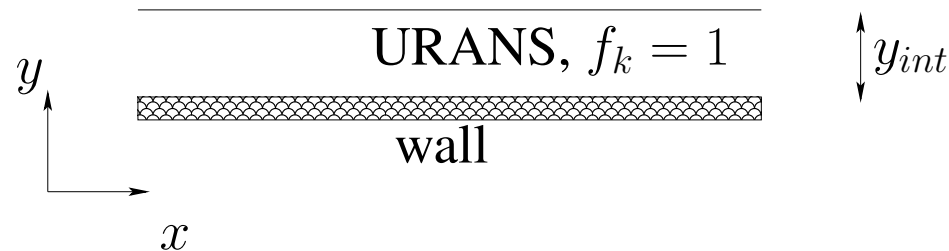
¶ See Section 23.2, Zonal PANS: different treatments of the RANS-LES interface

► In the previous slides we assumed that f_k is constant. ($f_k = k/k_{tot}$, $k_{tot} = k_{res} + k$)

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► PANS as a hybrid RANS-LES model ($f_k = 1$ in RANS region, and $0 < f_k < 0.5$ in LES region)

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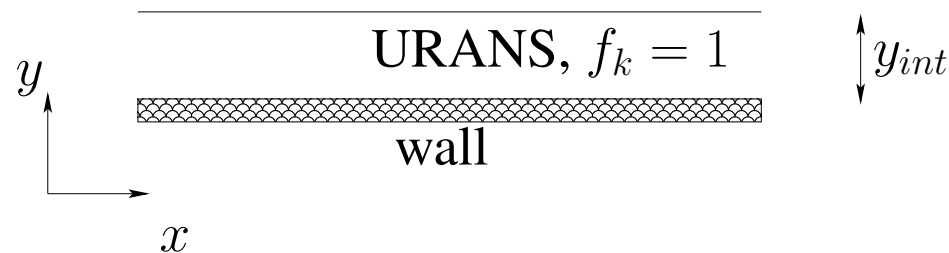
See Section 23.2, Zonal PANS: different treatments of the RANS-LES interface

In the previous slides we assumed that f_k is constant. ($f_k = k/k_{tot}$, $k_{tot} = k_{res} + k$)

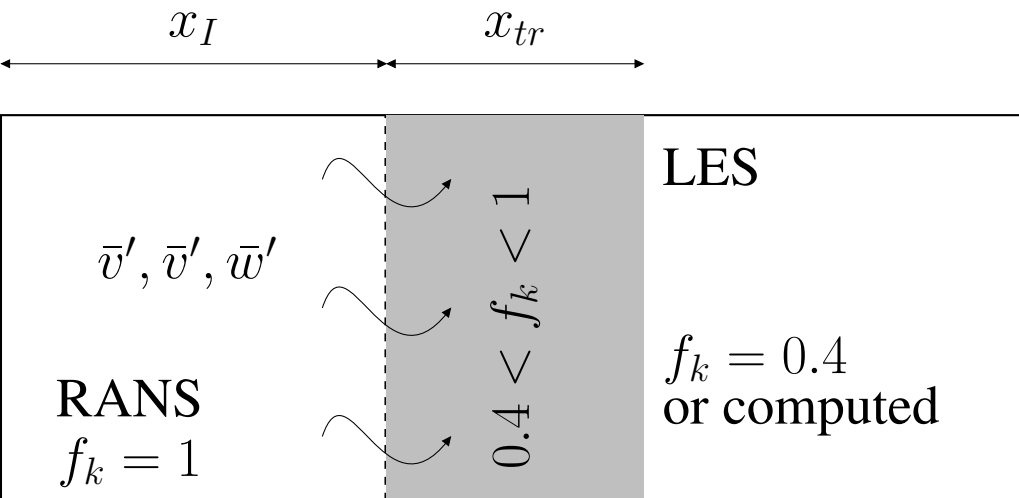
$$f_k \frac{dk_{tot}}{dt} = \frac{d(f_k k_{tot})}{dt} = \frac{dk}{dt} \quad (40.2)$$

PANS as a hybrid RANS-LES model ($f_k = 1$ in RANS region, and $0 < f_k < 0.5$ in LES region)

LES, $f_k = 0.4$ or computed



The URANS and the LES regions near a wall (horizontal interface).



Embedded LES. RANS-LES interface at x_I .

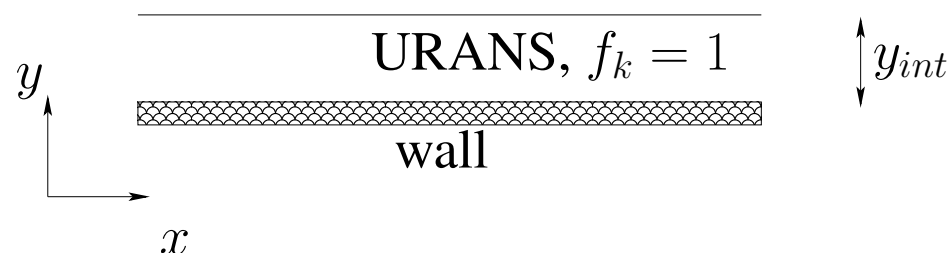
See Section 23.2, Zonal PANS: different treatments of the RANS-LES interface

In the previous slides we assumed that f_k is constant. ($f_k = k/k_{tot}$, $k_{tot} = k_{res} + k$)

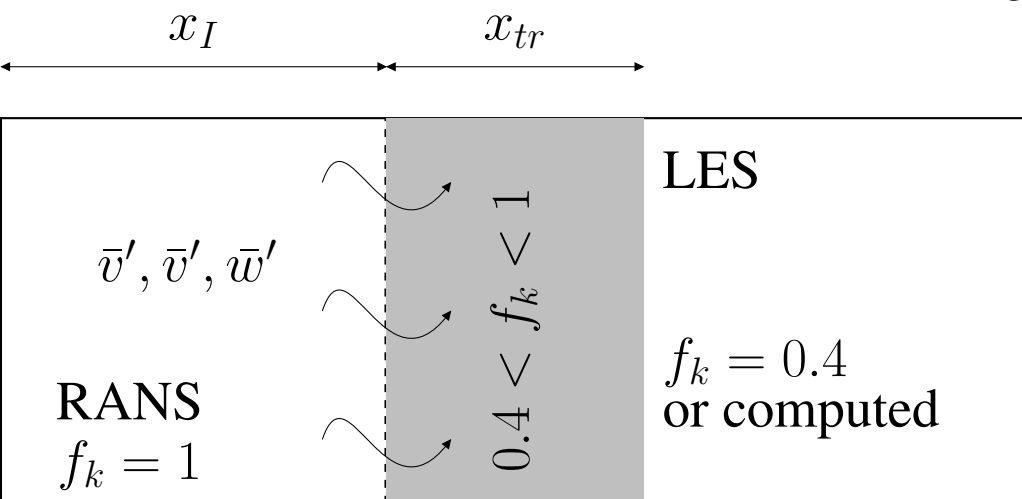
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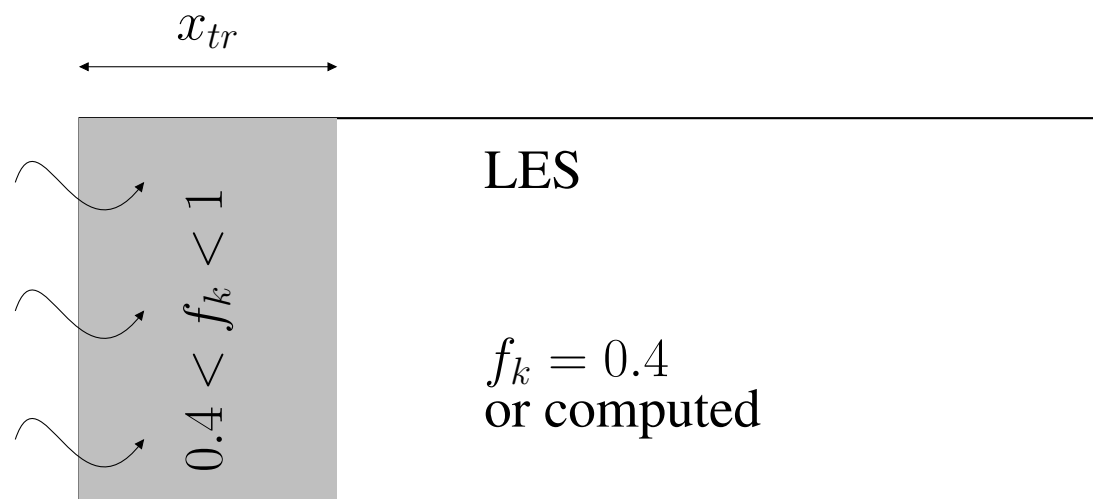
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RANS-LES interface at inlet.

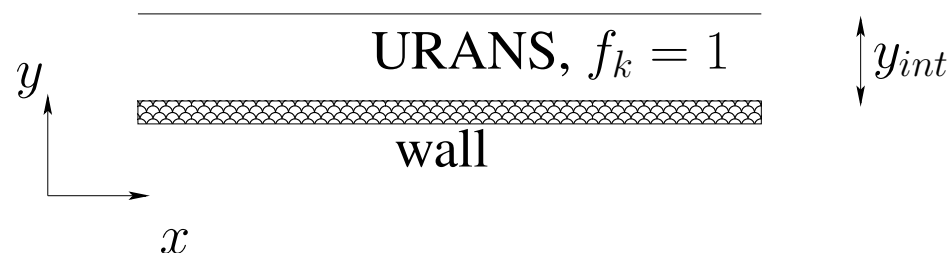
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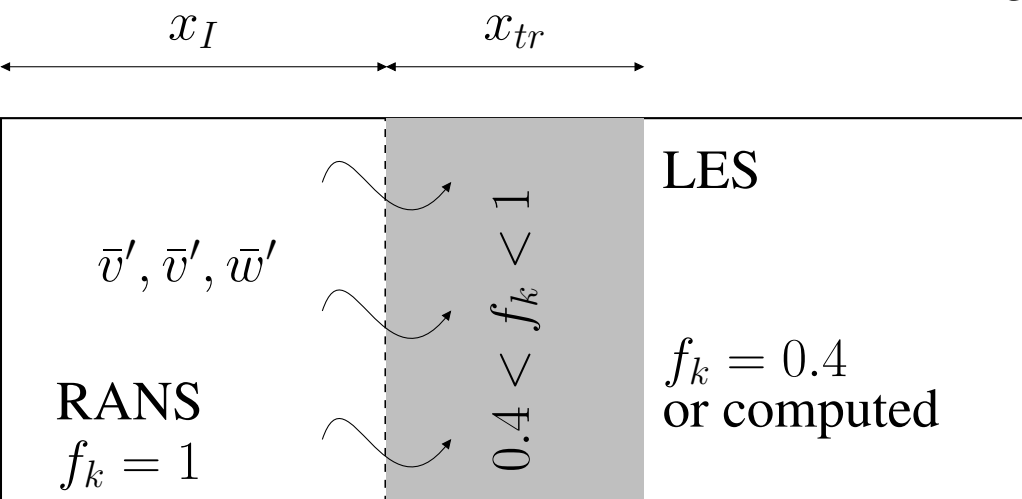
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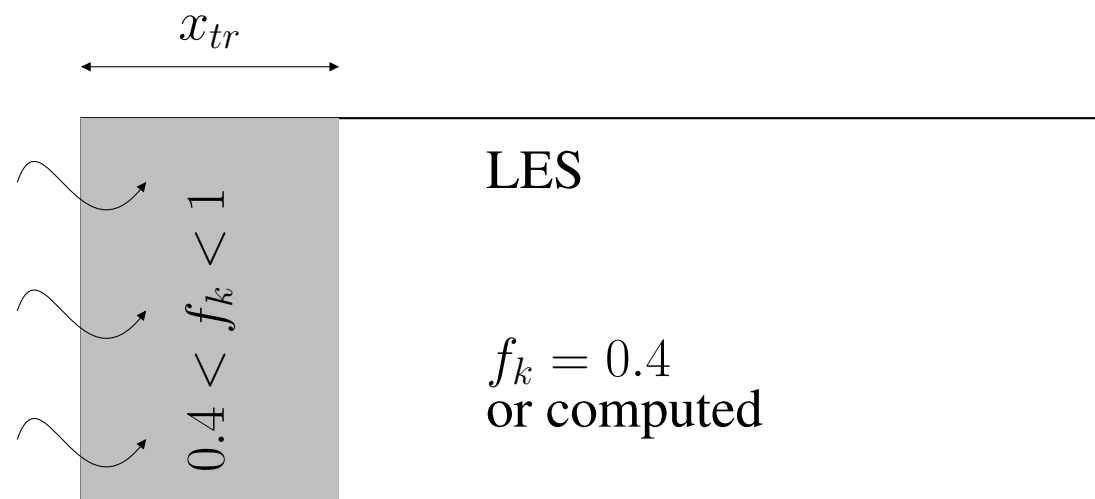
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¶ See Section 23.3, A new formulation of f_k for the PANS model

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▶ How to compute f_k ?

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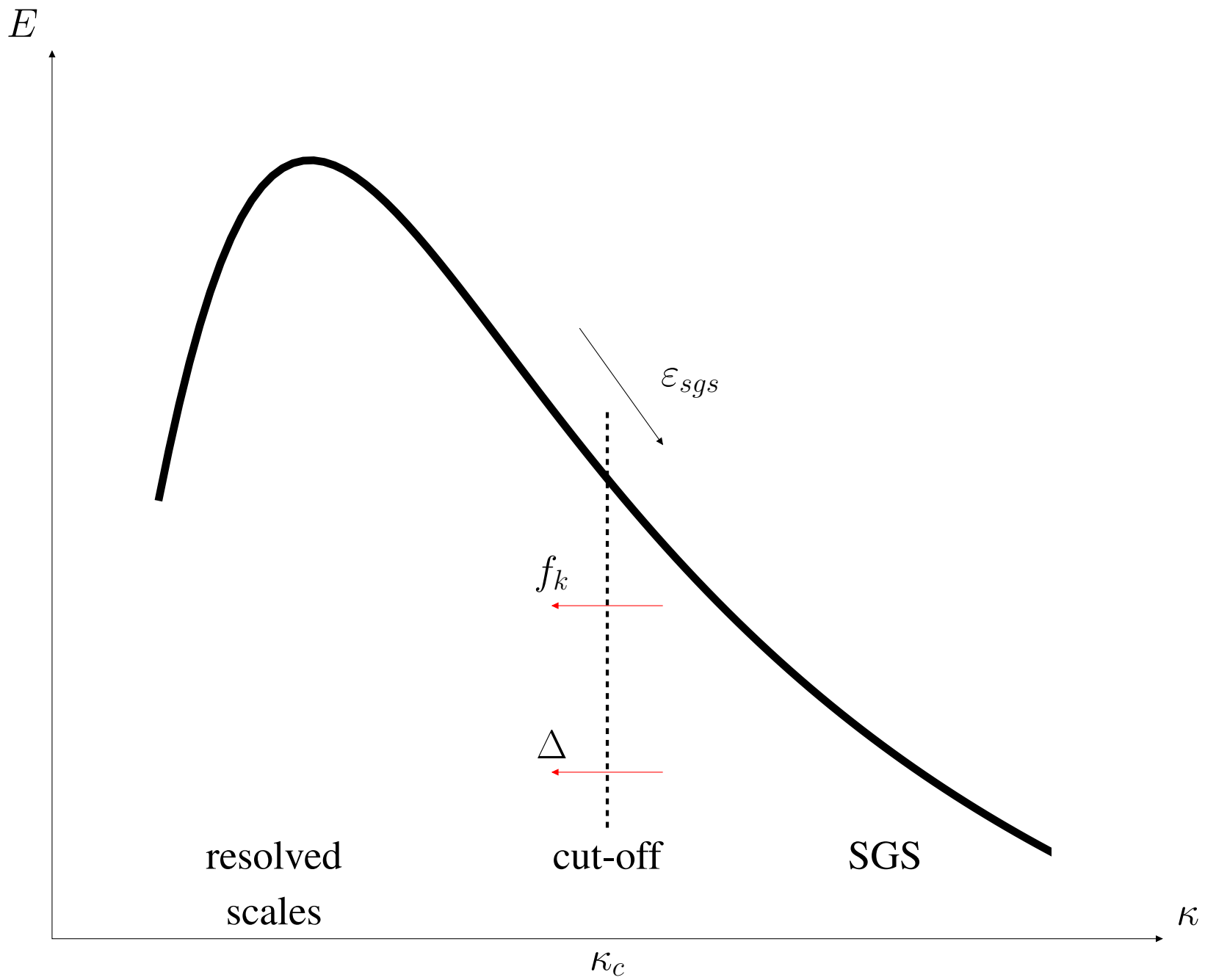
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Spectrum of velocity fluctuations.

► DES and PANS I

$$C^k - D^k \simeq$$

► DES and PANS I

$$C^k - D^k \simeq C^\varepsilon - D^\varepsilon \simeq 0$$

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- **Advantage** of the new PANS model vs. the DES model
 - The PANS model is based on a **rigorous** derivation whereas DES is based on an **ad-hoc** modification of RANS models

On-line Lecture 12

¶ See Section 27.1, Synthesized turbulence

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► In LES, large-scale turbulence is resolved

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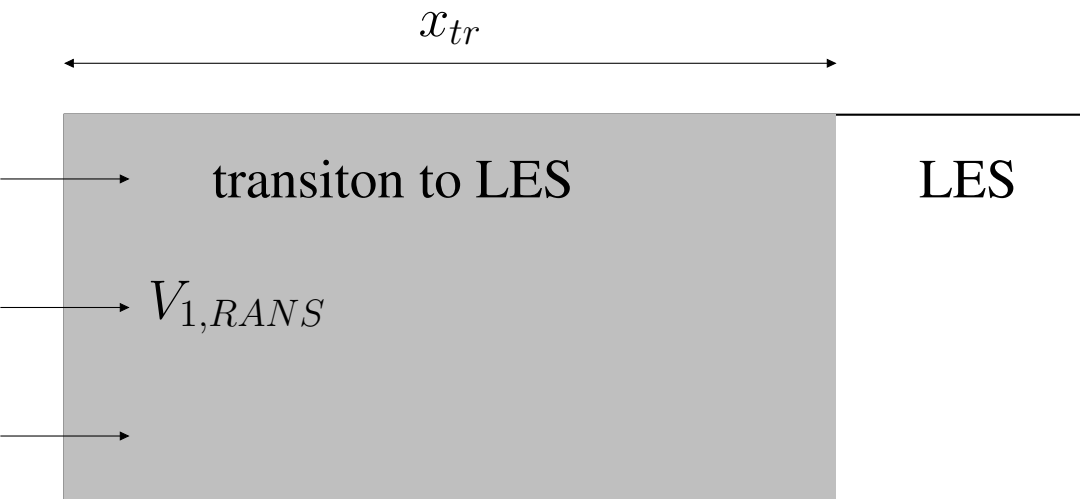
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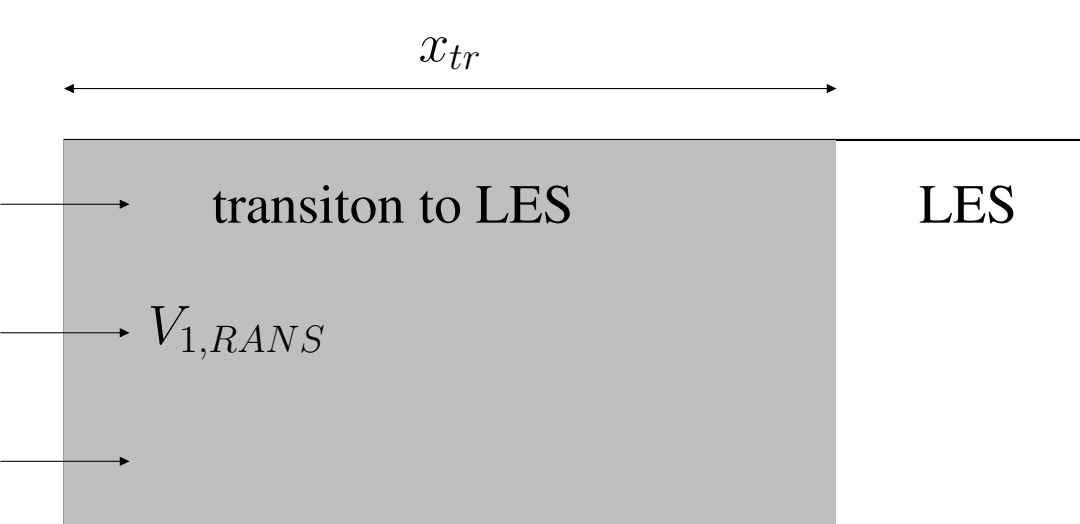
No inlet fluctuations, **large** x_{tr} .

On-line Lecture 12

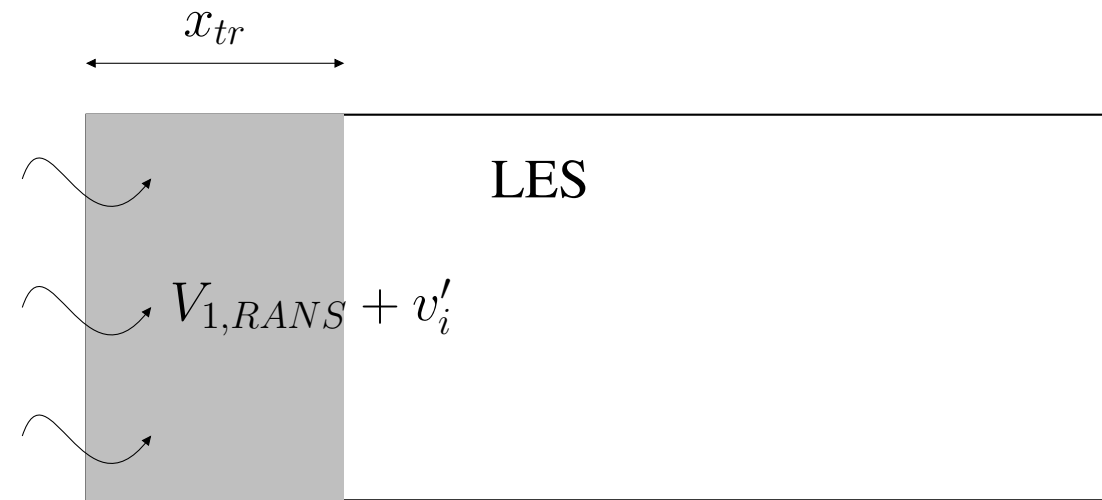
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Realistic, synthetic inlet fluctuations, **small** x_{tr} .

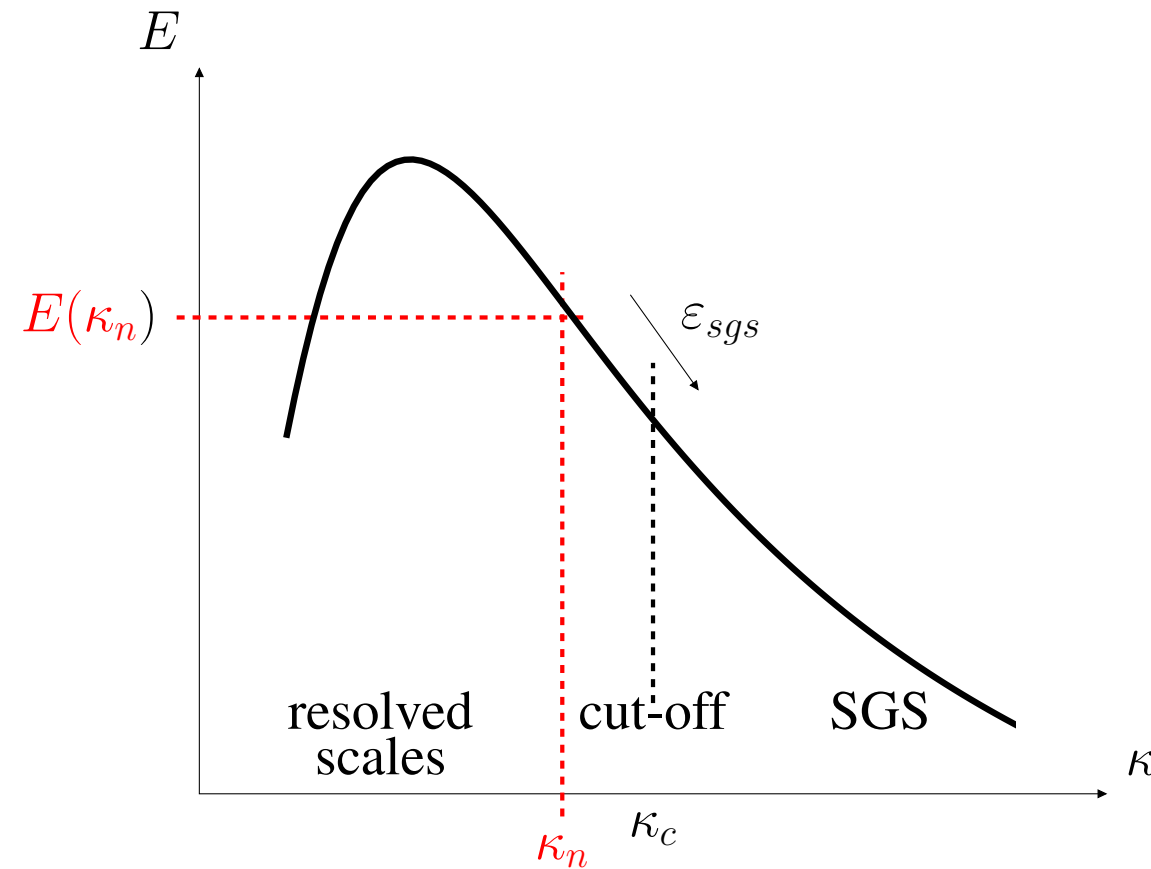
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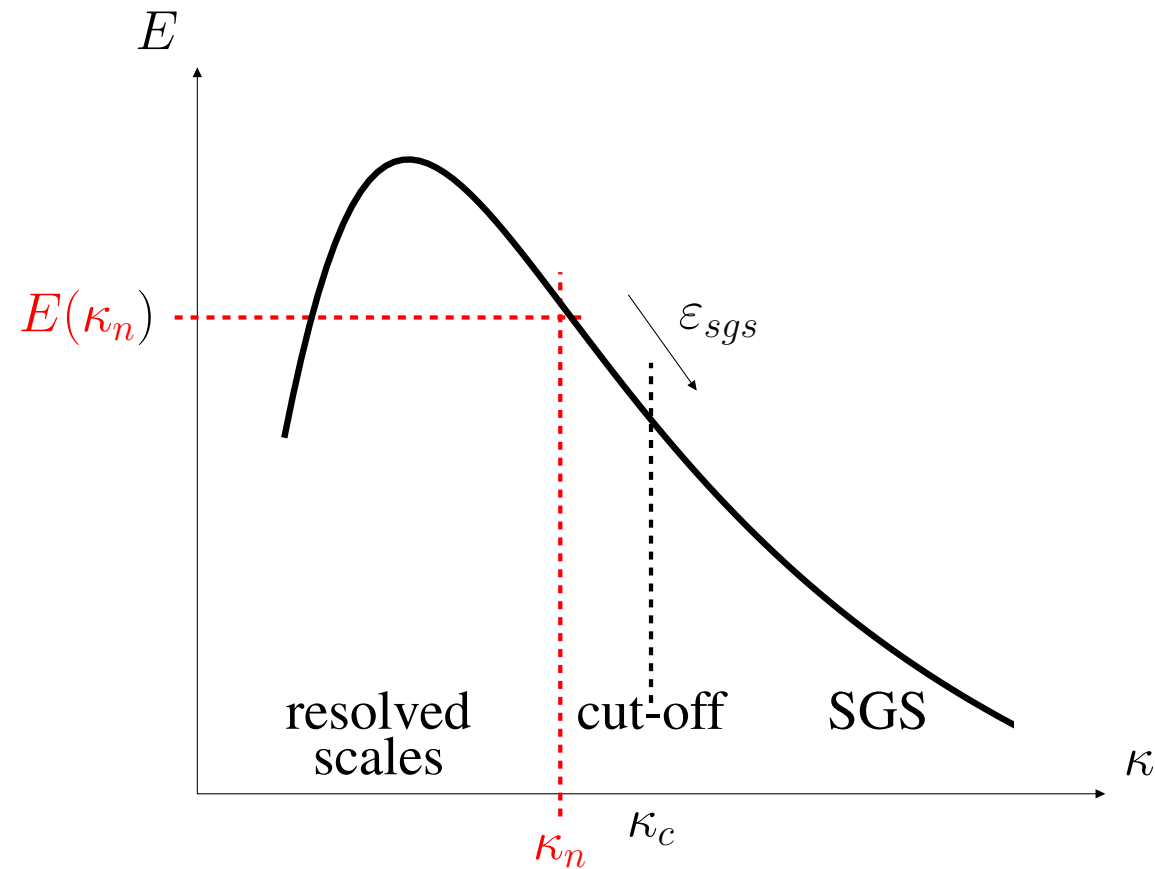
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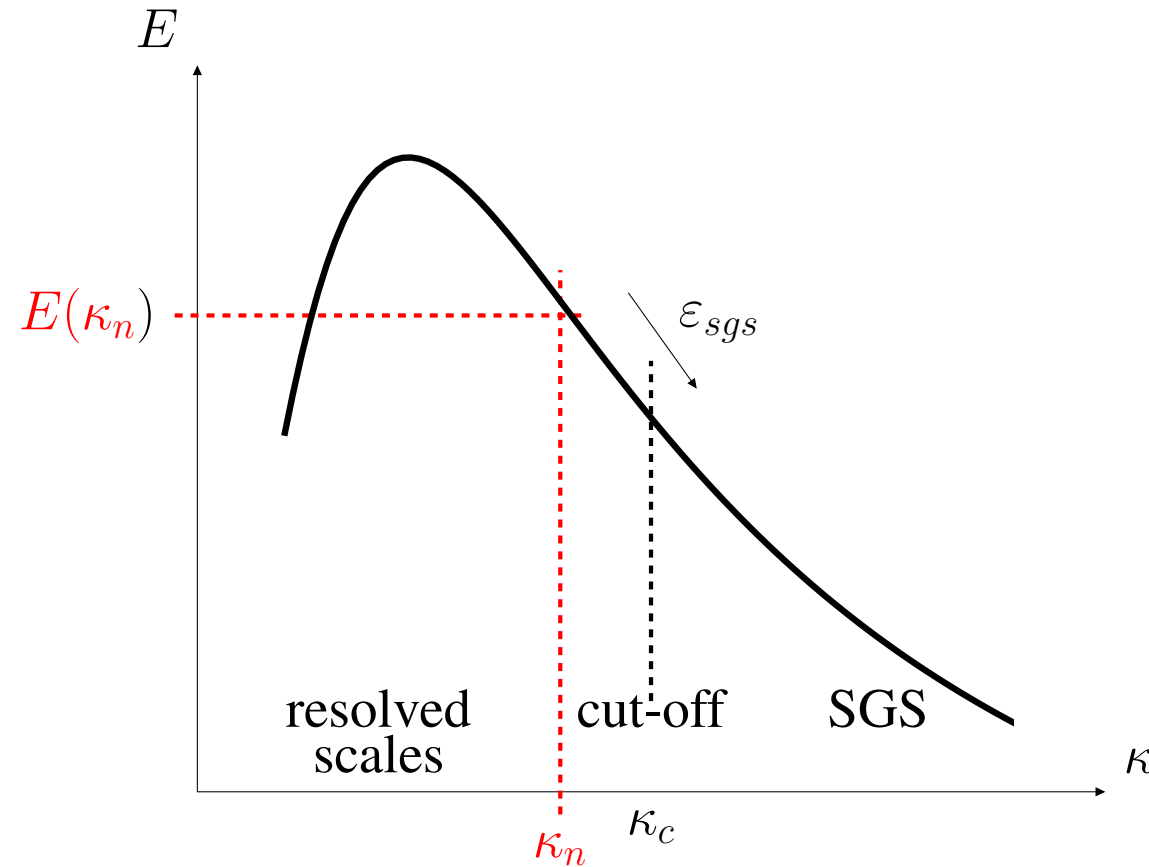


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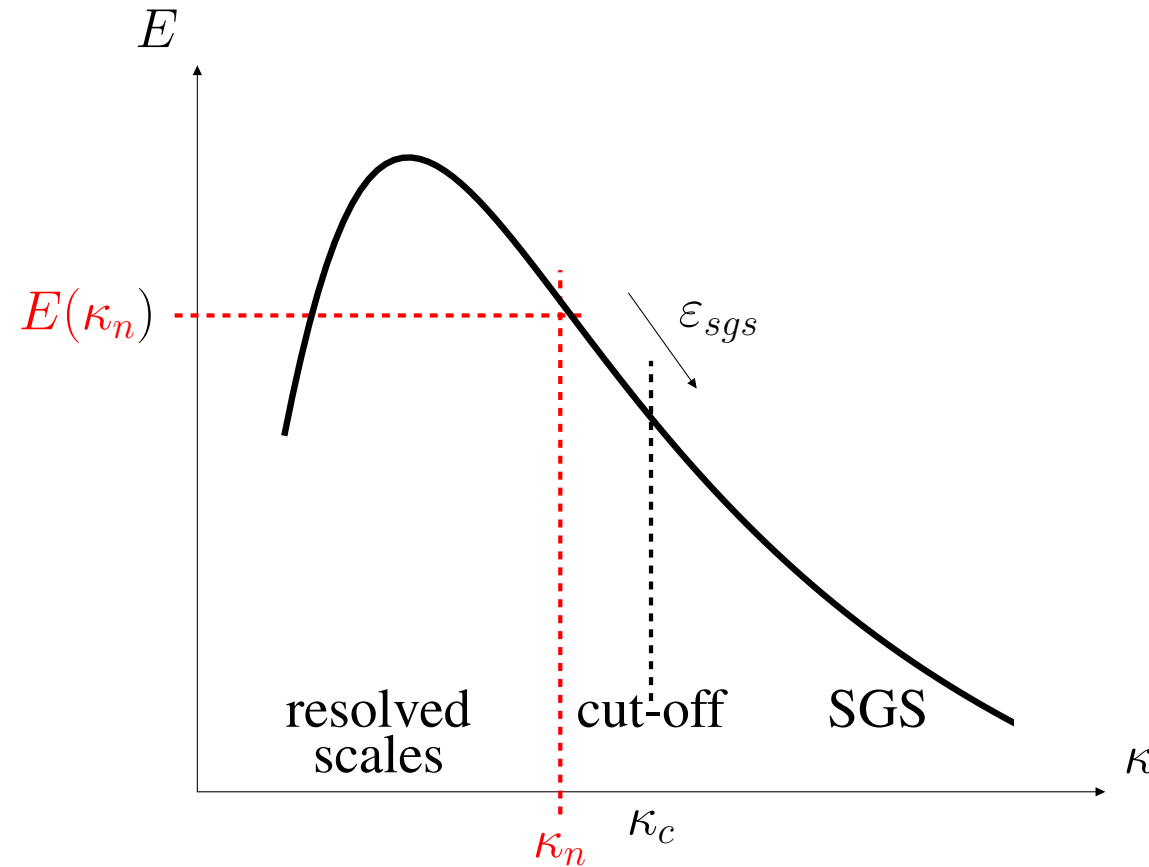


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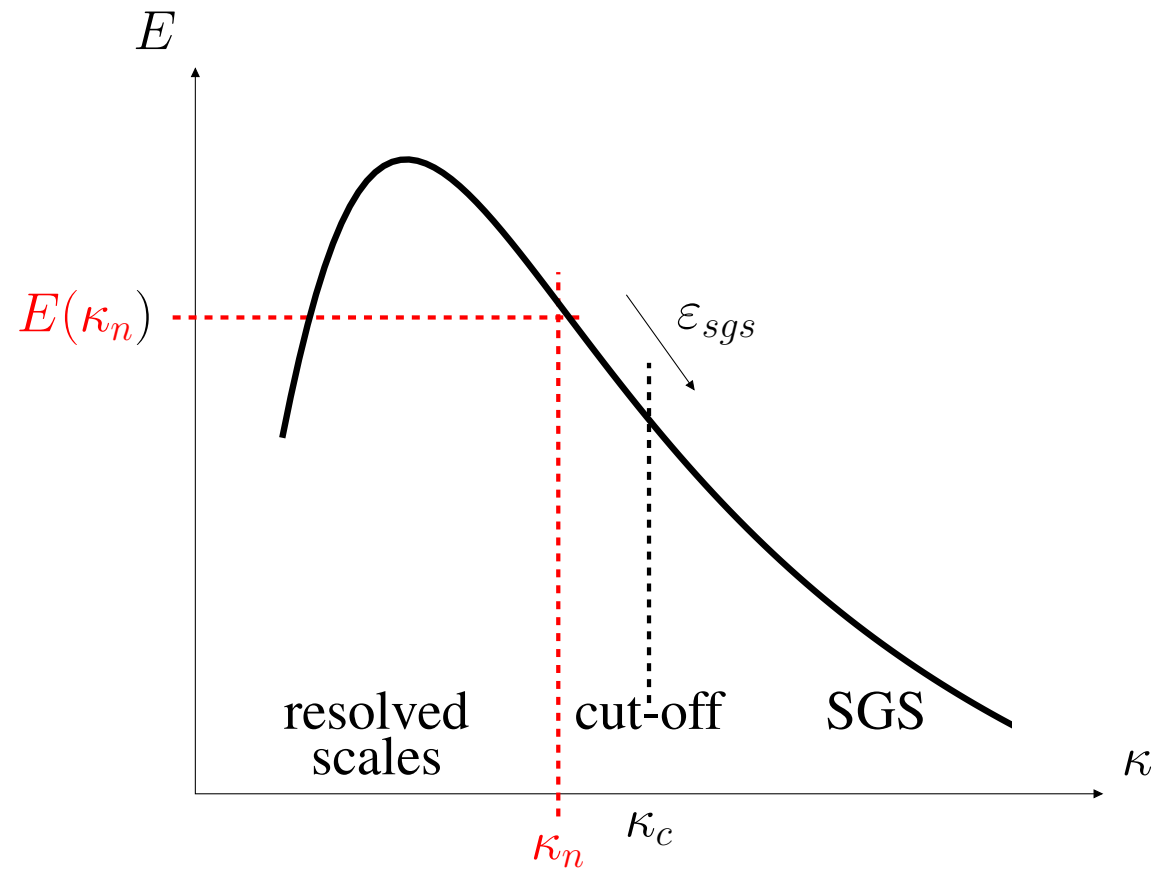


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$$\mathbf{v}'(\mathbf{x}) = 2 \sum_{n=1}^N \hat{u}^n \cos(\boldsymbol{\kappa}^n \cdot \mathbf{x} + \psi^n) \boldsymbol{\sigma}^n$$



Spectrum of velocity fluctuations.

► Usually we generate energy spectra from turbulent fluctuations. ► Here we prescribe a spectrum and generate turbulent fluctuations. ► $-5/3$ spectrum: ► this gives the amplitude \hat{u}^n for wavenumber κ_n

See Section 27.2, Random angles

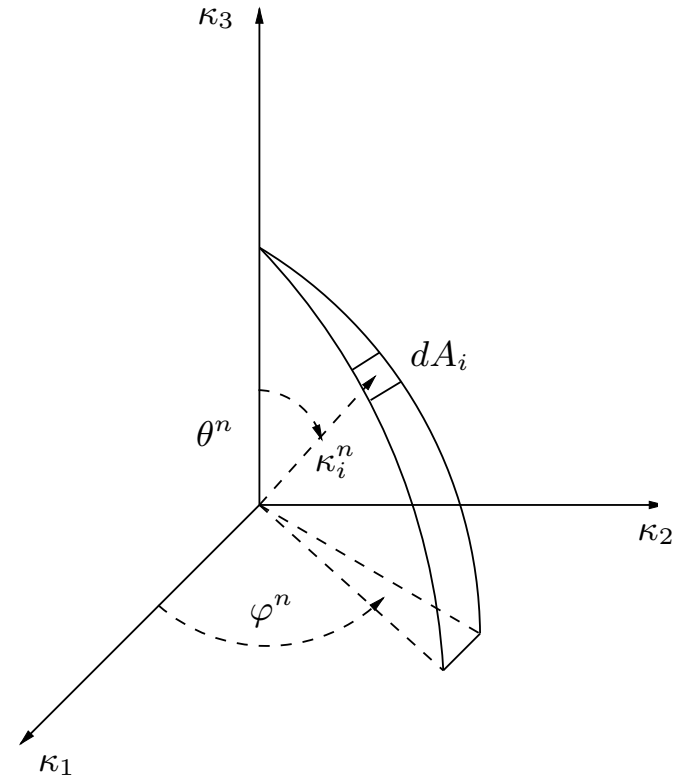
$$\mathbf{v}'(\mathbf{x}) = 2 \sum_{n=1}^N \hat{u}^n \cos(\boldsymbol{\kappa}^n \cdot \mathbf{x} + \psi^n) \boldsymbol{\sigma}^n,$$

Fourier serie

$p(\varphi^n) = 1/(2\pi)$	$0 \leq \varphi^n \leq 2\pi$
$p(\psi^n) = 1/(2\pi)$	$0 \leq \psi^n \leq 2\pi$
$p(\theta^n) = 1/2 \sin(\theta)$	$0 \leq \theta^n \leq \pi$
$p(\alpha^n) = 1/(2\pi)$	$0 \leq \alpha^n \leq 2\pi$

Probability distributions of the random variables.

α^n is the angle for $\boldsymbol{\sigma}^n$.



The probability of a wave in wave-space is the same for all dA_i on the shell of a sphere.

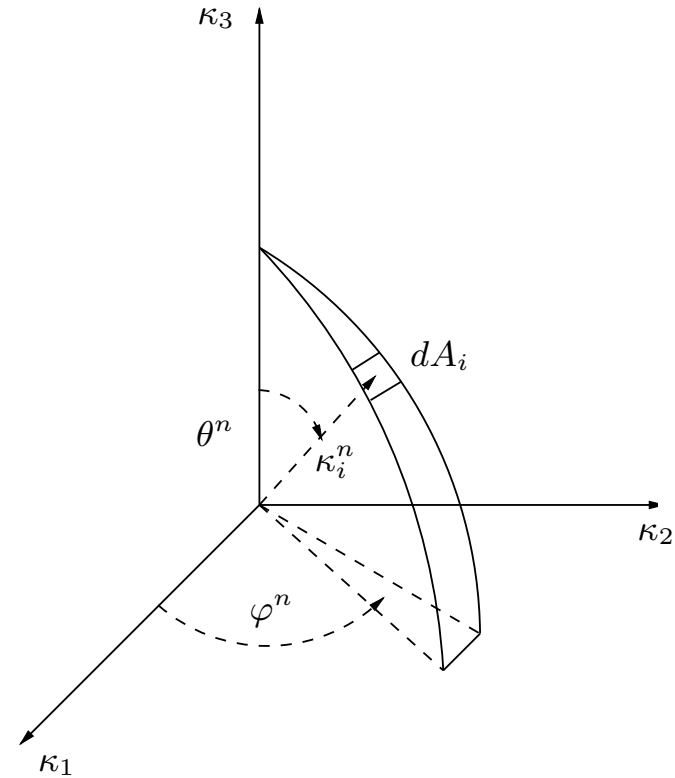
See Section 27.2, Random angles

$$\mathbf{v}'(\mathbf{x}) = 2 \sum_{n=1}^N \hat{u}^n \cos(\boldsymbol{\kappa}^n \cdot \mathbf{x} + \psi^n) \boldsymbol{\sigma}^n, \quad \text{Fourier serie}$$

$p(\varphi^n) = 1/(2\pi)$	$0 \leq \varphi^n \leq 2\pi$
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► Randomize the angles according to the table. The figure above gives

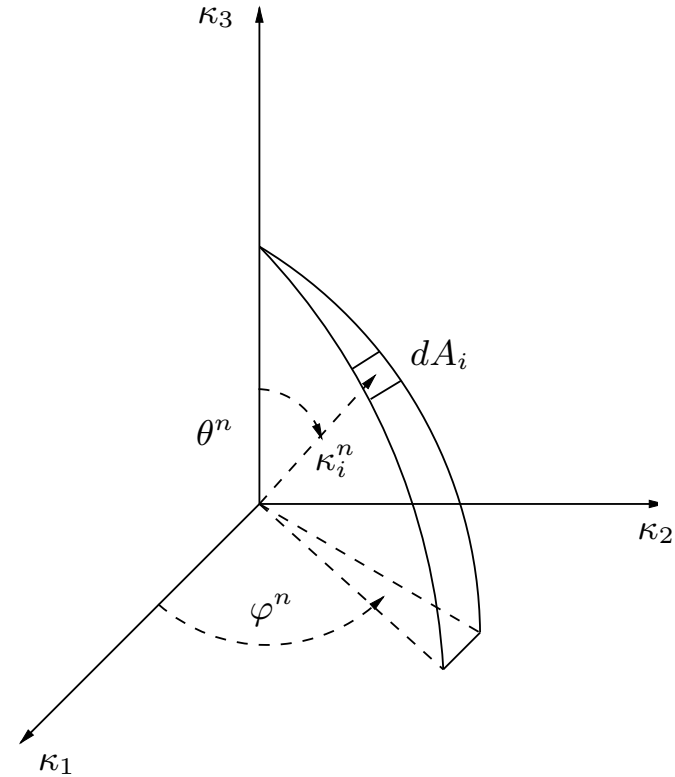
See Section 27.2, Random angles

$$\mathbf{v}'(\mathbf{x}) = 2 \sum_{n=1}^N \hat{u}^n \cos(\boldsymbol{\kappa}^n \cdot \mathbf{x} + \psi^n) \boldsymbol{\sigma}^n, \quad \text{Fourier serie}$$

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$$\kappa_1^n =$$

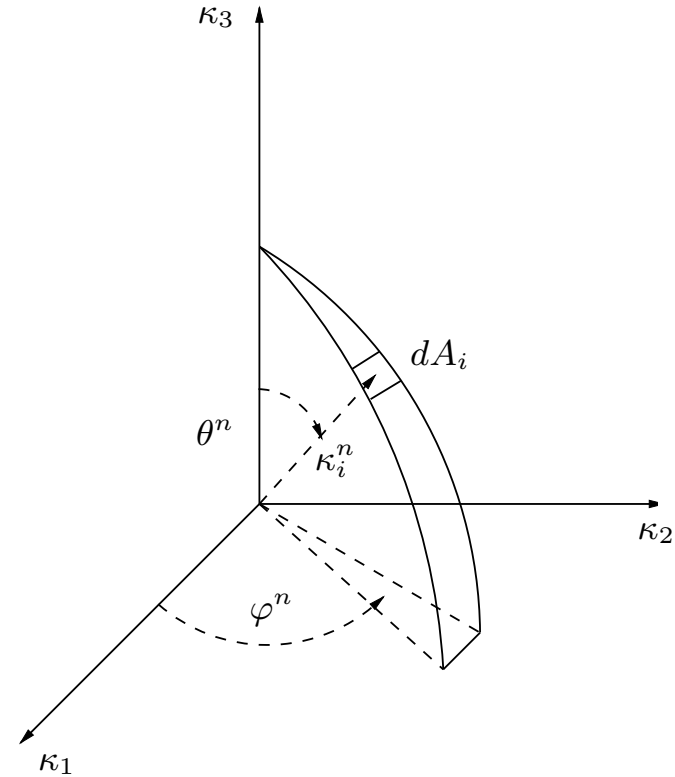
See Section 27.2, Random angles

$$\mathbf{v}'(\mathbf{x}) = 2 \sum_{n=1}^N \hat{u}^n \cos(\boldsymbol{\kappa}^n \cdot \mathbf{x} + \psi^n) \boldsymbol{\sigma}^n, \quad \text{Fourier serie}$$

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$$\kappa_1^n = \sin(\theta^n) \cos(\varphi^n)$$

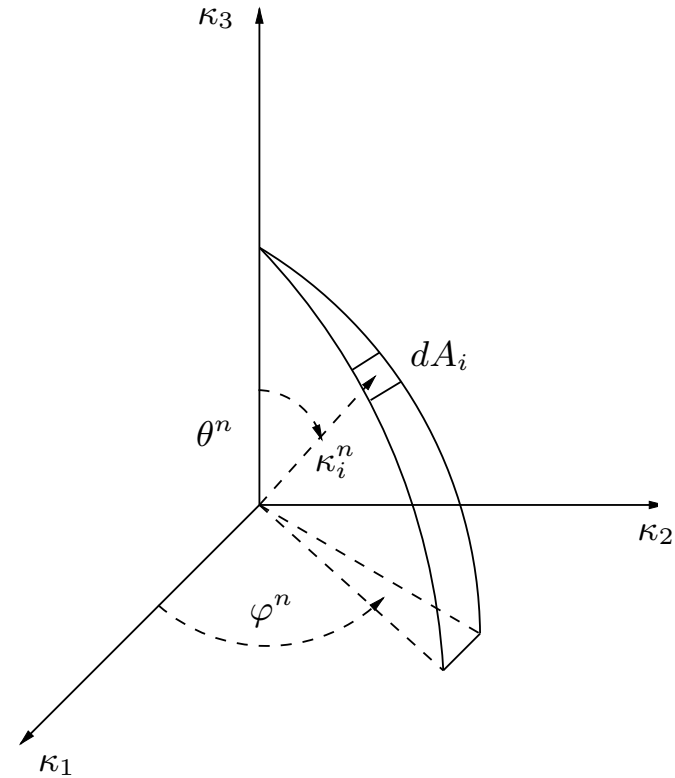
See Section 27.2, Random angles

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See Section 27.2, Random angles

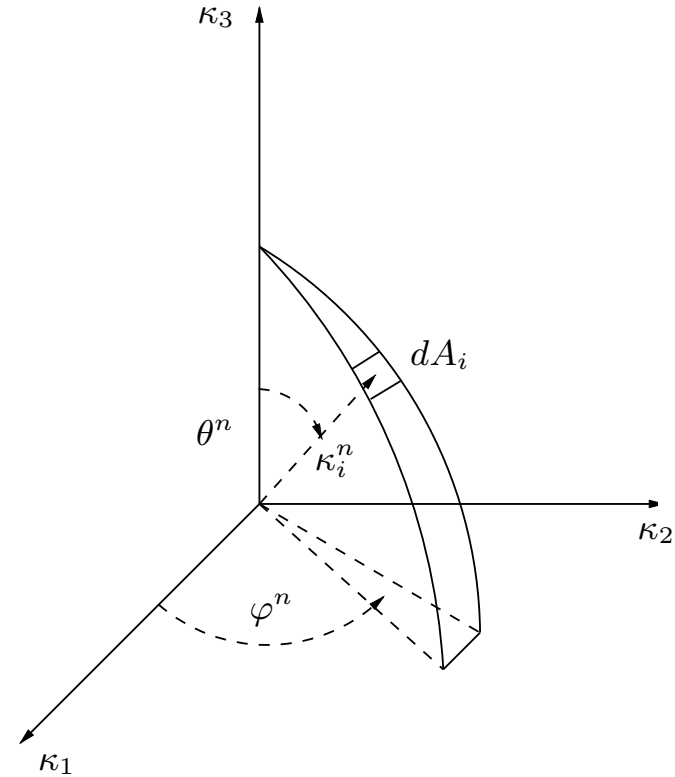
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See Section 27.2, Random angles

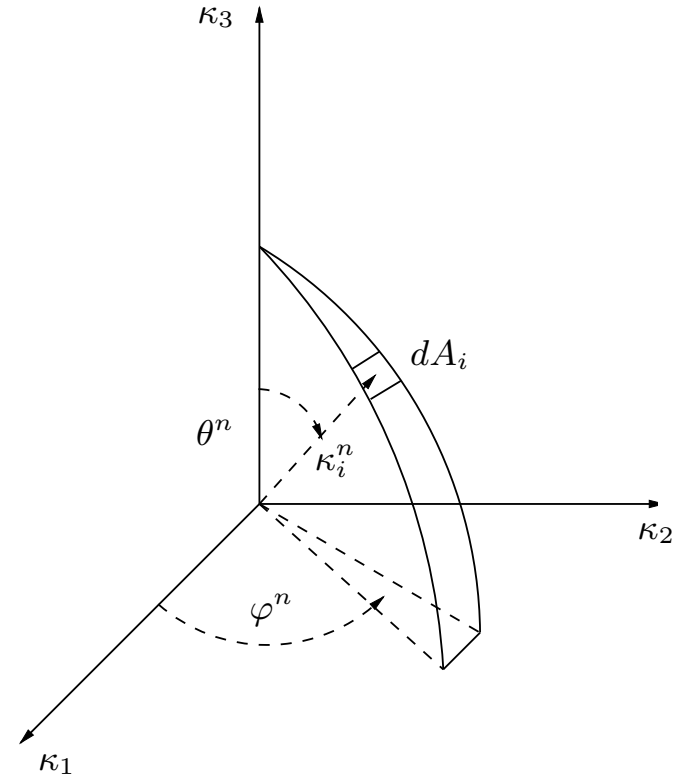
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$$\kappa_1^n = \sin(\theta^n) \cos(\varphi^n)$$

$$\kappa_2^n = \sin(\theta^n) \sin(\varphi^n)$$

$$\kappa_3^n =$$

See Section 27.2, Random angles

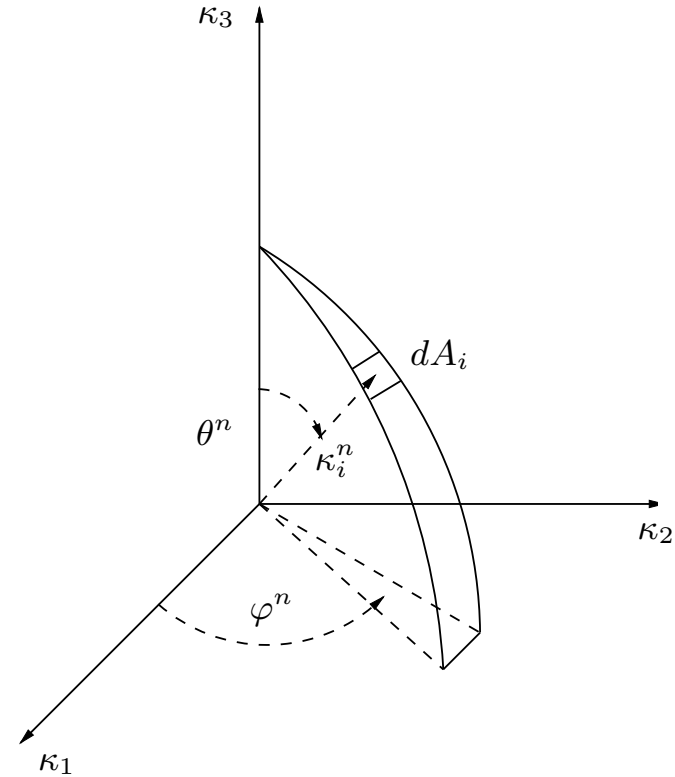
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Fourier serie

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$$\kappa_1^n = \sin(\theta^n) \cos(\varphi^n)$$

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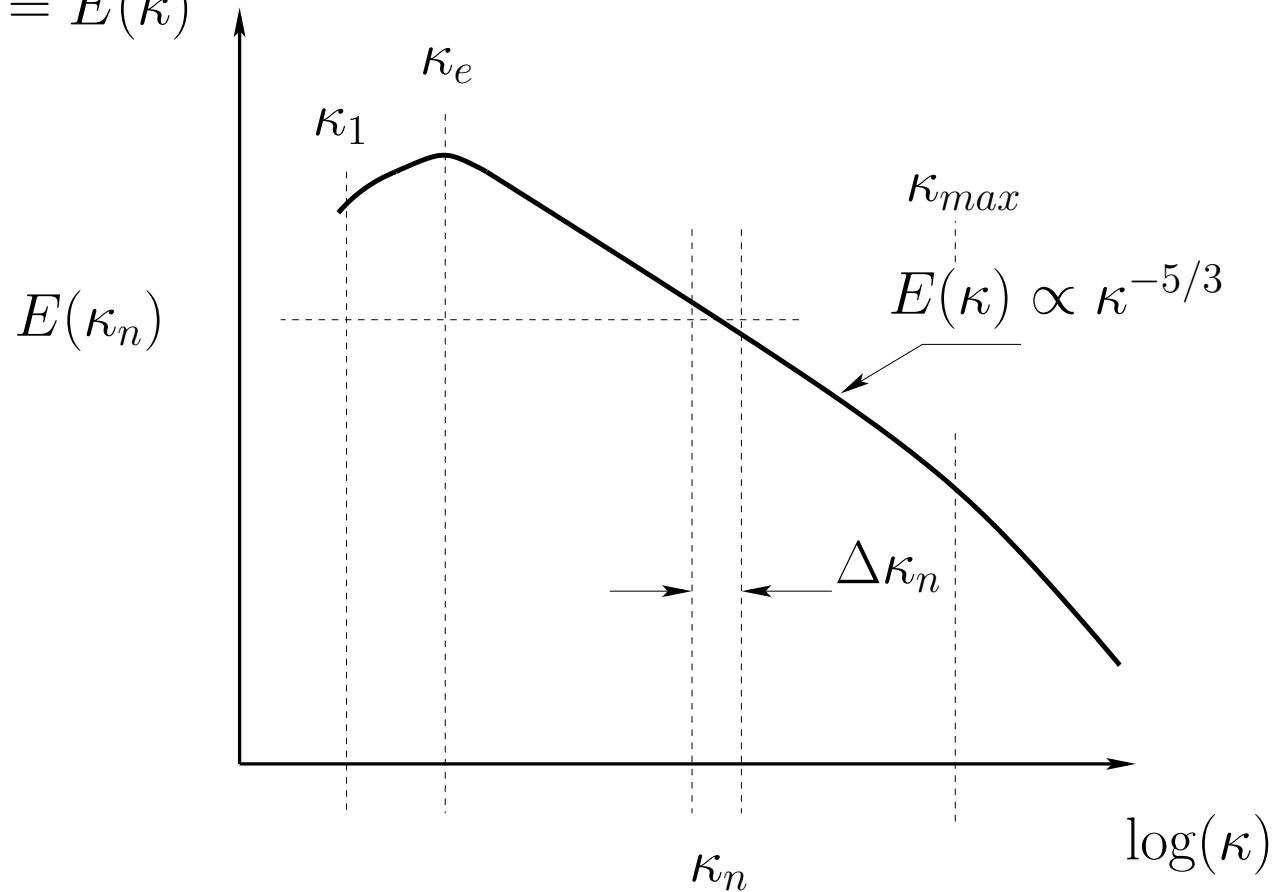
$$\kappa_3^n = \cos(\theta^n)$$

$$\mathbf{v}'(\mathbf{x}) = 2 \sum_{n=1}^N \hat{u}^n \cos(\boldsymbol{\kappa}^n \cdot \mathbf{x} + \psi^n) \boldsymbol{\sigma}^n, \quad \text{Fourier serie}$$

$$\mathbf{v}'(\mathbf{x}) = 2 \sum_{n=1}^N \hat{u}^n \cos(\boldsymbol{\kappa}^n \cdot \mathbf{x} + \psi^n) \boldsymbol{\sigma}^n, \quad \text{Fourier serie}$$

► Amplitude \hat{u}^n related to energy spectrum: $\hat{u}^n = (E(\kappa)\Delta\kappa)^{1/2}$

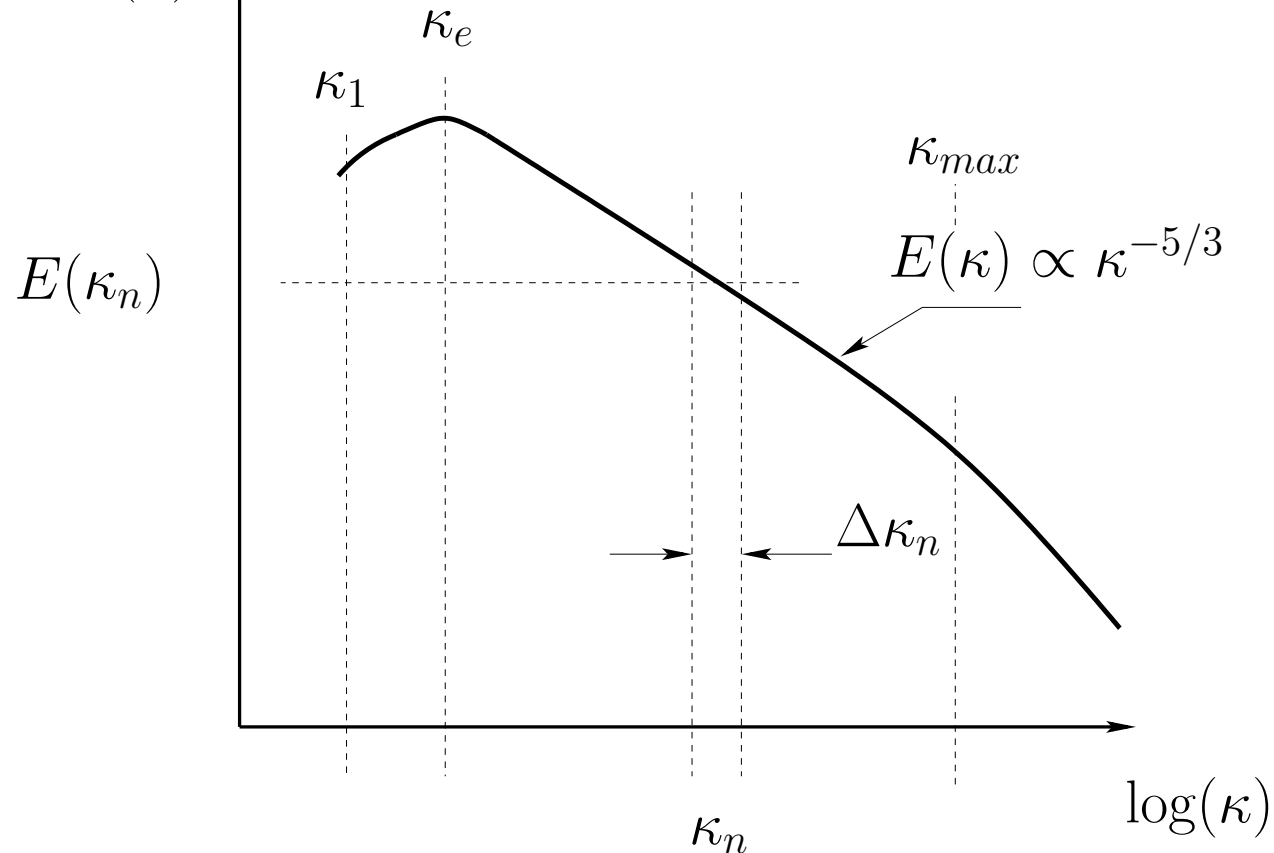
$$\hat{u}^2 / (\Delta\kappa) = E(\kappa)$$



$$\mathbf{v}'(\mathbf{x}) = 2 \sum_{n=1}^N \hat{u}^n \cos(\boldsymbol{\kappa}^n \cdot \mathbf{x} + \psi^n) \boldsymbol{\sigma}^n, \quad \text{Fourier serie}$$

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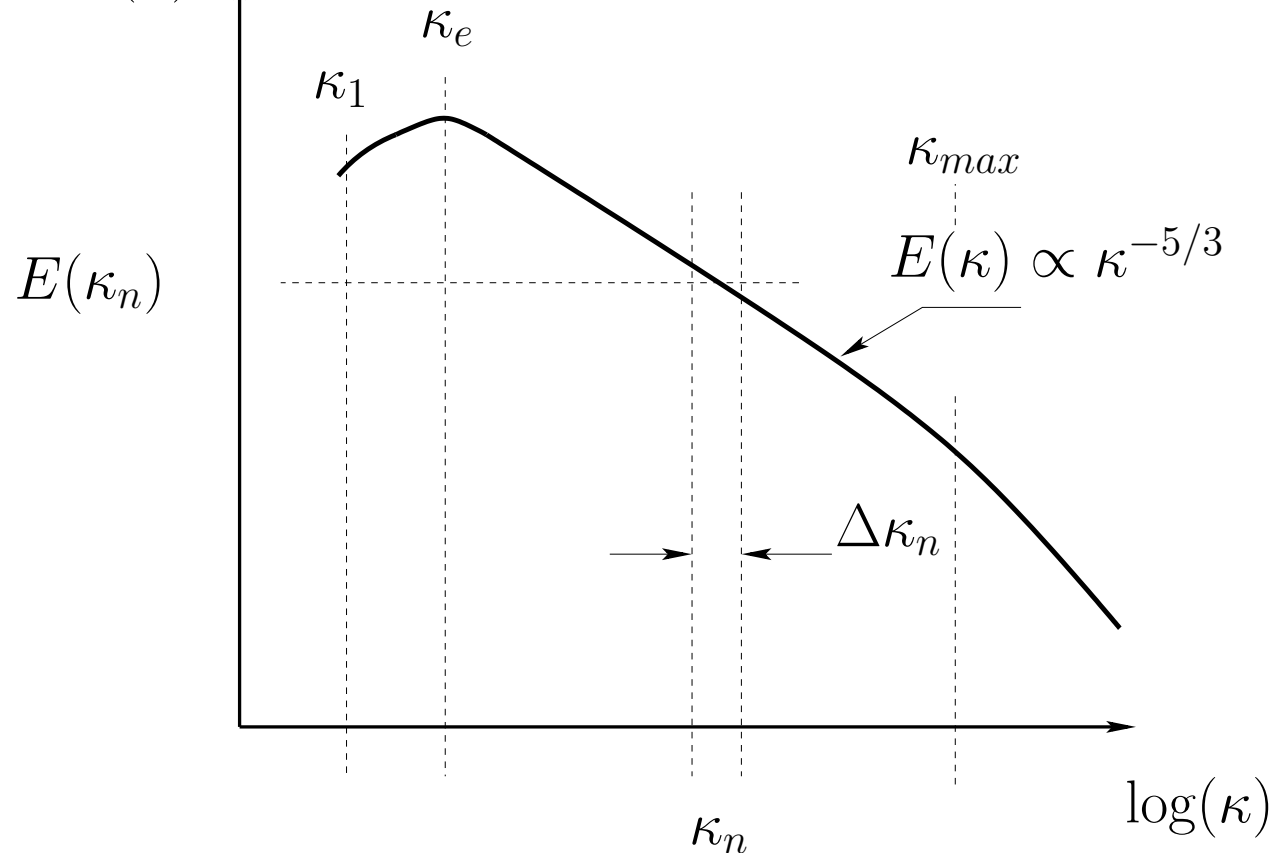


► For each wavenumber κ_n the energy spectrum above gives the amplitude \hat{u}^n

$$\mathbf{v}'(\mathbf{x}) = 2 \sum_{n=1}^N \hat{u}^n \cos(\boldsymbol{\kappa}^n \cdot \mathbf{x} + \psi^n) \boldsymbol{\sigma}^n, \quad \text{Fourier serie}$$

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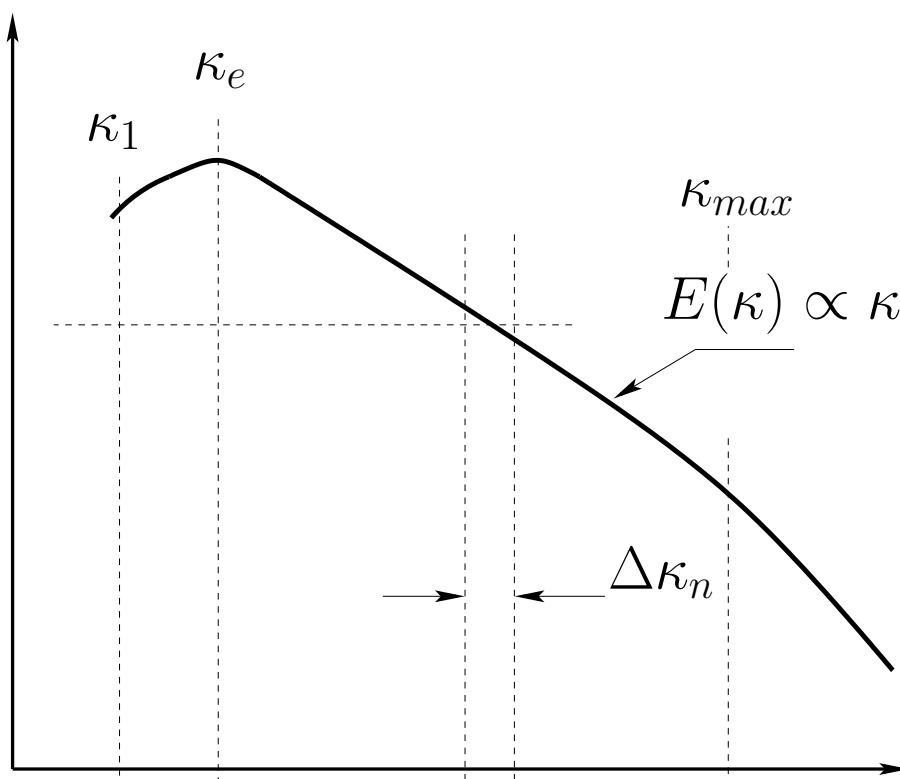
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► For each wavenumber κ_n the energy spectrum above gives the amplitude \hat{u}^n

$$\hat{u}^2 / (\Delta\kappa) = E(\kappa)$$

$E(\kappa_n)$



κ_{max}

$E(\kappa) \propto \kappa^{-5/3}$

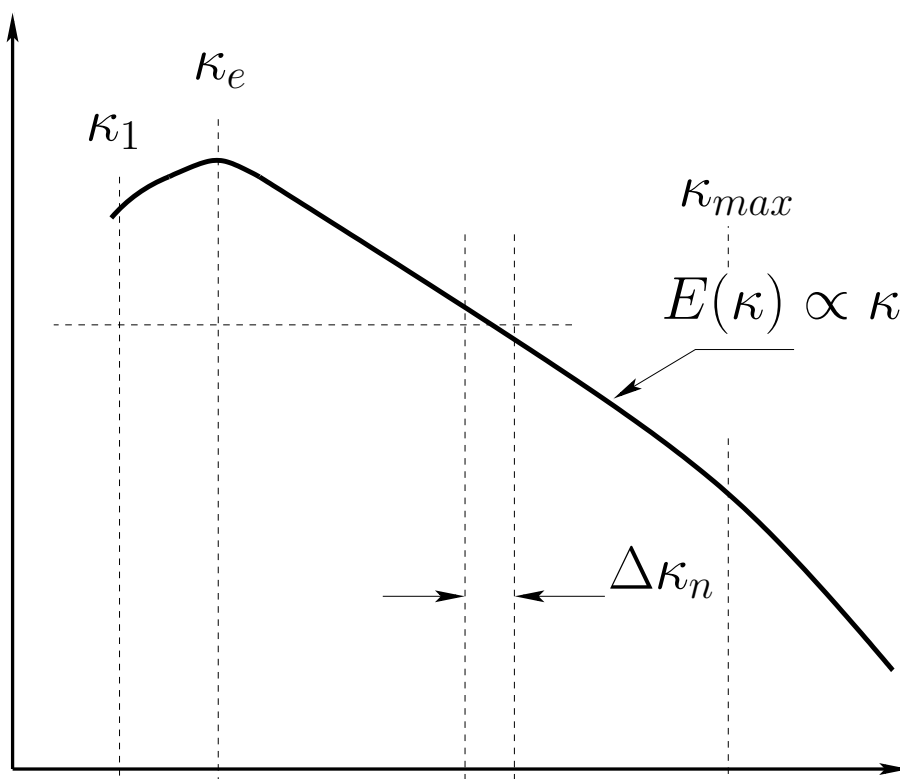
$\Delta\kappa_n$

κ_n

$\log(\kappa)$

$$\hat{u}^2 / (\Delta\kappa) = E(\kappa)$$

$E(\kappa_n)$



κ_{max}

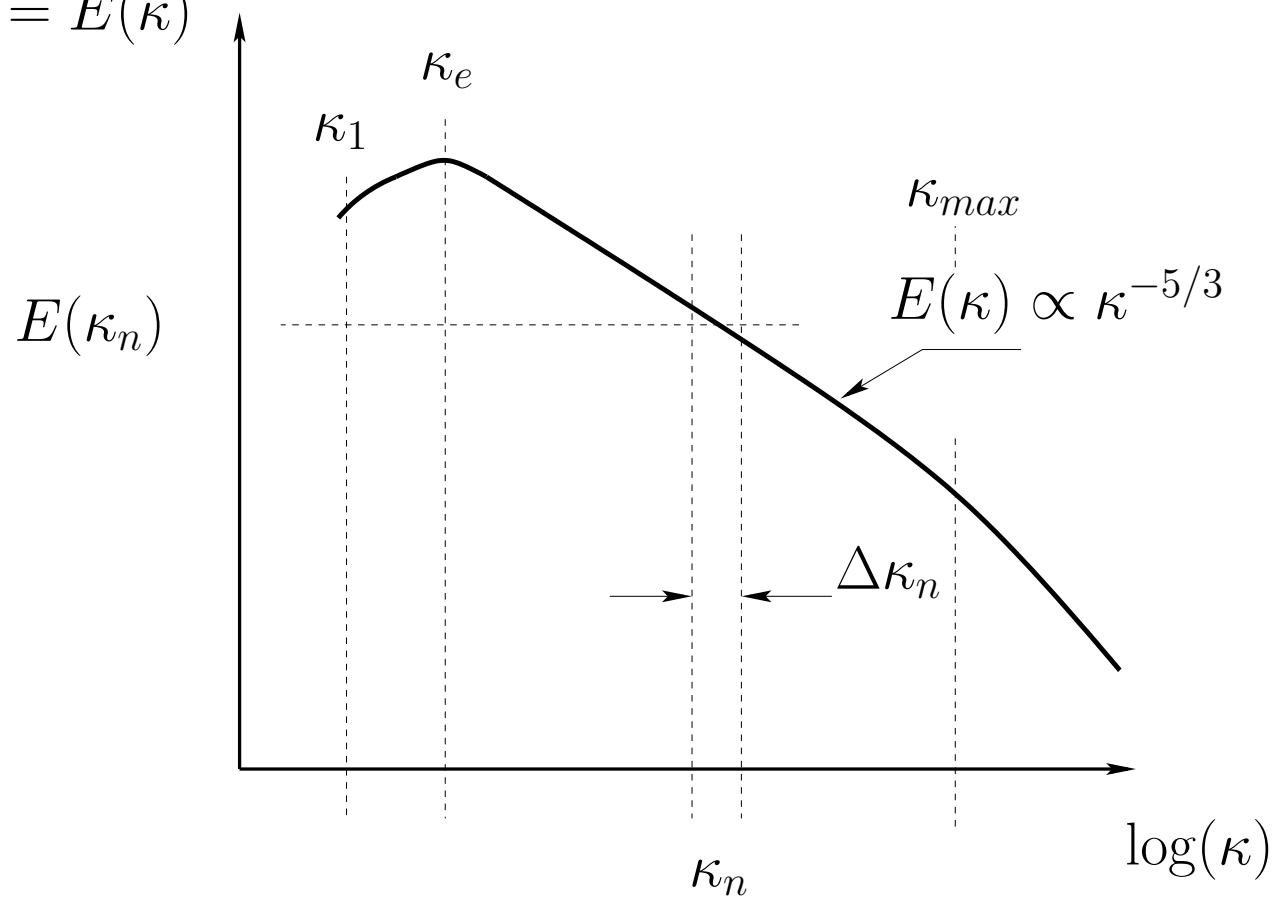
$E(\kappa) \propto \kappa^{-5/3}$

$\Delta\kappa_n$

κ_n

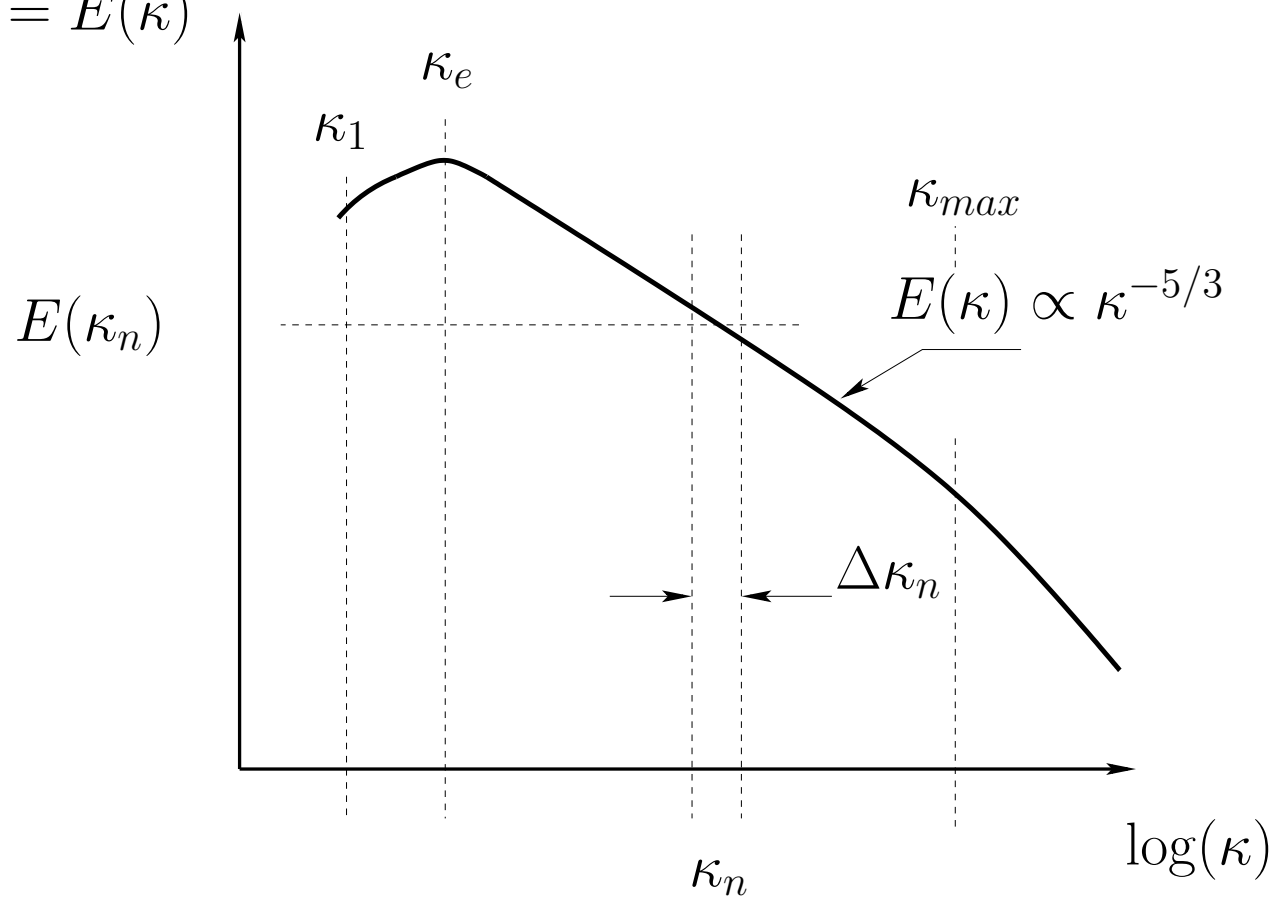
$\log(\kappa)$

$$\hat{u}^2 / (\Delta\kappa) = E(\kappa)$$



► Highest wave number: $\kappa_{max} = 2\pi / 2\Delta$ from the cell size, $\Delta = \min(\Delta x_2)$

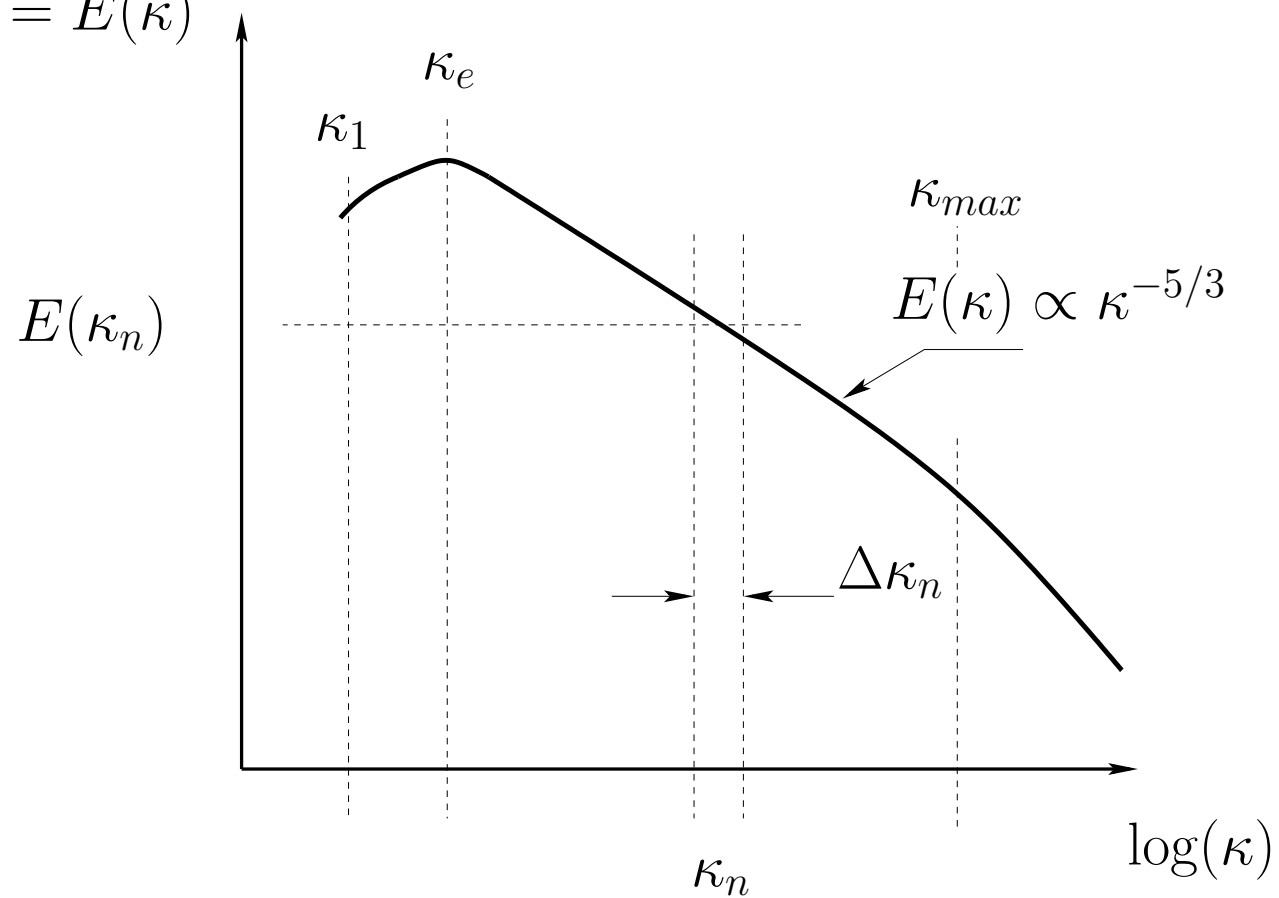
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► Highest wave number: $\kappa_{max} = 2\pi/2\Delta$ from the cell size, $\Delta = \min(\Delta x_2)$

► Most energetic wave number: $\kappa_e \propto 1/L_t$:

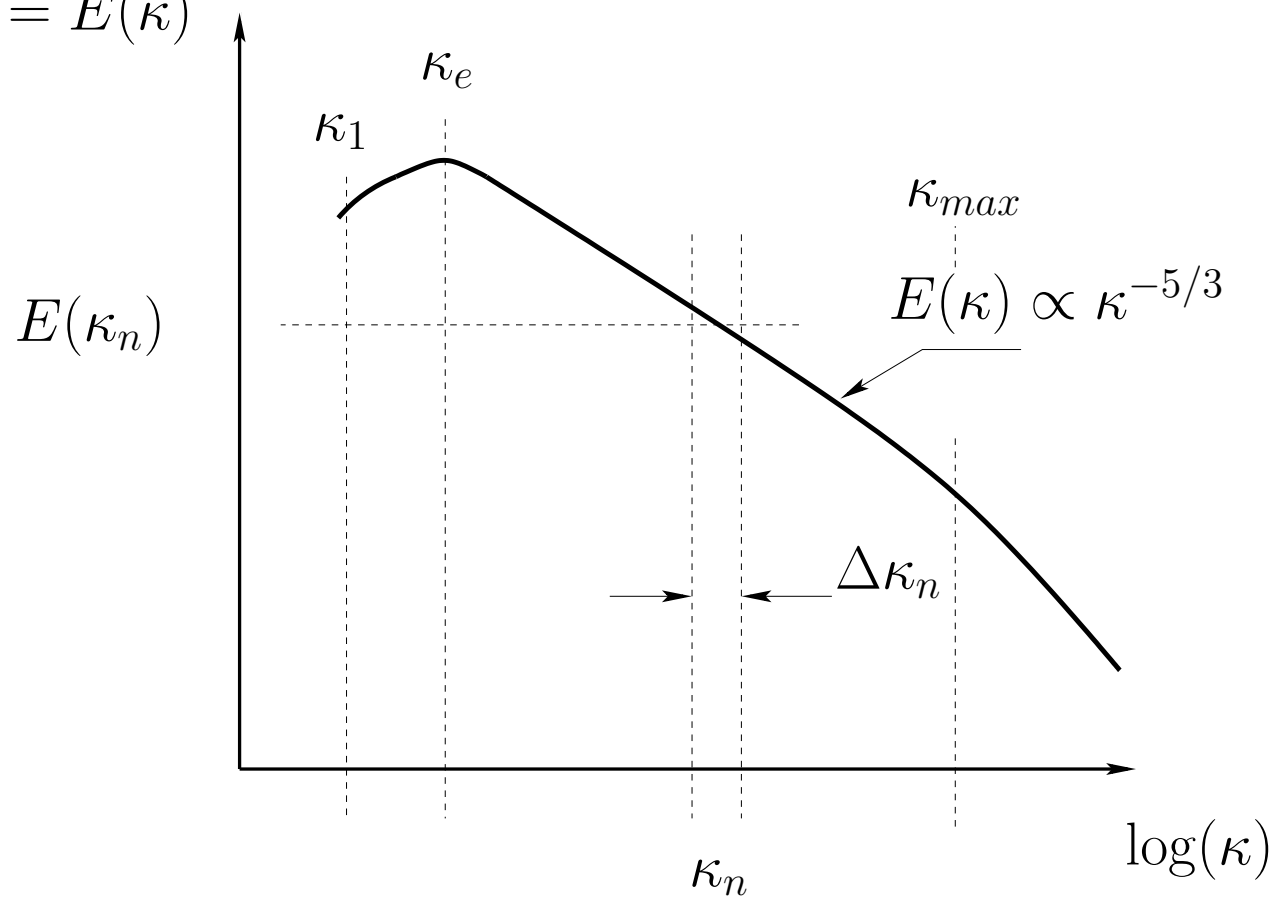
$$\hat{u}^2 / (\Delta\kappa) = E(\kappa)$$



► Highest wave number: $\kappa_{max} = 2\pi/2\Delta$ from the cell size, $\Delta = \min(\Delta x_2)$

► Most energetic wave number: $\kappa_e \propto 1/L_t$: integral turbulent length scale.

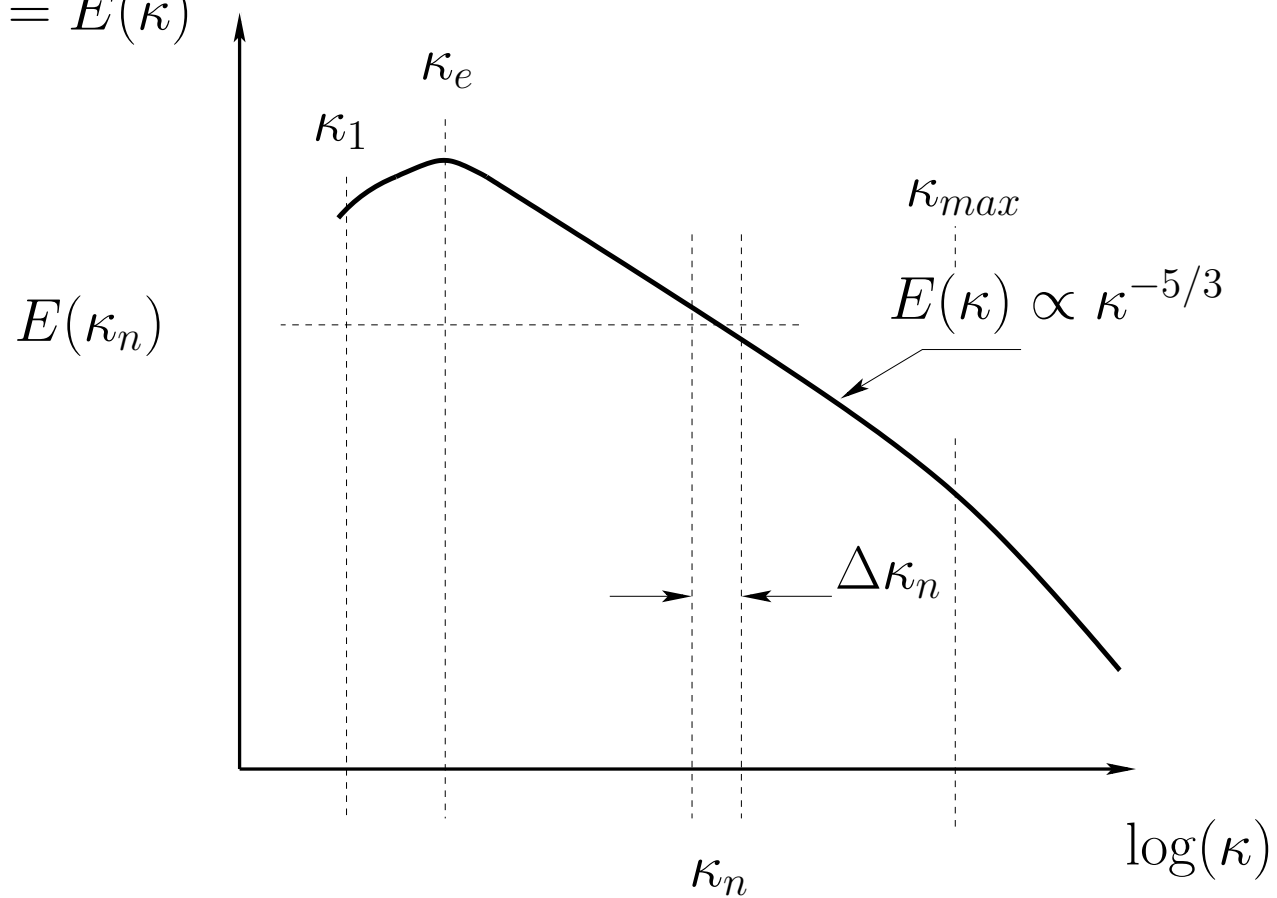
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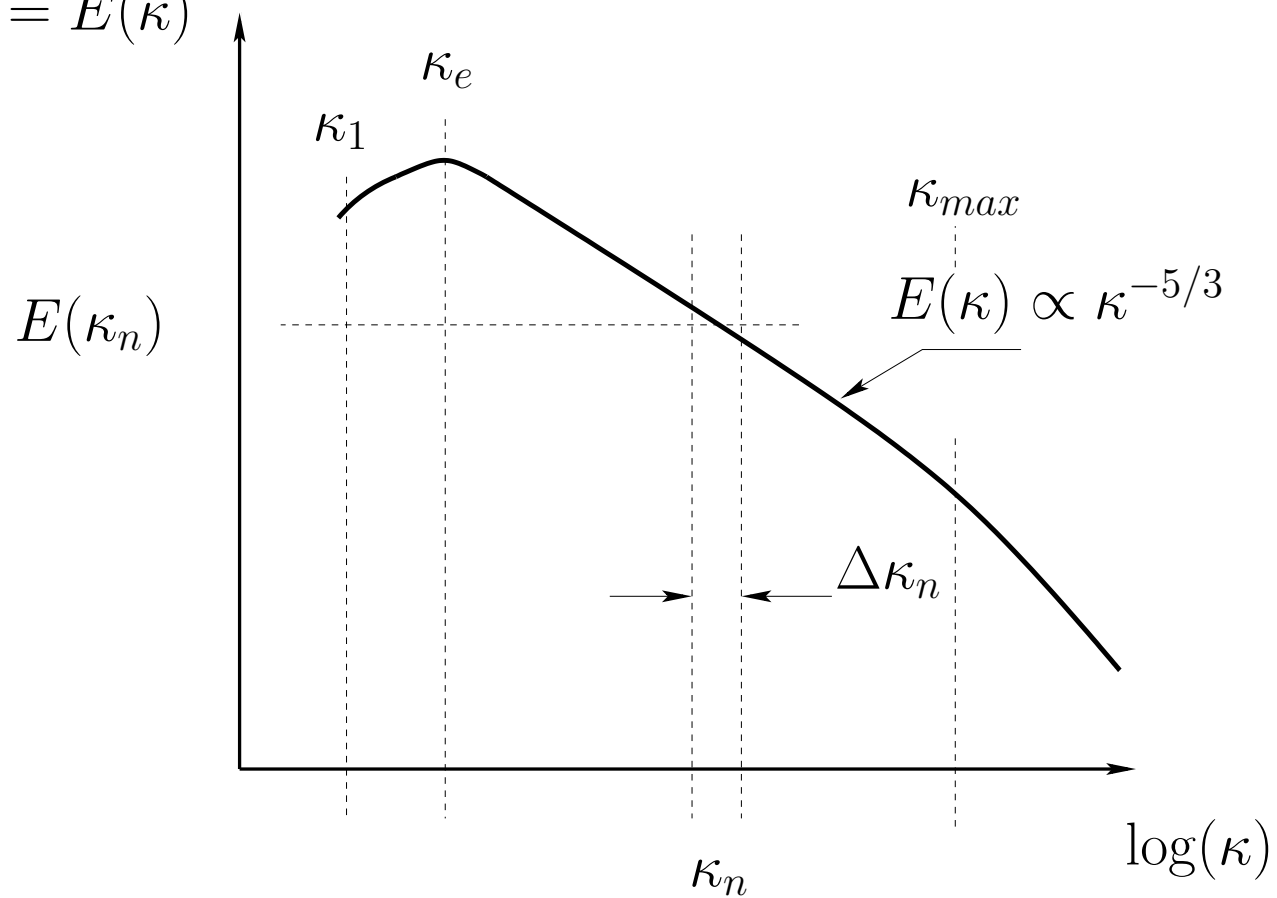
► Most energetic wave number: $\kappa_e \propto 1/L_t$: integral turbulent length scale. ► $\kappa_e = 0.75/L_t$

$$\hat{u}^2 / (\Delta\kappa) = E(\kappa)$$



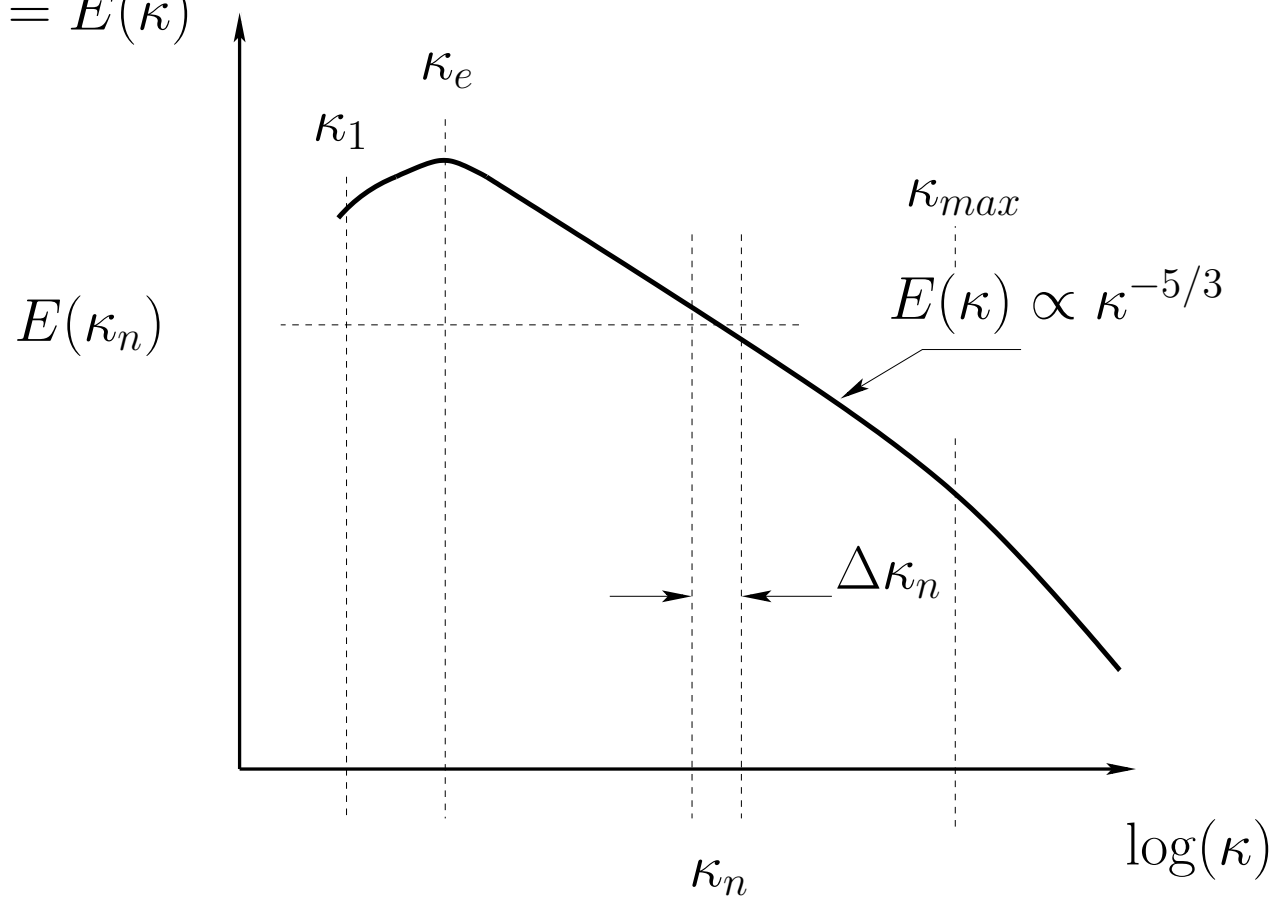
- ▶ Highest wave number: $\kappa_{max} = 2\pi/2\Delta$ from the cell size, $\Delta = \min(\Delta x_2)$
- ▶ Most energetic wave number: $\kappa_e \propto 1/L_t$: integral turbulent length scale. ▶ $\kappa_e = 0.75/L_t$
- ▶ Smallest wave number: $\kappa_{min} = \kappa_1 = \kappa_e/5$, $\Delta\kappa = (\kappa_{max} - \kappa_{min})/N$

$$\hat{u}^2 / (\Delta\kappa) = E(\kappa)$$



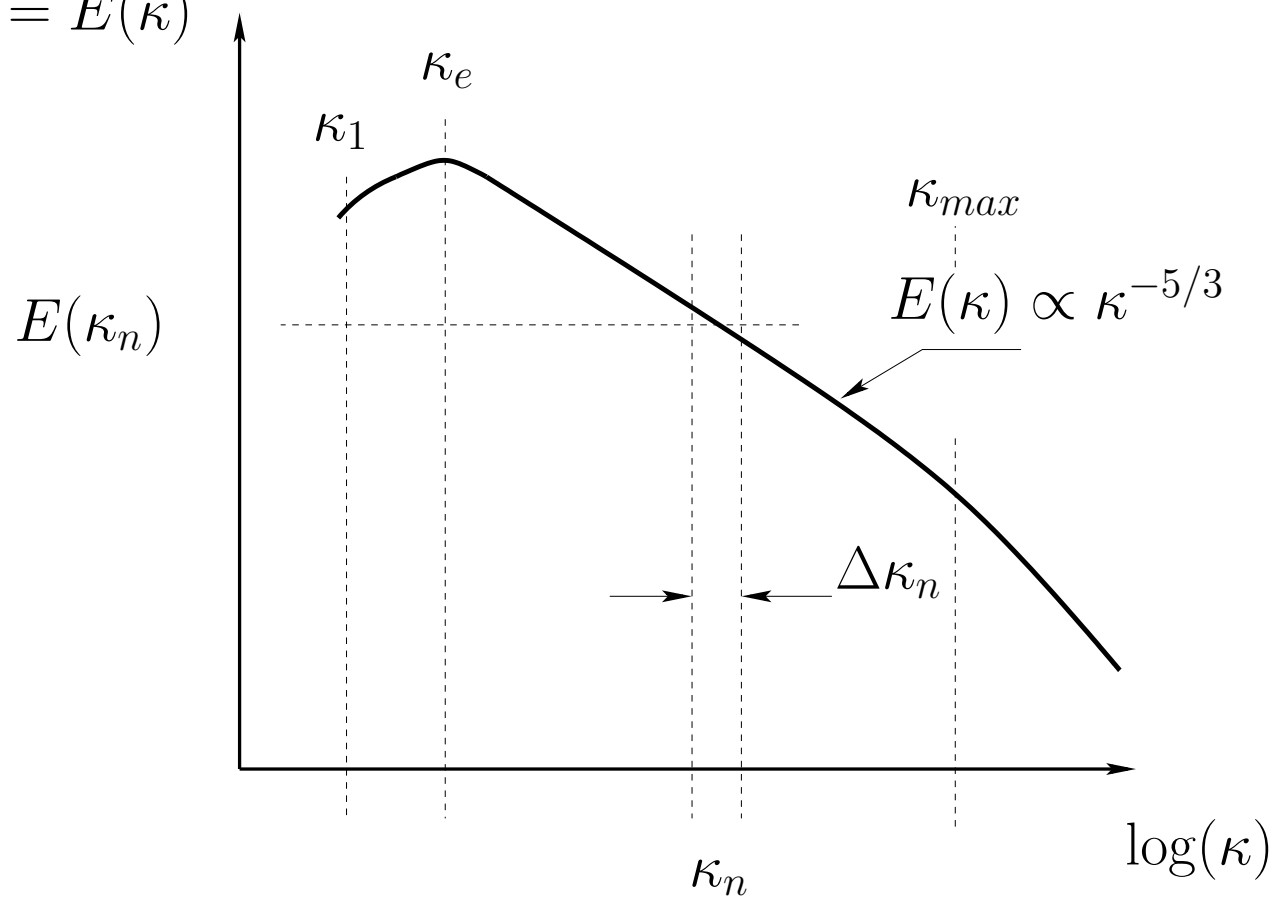
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- ▶ Number of wave numbers: N

$$\hat{u}^2 / (\Delta\kappa) = E(\kappa)$$



- ▶ Highest wave number: $\kappa_{max} = 2\pi/2\Delta$ from the cell size, $\Delta = \min(\Delta x_2)$
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- ▶ Smallest wave number: $\kappa_{min} = \kappa_1 = \kappa_e/5$, $\Delta\kappa = (\kappa_{max} - \kappa_{min})/N$
- ▶ Number of wave numbers: N ▶ 150

$$\hat{u}^2 / (\Delta\kappa) = E(\kappa)$$



- ▶ Highest wave number: $\kappa_{max} = 2\pi/2\Delta$ from the cell size, $\Delta = \min(\Delta x_2)$
- ▶ Most energetic wave number: $\kappa_e \propto 1/L_t$: integral turbulent length scale. ▶ $\kappa_e = 0.75/L_t$
- ▶ Smallest wave number: $\kappa_{min} = \kappa_1 = \kappa_e/5$, $\Delta\kappa = (\kappa_{max} - \kappa_{min})/N$
- ▶ Number of wave numbers: N ▶ 150
- ▶ Now the fluctuations, $\mathbf{v}'(\mathbf{x})$, can be computed

$$v'_1 = 2 \sum_{n=1}^N \hat{u}^n \cos(\beta^n) \sigma_1$$

$$v'_2 = 2 \sum_{n=1}^N \hat{u}^n \cos(\beta^n) \sigma_2$$

$$v'_3 = 2 \sum_{n=1}^N \hat{u}^n \cos(\beta^n) \sigma_3$$

$$\beta^n = k_1^n x_1 + k_2^n x_2 + k_3^n x_3 + \psi^n$$

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► Synthetic turbulent isotropic fluctuations at the inlet plane for all time steps.

$$v'_1 = 2 \sum_{n=1}^N \hat{u}^n \cos(\beta^n) \sigma_1$$

$$v'_2 = 2 \sum_{n=1}^N \hat{u}^n \cos(\beta^n) \sigma_2$$

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- ▶ Synthetic turbulent isotropic fluctuations at the inlet plane for all time steps.
- ▶ With a specified integral lengthscale

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▶ Synthetic turbulent isotropic fluctuations at the inlet plane for all time steps.

▶ With a specified integral lengthscale

▶ **BUT:**

$$v'_1 = 2 \sum_{n=1}^N \hat{u}^n \cos(\beta^n) \sigma_1$$

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- ▶ Synthetic turbulent isotropic fluctuations at the inlet plane for all time steps.
- ▶ With a specified integral lengthscale
- ▶ **BUT:** ▶ no correlation between the timesteps

$$v'_1 = 2 \sum_{n=1}^N \hat{u}^n \cos(\beta^n) \sigma_1$$

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- ▶ Synthetic turbulent isotropic fluctuations at the inlet plane for all time steps.
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- ▶ **BUT:** ▶ no correlation between the timesteps ▶ i.e. white noise in time

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- ▶ Synthetic turbulent isotropic fluctuations at the inlet plane for all time steps.
- ▶ With a specified integral lengthscale
- ▶ **BUT:** ▶ no correlation between the timesteps ▶ i.e. white noise in time

¶ See Section 27.8, Introducing time correlation

¶ See Section 27.8, [Introducing time correlation](#)

▶ The synthetic fluctuations are not correlated in time. An asymmetric time filter is used

$$(\mathcal{V}'_1)^m = a(\mathcal{V}'_1)^{m-1} + b(v'_1)^m$$

¶ See Section 27.8, [Introducing time correlation](#)

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¶ See Section 27.8, [Introducing time correlation](#)

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$$(\mathcal{V}'_1)^m = a(\mathcal{V}'_1)^{m-1} + b(v'_1)^m$$

▶ The coefficient a is related to the turbulent integral timescale, \mathcal{T} , as

¶ See Section 27.8, [Introducing time correlation](#)

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$$a = \exp(-\Delta t/\mathcal{T}) \tag{41.1}$$

¶ See Section 27.8, [Introducing time correlation](#)

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► We want $\mathcal{V}'_{1,rms} = v'_{1,rms}$

¶ See Section 27.8, [Introducing time correlation](#)

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¶ See Section 27.8, [Introducing time correlation](#)

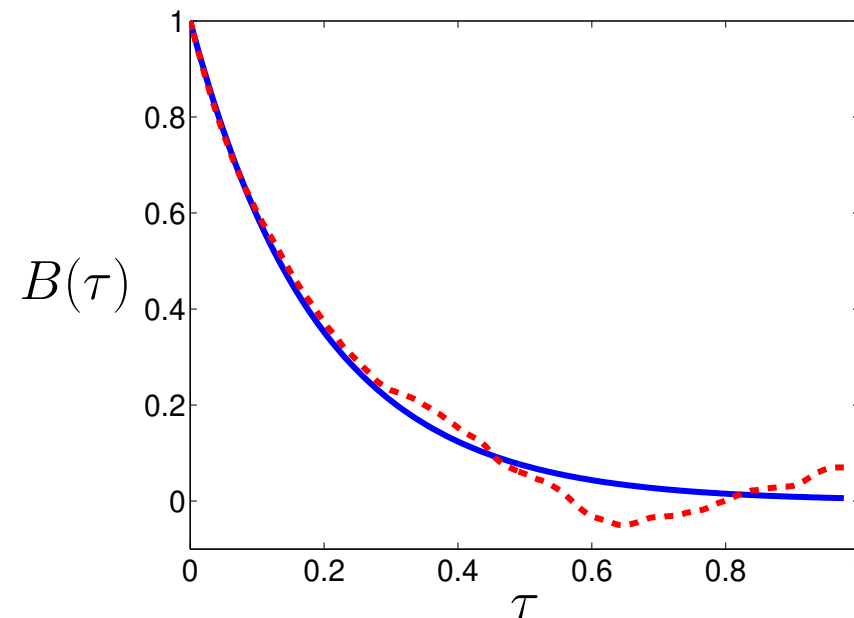
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▶ We want $\mathcal{V}'_{1,rms} = v'_{1,rms}$ ▶ $b = (1 - a^2)^{1/2}$ ensures that



Auto correlation. —: Eq. 41.1; - -: $B(\tau) = \langle \mathcal{V}'_1(t)\mathcal{V}'_1(t - \tau) \rangle_t$.

¶ See Section 27.8, [Introducing time correlation](#)

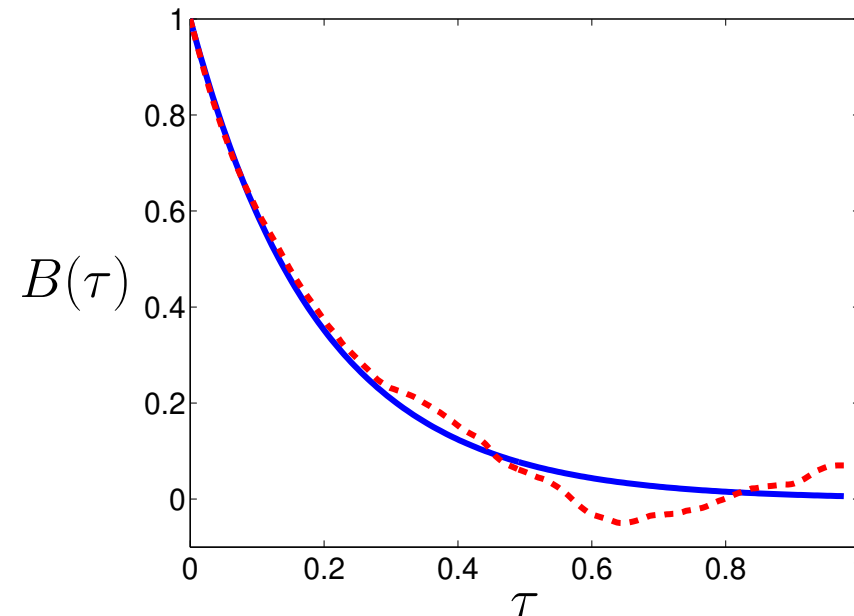
▶ The synthetic fluctuations are not correlated in time. An asymmetric time filter is used

$$(\mathcal{V}'_1)^m = a(\mathcal{V}'_1)^{m-1} + b(v'_1)^m$$

▶ The coefficient a is related to the turbulent integral timescale, \mathcal{T} , as

$$a = \exp(-\Delta t/\mathcal{T}) \tag{41.1}$$

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Auto correlation. —: Eq. 41.1; --: $B(\tau) = \langle \mathcal{V}'_1(t)\mathcal{V}'_1(t - \tau) \rangle_t$.

▶ Finally, the turbulent synthetic fluctuations are superimposed to the inlet mean velocity.

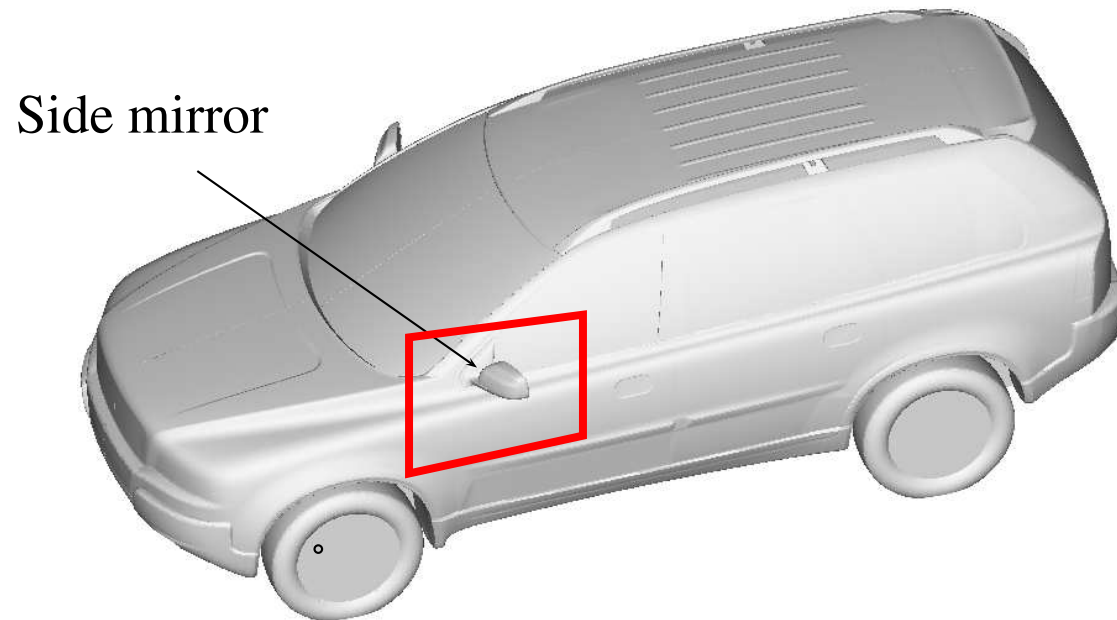
¶ See Section 23.2.1, The Interface Condition

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▶ Embedded LES and inlet b.c. for k and ε using PANS

See Section 23.2.1, The Interface Condition

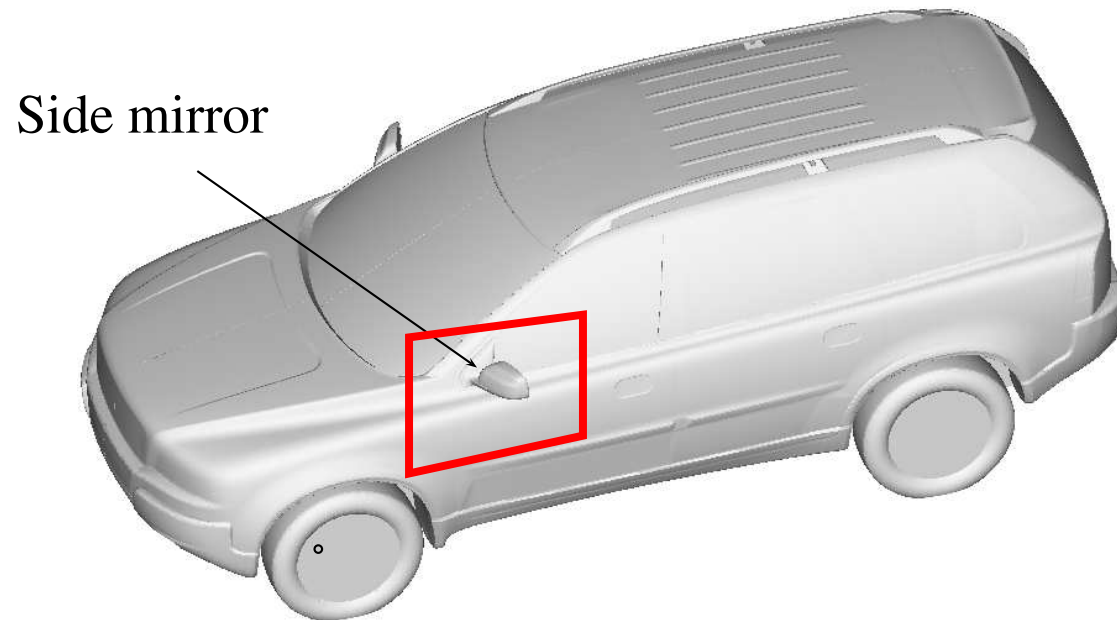
► Embedded LES and inlet b.c. for k and ε using PANS



Vehicle geometry (from [116]). Colored rectangle shows embedded LES region

See Section 23.2.1, The Interface Condition

► Embedded LES and inlet b.c. for k and ε using PANS

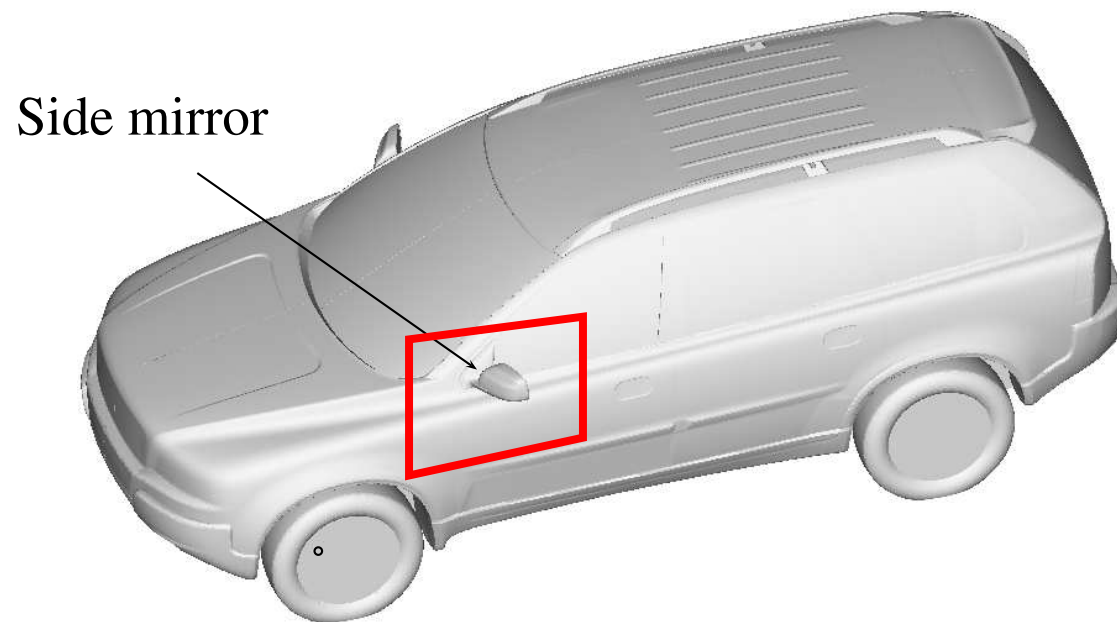


Vehicle geometry (from [116]). Colored rectangle shows embedded LES region

► An LES region (e.g. the side mirror, see figure above) is embedded in a steady RANS simulation.

See Section 23.2.1, The Interface Condition

► Embedded LES and inlet b.c. for k and ε using PANS

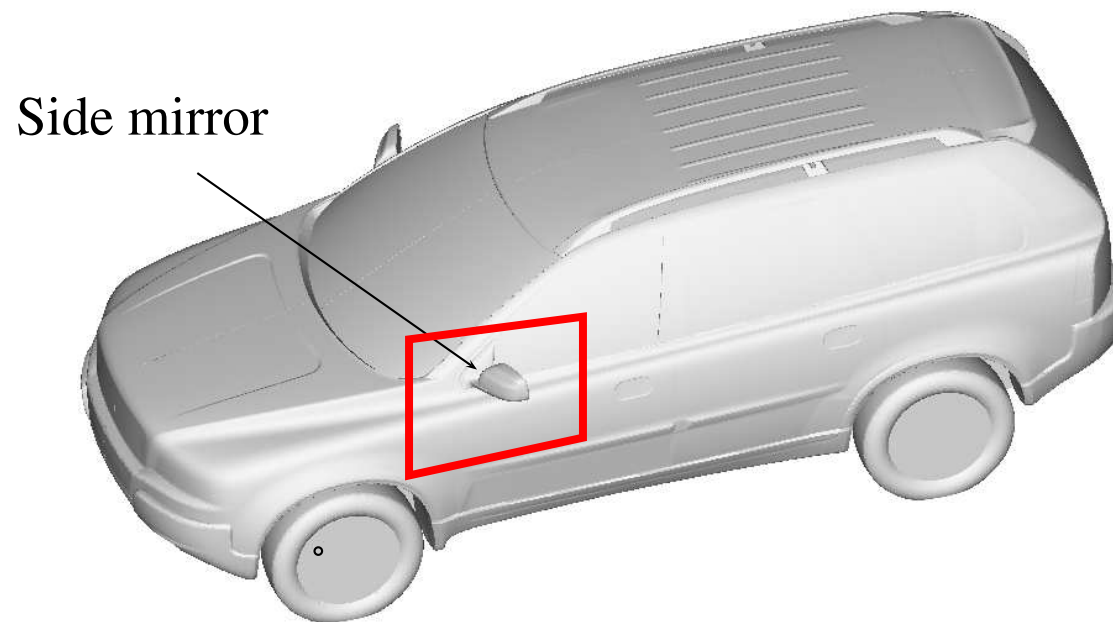


Vehicle geometry (from [116]). Colored rectangle shows embedded LES region

- An LES region (e.g. the side mirror, see figure above) is embedded in a steady RANS simulation.
- LES is used around the mirror in order to compute aeroacoustic sources (wind noise)

See Section 23.2.1, The Interface Condition

► Embedded LES and inlet b.c. for k and ε using PANS

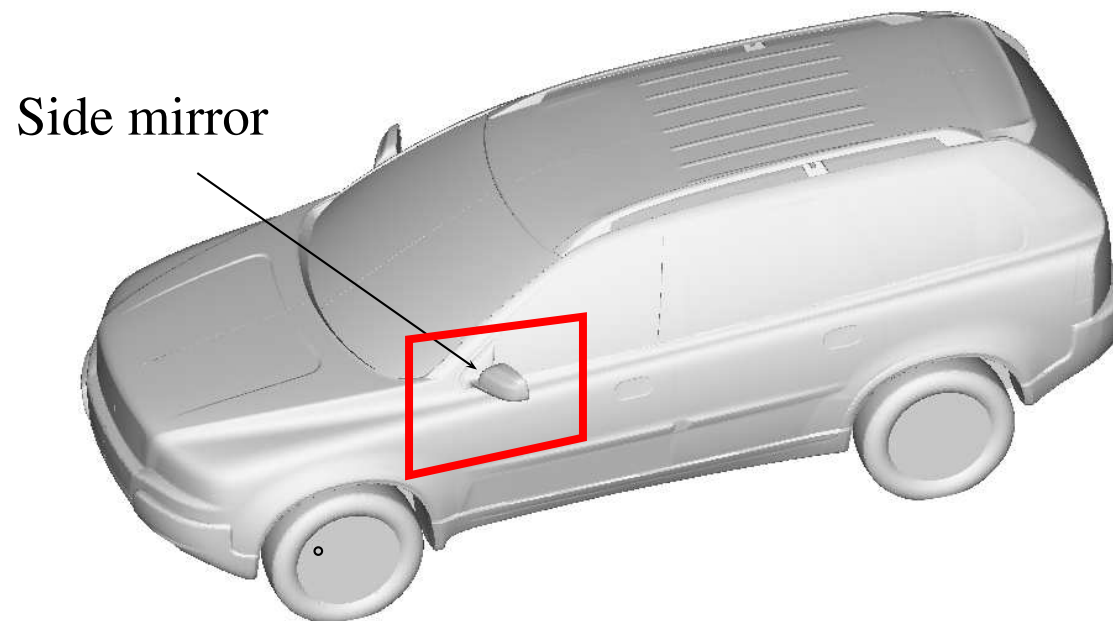


Vehicle geometry (from [116]). Colored rectangle shows embedded LES region

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- LES is used around the mirror in order to compute aeroacoustic sources (wind noise)
- Synthetic fluctuations are needed at the inlet region of LES.

See Section 23.2.1, The Interface Condition

▶ Embedded LES and inlet b.c. for k and ε using PANS



Vehicle geometry (from [116]). Colored rectangle shows embedded LES region

- ▶ An LES region (e.g. the side mirror, see figure above) is embedded in a steady RANS simulation.
- ▶ LES is used around the mirror in order to compute aeroacoustic sources (wind noise)
- ▶ Synthetic fluctuations are needed at the inlet region of LES.
- ▶ Mean velocity, k and ε at the LES inlet region are taken from the RANS simulation

► Summary

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- For more detail, see Section 5 in [183]