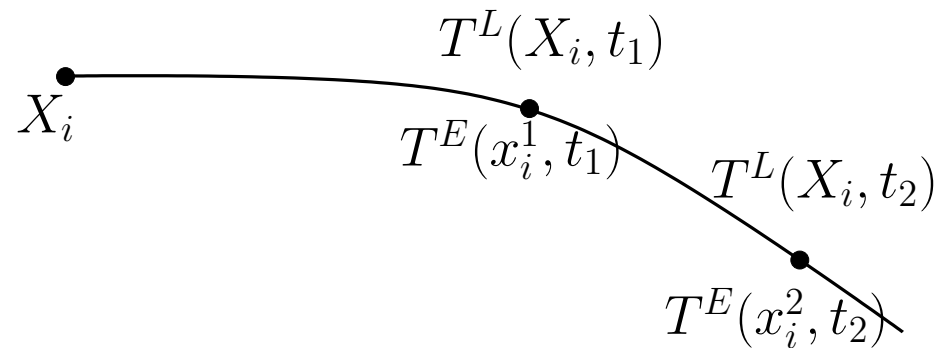


## On-line Lecture 1

¶ See Section 1.1, Eulerian, Lagrangian, material derivative



### ► Lagrangian approach

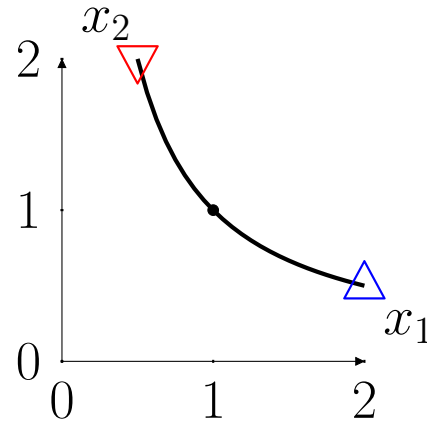
- The (fluid) particle is described by its initial position,  $X_i$ , and time,  $t$
- In other words we “label” a particle with  $X_i$  and then follow it.
- The variation of  $T^L$  is expressed as  $dT^L/dt$ .

### ► Eulerian approach

- We look a point,  $x_i$ , and see what happens.
- Hence  $T^E$  depends on both  $x_i$  and  $t$

- Chain rule: 
$$\frac{dT^E}{dt} = \frac{\partial T^E}{\partial t} + \frac{dx_i}{dt} \frac{\partial T^E}{\partial x_i} = \frac{\partial T^E}{\partial t} + v_i \frac{\partial T^E}{\partial x_i} \quad \rightarrow \quad \underbrace{\frac{dT^E}{dt}}_{\text{material change}} = \underbrace{\frac{\partial T^E}{\partial t}}_{\text{local change}} + \underbrace{v_j \frac{\partial T^E}{\partial x_j}}_{\text{convective change}}$$

¶ See Section 1.2, What is the difference between  $\frac{dv_2}{dt}$  and  $\frac{\partial v_2}{\partial t}$ ?



Flow path  $x_2 = 1/x_1$ . Filled circle:  $(x_1, x_2) = (1, 1)$ .

$$x_1 = \exp(t), \quad x_2 = \exp(-t), \quad \text{and hence } x_2 = 1/x_1 \quad (30.1)$$

⇒  $\nabla$ : start:  $t = \ln(0.5)$   $\triangle$ : end:  $t = \ln(2)$

► The flow is steady (in Eulerian coordinates).

► Equation 30.1 gives the velocities

$$v_1^L = \frac{dx_1}{dt} = \exp(t), \quad v_2^L = \frac{dx_2}{dt} = -\exp(-t) \quad (30.2)$$

► Equations 30.1 and 30.2 give

$$v_1^E = x_1, \quad v_2^E = -x_2 \quad (30.3)$$

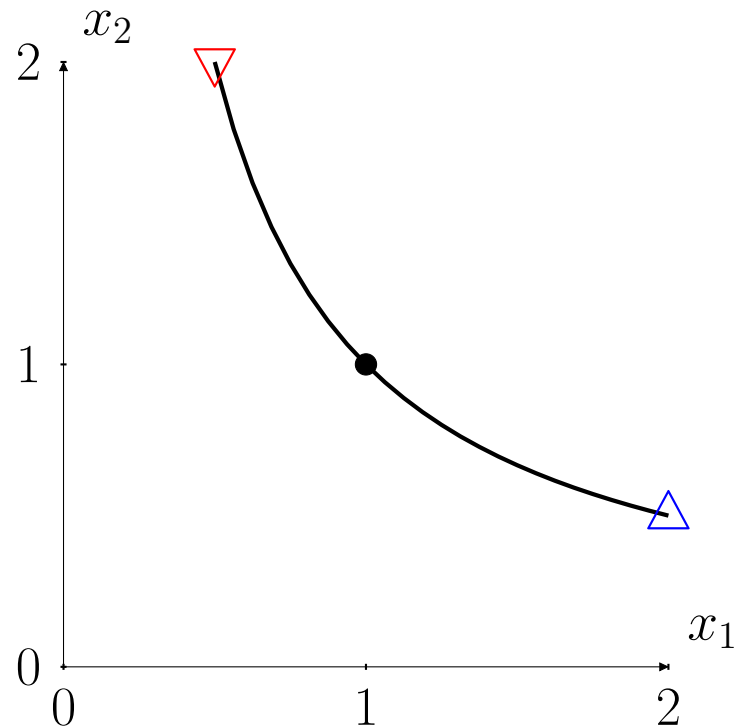
$$x_1 = \exp(t), \quad x_2 = \exp(-t), \quad v_1^L = \exp(t), \quad v_2^L = -\exp(-t), \quad v_1^E = x_1, \quad v_2^E = -x_2$$

$$\blacktriangleright \frac{dv_2}{dt} = \frac{dv_2^L}{dt}, \quad \frac{dv_2^E}{dt} = \frac{\partial v_2}{\partial t} + v_j \frac{\partial v_2}{\partial x_j} \quad \blacktriangleright \text{Let's compute them at point } (1, 1)$$

$$\frac{dv_2^L}{dt} = \exp(-t), \quad t = \ln(1) = 0 \quad \Rightarrow \quad \frac{dv_2^L}{dt} = 1$$

$$\frac{dv_2^E}{dt} = \frac{\partial v_2^E}{\partial t} + v_1^E \frac{\partial v_2^E}{\partial x_1} + v_2^E \frac{\partial v_2^E}{\partial x_2} = 0 + x_1 \cdot 0 - x_2 \cdot (-1) = x_2 = 1$$

$$\blacktriangleright \text{Of course} \quad \frac{dv_2}{dt} = \frac{dv_2^E}{dt} = \frac{dv_2^L}{dt} = 1$$



Flow path  $x_2 = 1/x_1$ . Filled circle:  $(x_1, x_2) = (1, 1)$ .

►  $\frac{dv_2^E}{dt} = x_2, \quad \frac{dv_2^L}{dt} = \exp(-t).$

► Consider the point  $(x_1, x_2) = (1, 1)$ . The velocity at this point does not change in time; hence  $\frac{\partial v_2^E}{\partial t} = 0$ .

► If we however travel with the particle then the  $v_2$  velocity changes with time, i.e.  $\frac{dv_2^L}{dt} = \frac{dv_2}{dt} = 1$  (it increases, i.e. it gets less negative with time).

¶ See Section B, [Introduction to tensor notation](#)

▶  $a$ : A tensor of zeroth rank (scalar)

▶  $a_i$ : A tensor of first rank (vector)  $\rightarrow a_i = (2, 1, 0)$

▶  $a_{ij}$ : A tensor of second rank (tensor)

$$\sigma_{ij} = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{pmatrix}$$

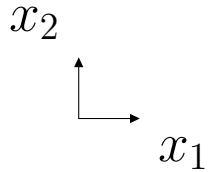
$$\sigma_{ij} = \sigma_{ji}$$

► What is a tensor?

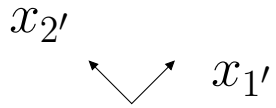
► A tensor is a *physical* quantity. It is independent of the coordinate system. The tensor of rank one (vector)  $b_i$  below



is physically the same expressed in the coordinate system  $(x_1, x_2)$



where  $b_i = (1/\sqrt{2}, 1/\sqrt{2}, 0)^T$  and in the coordinate system  $(x_{1'}, x_{2'})$



where  $b_{i'} = (1, 0, 0)^T$ . The tensor is the same even if its *components* are different.

► This also applied for  $\sigma_{ij}$

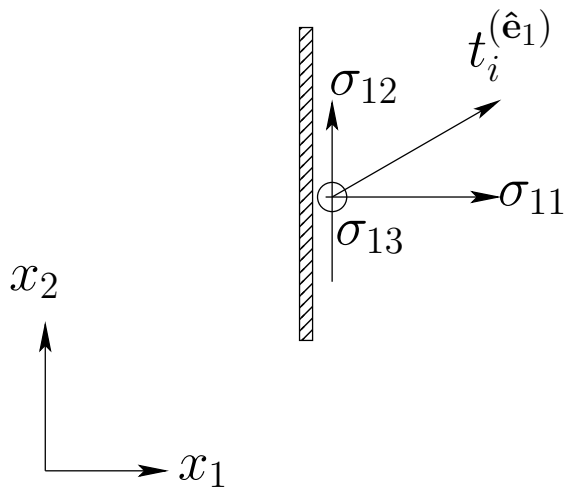
¶ See Section 1.3, [Viscous stress, pressure](#)

► The momentum balance equation derived in the continuum mechanics lectures reads

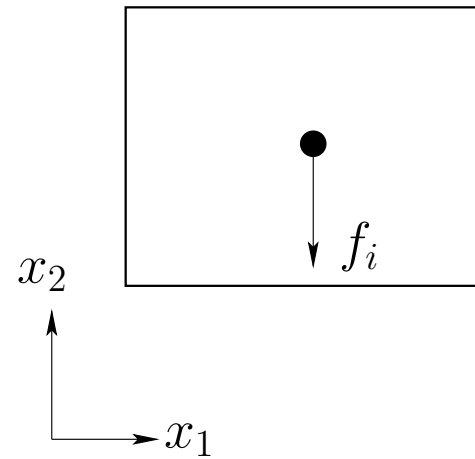
$$\rho \dot{v}_i - \sigma_{ji,j} - \rho f_i = 0$$

► We write it as

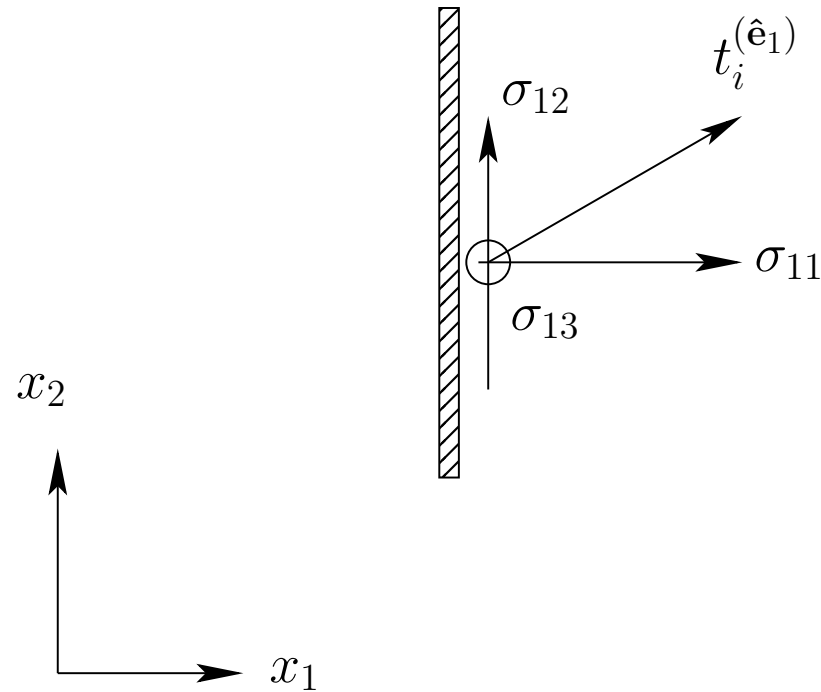
$$\rho \frac{dv_i}{dt} = \frac{\partial \sigma_{ji}}{\partial x_j} + \rho f_i \quad (30.4)$$



Stress components and stress vector on a surface.



Volume force,  $f_i = (0, -g, 0)$ , acting in the middle of the fluid element.



Stress components and stress vector on a surface.

► surface forces ( $\sigma_{ij}$  denotes the stress tensor). Stress is force per unit area. The surface stress vector is computed as

$$t_i^{(\hat{\mathbf{n}})} = \sigma_{ji}n_j$$

where  $\hat{\mathbf{n}} = n_j$  is the unit normal vector of the surface.

► The stress tensor,  $\sigma_{ij}$ , is split into one part which includes pressure,  $P$ , and one which includes viscous stresses (friction)

$$\sigma_{ij} = -P\delta_{ij} + \tau_{ij}$$

where  $P = -\frac{1}{3}\sigma_{kk}$ .



► A constitutive relation can be derived for the stress tensor which reads

$$\sigma_{ij} = -P\delta_{ij} + 2\mu S_{ij} - \frac{2}{3}\mu S_{kk}\delta_{ij}, \quad \tau_{ij} = 2\mu S_{ij} - \frac{2}{3}\mu S_{kk}\delta_{ij}, \quad S_{ij} = \frac{1}{2} \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) \quad (30.5)$$

► Before we insert Eq. 30.5 into Eq. 30.4, let's look at  $\frac{\partial v_i}{\partial x_j}$ , and  $S_{ij}$  in some detail.

¶ See Section 1.4, [Strain rate tensor, vorticity](#)

$$\frac{\partial v_i}{\partial x_j} = \frac{1}{2} \left( \underbrace{\frac{\partial v_i}{\partial x_j} + \frac{\partial v_i}{\partial x_j}}_{2\partial v_i/\partial x_j} + \underbrace{\frac{\partial v_j}{\partial x_i} - \frac{\partial v_j}{\partial x_i}}_{=0} \right) = \frac{1}{2} \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) + \frac{1}{2} \left( \frac{\partial v_i}{\partial x_j} - \frac{\partial v_j}{\partial x_i} \right) = S_{ij} + \Omega_{ij} \quad (30.6)$$

► The vorticity reads

$$\boldsymbol{\omega} = \nabla \times \mathbf{v}, \quad \omega_i = \varepsilon_{ijk} \frac{\partial v_k}{\partial x_j}$$

► The vorticity represents rotation of a fluid particle. Inserting the expression for  $S_{ij}$  and  $\Omega_{ij}$  gives

$$\omega_i = \varepsilon_{ijk} (S_{kj} + \Omega_{kj}) = \varepsilon_{ijk} \Omega_{kj} \quad (30.7)$$

the product of a symmetric,  $S_{kj}$ , and an antisymmetric tensor,  $\varepsilon_{ijk}$ , is zero.

$$\omega_i = \varepsilon_{ijk}(S_{kj} + \Omega_{kj}) = \varepsilon_{ijk}\Omega_{kj} \quad (30.7)$$

► Now let's invert Eq. 30.7. ► We start by multiplying it with  $\varepsilon_{ilm}$  so that

$$\varepsilon_{ilm}\omega_i = \varepsilon_{ilm}\varepsilon_{ijk}\Omega_{kj} \quad (30.8)$$

•  $\varepsilon_{ijk}$  is the permutation tensor.

- It is one if  $ijk$  is equal to 123 or any cyclic permutation ►  $\varepsilon_{123} = \varepsilon_{312} = \varepsilon_{231} = 1$ .
- Switch two indices and it is equal to minus one ► i.e,  $\varepsilon_{132} = \varepsilon_{213} = \varepsilon_{132} = -1$ .
- If two indices are equal, then  $\varepsilon_{ijk}$  is zero.

•  $\delta_{ij}$  is the unit or identity tensor. It is one if  $ijk$  are equal and zero otherwise, i.e.

$$\delta_{11} = \delta_{22} = \delta_{33} = 1$$

$$\delta_{12} = \delta_{13} = \delta_{21} = \delta_{23} = \delta_{31} = \delta_{32} = 0$$

► Using the  $\varepsilon$ - $\delta$ -identity (see Section C) on the right side of Eq. 30.8 gives

$$\varepsilon_{ilm}\varepsilon_{ijk}\Omega_{kj} = (\delta_{lj}\delta_{mk} - \delta_{lk}\delta_{mj})\Omega_{kj} = \delta_{lj}\delta_{mk}\Omega_{kj} - \delta_{lk}\delta_{mj}\Omega_{kj} = \delta_{mk}\Omega_{k\ell} - \delta_{mj}\Omega_{\ell j} = \Omega_{m\ell} - \Omega_{\ell m} = 2\Omega_{m\ell}$$

$$\varepsilon_{ilm}\omega_i = \varepsilon_{ilm}\varepsilon_{ijk}\Omega_{kj} \quad (30.8)$$

$$\varepsilon_{ilm}\varepsilon_{ijk}\Omega_{kj} = 2\Omega_{ml}$$

► Inserted in Eq. 30.8 we get

$$\Omega_{ml} = \frac{1}{2}\varepsilon_{ilm}\omega_i = \frac{1}{2}\varepsilon_{mil}\omega_i = -\frac{1}{2}\varepsilon_{mli}\omega_i$$

where we first used cyclic permutation of  $\varepsilon_{ilm}$ , ► then used the fact that  $\varepsilon_{ilm}$  is anti-symmetric.

► Actually, it is easier to invert Eq. 30.7  $\omega_i = \varepsilon_{ijk}\Omega_{kj}$  component-by-component.

► For example, for  $i = 3$

$$\omega_3 = \varepsilon_{3jk}\Omega_{kj} = \varepsilon_{321}\Omega_{12} + \varepsilon_{312}\Omega_{21} = -1 \cdot \Omega_{12} + 1 \cdot \Omega_{21} = -2\Omega_{12}$$

►  $\Rightarrow \Omega_{12} = -\frac{1}{2}\omega_3$

¶ See Section 1.5, [Product of a symmetric and antisymmetric tensor](#)

▶ The product of a symmetric,  $a_{ji}$ , and antisymmetric tensor,  $b_{ji}$ , is zero

$$a_{ij}b_{ij} = a_{ji}b_{ij} = -a_{ji}b_{ji},$$

where we used

2nd expression  $a_{ij} = a_{ji}$  (symmetric)

last expression  $b_{ij} = -b_{ji}$  (antisymmetric)

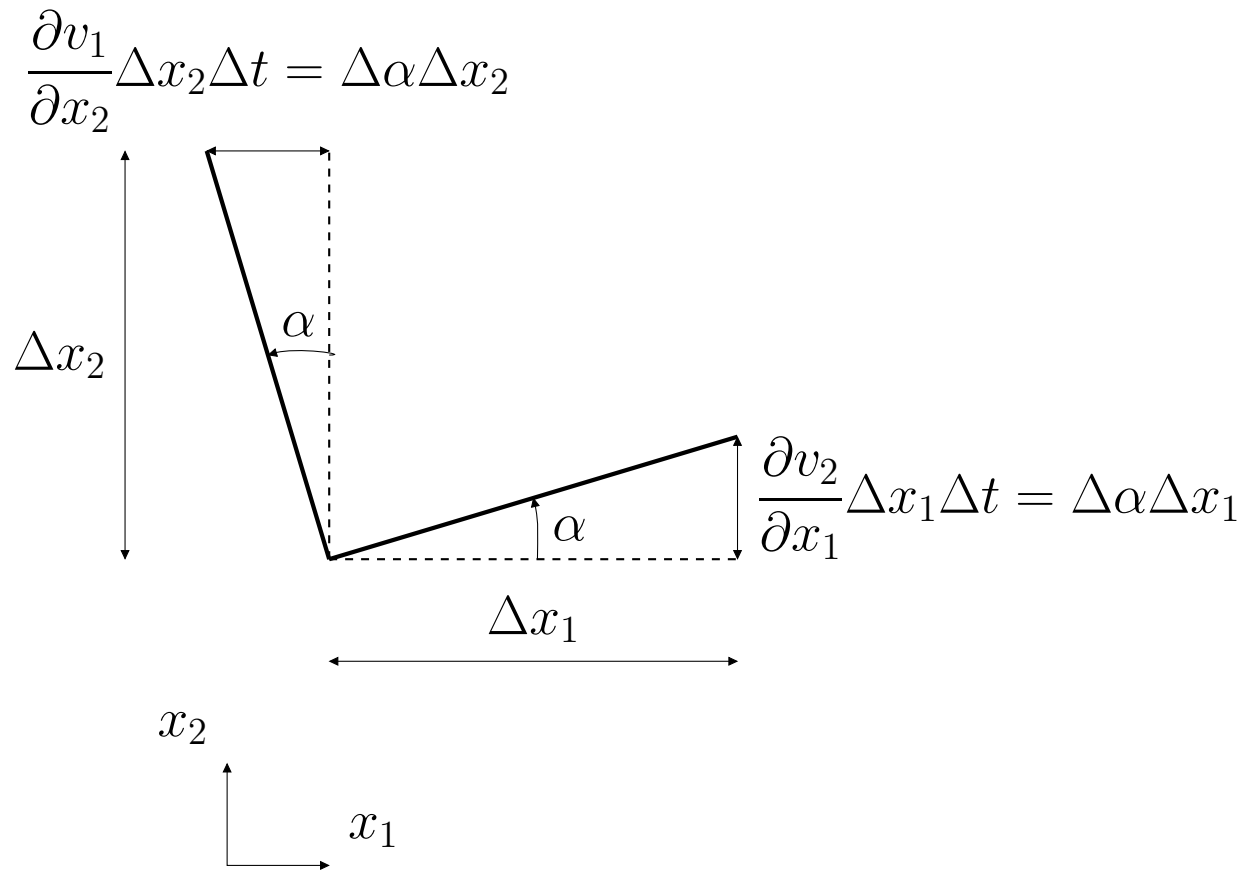
▶ Indices  $i$  and  $j$  are dummy indices  $\Rightarrow$

$$a_{ij}b_{ij} = -a_{ij}b_{ij}$$

▶ This expression says that  $A = -A$  which can be only true if  $A = 0$  and hence  $a_{ij}b_{ij} = 0$ .

¶ See Section 1.6, [Deformation, rotation](#)

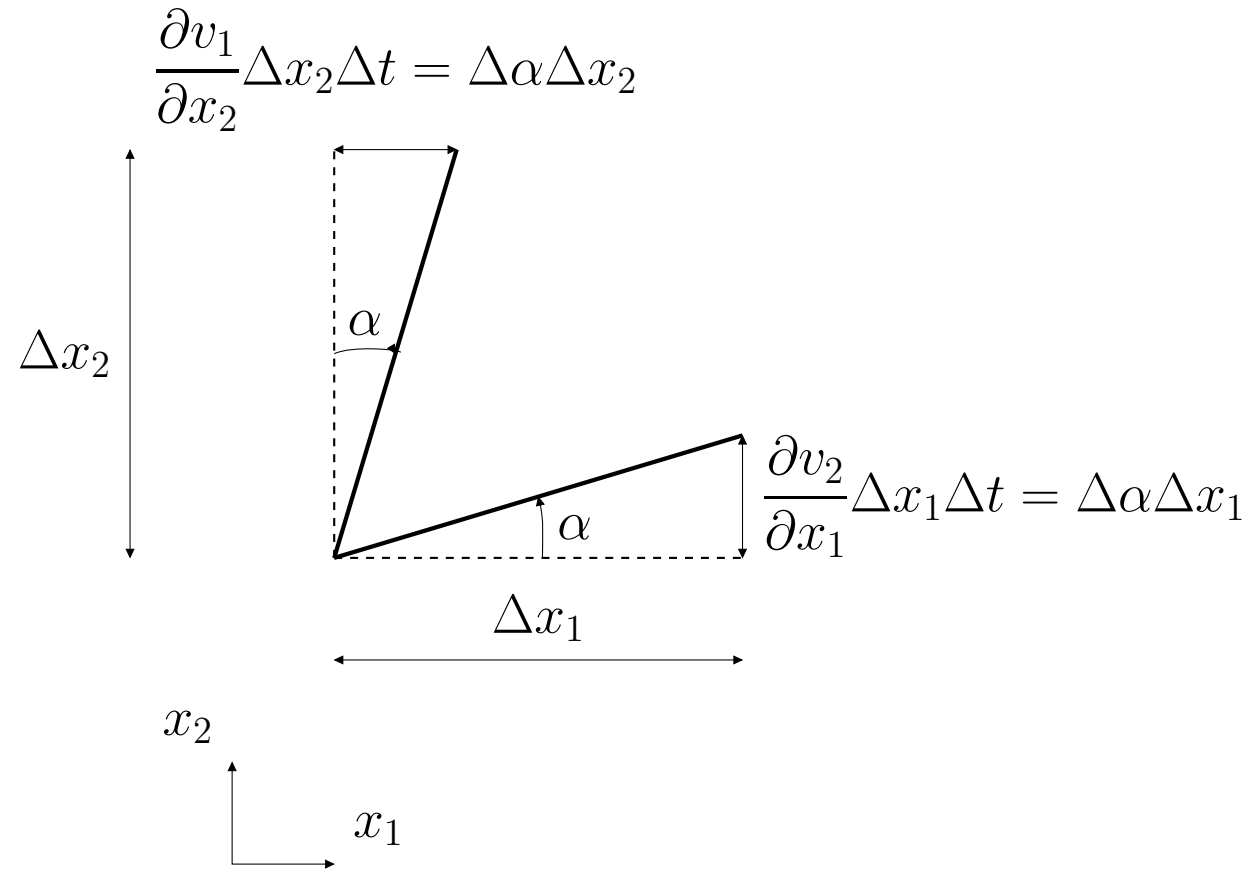
► Rotation of a fluid particle ( $\omega_3 > 0$ ,  $\Omega_{12} < 0$ ) during time  $\Delta t$



$\frac{\partial v_2}{\partial x_1} \Delta x_1$  ► = the  $v_2$  vel. at right end of horizontal edge ►  $\frac{\partial v_2}{\partial x_1} \Delta x_1 \Delta t$  is the vertical displacement

- angle rotation per unit time:  $\frac{\Delta \alpha}{\Delta t} \simeq d\alpha/dt = \partial v_2/\partial x_1 = -\partial v_1/\partial x_2$
- If not solid body, we take the average  $d\alpha/dt = (\partial v_2/\partial x_1 - \partial v_1/\partial x_2)/2$ .
- $\omega_3 = \partial v_2/\partial x_1 - \partial v_1/\partial x_2 = -2\Omega_{12}$  is twice the average rotation of the horizontal and vertical edge

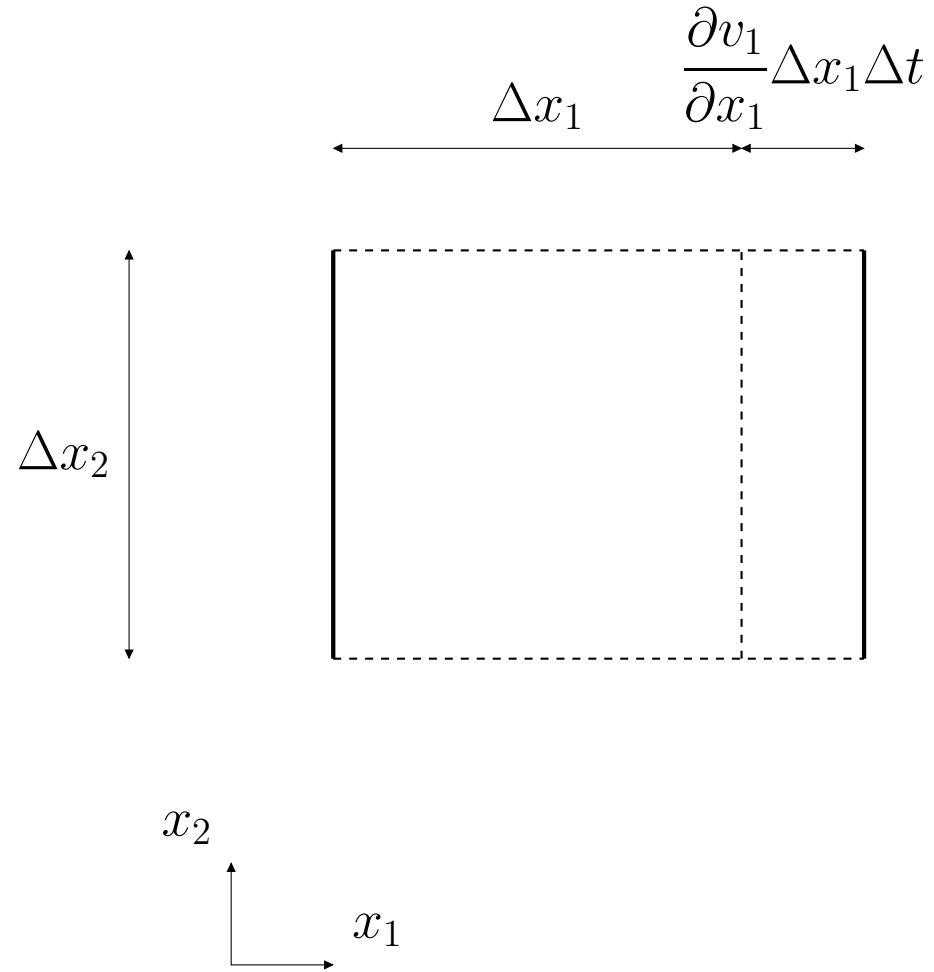
► Deformation of a fluid particle by shear during time  $\Delta t$ .



► Here, we take the average of  $\partial v_2 / \partial x_1$  and  $\partial v_1 / \partial x_2$

$$S_{12} = (\partial v_1 / \partial x_2 + \partial v_2 / \partial x_1) / 2.$$

► Elongation of a fluid particle during time  $\Delta t$ .



$\frac{\partial v_1}{\partial x_1} \Delta x_1$  ► This is the  $v_1$  vel. of the right edge    ►  $\frac{\partial v_1}{\partial x_1} \Delta x_1 \Delta t$  is the horizontal elongation

► Summary:

- Rotation of a fluid element is described by  $\Omega_{ij}$
- Shear corresponds to the off-diagonal elements of  $S_{ij}$

- The diagonal elements of  $S_{ij}$  represents elongation of a fluid element

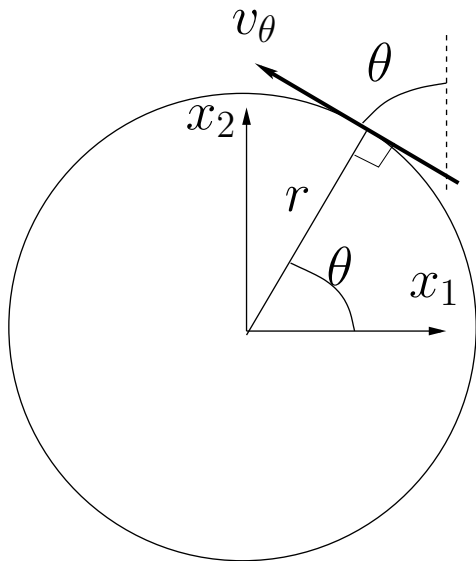


¶ See Section 1.7, Irrotational and rotational flow

► Flows are often classified based on rotation: they are *rotational* ( $\omega_i \neq 0$ ) or *irrotational* ( $\omega_i = 0$ )

¶ See Section 1.7.1, Ideal vortex line

$$\Phi = \frac{\Gamma\theta}{2\pi}, \quad v_k = \frac{\partial\Phi}{\partial x_k}, \quad v_\theta = \frac{\Gamma}{2\pi r}, \quad v_r = 0$$

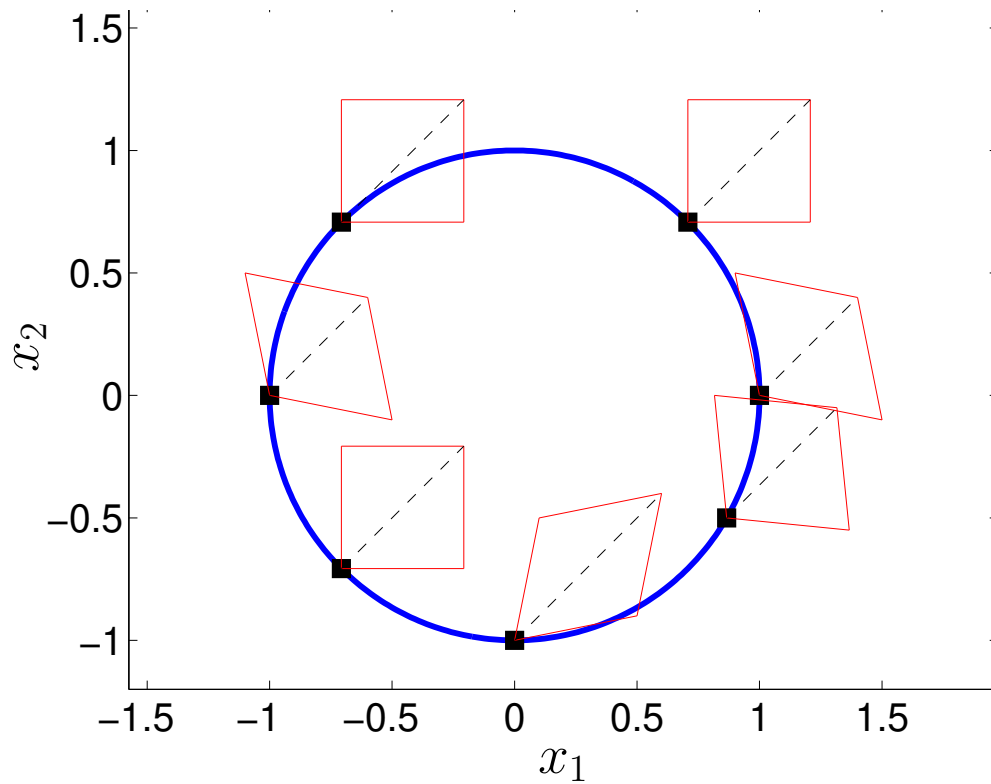


Transform  $v_\theta$  into Cartesian components.

$$v_1 = -\frac{\Gamma x_2}{2\pi(x_1^2 + x_2^2)}, \quad v_2 = \frac{\Gamma x_1}{2\pi(x_1^2 + x_2^2)}.$$

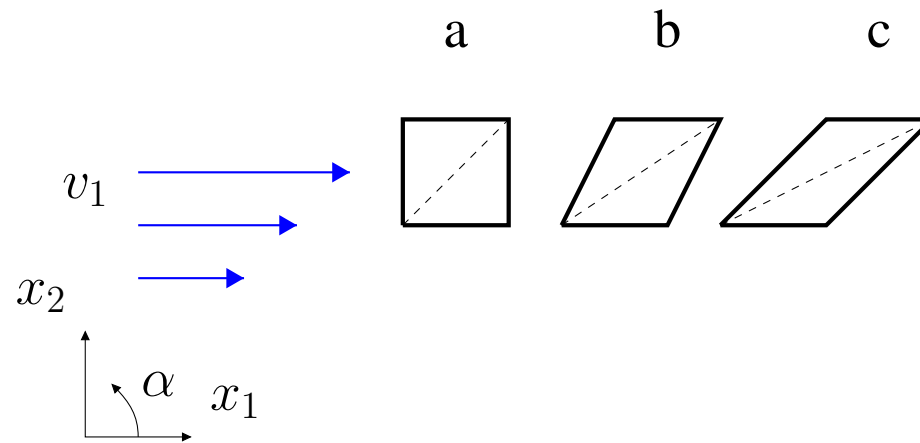
$$\frac{\partial v_1}{\partial x_2} = -\frac{\Gamma}{2\pi} \frac{x_1^2 - x_2^2}{(x_1^2 + x_2^2)^2}, \quad \frac{\partial v_2}{\partial x_1} = \frac{\Gamma}{2\pi} \frac{x_2^2 - x_1^2}{(x_1^2 + x_2^2)^2}$$

$$\Rightarrow \omega_3 = \frac{\partial v_2}{\partial x_1} - \frac{\partial v_1}{\partial x_2} = 0 \quad \Rightarrow \quad \text{irrotational flow} \quad \blacktriangleright \text{N.B.: vortex vs. vorticity}$$



- The locations of the fluid particle is indicated by filled squares.
- The diagonals are shown as dashed lines.
- The fluid particle is shown at  $\theta = 0, \pi/4, 3\pi/4, \pi, 5\pi/4, 3\pi/2$  and  $-\pi/6$ .
- The fluid particle (i.e. its diagonal) does **not rotate**.
- Or, rather, the velocity field does not **try** to rotate the fluid elements

¶ See Section 1.7.2, Shear flow



▶ Consider shear flow with  $v_1 = cx_2^2$ ,  $v_2 = 0$ , see figure above.

▶ The vorticity is computed as

$$\omega_1 = \frac{\partial v_2}{\partial x_3} - \frac{\partial v_3}{\partial x_2} = 0, \quad \omega_2 = \frac{\partial v_1}{\partial x_3} - \frac{\partial v_3}{\partial x_1} = 0, \quad \omega_3 = \frac{\partial v_2}{\partial x_1} - \frac{\partial v_1}{\partial x_2} = -2cx_2 \neq 0$$

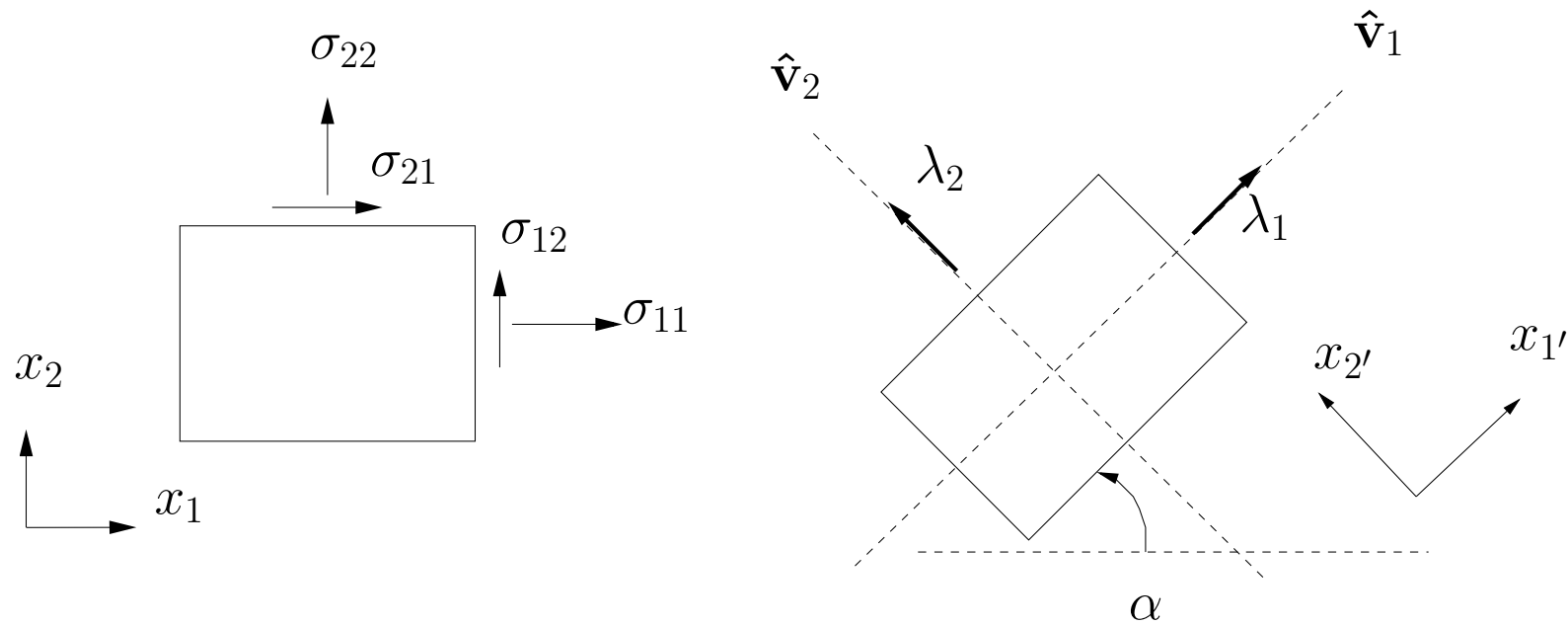
Hence the flow is **rotational**

▶ The fluid particles rotate clock-wise (see figure above); i.e. they rotate in negative  $\alpha$  direction.

▶ Finally:  $\omega_i \neq 0$  does not really mean that a fluid element rotates.

▶ It only means that the velocity field **tries** to do that.

¶ See Section 1.8, Eigenvalues and eigenvectors: physical interpretation



- A two-dimensional fluid element.
  - Left: in original state;  $\sigma_{ij}$  is **symmetric**;
  - right: rotated to **principal** coordinate directions.
  - $\lambda_1 = \sigma_{1'1'}$  and  $\lambda_2 = \sigma_{2'2'}$  denote **eigenvalues**;
  - $\hat{v}_1$  and  $\hat{v}_2$  denote unit **eigenvectors**.

## Lecture 2

¶ See Section 2.1.1, The continuity equation

$$\frac{d\rho}{dt} + \rho \frac{\partial v_i}{\partial x_i} = 0 \quad \text{incompressible flow gives} \quad \frac{\partial v_i}{\partial x_i} = 0$$

¶ See Section 2.1.2, The momentum equation

$$\begin{aligned} \sigma_{ij} &= -P\delta_{ij} + 2\mu S_{ij} - \frac{2}{3}\mu S_{kk}\delta_{ij} \\ \rho \frac{dv_i}{dt} &= \frac{\partial \sigma_{ji}}{\partial x_j} + \rho f_i \\ &= -\frac{\partial P}{\partial x_j} \delta_{ij} + \frac{\partial}{\partial x_j} \left( 2\mu S_{ij} - \frac{2}{3}\mu S_{kk}\delta_{ij} \right) + \rho f_i \\ &= -\frac{\partial P}{\partial x_i} + \frac{\partial}{\partial x_j} (2\mu S_{ij}) - \frac{2}{3} \frac{\partial}{\partial x_j} (\mu S_{kk}\delta_{ij}) + \rho f_i \\ &= -\frac{\partial P}{\partial x_i} + \frac{\partial}{\partial x_j} (2\mu S_{ij}) - \frac{2}{3} \frac{\partial}{\partial x_i} (\mu S_{kk}) + \rho f_i \end{aligned}$$

$$\rho \frac{dv_i}{dt} = -\frac{\partial P}{\partial x_i} + \frac{\partial}{\partial x_j} (2\mu S_{ij}) - \frac{2}{3} \frac{\partial}{\partial x_i} (\mu S_{kk}) + \rho f_i$$

► Note that the right-side (stress tensor,  $\sigma_{ij}$ ) depends only on  $S_{ij}$  (deformation), not on  $\Omega_{ij}$  (rotation).

► Incompressible flow:

$$\frac{\partial v_i}{\partial x_i} = 0 = S_{ii} \quad \text{continuity equation}$$

$$\rho \frac{dv_i}{dt} = -\frac{\partial P}{\partial x_i} + \frac{\partial}{\partial x_j} (2\mu S_{ij}) + \rho f_i$$

► Incompressible and constant  $\mu$ :

$$\begin{aligned} \rho \frac{dv_i}{dt} &= -\frac{\partial P}{\partial x_i} + \frac{\partial}{\partial x_j} \left\{ \mu \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) \right\} + \rho f_i \\ &= -\frac{\partial P}{\partial x_i} + \mu \frac{\partial}{\partial x_j} \left\{ \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) \right\} + \rho f_i \\ &= -\frac{\partial P}{\partial x_i} + \mu \frac{\partial}{\partial x_j} \left( \frac{\partial v_i}{\partial x_j} \right) + \mu \frac{\partial}{\partial x_j} \left( \frac{\partial v_j}{\partial x_i} \right) + \rho f_i \\ &= -\frac{\partial P}{\partial x_i} + \mu \frac{\partial^2 v_i}{\partial x_j \partial x_j} + \mu \frac{\partial}{\partial x_i} \left( \frac{\partial v_j}{\partial x_j} \right) + \rho f_i \\ &= -\frac{\partial P}{\partial x_i} + \mu \frac{\partial^2 v_i}{\partial x_j \partial x_j} + \rho f_i \end{aligned}$$

¶ See Section 2.2, The energy equation

► First law of thermodynamics:

$$\underbrace{\rho \frac{du}{dt}}_{\text{internal energy change}} = \underbrace{\sigma_{ji} \frac{\partial v_i}{\partial x_j}}_{\text{exchange of work}} - \underbrace{\frac{\partial q_i}{\partial x_i}}_{\text{exchange of heat}} \quad (31.1)$$

$$q_i = -k \frac{\partial T}{\partial x_i} \quad \text{constitutive law}$$

$$\sigma_{ij} = -P\delta_{ij} + 2\mu S_{ij} - \frac{2}{3}\mu S_{kk}\delta_{ij} \quad \text{constitutive law}$$

► Recall:

$$\frac{\partial v_i}{\partial x_j} = S_{ij} + \Omega_{ij}, \quad S_{ij} = \frac{1}{2} \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right), \quad \Omega_{ij} = \frac{1}{2} \left( \frac{\partial v_i}{\partial x_j} - \frac{\partial v_j}{\partial x_i} \right)$$

$$\sigma_{ij} \frac{\partial v_i}{\partial x_j} = \sigma_{ij} (S_{ij} + \Omega_{ij}) = \sigma_{ij} S_{ij}$$

► This gives

$$\begin{aligned} \sigma_{ij} \frac{\partial v_i}{\partial x_j} &= \left\{ -P\delta_{ij} + 2\mu S_{ij} - \frac{2}{3}\mu S_{kk}\delta_{ij} \right\} S_{ij} = \\ &= -P\delta_{ij} S_{ij} + 2\mu S_{ij} S_{ij} - \frac{2}{3}\mu S_{kk} S_{ij} \delta_{ij} = -P S_{ii} + 2\mu S_{ij} S_{ij} - \frac{2}{3}\mu S_{kk} S_{ii} \end{aligned}$$

$$\underbrace{\rho \frac{du}{dt}}_{\text{internal energy change}} = \underbrace{\sigma_{ji} \frac{\partial v_i}{\partial x_j}}_{\text{exchange of work}} - \underbrace{\frac{\partial q_i}{\partial x_i}}_{\text{exchange of heat}} \quad (31.1)$$

$$\sigma_{ij} \frac{\partial v_i}{\partial x_j} = -P \frac{\partial v_i}{\partial x_i} + 2\mu S_{ij} S_{ij} - \frac{2}{3}\mu S_{kk} S_{ii}, \quad q_i = -k \frac{\partial T}{\partial x_i}$$

Insert the constitutive relations above into Eq. 31.1 gives

$$\underbrace{\rho \frac{du}{dt}}_{\Delta U} = - \underbrace{P \frac{\partial v_i}{\partial x_i}}_{Rev} + \underbrace{2\mu S_{ij} S_{ij} - \frac{2}{3}\mu S_{kk} S_{ii}}_{\Phi} + \underbrace{\frac{\partial}{\partial x_i} \left( k \frac{\partial T}{\partial x_i} \right)}_Q$$

- ▶ During time,  $dt$ , the following happens:
- ▶  $\Delta U$ : Change of internal energy of the fluid
- ▶ Rev: **Reversible** work done by the fluid (compression or expansion)
- ▶  $\Phi$ : **Irreversible** work (dissipation) done by the fluid
- ▶ Q: Exchange of heat to the surrounding fluid



► Incompressible flow (low speed,  $|v_i| < \frac{1}{3}$  speed of sound)

$$\underbrace{\rho \frac{du}{dt}}_{\Delta U} = \underbrace{-P \frac{\partial v_i}{\partial x_i}}_{Rev} + \underbrace{2\mu S_{ij}S_{ij} - \frac{2}{3}\mu S_{kk}S_{ii}}_{\Phi} + \underbrace{\frac{\partial}{\partial x_i} \left( k \frac{\partial T}{\partial x_i} \right)}_Q$$

$$du = c_p dT \quad \Rightarrow \quad \rho c_p \frac{dT}{dt} = \Phi + \frac{\partial}{\partial x_i} \left( k \frac{\partial T}{\partial x_i} \right)$$

►  $\Phi$  important for lubricant oils, See paper of Erwin Adi Hartono at course www page.

► For gases and “usual” liquids (i.e. not lubricant oils) we get ( $\Phi \simeq 0$ ,  $k$  is constant)

$$\frac{dT}{dt} = \alpha \frac{\partial^2 T}{\partial x_i \partial x_i}, \quad \alpha = \frac{k}{\rho c_p}, \quad Pr = \frac{\nu}{\alpha}$$

¶ See Section 2.3, Transformation of energy

►  $k = v_i v_i / 2$  equation (multiply the momentum equation by  $v_i$ )

$$v_i \left( \rho \frac{dv_i}{dt} - \frac{\partial \sigma_{ji}}{\partial x_j} - \rho f_i \right) = v_i \rho \frac{dv_i}{dt} - v_i \frac{\partial \sigma_{ji}}{\partial x_j} - v_i \rho f_i = 0 \quad (31.2)$$

► The first term on the left side can be re-written (Trick 2)

$$\rho v_i \frac{dv_i}{dt} = \frac{1}{2} \rho \frac{d(v_i v_i)}{dt} = \rho \frac{dk}{dt}, \quad v_i v_i / 2 = v^2 / 2 = k \quad (31.3)$$

► **Trick 2:** the product rule  $\frac{1}{2} \frac{\partial A_i A_i}{\partial x_j} = \frac{1}{2} \left( A_i \frac{\partial A_i}{\partial x_j} + A_i \frac{\partial A_i}{\partial x_j} \right) = A_i \frac{\partial A_i}{\partial x_j}$

Using it backwards  $A_i \frac{\partial A_i}{\partial x_j} = \frac{1}{2} \frac{\partial A_i A_i}{\partial x_j}$

► Eqs. 31.2 and 31.3 give

$$\rho \frac{dk}{dt} = v_i \frac{\partial \sigma_{ji}}{\partial x_j} + \rho v_i f_i$$

Re-write the stress-velocity term so that (Trick 1)

$$\rho \frac{dk}{dt} = \frac{\partial v_i \sigma_{ji}}{\partial x_j} - \sigma_{ji} \frac{\partial v_i}{\partial x_j} + \rho v_i f_i$$

► Compare with the equation for internal energy (Eq. 31.1)

$$\rho \frac{du}{dt} = \sigma_{ji} \frac{\partial v_i}{\partial x_j} - \frac{\partial q_i}{\partial x_i}$$

► **Trick 1:** the product rule  $\frac{\partial A_i B_i}{\partial x_j} = \left( A_i \frac{\partial B_i}{\partial x_j} + B_i \frac{\partial A_i}{\partial x_j} \right)$

Using it backwards  $A_i \frac{\partial B_i}{\partial x_j} = \frac{\partial A_i B_i}{\partial x_j} - B_i \frac{\partial A_i}{\partial x_j}$

¶ See Section 2.4, Left side of the transport equations

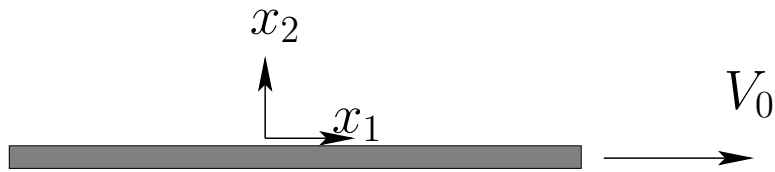
▶ Left-hand side ( $\Psi = v_i, u, T \dots$ )

$$\begin{aligned} \rho \frac{d\Psi}{dt} &= \rho \frac{\partial \Psi}{\partial t} + \rho v_j \frac{\partial \Psi}{\partial x_j} \\ \rho \frac{\partial \Psi}{\partial t} + \rho v_j \frac{\partial \Psi}{\partial x_j} + \underbrace{\Psi \left( \frac{d\rho}{dt} + \rho \frac{\partial v_j}{\partial x_j} \right)}_{=0} \\ \underbrace{\rho \frac{\partial \Psi}{\partial t}} + \underbrace{\rho v_j \frac{\partial \Psi}{\partial x_j}} + \Psi \left( \underbrace{\frac{\partial \rho}{\partial t}} + \underbrace{v_j \frac{\partial \rho}{\partial x_j}} + \underbrace{\rho \frac{\partial v_j}{\partial x_j}} \right) &= \underbrace{\frac{\partial \rho \Psi}{\partial t}} + \underbrace{\frac{\partial \rho v_j \Psi}{\partial x_j}} \end{aligned}$$

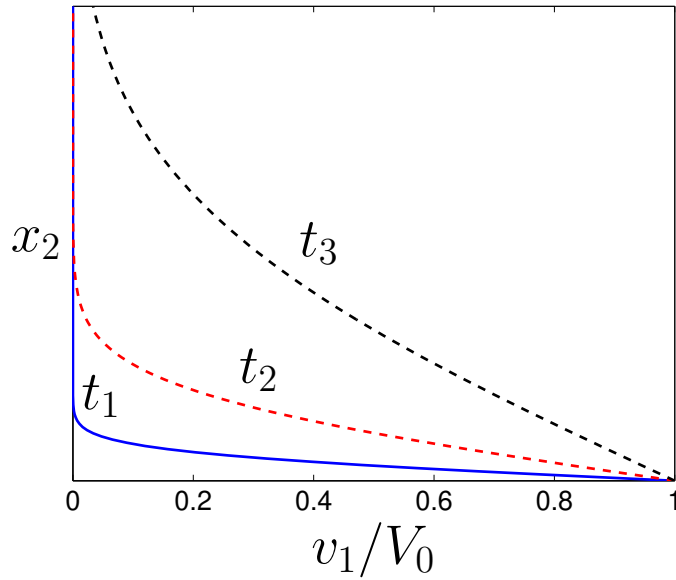
$$\rho \frac{\partial \Psi}{\partial t} + \rho v_j \frac{\partial \Psi}{\partial x_j} \quad \text{non-conservative}$$

$$\frac{\partial \rho \Psi}{\partial t} + \frac{\partial \rho v_j \Psi}{\partial x_j} \quad \text{conservative}$$

See Section 3.1, The Rayleigh problem



The plate moves to the right with speed  $V_0$  for  $t > 0$ .



► The  $v_1$  velocity at three different times.  $t_3 > t_2 > t_1$ .

$$\rho \frac{dv_1}{dt} \equiv \rho \frac{\partial v_1}{\partial t} + \rho v_j \frac{\partial v_1}{\partial x_j} = -\frac{\partial P}{\partial x_1} + \mu \frac{\partial^2 v_1}{\partial x_j \partial x_j} + \rho f_1$$

► Simplifications: ►  $\frac{\partial v_1}{\partial x_1} = \frac{\partial v_3}{\partial x_3} = 0 \Rightarrow \frac{\partial v_2}{\partial x_2} = 0 \Rightarrow v_2 = C_1$  b.c.  $\Rightarrow v_2 \equiv 0$

$$\frac{\partial v_1}{\partial t} = \nu \frac{\partial^2 v_1}{\partial x_2^2}, \quad \nu = \frac{\mu}{\rho}$$

$$\frac{\partial v_1}{\partial t} = \nu \frac{\partial^2 v_1}{\partial x_2^2}$$

► Similarity solution: the number of independent variables is reduced by one: from two ( $x_2$  and  $t$ ) to one ( $\eta$ ).

$$\eta = \frac{x_2}{2\sqrt{\nu t}}$$

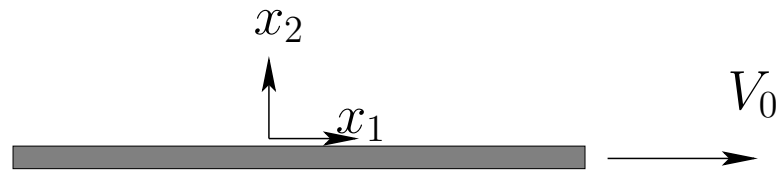
$$\frac{\partial v_1}{\partial t} = \frac{dv_1}{d\eta} \frac{\partial \eta}{\partial t} = -\frac{x_2 t^{-3/2}}{4\sqrt{\nu}} \frac{dv_1}{d\eta} = -\frac{1}{2} \frac{\eta}{t} \frac{dv_1}{d\eta}$$

$$\frac{\partial v_1}{\partial x_2} = \frac{dv_1}{d\eta} \frac{\partial \eta}{\partial x_2} = \frac{1}{2\sqrt{\nu t}} \frac{dv_1}{d\eta}$$

$$\begin{aligned} \frac{\partial^2 v_1}{\partial x_2^2} &= \frac{\partial}{\partial x_2} \left( \frac{\partial v_1}{\partial x_2} \right) = \frac{\partial}{\partial x_2} \left( \frac{1}{2\sqrt{\nu t}} \frac{dv_1}{d\eta} \right) = \frac{1}{2\sqrt{\nu t}} \frac{\partial}{\partial x_2} \left( \frac{dv_1}{d\eta} \right) \\ &= \frac{1}{2\sqrt{\nu t}} \frac{dv_1}{d\eta} \frac{\partial}{\partial \eta} \left( \frac{dv_1}{d\eta} \right) = \frac{1}{4\nu t} \frac{d^2 v_1}{d\eta^2} \end{aligned}$$

► We get

$$f = \frac{v_1}{V_0}, \quad \frac{d^2 f}{d\eta^2} + 2\eta \frac{df}{d\eta} = 0$$



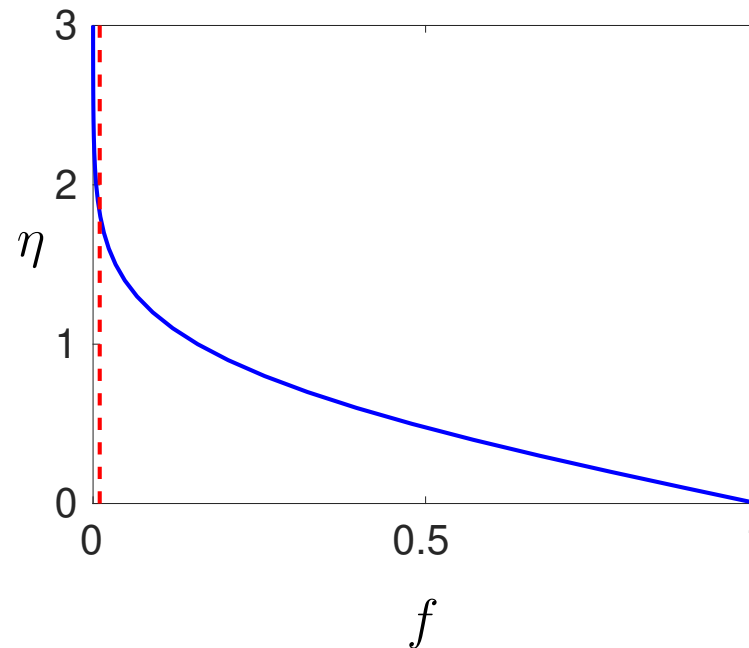
► Boundary conditions

$$\eta = \frac{x_2}{2\sqrt{\nu t}}, \quad f = \frac{v_1}{V_0}, \quad \frac{d^2 f}{d\eta^2} + 2\eta \frac{df}{d\eta} = 0$$

$$\begin{aligned} v_1(x_2, t = 0) = 0 &\Rightarrow f(\eta \rightarrow \infty) = 0 \\ v_1(x_2 = 0, t) = V_0 &\Rightarrow f(\eta = 0) = 1 \\ v_1(x_2 \rightarrow \infty, t) = 0 &\Rightarrow f(\eta \rightarrow \infty) = 0 \end{aligned}$$

► The solution reads

$$f(\eta) = 1 - \operatorname{erf}(\eta), \quad \eta = \frac{x_2}{2\sqrt{\nu t}}, \quad f = \frac{v_1}{V_0} \quad (31.4)$$



The velocity,  $f = v_1/V_0$ , given by Eq. 31.4.

►  $v_1 = 0.99V_0$ , usual boundary layer.    ► Boundary layer thickness:  $f = v_1/V_0 = 0.01$  (dashed line)

► The figure above gives (for  $f = 0.01$ )  $\eta = 1.8$  so that

$$\eta = 1.8 = \frac{\delta}{2\sqrt{\nu t}} \Rightarrow \delta = 3.6\sqrt{\nu t}, \quad t = \frac{\delta^2}{3.6^2\nu}$$

$$\delta = 10.8\text{cm} \quad \text{air, after 10 minutes}$$

$$\delta = 2.8\text{cm} \quad \text{water, after 10 minutes}$$

$$\delta = 1\text{m} \quad \text{air} \Rightarrow 84 \text{ minutes}$$

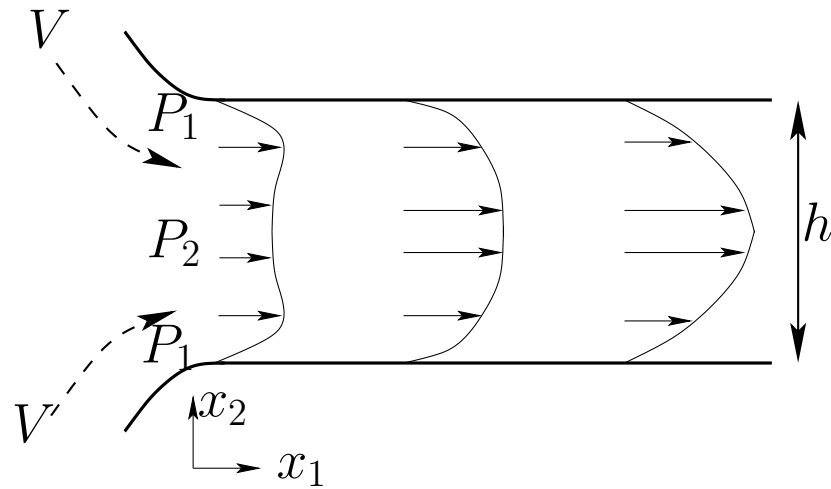




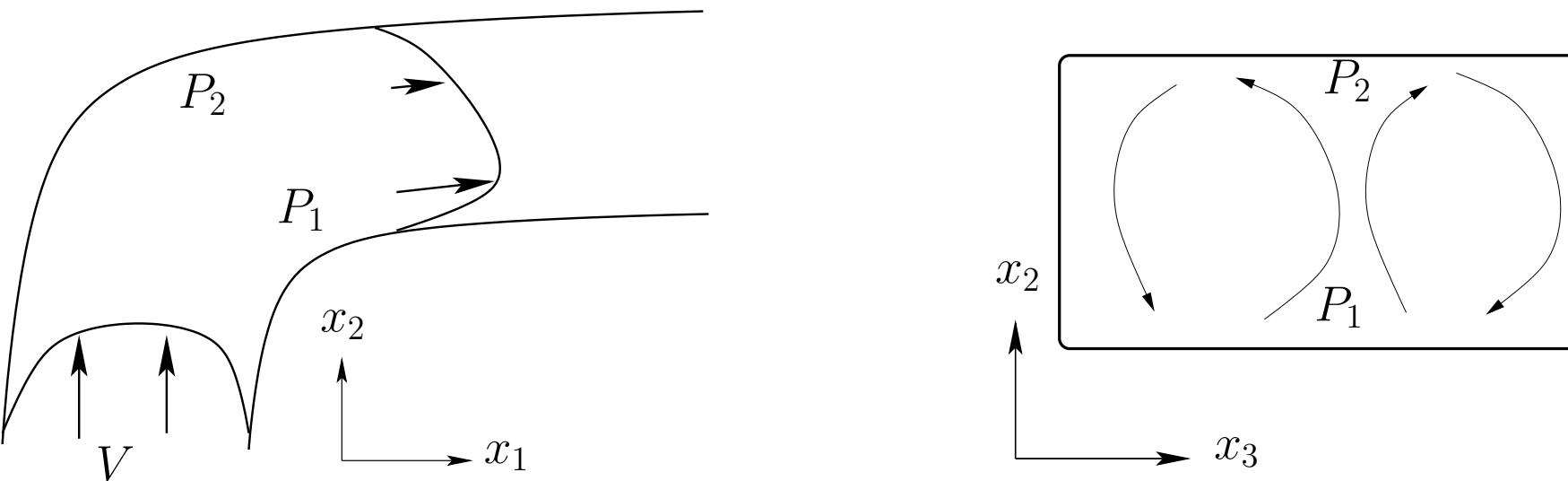
## Lecture 3

See Section 3.2.1, Curved plates

The inlet part of a channel.  $P_2 > P_1$



Flow in a channel bend.  $P_2 > P_1$





See Section 3.2.2, Flat plates

Fully developed incompressible flow in a channel. 2D and steady.  $0 = \frac{\partial v_1}{\partial x_1} = \frac{\partial v_2}{\partial x_1} = \frac{\partial v_3}{\partial x_3} = v_3$ .

$$\frac{\partial v_i}{\partial x_i} = 0 \Rightarrow \frac{\partial v_2}{\partial x_2} = 0 \Rightarrow v_2 = C_1(x_1) \Rightarrow v_2 \equiv 0$$

The Navier-Stokes for  $v_1$  ( $g_i = (0, -g, 0)$ )

$$\begin{aligned} \frac{dv_1}{dt} &\equiv \frac{\partial v_1}{\partial t} + v_j \frac{\partial v_1}{\partial x_j} = -\frac{1}{\rho} \frac{\partial P}{\partial x_1} + \nu \frac{\partial^2 v_1}{\partial x_j \partial x_j} + f_1 \\ \cancel{\frac{\partial v_1}{\partial t}} + v_1 \cancel{\frac{\partial v_1}{\partial x_1}} + v_2 \cancel{\frac{\partial v_1}{\partial x_2}} &= -\frac{\partial P}{\partial x_1} + \mu \left( \cancel{\frac{\partial^2 v_1}{\partial x_1^2}} + \frac{\partial^2 v_1}{\partial x_2^2} \right) + \cancel{f_1} \\ &\Rightarrow \mu \frac{\partial^2 v_1}{\partial x_2^2} = \frac{\partial P}{\partial x_1} \end{aligned} \quad (32.1)$$

The Navier-Stokes for  $v_2$  gives

$$\begin{aligned} \frac{\partial v_2}{\partial t} + v_j \frac{\partial v_2}{\partial x_j} &= -\frac{1}{\rho} \frac{\partial P}{\partial x_2} + \nu \frac{\partial^2 v_2}{\partial x_j \partial x_j} + f_2 \\ \cancel{\frac{\partial v_2}{\partial t}} + v_1 \cancel{\frac{\partial v_2}{\partial x_1}} + v_2 \cancel{\frac{\partial v_2}{\partial x_2}} &= -\frac{\partial P}{\partial x_2} + \mu \left( \cancel{\frac{\partial^2 v_2}{\partial x_1^2}} + \cancel{\frac{\partial^2 v_2}{\partial x_2^2}} \right) - \rho g \Rightarrow 0 = -\frac{\partial P}{\partial x_2} - \rho g \end{aligned}$$

$$0 = -\frac{\partial P}{\partial x_2} - \rho g \Rightarrow P = -\rho g x_2 + C_1(x_1) = -\rho g x_2 + p(x_1)$$

$$\Rightarrow -\frac{\partial P}{\partial x_1} = -\frac{\partial p}{\partial x_1} \quad (p = p(x_1) \text{ is pressure at lower wall})$$

$$\Rightarrow \mu \frac{\partial^2 v_1}{\partial x_2^2} = \frac{\partial P}{\partial x_1} \quad (32.1)$$

► The Navier-Stokes for  $v_1$  (replacing  $\partial P/\partial x_1$  by  $\partial p/\partial x_1$  in Eq. 32.1)

$$\Rightarrow \mu \frac{\partial^2 v_1}{\frac{\partial x_2^2}{f(x_2)}} = \frac{\partial p}{\frac{\partial x_1}{f(x_1)}} = \text{const}$$

► Integrate twice gives  $v_1 = -\frac{h}{2\mu} \frac{dp}{dx_1} x_2 \left(1 - \frac{x_2}{h}\right)$

See Section 3.3, **Two-dimensional boundary layer flow over flat plate**

$$v_1 \frac{\partial v_1}{\partial x_1} + v_2 \frac{\partial v_1}{\partial x_2} = \nu \frac{\partial^2 v_1}{\partial x_2^2}, \quad \frac{\partial p}{\partial x_1} = 0, \quad \frac{\partial p}{\partial x_2} = 0, \quad \frac{\partial v_1}{\partial x_1} + \frac{\partial v_2}{\partial x_2} = 0$$

(note that both terms on the left side are retained)

► Streamfunction  $\Psi$ :  $v_1 = \frac{\partial \Psi}{\partial x_2}$ ,  $v_2 = -\frac{\partial \Psi}{\partial x_1}$  ► The continuity equation is automatically satisfied

$$0 = \frac{\partial v_1}{\partial x_1} + \frac{\partial v_2}{\partial x_2} = \frac{\partial^2 \Psi}{\partial x_1 \partial x_2} - \frac{\partial^2 \Psi}{\partial x_2 \partial x_1} = 0$$

► Inserting the equation above into the streamwise momentum equation

$$\frac{\partial \Psi}{\partial x_2} \frac{\partial^2 \Psi}{\partial x_1 \partial x_2} - \frac{\partial \Psi}{\partial x_1} \frac{\partial^2 \Psi}{\partial x_2^2} = \nu \frac{\partial^3 \Psi}{\partial x_2^3}$$

► Similarity solution:  $x_1, x_2 \Rightarrow \xi$ ;  $\Psi \Rightarrow g(\xi)$ .

$$\xi = \left( \frac{V_{1,\infty}}{\nu x_1} \right)^{1/2} x_2, \quad \Psi = (\nu V_{1,\infty} x_1)^{1/2} g$$

$$\frac{\partial \Psi}{\partial x_2} \frac{\partial^2 \Psi}{\partial x_1 \partial x_2} - \frac{\partial \Psi}{\partial x_1} \frac{\partial^2 \Psi}{\partial x_2^2} = \nu \frac{\partial^3 \Psi}{\partial x_2^3}, \quad \xi = \left( \frac{V_{1,\infty}}{\nu x_1} \right)^{1/2} x_2, \quad \Psi = (\nu V_{1,\infty} x_1)^{1/2} g$$

► First we need the derivatives  $\partial \xi / \partial x_1$  and  $\partial \xi / \partial x_2$

$$\frac{\partial \xi}{\partial x_1} = -\frac{1}{2} \left( \frac{V_{1,\infty}}{\nu x_1} \right)^{1/2} \frac{x_2}{x_1} = -\frac{\xi}{2x_1}, \quad \frac{\partial \xi}{\partial x_2} = \left( \frac{V_{1,\infty}}{\nu x_1} \right)^{1/2} = \frac{\xi}{x_2}$$

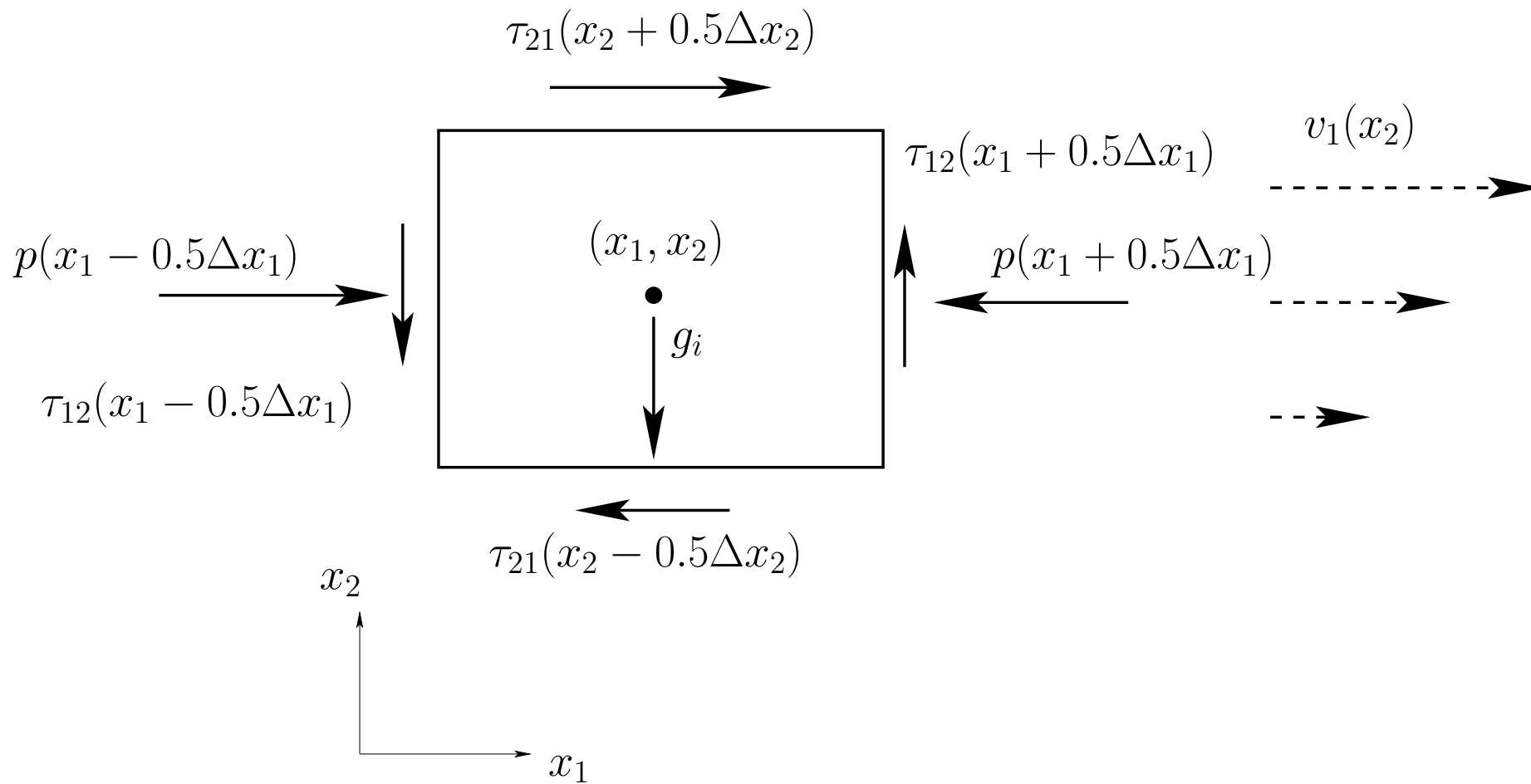
$$\begin{aligned} \frac{\partial \Psi}{\partial x_1} &= \frac{\partial}{\partial x_1} \left( (\nu V_{1,\infty} x_1)^{1/2} \right) g + (\nu V_{1,\infty} x_1)^{1/2} \frac{dg}{d\xi} \frac{\partial \xi}{\partial x_1} \\ &= \frac{\partial}{\partial x_1} \left( (\nu V_{1,\infty} x_1)^{1/2} \right) g + (\nu V_{1,\infty} x_1)^{1/2} g' \frac{\partial \xi}{\partial x_1} \\ &= \frac{1}{2} \left( \frac{\nu V_{1,\infty}}{x_1} \right)^{1/2} g - (\nu V_{1,\infty} x_1)^{1/2} g' \frac{\xi}{2x_1} \\ \dots &\Rightarrow -\frac{1}{2} g g'' + g''' = 0 \end{aligned}$$

► This is Blasius solution (from his PhD thesis in 1907).

► The numerical solution is given in Table 3.1.

## Lecture 4

See Section 4.1, Vorticity and rotation



► Surface forces.  $\partial\tau_{12}/\partial x_1 = 0$ ,  $\partial\tau_{21}/\partial x_2 > 0$ .



$$\frac{\partial \tau_{ji}}{\partial x_j} = \mu \frac{\partial^2 v_i}{\partial x_j \partial x_j}$$

► The right side can be re-written as

$$\begin{aligned} \frac{\partial^2 v_i}{\partial x_j \partial x_j} &= \frac{\partial^2 v_j}{\partial x_j \partial x_i} - \left( \frac{\partial^2 v_j}{\partial x_j \partial x_i} - \frac{\partial^2 v_i}{\partial x_j \partial x_j} \right) \\ &= \underbrace{\frac{\partial}{\partial x_i} \left( \frac{\partial v_j}{\partial x_j} \right)}_{=0} - \varepsilon_{inm} \varepsilon_{mjk} \frac{\partial^2 v_k}{\partial x_j \partial x_n} = -\varepsilon_{inm} \varepsilon_{mjk} \frac{\partial^2 v_k}{\partial x_j \partial x_n} \end{aligned}$$

► Let's verify that

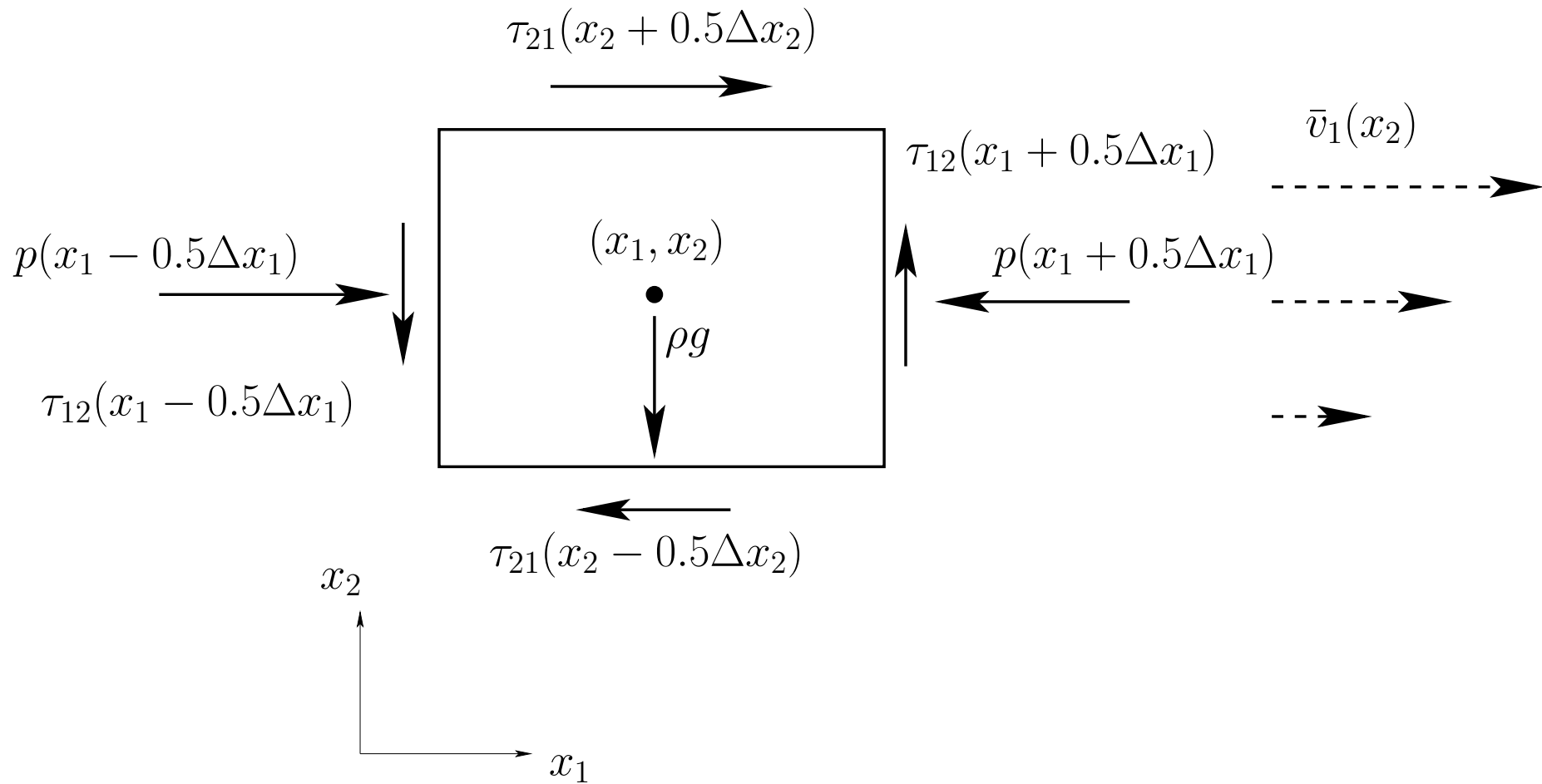
$$\left( \frac{\partial^2 v_j}{\partial x_j \partial x_i} - \frac{\partial^2 v_i}{\partial x_j \partial x_j} \right) = \varepsilon_{inm} \varepsilon_{mjk} \frac{\partial^2 v_k}{\partial x_j \partial x_n}$$

► Use the  $\varepsilon - \delta$ -identity

$$\varepsilon_{inm} \varepsilon_{mjk} \frac{\partial^2 v_k}{\partial x_j \partial x_n} = (\delta_{ij} \delta_{nk} - \delta_{ik} \delta_{nj}) \frac{\partial^2 v_k}{\partial x_j \partial x_n} = \frac{\partial^2 v_k}{\partial x_i \partial x_k} - \frac{\partial^2 v_i}{\partial x_j \partial x_j} \quad \text{verified!}$$

$$\frac{\partial^2 v_i}{\partial x_j \partial x_j} = -\varepsilon_{inm} \varepsilon_{mjk} \frac{\partial^2 v_k}{\partial x_j \partial x_n} = -\varepsilon_{inm} \frac{\partial}{\partial x_n} \left( \varepsilon_{mjk} \frac{\partial v_k}{\partial x_j} \right) = -\varepsilon_{inm} \frac{\partial \omega_m}{\partial x_n}$$

$$\rho \frac{dv_i}{dt} = -\frac{\partial P}{\partial x_i} + \boxed{\frac{\partial \tau_{ji}}{\partial x_j}} = -\frac{\partial P}{\partial x_i} \boxed{-\mu \varepsilon_{inm} \frac{\partial \omega_m}{\partial x_n}} \quad (33.1)$$



► change in vorticity  $\Leftrightarrow$  change in shear stresses ► irrotational flow  $\Leftrightarrow$  ► potential flow  $\Leftrightarrow$

► no change in  $\omega_i$  (often  $\omega_i = 0$ )

► As a first step for deriving the  $\omega_i$  transport equation, let's re-write the left-side of N-S:

$$v_j \frac{\partial v_i}{\partial x_j} = v_j (S_{ij} + \Omega_{ij}) = v_j \left( S_{ij} - \frac{1}{2} \varepsilon_{ijk} \omega_k \right) \quad (33.2)$$

Inserting  $S_{ij} = (\partial v_i / \partial x_j + \partial v_j / \partial x_i) / 2$  and multiplying by two gives

$$2v_j \frac{\partial v_i}{\partial x_j} = v_j \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) - \varepsilon_{ijk} v_j \omega_k$$

$$\Rightarrow v_j \frac{\partial v_i}{\partial x_j} = v_j \frac{\partial v_j}{\partial x_i} - \varepsilon_{ijk} v_j \omega_k \quad (33.3)$$

► The first term on the right side can be written as (Trick 2)

$$v_j \frac{\partial v_j}{\partial x_i} = \frac{1}{2} \frac{\partial (v_j v_j)}{\partial x_i} \quad (33.4)$$

► With Eqs. 33.3, 33.4 and Eq. 33.2 N-S can be written

$$\frac{\partial v_i}{\partial t} + \underbrace{\frac{\partial \frac{1}{2} v^2}{\partial x_i}}_{\text{no rotation}} - \underbrace{\frac{\varepsilon_{ijk} v_j \omega_k}{\text{rotation}}} = - \frac{1}{\rho} \frac{\partial P}{\partial x_i} + \nu \frac{\partial^2 v_i}{\partial x_j \partial x_j} + f_i \quad (33.5)$$

$$\frac{\partial v_i}{\partial t} + \underbrace{\frac{\partial \frac{1}{2}v^2}{\partial x_i}}_{\text{no rotation}} - \underbrace{\frac{\varepsilon_{ijk}v_j\omega_k}{\text{rotation}}}_{\text{rotation}} = -\frac{1}{\rho}\frac{\partial P}{\partial x_i} + \nu\frac{\partial^2 v_i}{\partial x_j\partial x_j} + f_i \quad (33.5)$$

► Now we will derive the transport equation for  $\omega_p = \varepsilon_{pqi}\partial v_i/\partial x_q$ .  $\omega_p = (\varepsilon_{pqi}\partial/\partial x_q)(v_i)$ .

► Multiply the Navier-Stokes equation by  $\varepsilon_{pqi}\partial/\partial x_q$  so that

$$\varepsilon_{pqi}\frac{\partial^2 v_i}{\partial t\partial x_q} + \cancel{\varepsilon_{pqi}\frac{\partial^2 \frac{1}{2}v^2}{\partial x_i\partial x_q} \rightarrow 0} - \varepsilon_{pqi}\varepsilon_{ijk}\frac{\partial v_j\omega_k}{\partial x_q} = -\cancel{\varepsilon_{pqi}\frac{1}{\rho}\frac{\partial^2 P}{\partial x_i\partial x_q} \rightarrow 0} + \nu\varepsilon_{pqi}\frac{\partial^3 v_i}{\partial x_j\partial x_j\partial x_q} + \cancel{\varepsilon_{pqi}\frac{\partial g_i}{\partial x_q} \rightarrow 0} \quad (33.6)$$

- Term 2 on left side: zero because product of anti-symmetric & symmetric tensor
- Term 1 in right side: zero because product of anti-symmetric & symmetric tensor
- last term: zero because  $g_i$  is constant

► Re-write unsteady and viscous terms in Eq. 33.6:

$$\varepsilon_{pqi}\frac{\partial^2 v_i}{\partial t\partial x_q} = \frac{\partial}{\partial t} \left( \varepsilon_{pqi}\frac{\partial v_i}{\partial x_q} \right) = \frac{\partial \omega_p}{\partial t}, \quad \nu\varepsilon_{pqi}\frac{\partial^3 v_i}{\partial x_j\partial x_j\partial x_q} = \nu\frac{\partial^2}{\partial x_j\partial x_j} \left( \varepsilon_{pqi}\frac{\partial v_i}{\partial x_q} \right) = \nu\frac{\partial^2 \omega_p}{\partial x_j\partial x_j}$$

► Inserted in Eq. 33.6 gives

$$\frac{\partial \omega_p}{\partial t} - \varepsilon_{pqi}\varepsilon_{ijk}\frac{\partial v_j\omega_k}{\partial x_q} = \nu\frac{\partial^2 \omega_p}{\partial x_j\partial x_j}$$

$$\frac{\partial \omega_p}{\partial t} - \varepsilon_{pqi} \varepsilon_{ijk} \frac{\partial v_j \omega_k}{\partial x_q} = \nu \frac{\partial^2 \omega_p}{\partial x_j \partial x_j}$$

► The second term on the left side is re-written using the  $\varepsilon$ - $\delta$  identity

$$\begin{aligned} \varepsilon_{pqi} \varepsilon_{ijk} \frac{\partial v_j \omega_k}{\partial x_q} &= (\delta_{pj} \delta_{qk} - \delta_{pk} \delta_{qj}) \frac{\partial v_j \omega_k}{\partial x_q} = \frac{\partial v_p \omega_k}{\partial x_k} - \frac{\partial v_q \omega_p}{\partial x_q} \\ &= v_p \frac{\partial \omega_k}{\partial x_k} + \omega_k \frac{\partial v_p}{\partial x_k} - v_q \frac{\partial \omega_p}{\partial x_q} - \cancel{\omega_p \frac{\partial v_q}{\partial x_q}} \end{aligned} \quad (33.7)$$

► Term 1: Using the definition of  $\omega_i$  we find that

$$\frac{\partial \omega_i}{\partial x_i} = \frac{\partial}{\partial x_i} \left( \varepsilon_{ijk} \frac{\partial v_k}{\partial x_j} \right) = \varepsilon_{ijk} \frac{\partial^2 v_k}{\partial x_j \partial x_i} = 0 \quad (33.8)$$

(product of symmetric and anti-symmetric tensor).

► Using Eq. 33.8, Eq. 33.7 can be written

$$\varepsilon_{pqi} \varepsilon_{ijk} \frac{\partial v_j \omega_k}{\partial x_q} = \omega_k \frac{\partial v_p}{\partial x_k} - v_k \frac{\partial \omega_p}{\partial x_k} \quad (33.9)$$

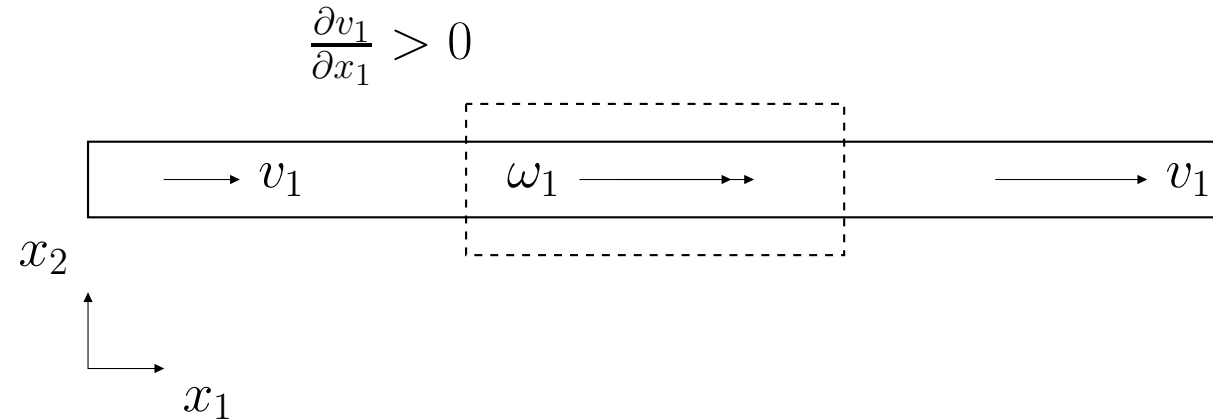
► Finally, we can write the transport equation for the vorticity

$$\frac{\partial \omega_p}{\partial t} + v_k \frac{\partial \omega_p}{\partial x_k} = \omega_k \frac{\partial v_p}{\partial x_k} + \nu \frac{\partial^2 \omega_p}{\partial x_j \partial x_j}$$

$$\frac{\partial \omega_p}{\partial t} + v_k \frac{\partial \omega_p}{\partial x_k} = \underbrace{\omega_k \frac{\partial v_p}{\partial x_k}} + \nu \frac{\partial^2 \omega_p}{\partial x_j \partial x_j}$$

► Underlined term: **Vortex stretching** and **vortex tilting**

► **Vortex stretching**

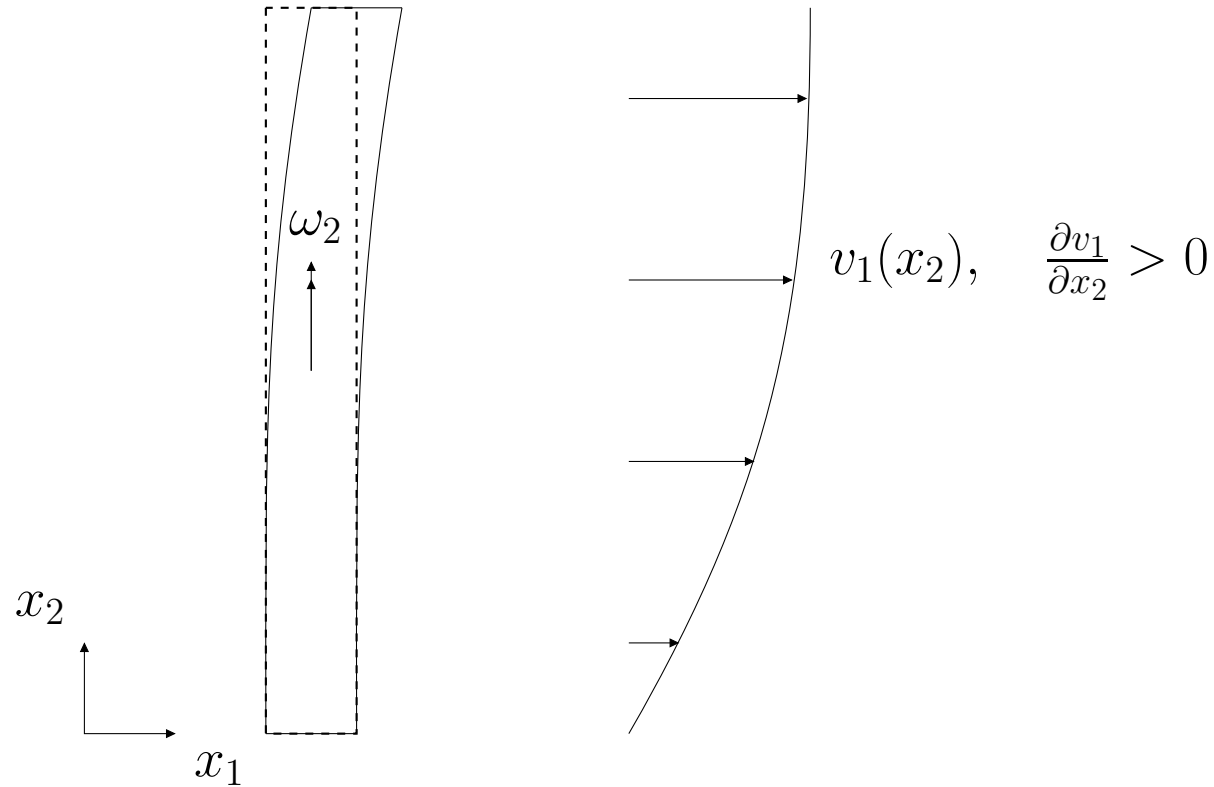


$$\omega_k \frac{\partial v_p}{\partial x_k} = \begin{cases} \omega_1 \frac{\partial v_1}{\partial x_1} + \omega_2 \frac{\partial v_1}{\partial x_2} + \omega_3 \frac{\partial v_1}{\partial x_3}, & p = 1 \\ \omega_1 \frac{\partial v_2}{\partial x_1} + \omega_2 \frac{\partial v_2}{\partial x_2} + \omega_3 \frac{\partial v_2}{\partial x_3}, & p = 2 \\ \omega_1 \frac{\partial v_3}{\partial x_1} + \omega_2 \frac{\partial v_3}{\partial x_2} + \omega_3 \frac{\partial v_3}{\partial x_3}, & p = 3 \end{cases}$$

$\frac{\partial v_1}{\partial x_1} > 0$ : the term  $\omega_1 \frac{\partial v_1}{\partial x_1}$  will increase  $\omega_1$

$$\omega_k \frac{\partial v_p}{\partial x_k} = \begin{cases} \omega_1 \frac{\partial v_1}{\partial x_1} + \omega_2 \frac{\partial v_1}{\partial x_2} + \omega_3 \frac{\partial v_1}{\partial x_3}, & p = 1 \\ \omega_1 \frac{\partial v_2}{\partial x_1} + \omega_2 \frac{\partial v_2}{\partial x_2} + \omega_3 \frac{\partial v_2}{\partial x_3}, & p = 2 \\ \omega_1 \frac{\partial v_3}{\partial x_1} + \omega_2 \frac{\partial v_3}{\partial x_2} + \omega_3 \frac{\partial v_3}{\partial x_3}, & p = 3 \end{cases}$$

► Vortex tilting/deflection    ► Assume  $\frac{\partial v_1}{\partial x_2} > 0$



►  $\frac{\partial v_1}{\partial x_2} > 0$ : the term  $\omega_2 \frac{\partial v_1}{\partial x_2}$  will increase  $\omega_1$

¶ See Section 4.3, The vorticity transport equation in two dimensions

▶ 3D flow: 
$$\frac{\partial \omega_p}{\partial t} + v_k \frac{\partial \omega_p}{\partial x_k} = \omega_k \frac{\partial v_p}{\partial x_k} + \nu \frac{\partial^2 \omega_p}{\partial x_j \partial x_j}$$

▶ 2D flow:  $v_i = (v_1, v_2, 0), \quad \frac{\partial}{\partial x_3} = v_3 = 0$

▶ The vorticity:  $\omega_i = \varepsilon_{ijk} \frac{\partial v_k}{\partial x_j}$

$$\omega_1 = \frac{\partial v_2}{\partial x_3} - \frac{\partial v_3}{\partial x_2} = 0, \quad \omega_2 = \frac{\partial v_1}{\partial x_3} - \frac{\partial v_3}{\partial x_1} = 0, \quad \omega_3 \neq 0$$

▶ Hence, the vortex stretching/tilting term  $\omega_k \frac{\partial v_p}{\partial x_k} = \omega_3 \frac{\partial v_p}{\partial x_3} = 0$

▶ The 2D  $\omega_3$  equation reads

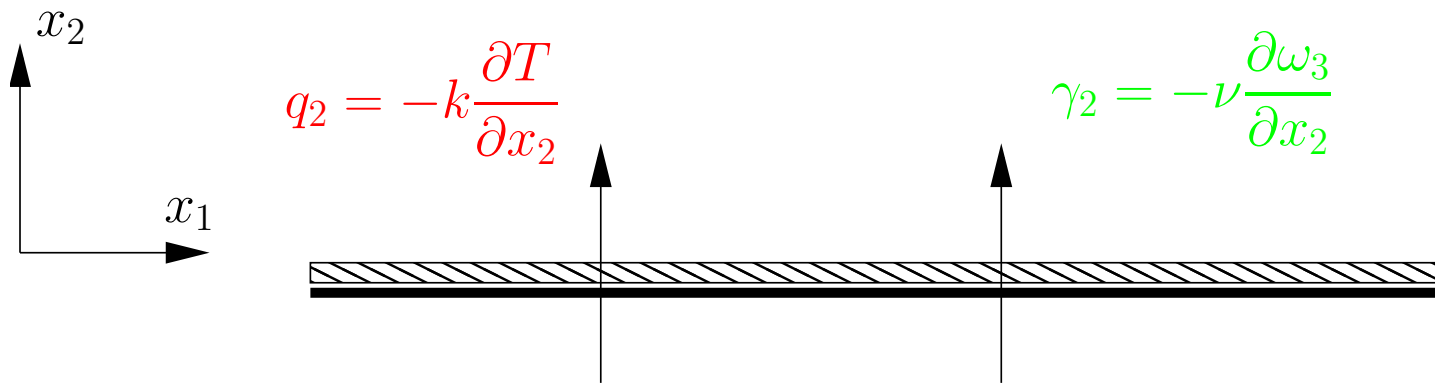
$$\frac{\partial \omega_3}{\partial t} + v_k \frac{\partial \omega_3}{\partial x_k} = \nu \frac{\partial^2 \omega_3}{\partial x_j \partial x_j}$$



$$\frac{\partial \omega_3}{\partial t} + v_k \frac{\partial \omega_3}{\partial x_k} = \nu \frac{\partial^2 \omega_3}{\partial x_j \partial x_j}$$

► Consider fully developed channel flow

► **heat conduction:**  $0 = k \frac{\partial^2 T}{\partial x_2^2}$     ► **vorticity diffusion**  $0 = \nu \frac{\partial^2 \omega_3}{\partial x_2^2}$



► Temperature:  $q_2 = 0 \Rightarrow$  no temperature (increase)

► Vorticity:  $\gamma_2 = 0 \Rightarrow$  no vorticity (increase)

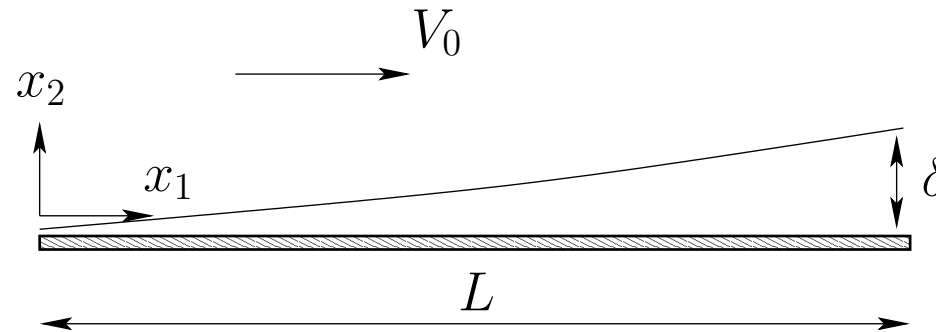
– In a boundary layer this is true because  $\frac{\partial p}{\partial x_1} = 0 \Leftrightarrow \left( \frac{\partial^2 v_1}{\partial^2 x_2} \right)_{wall} = 0$

– for channel flow,  $\frac{\partial p}{\partial x_1} \neq 0 \Rightarrow \gamma_2 \neq 0$

¶ See Section 4.3.1, [Boundary layer thickness from the Rayleigh problem](#)

► Rayleigh problem:  $\delta(t) = 3.6\sqrt{\nu t}$  was presented for the  $v_1$  equation.  
Also for the concentration/temperature equation.

► Here we will use it for the vorticity equation.



► Boundary layer thickness:  $\delta \propto \sqrt{\nu t} = \sqrt{\frac{L\nu}{V_0}} = L\sqrt{\frac{\nu}{V_0 L}} \Rightarrow \frac{\delta}{L} \propto \sqrt{\frac{1}{Re_L}}$

## Lecture 5

¶ See Section 4.4, Potential flow

► Define a potential

$$v_i = \frac{\partial \Phi}{\partial x_i} \quad (34.1)$$

If it exists, the vorticity is zero

$$\omega_i = \varepsilon_{ijk} \frac{\partial v_k}{\partial x_j} = \varepsilon_{ijk} \frac{\partial^2 \Phi}{\partial x_j \partial x_k} = 0$$

The continuity eq. reads

$$0 = \frac{\partial v_i}{\partial x_i} = \frac{\partial}{\partial x_i} \left( \frac{\partial \Phi}{\partial x_i} \right) = \frac{\partial^2 \Phi}{\partial x_i \partial x_i} \quad (34.2)$$

► Derive the Bernoulli eq.    ► The N-S reads (see Eqs. 33.1 and 33.5)

$$\frac{\partial v_i}{\partial t} + \underbrace{\frac{\partial \frac{1}{2} v^2}{\partial x_i}}_{\text{no rotation}} - \underbrace{\varepsilon_{ijk} v_j \omega_k}_{\text{rotation}} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} - \nu \varepsilon_{inm} \frac{\partial \omega_m}{\partial x_n} + g_i$$

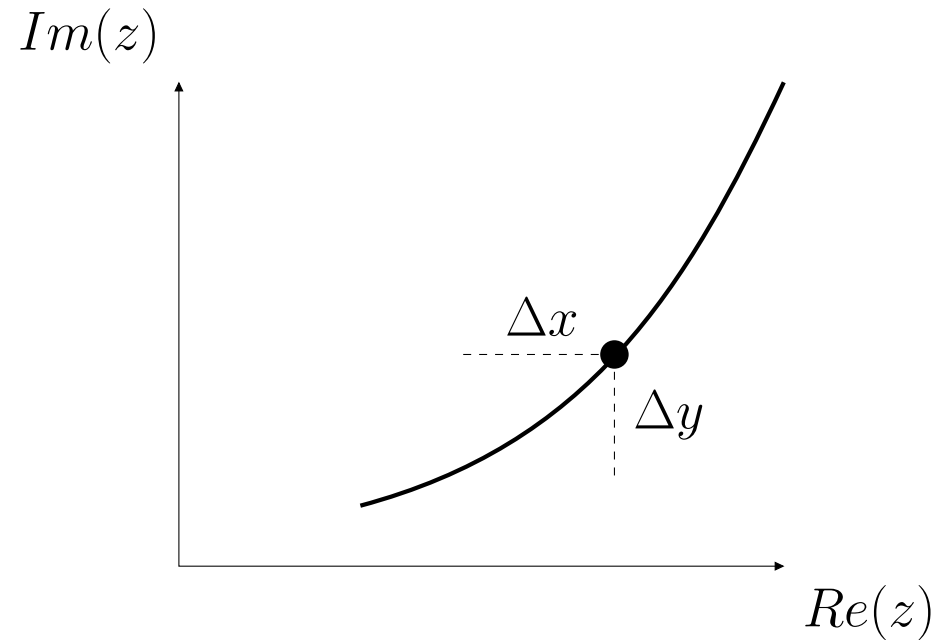
In potential flow,  $\omega_i = 0$ . Insert  $\Phi$  (Eq. 34.1) and a gravitation potential ( $g_i = -\partial \mathcal{X} / \partial x_i$ )

$$\frac{\partial}{\partial x_i} \left( \frac{\partial \Phi}{\partial t} \right) + \frac{\partial \frac{1}{2} v^2}{\partial x_i} + \frac{1}{\rho} \frac{\partial p}{\partial x_i} + \frac{\partial \mathcal{X}}{\partial x_i} = 0 \quad \text{Integrate: } \frac{\partial \Phi}{\partial t} + \frac{1}{2} v^2 + \frac{p}{\rho} + \mathcal{X} = C_1 \quad \mathcal{X} = -g_3 x_3 = gh \quad \text{Bernoulli}$$

¶ See Section 4.4.2, [Complex variables for potential solutions of plane flows](#)

► Complex functions.

► The derivative of a complex function,  $f$ , by a complex variable,  $z$  ( $f = u + iv$  and  $z = x + iy$ ) is defined only if the derivatives in the real and imaginary directions are the same, i.e.



$$\frac{df}{dz} = \lim_{\Delta z \rightarrow 0} \frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z} \quad (34.3)$$

$$= \lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x, iy_0) - f(x_0, iy_0)}{\Delta x} = \lim_{\Delta y \rightarrow 0} \frac{f(x_0, iy_0 + i\Delta y) - f(x_0, iy_0)}{i\Delta y}. \quad (34.4)$$

► This means that

$$\frac{\partial f}{\partial x} = \frac{1}{i} \frac{\partial f}{\partial y} = \frac{i \partial f}{i^2 \partial y} = -i \frac{\partial f}{\partial y} \quad (34.5)$$

$$\frac{\partial f}{\partial x} = -i \frac{\partial f}{\partial y} \quad (34.5)$$

► Inserting  $f = u + iv$  in Eq. 34.5 gives

$$\frac{\partial u}{\partial x} + i \frac{\partial v}{\partial x} = -i \frac{\partial u}{\partial y} - i^2 \frac{\partial v}{\partial y} = -i \frac{\partial u}{\partial y} + \frac{\partial v}{\partial y}$$

We get

$$\begin{aligned} \text{real part:} \quad & \frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \\ \text{imaginary part:} \quad & \frac{\partial v}{\partial x} = -\frac{\partial u}{\partial y} \end{aligned} \quad (34.6)$$

They are called the *Cauchy-Riemann* equations.

► A complex function in polar coordinates:  $z = re^{i\theta} = r(\cos \theta + i \sin \theta)$

$$\text{Cauchy-Riemann} \quad \frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}, \quad \frac{\partial v}{\partial x} = -\frac{\partial u}{\partial y} \quad (34.6)$$

► Fluid dynamics: define a complex potential  $f = \Phi + i\Psi$  where  $\Psi$  is the streamfunction: recall

$$v_1 = \frac{\partial \Psi}{\partial y} = \frac{\partial \Phi}{\partial x} \quad \text{and} \quad v_2 = -\frac{\partial \Psi}{\partial x} = \frac{\partial \Phi}{\partial y} \quad (34.7)$$

► We want  $f$  to be differentiable: hence Eq. 34.6 must hold (replace  $u$  and  $v$  with  $\Phi$  and  $\Psi$ )

$$\frac{\partial \Phi}{\partial x} = \frac{\partial \Psi}{\partial y}, \quad \frac{\partial \Phi}{\partial y} = -\frac{\partial \Psi}{\partial x} \quad \text{which is satisfied, see Eq. 34.7} \quad (34.8)$$

►  $\Phi$  satisfies Laplace eq. (see Eq. 34.2). Since  $\omega_3 = 0$  (potential flow), this applies also for  $\Psi$

$$\frac{\partial^2 \Psi}{\partial x_1^2} + \frac{\partial^2 \Psi}{\partial x_2^2} = -\frac{\partial v_2}{\partial x_1} + \frac{\partial v_1}{\partial x_2} = -\omega_3 = 0 \quad (34.9)$$

►  $\Phi$  and  $\Psi$  satisfy Laplace equation. ► Hence,  $f$  also satisfies Laplace equation

► Furthermore,  $f$  has a physical meaning in fluid dynamics: it describes potential flow

► namely, continuity equation, i.e.  $\frac{\partial^2 \Phi}{\partial x_i \partial x_i} = 0$  ► and  $\omega_3 = 0$ , i.e.  $\frac{\partial^2 \Psi}{\partial x_i \partial x_i} = 0$

¶ See Section 4.4.3,  $f \propto z^n$

1. Now we “guess”/dream up a complex function  $f = \Phi + i\Psi$
2. then we check if it satisfies the Laplace equation (i.e. the continuity equation, 34.2 and that the flow is inviscid,  $\omega_3 = 0$ , Eq. 34.9)
3. then we find out if  $f$  corresponds to a meaningful fluid flow situation

► We guess  $f = C_1 z^n = C_1 r^n e^{in\theta} = C_1 r^n (\cos(n\theta) + i \sin(n\theta))$

Check that it satisfies Laplace equation

$$\nabla^2 f = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$$

► It does, see eBook

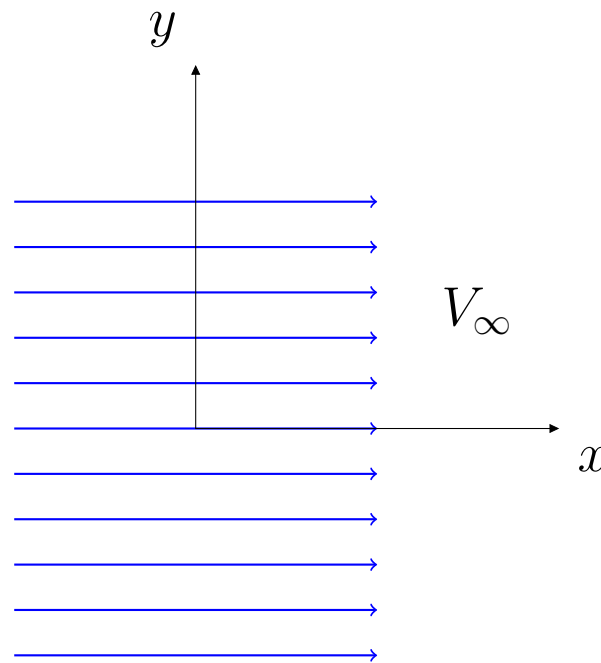
¶ See Section 4.4.3.1, *Parallel flow*

► Our guess  $f = C_1 r^n (\cos(n\theta) + i \sin(n\theta))$

► Parallel flow,  $n = 1$ .  $f = C_1 z = V_\infty z = V_\infty (x + iy)$

The streamfunction,  $\Psi$ , is the imaginary part of  $f$ , i.e.  $\Psi = V_\infty y$  which gives

$$v_1 = \frac{\partial \Psi}{\partial y} = V_\infty, \quad v_2 = -\frac{\partial \Psi}{\partial x} = 0$$





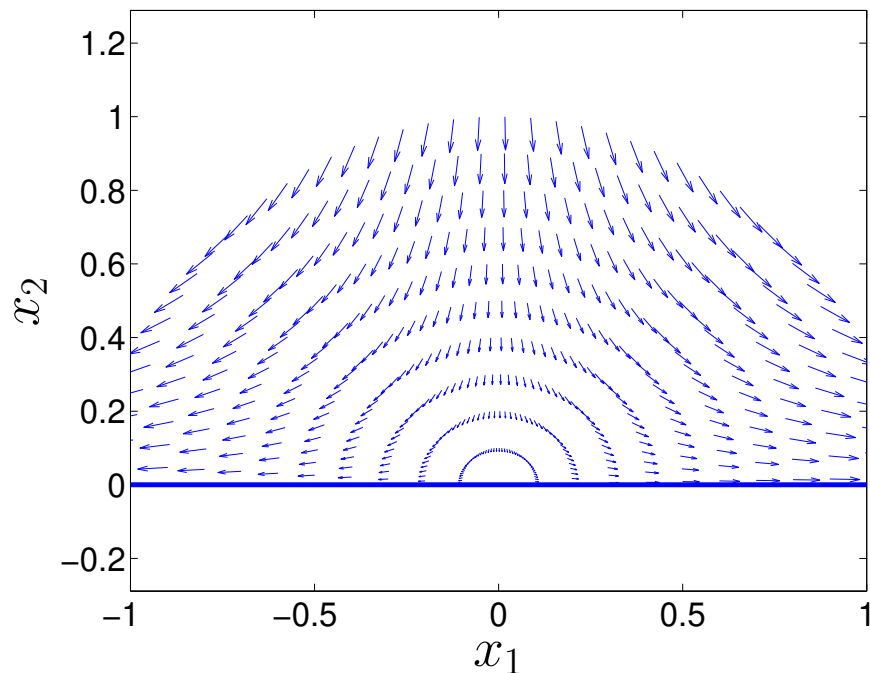
See Section 4.4.3.2, *Stagnation flow*

Our guess with  $n = 2$ :  $f = r^2(\cos(2\theta) + i \sin(2\theta))$

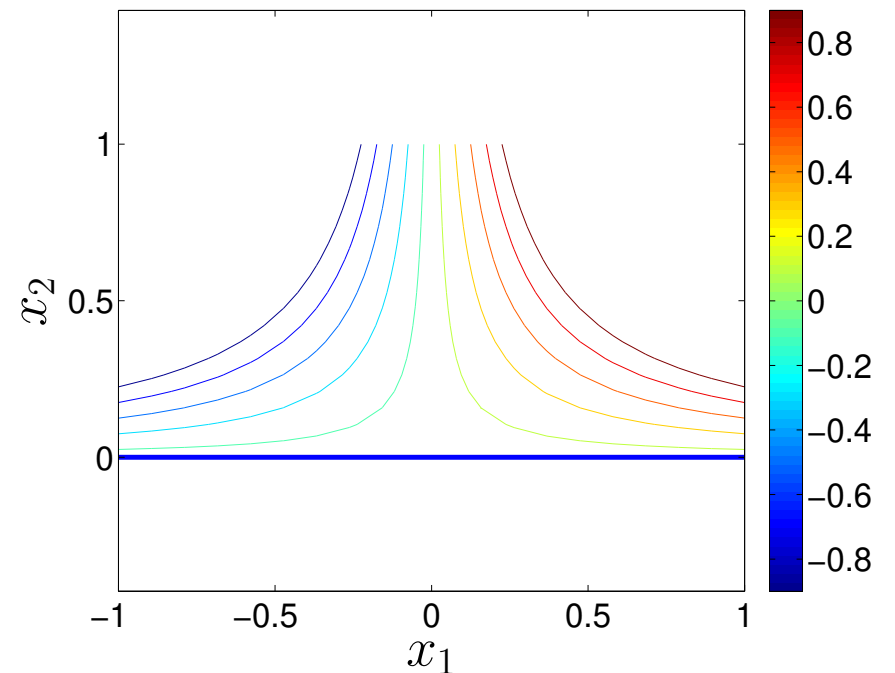
The streamfunction,  $\Psi$ , is the imaginary part of  $f$ , i.e.  $\Psi = r^2 \sin(2\theta)$

The polar and Cartesian velocity components are obtained as

$$\begin{aligned} v_r &= \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = 2r \cos(2\theta), & v_\theta &= -\frac{\partial \Psi}{\partial r} = -2r \sin(2\theta) \\ v_1 &= 2x_1, & v_2 &= -2x_2 \end{aligned}$$



Vector plot.



Streamlines. Colors represent  $\Psi$ .

The flow impinges at the wall at  $x_2 = 0$  where  $v_2 = 0$ .

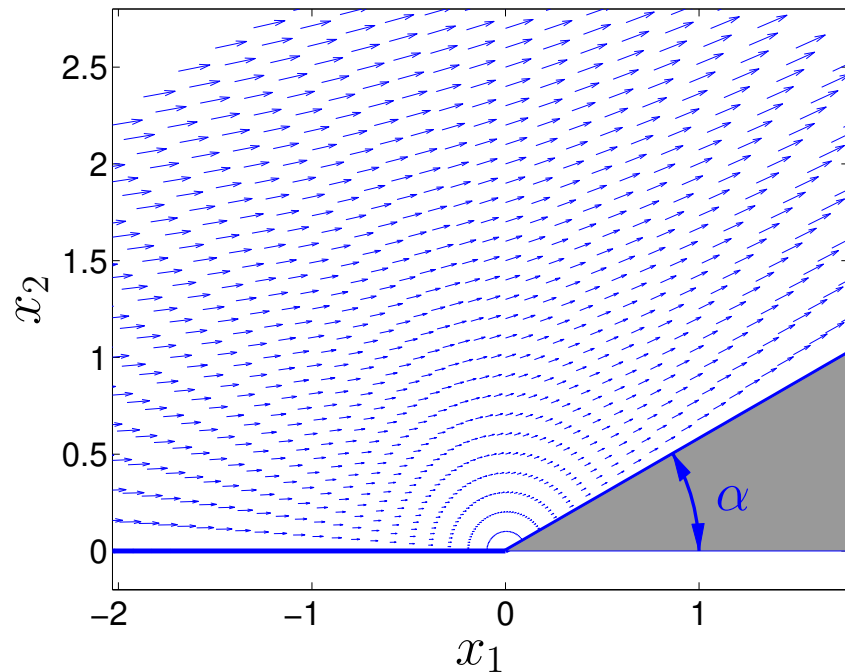
$\Psi=0$  along the symmetry line,  $x_1 = 0$ , and it is negative to the left and positive to the right.

See Section 4.4.3.3, *Flow over a wedge and flow in a concave corner*

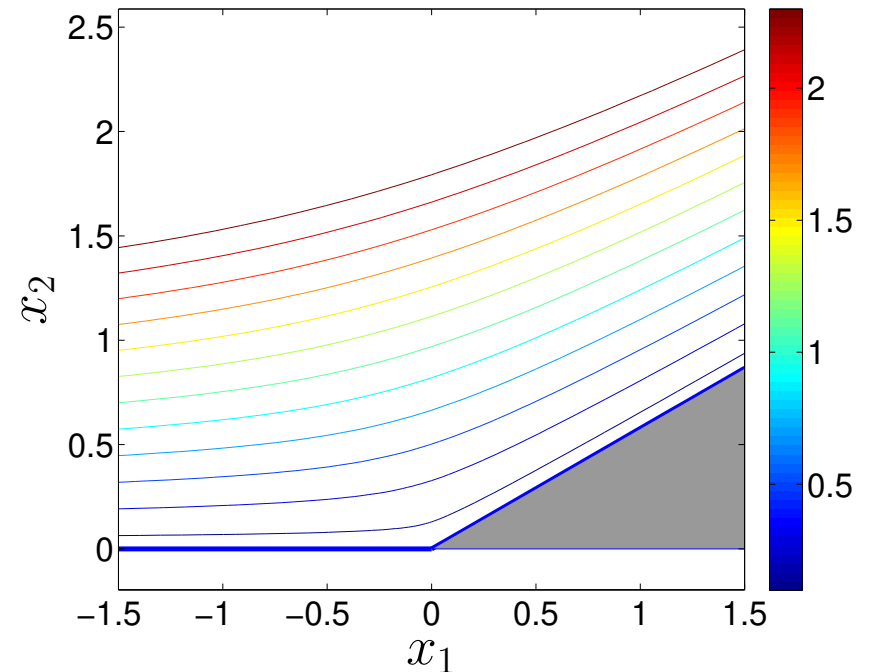
Our guess with  $n = 6/5$ :  $f = r^{6/5}(\cos(6\theta/5) + i \sin(6\theta/5))$

The streamfunction,  $\Psi$ , is the imaginary part of  $f$ , i.e.  $\Psi = r^{6/5} \sin(6\theta/5)$

$$v_r = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = \frac{6}{5} r \cos(6\theta/5), \quad v_\theta = -\frac{\partial \Psi}{\partial r} = -\frac{6}{5} r \sin(6\theta/5)$$



Vector plot.



Streamlines. Colors represent  $\Psi$ .

The lower boundary for  $x_1 < 0$  can either be a wall (concave corner) or symmetry line (wedge).

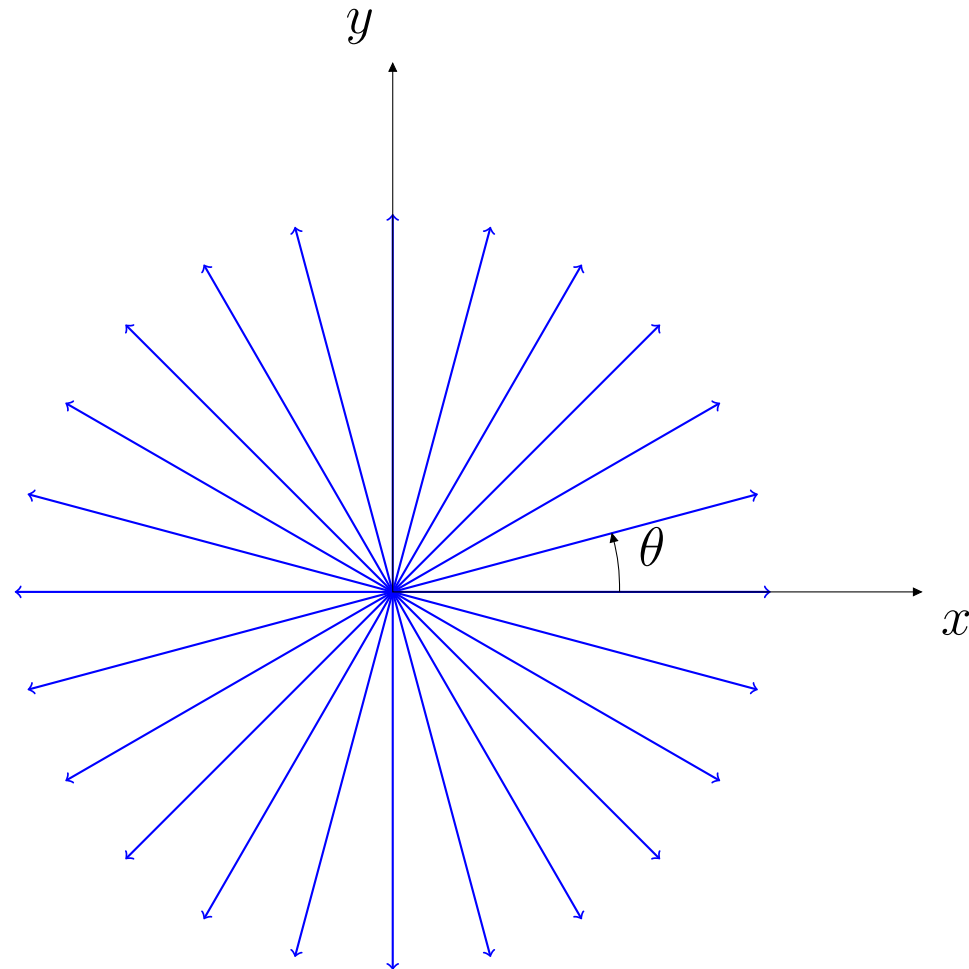
$\Psi=0$  along the lower boundary. The angle,  $\alpha$ , in the figure above is given by  $\alpha = \frac{(n-1)\pi}{n} = \frac{\pi}{6}$

¶ See Section 4.4.4, [Analytical solutions for a line source](#)

$$f = \frac{\dot{m}}{2\pi} \ln z = \frac{\dot{m}}{2\pi} \ln (re^{i\theta}) = \frac{\dot{m}}{2\pi} (\ln r + \ln (e^{i\theta})) = \frac{\dot{m}}{2\pi} (\ln r + i\theta)$$

Check that it satisfies Laplace equation (it does, see eBook)

$$\Psi = \frac{\dot{m}\theta}{2\pi}, \quad v_r = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = \frac{\dot{m}}{2\pi r}, \quad v_\theta = -\frac{\partial \Psi}{\partial r} = 0$$

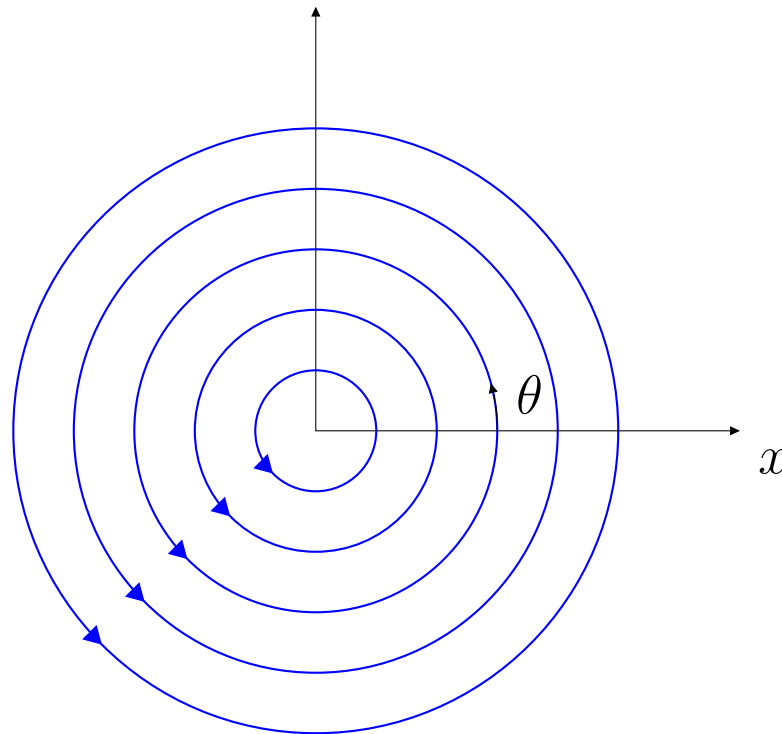


See Section 4.4.5, Analytical solutions for a vortex line

$$\begin{aligned} f &= -i \frac{\Gamma}{2\pi} \ln z = -i \frac{\Gamma}{2\pi} \ln (r e^{i\theta}) = -i \frac{\Gamma}{2\pi} (\ln r + \ln (e^{i\theta})) = \frac{\Gamma}{2\pi} (-i \ln r - i \ln (e^{i\theta})) \\ &= \frac{\Gamma}{2\pi} (-i \ln r - i^2 \theta) = \frac{\Gamma}{2\pi} (-i \ln r + \theta) \end{aligned}$$

Check if it satisfies Laplace equation (it does, see eBook)

$$\Psi = \frac{\Gamma}{2\pi} \ln r, \quad v_r = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = 0, \quad v_\theta = -\frac{\partial \Psi}{\partial r} = \frac{\Gamma}{2\pi r}$$



¶ See Section 4.4.6, [Analytical solutions for flow around a cylinder](#)

► Doublet: take a line source ( $\dot{m} > 0$ ) a line sink ( $\dot{m} < 0$ ) with a separation  $\varepsilon$ : let  $\varepsilon \rightarrow 0$  which gives

$$f = \frac{\mu}{\pi z} = \frac{V_\infty r_0^2}{z} \quad \text{where} \quad r_0^2 = \mu / (\pi V_\infty)$$

► Recall:  $\frac{\partial^2 \Psi}{\partial x_i \partial x_i} = 0$  is linear  $\Rightarrow \Psi_{sol} = \Psi_{sol,1} + \Psi_{sol,2} + \dots$

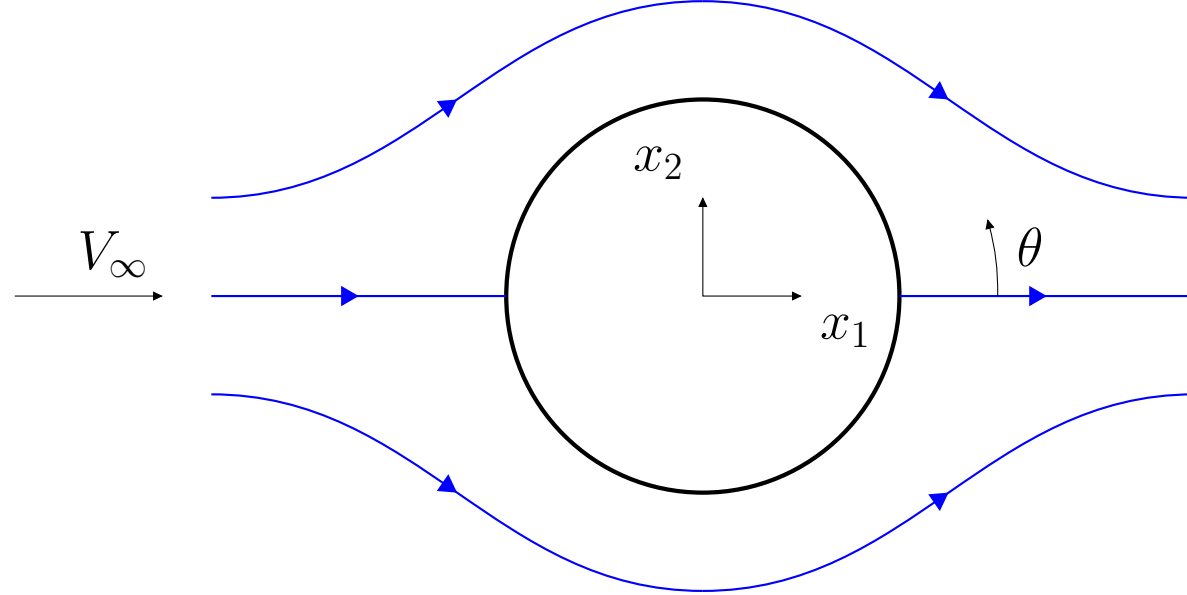
► Add parallel flow ( $f = V_\infty z$ ) gives cylinder flow

$$\begin{aligned} f &= \frac{V_\infty r_0^2}{z} + V_\infty z = \frac{V_\infty r_0^2}{r e^{i\theta}} + V_\infty r e^{i\theta} = V_\infty \left( \frac{r_0^2}{r} e^{-i\theta} + r e^{i\theta} \right) \\ &= \frac{V_\infty r_0^2}{r} (\cos \theta - i \sin \theta) + V_\infty r (\cos \theta + i \sin \theta) \end{aligned}$$

► The streamfunction reads (imaginary part)  $\Psi = V_\infty \left( r - \frac{r_0^2}{r} \right) \sin \theta$

and we get the velocity components

$$v_r = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = V_\infty \left( 1 - \frac{r_0^2}{r^2} \right) \cos \theta, \quad v_\theta = -\frac{\partial \Psi}{\partial r} = -V_\infty \left( 1 + \frac{r_0^2}{r^2} \right) \sin \theta$$



$$v_r = V_\infty \left( 1 - \frac{r_0^2}{r^2} \right) \cos \theta, \quad v_\theta = -V_\infty \left( 1 + \frac{r_0^2}{r^2} \right) \sin \theta$$

$$r \rightarrow r_0 : \quad v_r \rightarrow 0$$

$$\theta = 0, r \rightarrow \infty : \quad \Rightarrow v_r \rightarrow V_\infty$$

$$\theta = \pi, r \rightarrow \infty : \quad \Rightarrow v_r \rightarrow -V_\infty$$

¶ See Section 4.4.7, [Analytical solutions for flow around a cylinder with circulation](#)

► We have  $f$  for a cylinder. Now we add  $f$  for a vortex line

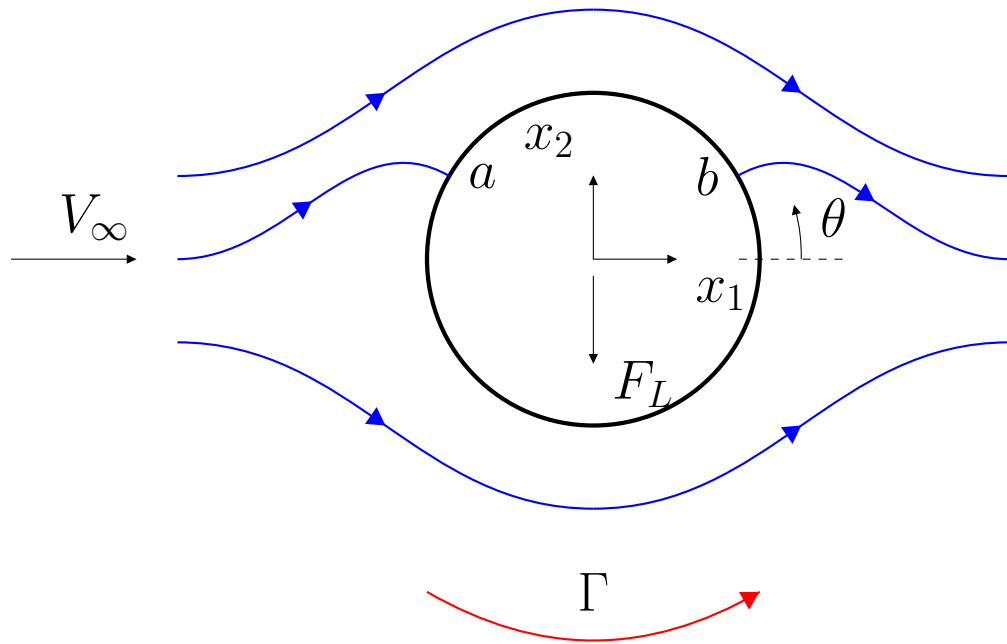
$$f = V_{\infty} \left( \frac{r_0^2}{r} (\cos \theta - i \sin \theta) + r (\cos \theta + i \sin \theta) \right) - i \frac{\Gamma}{2\pi} \ln z$$
$$\Gamma = \oint v_m t_m d\ell = \int_S \varepsilon_{ijk} \frac{\partial v_k}{\partial x_j} n_i dS = \int_S \omega_i n_i dS = \int_S \omega_3 dS$$

► The imaginary part gives the streamfunction

$$\Psi = V_{\infty} \left( r - \frac{r_0^2}{r} \right) \sin \theta - \frac{\Gamma}{2\pi} \ln r$$

We get the velocity components as

$$v_r = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = V_{\infty} \left( 1 - \frac{r_0^2}{r^2} \right) \cos \theta, \quad v_{\theta} = -\frac{\partial \Psi}{\partial r} = -V_{\infty} \left( 1 + \frac{r_0^2}{r^2} \right) \sin \theta + \frac{\Gamma}{2\pi r}$$



$$v_r = \frac{1}{r} \frac{\partial \Psi}{\partial \theta} = V_\infty \left( 1 - \frac{r_0^2}{r^2} \right) \cos \theta$$

$$v_\theta = -\frac{\partial \Psi}{\partial r} = -V_\infty \left( 1 + \frac{r_0^2}{r^2} \right) \sin \theta + \frac{\Gamma}{2\pi r}$$

- ▶ The velocity at the surface,  $r = r_0$ : ▶  $v_{r,s} = 0$ ,  $v_{\theta,s} = -2V_\infty \sin \theta + \frac{\Gamma}{2\pi r_0}$
- ▶ Location of the stagnation points, i.e. where  $v_{\theta,s} = 0$ . We get

$$2V_\infty \sin \theta_{stag} = \frac{\Gamma}{2\pi r_0} \Rightarrow \theta_{stag} = \arcsin \left( \frac{\Gamma}{4\pi r_0 V_\infty} \right)$$

- ▶ The surface pressure is obtained from Bernoulli equation

$$\frac{V_\infty^2}{2} + \frac{P_\infty}{\rho} = \frac{v_{\theta,s}^2}{2} + \frac{p_s}{\rho} \Rightarrow p_s = P_\infty + \rho \frac{V_\infty^2 - v_{\theta,s}^2}{2}$$

We get: ▶  $C_p = 1 - \frac{v_{\theta,s}^2}{V_\infty^2} = 1 - \left( -2 \sin \theta + \frac{\Gamma}{2\pi r_0 V_\infty} \right)^2$

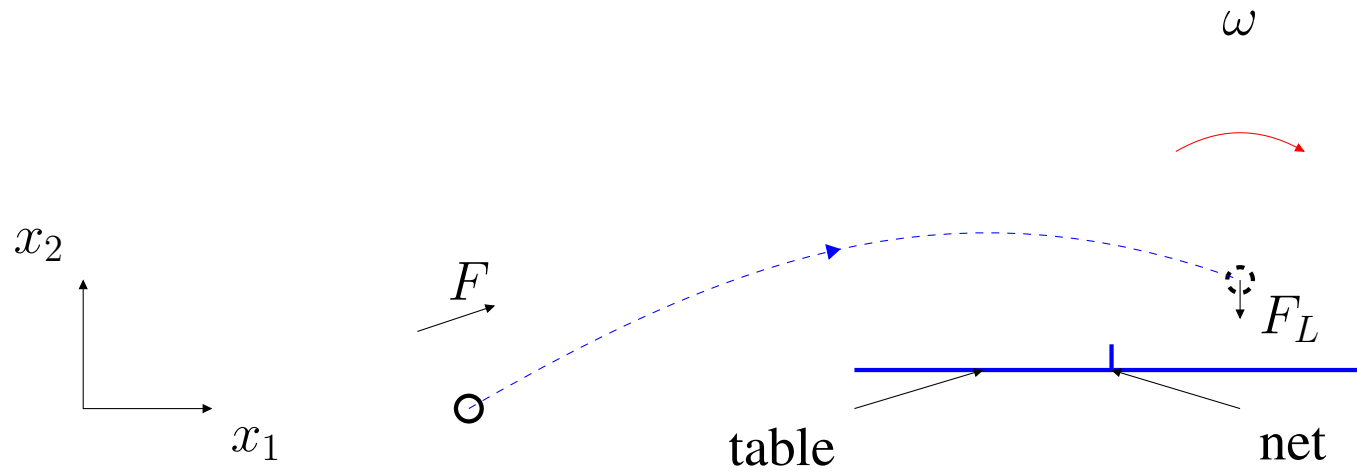
- ▶ Integration of  $C_p$  gives drag  $F_D = 0$  and lift  $F_L = -\rho V_\infty \Gamma$ .



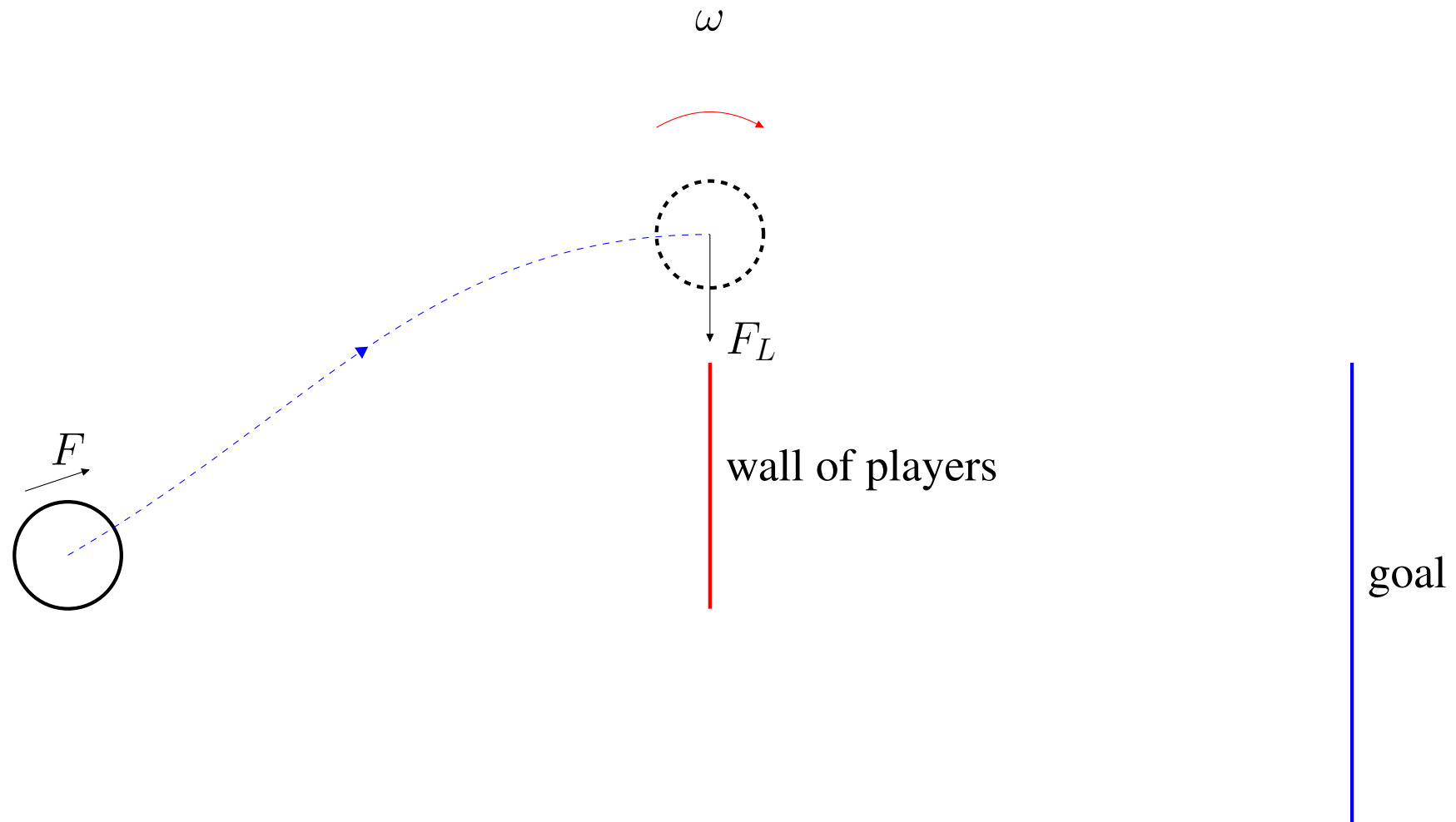
See Section 4.4.7.1, *The Magnus effect*

► The Magnus' effect: three applications

► Table tennis: loop or top-spin

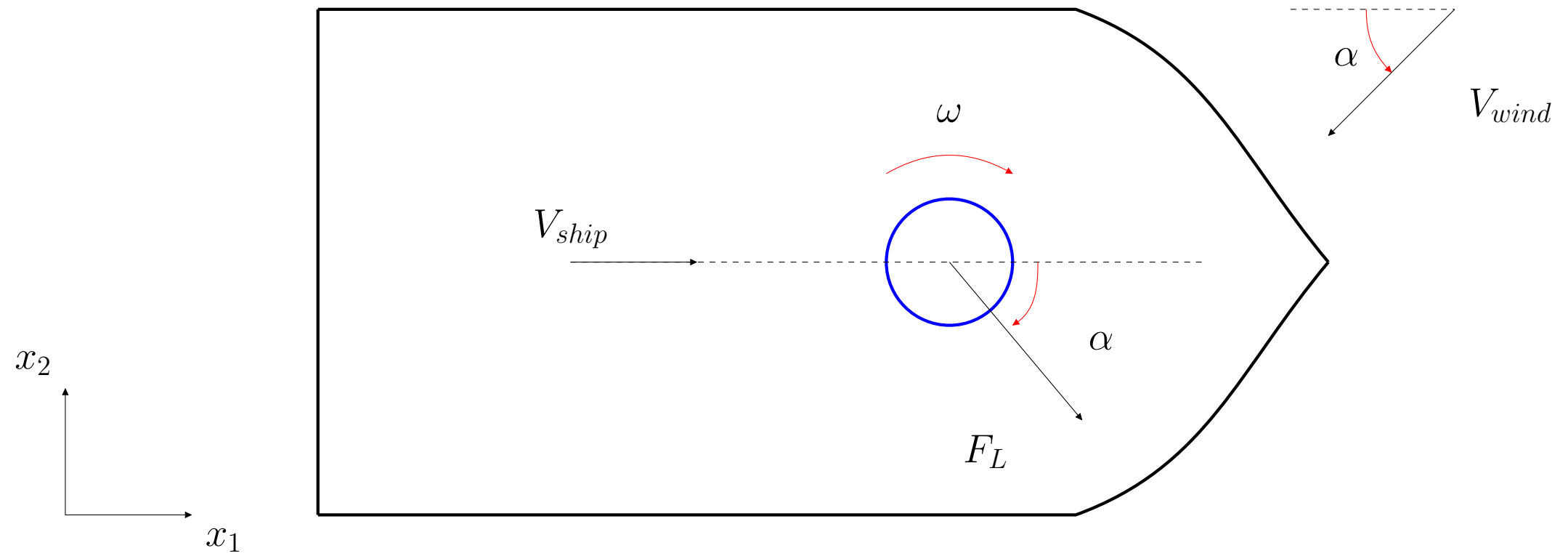


► Football: Free-kick



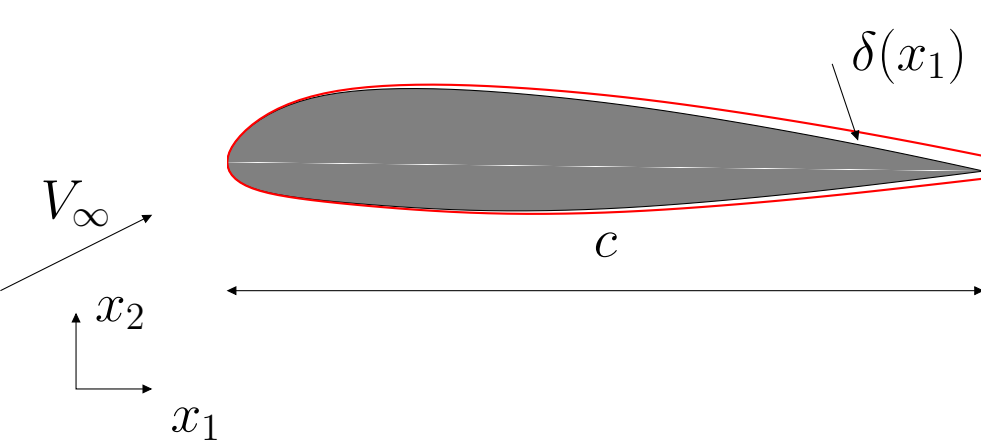
► Course [www page](#): "Effect of panel shape of soccer ball on its flight characteristics", rotation, ball trajectories for free-kicks in worldcup in football

► Flettner rotors: the Magnus effect  $\Rightarrow$  propulsion force of  $F_L \cos(\alpha)$

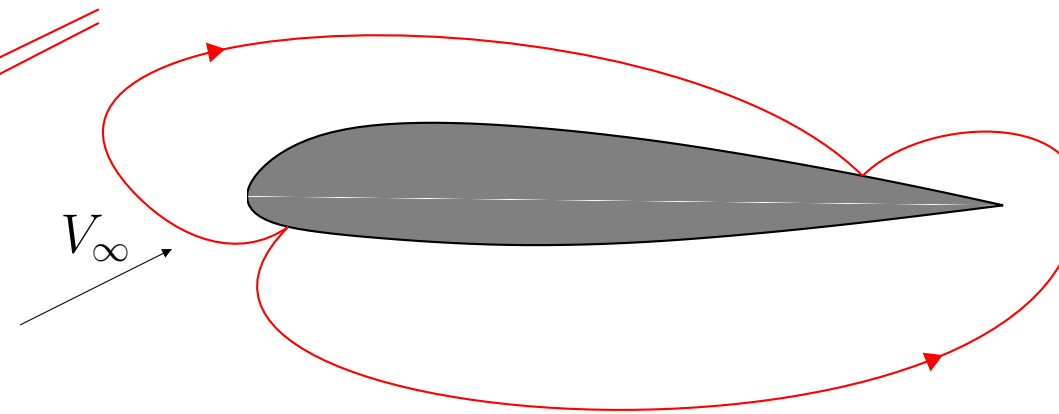


See Section 4.4.8, [The flow around an airfoil](#)

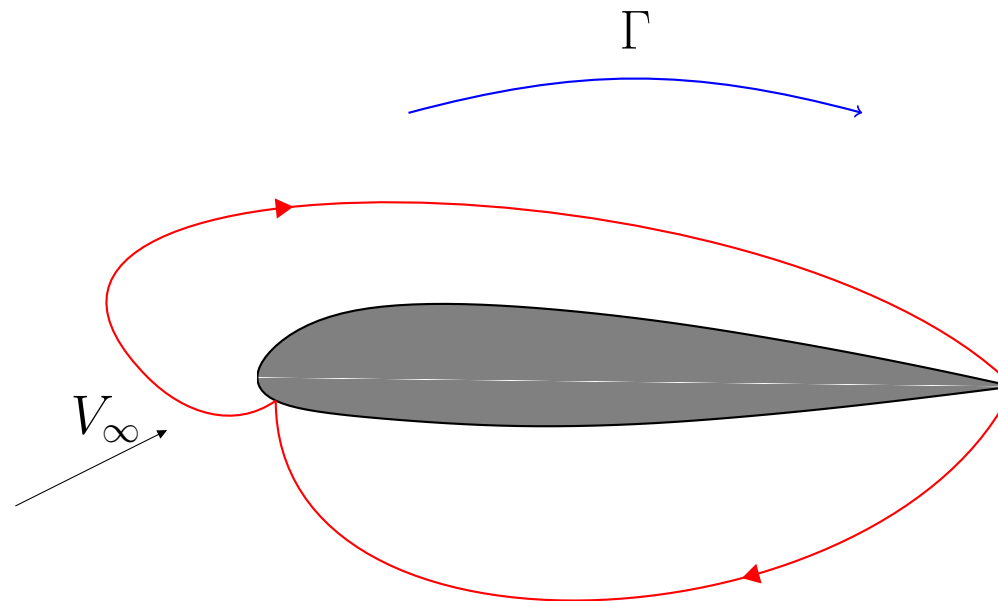
The boundary layers,  $\delta(x_1)$ , and the wake illustrated by the colored lines.



Real flow.



Unphysical rear stagnation point (suction side).

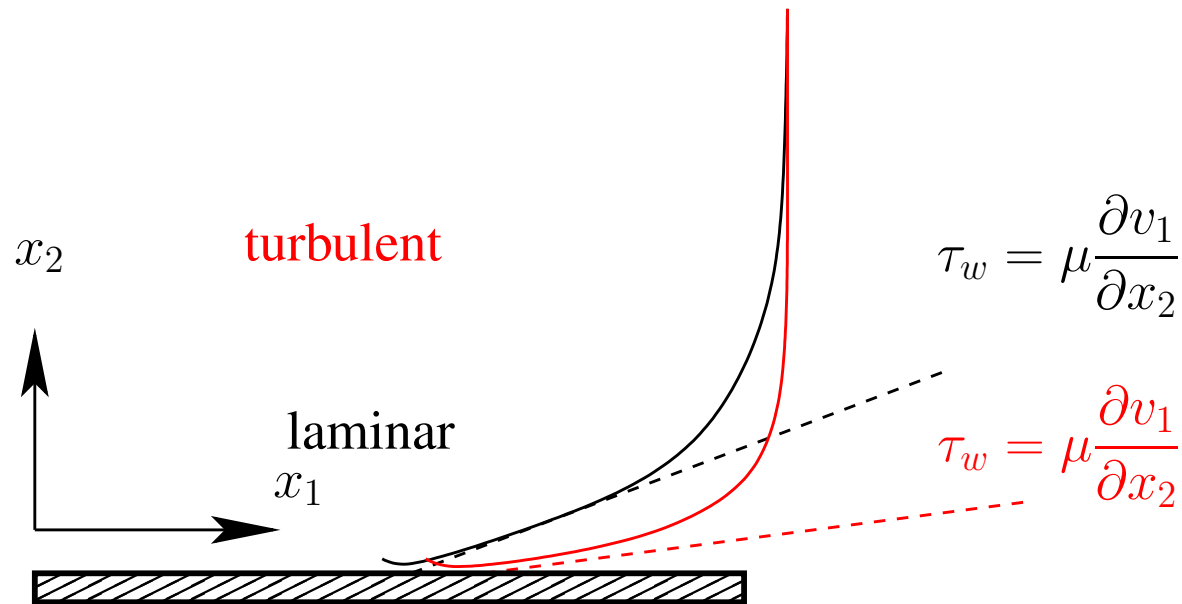


Potential flow, added  $\Gamma$ . Rear stagnation point at trailing edge. Lift force  $F_L = -\rho V_\infty \Gamma$

## Lecture 6

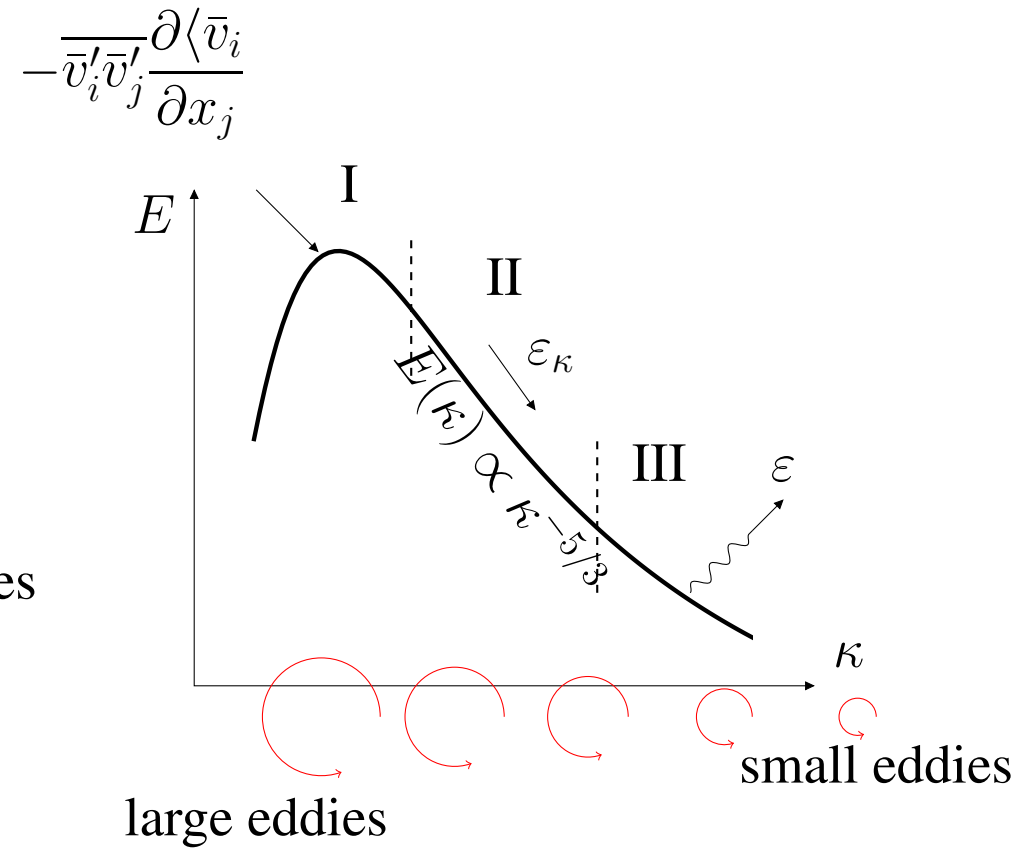
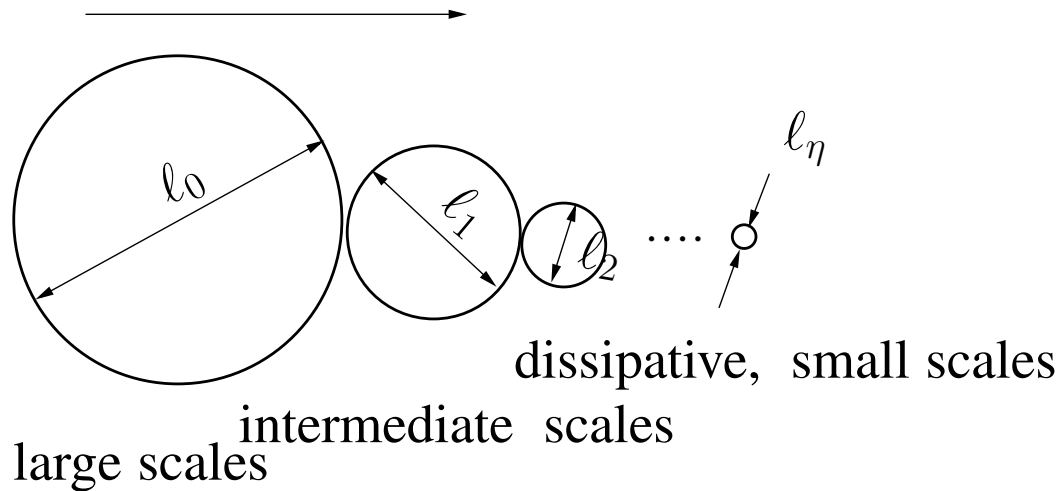
¶ See Section 5, Turbulence

- ▶  $v_i = \bar{v}_i + v'_i$ , is irregular and consists of eddies of different size
- ▶ increases diffusivity



- ▶ occurs at large Reynolds numbers. Pipes:  $Re_D = \frac{VD}{\nu} \simeq 2300$ ; boundary layers:  $Re_x = \frac{Vx}{\nu} \simeq 5E5$ .
- ▶ is three-dimensional
- ▶ is dissipative. Kinetic energy,  $v'_i v'_i / 2$ , in the small (dissipative) eddies  $\rightarrow$  thermal energy,  $\Delta T$
- ▶ Almost **all** flow are turbulent. Exceptions: blood flow in your veins.

transfer of kinetic energy per unit time =  $\varepsilon$



- ▶ Dissipation  $\varepsilon = \nu \overline{\frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}}$  ▶ All dissipation (say 90%) takes place at the small scales.
- ▶ This is called the cascade process

► Characterize the dissipation of kinetic energy at small scales in two relevant quantities:  $\varepsilon, \nu$

$$v_\eta = \nu^a \varepsilon^b$$
$$[m/s] = [m^2/s] [m^2/s^3]$$

$$[m] \quad 1 = 2a + 2b$$
$$[s] \quad -1 = -a - 3b$$

► This gives the Kolmogorov scales,  $a = b = 1/4$

$$v_\eta = (\nu\varepsilon)^{1/4}, \ell_\eta = \left(\frac{\nu^3}{\varepsilon}\right)^{1/4}, \tau_\eta = \left(\frac{\nu}{\varepsilon}\right)^{1/2}$$

► In a previous slide, we looked at energy spectra. It is based on Fourier series.

► Any periodic function,  $f$ , can be expressed as a Fourier series

$$f(x) = \frac{1}{2}a_0 + \sum_{n=1}^{\infty} (a_n \cos(\kappa_n x) + b_n \sin(\kappa_n x)), \quad f = v', \quad \kappa_n = \frac{n\pi}{L}$$

$$a_n = \frac{1}{L} \int_{-L}^L f(x) \cos(\kappa_n x) dx, \quad b_n = \frac{1}{L} \int_{-L}^L f(x) \sin(\kappa_n x) dx$$

► Parseval's formula states that the kinetic energy can be computed as

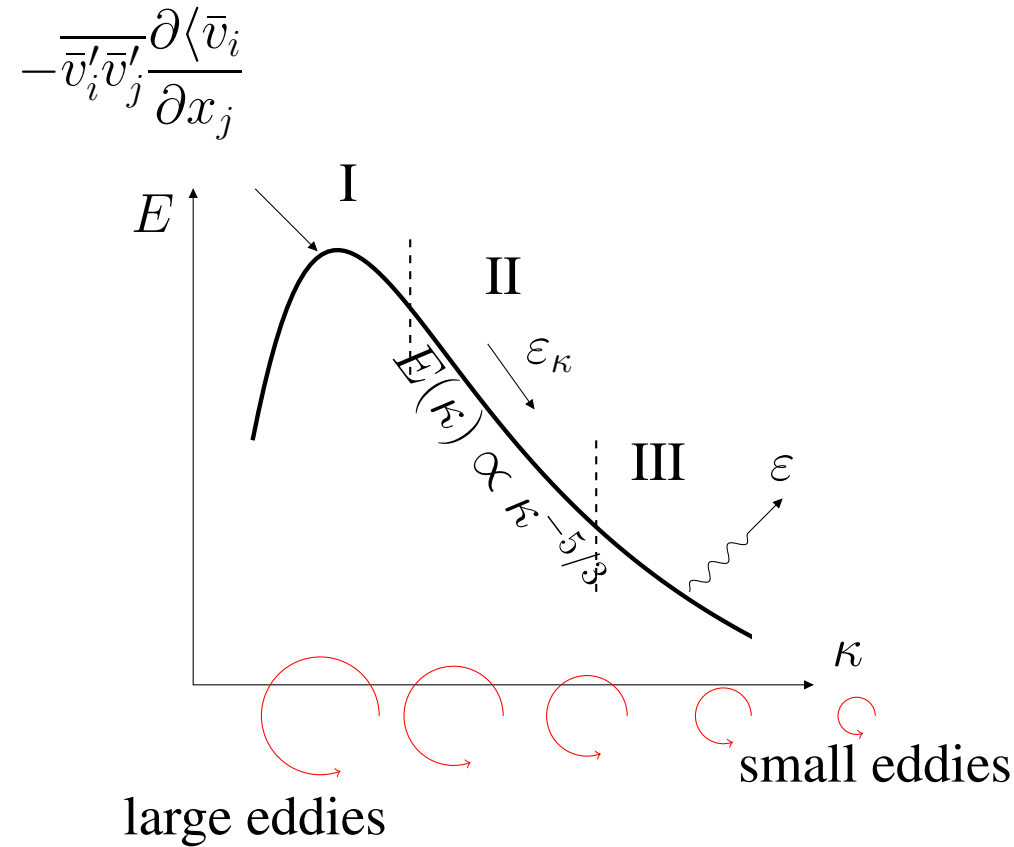
$$\int_{-L}^L v'^2(x) dx = \frac{L}{2} a_0^2 + L \sum_{n=1}^{\infty} (a_n^2 + b_n^2) \quad (35.1)$$

► Hence, you can compute the kinetic energy by:

- integrating in Fourier (wavenumber) space (right-hand side)
- or integrating in physical space over all fluctuations (left-hand side)



► Spectrum for turbulent kinetic energy,  $k$

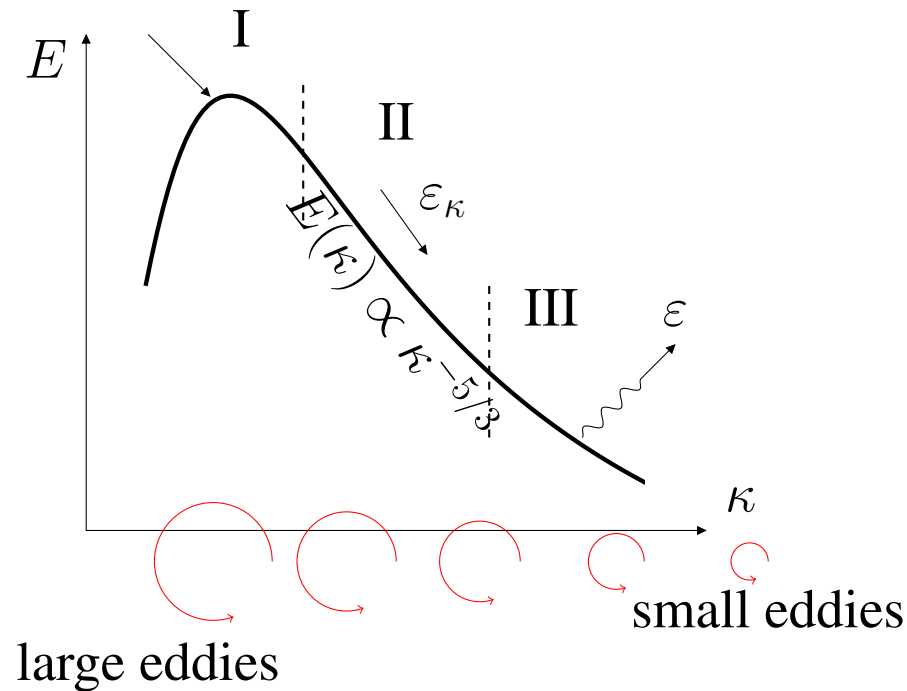


►  $E(\kappa_n) \propto a_n^2 + b_n^2$ , see the Fourier series on the previous slide ►

$$k = \int_0^\infty E(\kappa) d\kappa = \sum_0^\infty E(\kappa_n) \Delta\kappa_n \quad (35.2)$$

► which corresponds to Parseval's formula

$$-\overline{v'_i v'_j} \frac{\partial \langle \bar{v}_i \rangle}{\partial x_j}$$



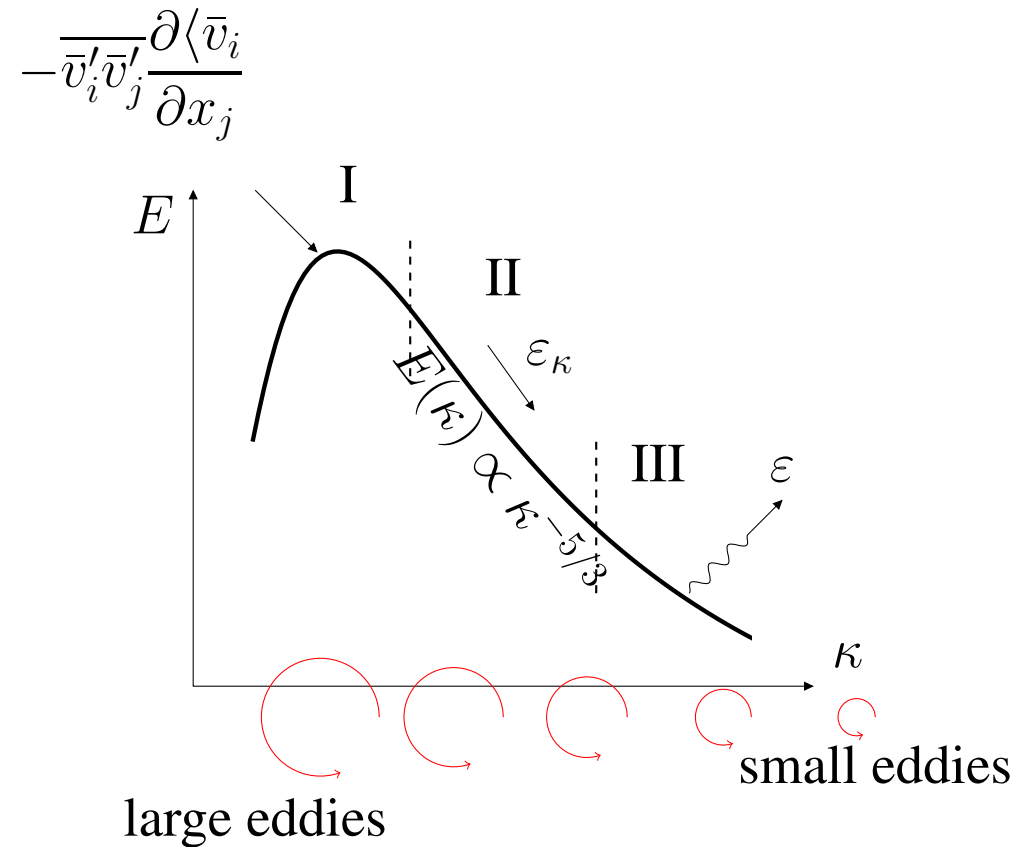
► The turbulence spectrum is divided into three regions:

**I.** Large eddies carry most of the turb. kinetic energy. They extract energy from the mean flow,  $P^k$ .

**II.** Inertial subrange. Independent of both large eddies (mean flow) and viscosity. Isotropic eddies.

**III.** Dissipation range. Isotropic eddies ( $\overline{v'_i v'_j} = c_1 \delta_{ij}$ ) described by the Kolmogorov scales.

► Turb. kinetic energy in Region II

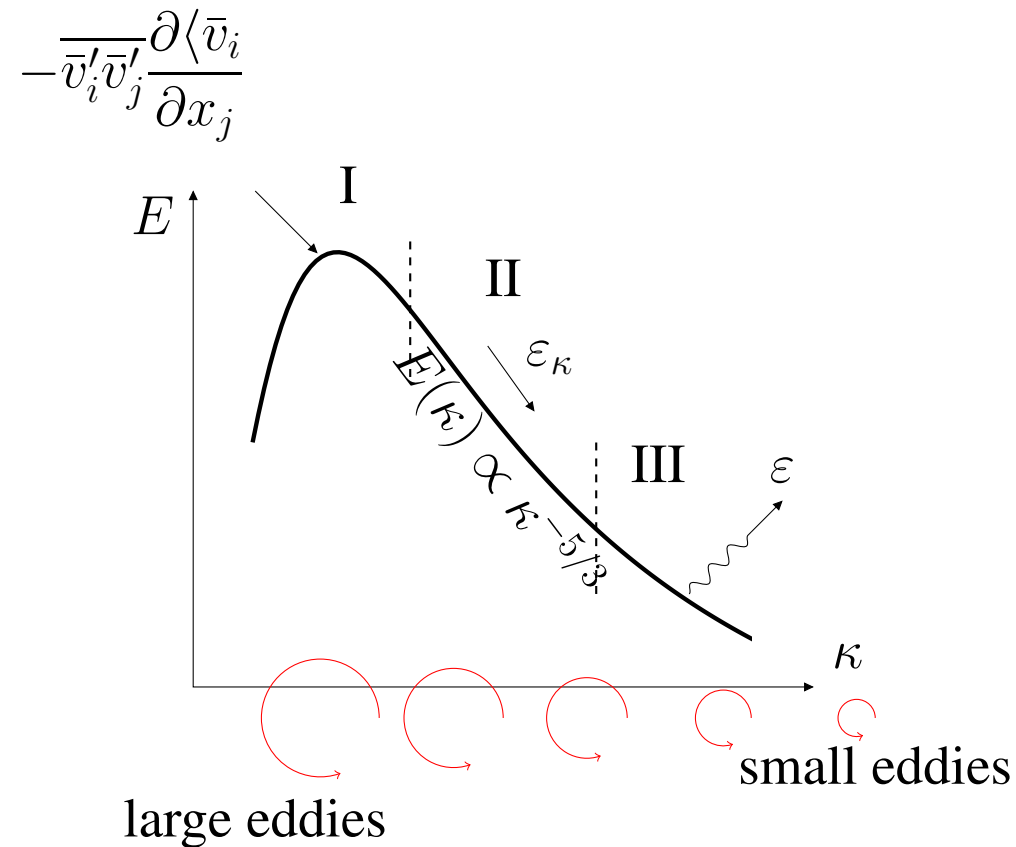


► Turb. kinetic energy in Region II depends on: ►  $\epsilon$  and ► eddy size  $1/\kappa$  Recall: ►  $k = \int_0^\infty E(\kappa) d\kappa$

$$\begin{array}{r}
 E = \kappa^a \quad \epsilon^b \\
 [m^3/s^2] = [1/m] \quad [m^2/s^3] \\
 [m] \quad 3 = -a + 2b \\
 [s] \quad -2 = -3b
 \end{array}$$

$b = 2/3, a = -5/3$  so that ►  $E(\kappa) = C_K \epsilon^{2/3} \kappa^{-5/3}$  ► This is **Kolmogorov spectrum law** or **-5/3 law**

► Turb. kinetic energy in Region III



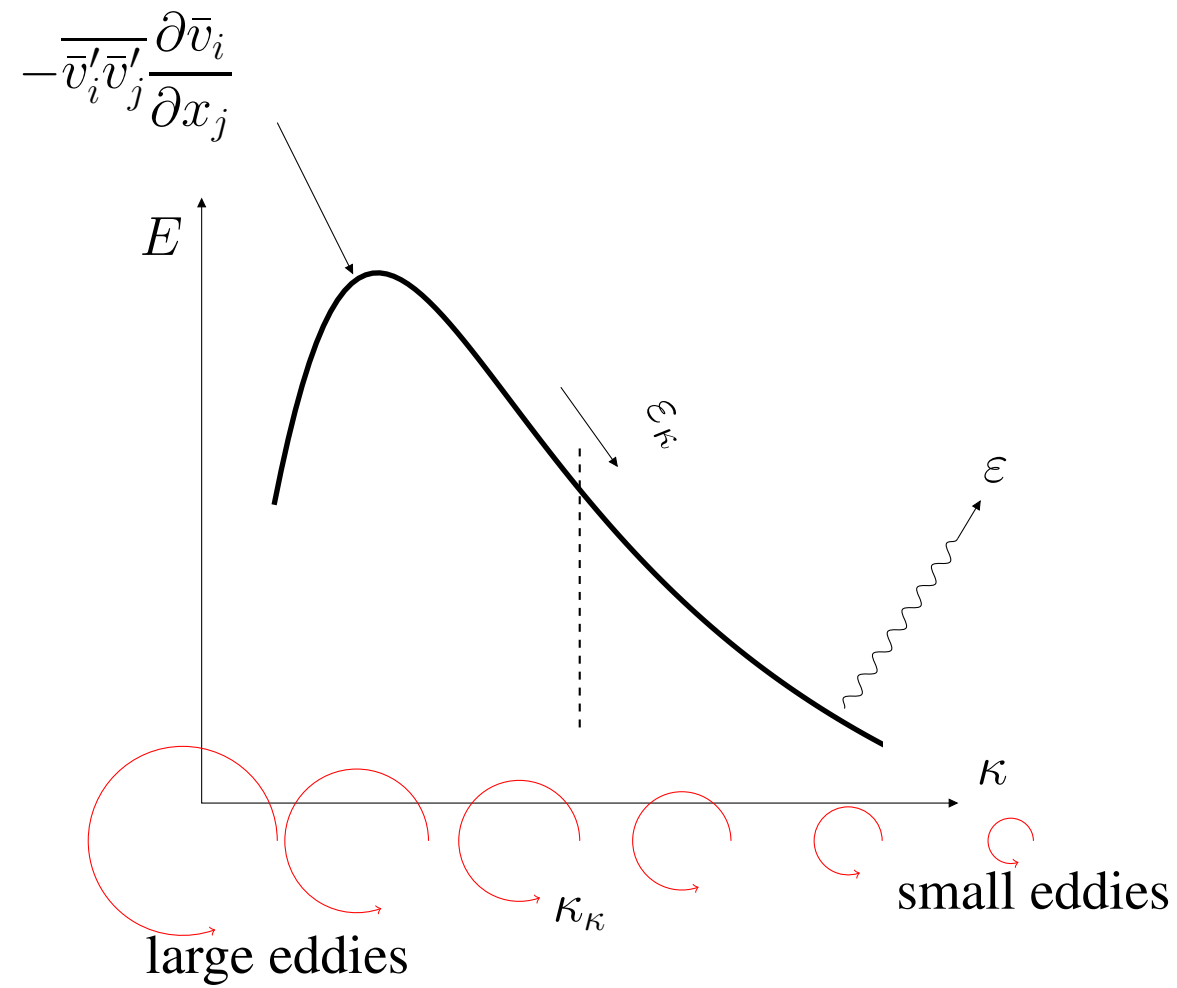
► Small-scale turbulence is isotropic (see Section 5.3):

$$\overline{v_1'^2} = \overline{v_2'^2} = \overline{v_3'^2}. \quad \text{Not true instantaneously, i.e. } v_1' \neq v_2' \neq v_3'.$$

**Isotropy:** if a coordinate direction is switched (i.e. rotated  $180^\circ$ ), nothing should change.  
 $\Rightarrow \overline{v_1'v_2'}$  in both coordinate directions must be the same.  $\Rightarrow \overline{v_1'v_2'} = (\overline{v_1'v_2'})_{180^\circ} = -\overline{v_1'v_2'} = 0$ .

► On tensor form:  $\overline{v_i'v_j'} = \text{const.} \delta_{ij}$

► Energy transfer from eddy-to-eddy,  $\kappa_n$



$$\epsilon_K \propto v_K^2 / t_K \propto v_K^2 / (\ell_K / v_K) \propto \frac{v_K^3}{\ell_K} \propto \frac{v_0^3}{l_0}$$

► Find relation between largest and smallest scales:  $Re = v_0 \ell_0 / \nu$ ,  $v_\eta = (\nu \varepsilon)^{1/4}$ ,  $\varepsilon = v_0^3 / \ell_0$

$$\frac{v_0}{v_\eta} = (\nu \varepsilon)^{-1/4} v_0 = (\nu v_0^3 / \ell_0)^{-1/4} v_0 = (v_0 \ell_0 / \nu)^{1/4} = Re^{1/4}$$

$$\frac{\ell_0}{\ell_\eta} = \left( \frac{\nu^3}{\varepsilon} \right)^{-1/4} \ell_0 = \left( \frac{\nu^3 \ell_0}{v_0^3} \right)^{-1/4} \ell_0 = \left( \frac{\nu^3}{v_0^3 \ell_0^3} \right)^{-1/4} = Re^{3/4}$$

$$\frac{\tau_o}{\tau_\eta} = \left( \frac{\nu \ell_0}{v_0^3} \right)^{-1/2} \tau_0 = \left( \frac{v_0^3}{\nu \ell_0} \right)^{1/2} \frac{\ell_0}{v_0} = \left( \frac{v_0 \ell_0}{\nu} \right)^{1/2} = Re^{1/2}$$

► We do a DNS (Direct Numerical Simulation) at a certain Reynolds number.

► Now if we double the Re number, how much finer must the grid be?

$$\underbrace{2^{3/4}}_{x_1 \text{ dir}} \times \underbrace{2^{3/4}}_{x_2 \text{ dir}} \times \underbrace{2^{3/4}}_{x_3 \text{ dir}} \times \underbrace{2^{1/2}}_{\text{time}} = 2^{11/4} \simeq 7$$

► Hence, doubling the Re number requires 7 times more computational effort

► This explains why DNS (Direct Numerical Simulation) is too expensive at high Re numbers.

## Lecture 7

¶ See Section 6, Turbulent mean flow

► The continuity and the Navier-Stokes for incompressible flow with constant  $\mu$  read

$$\frac{\partial v_i}{\partial x_i} = 0, \quad \rho \frac{\partial v_i}{\partial t} + \rho \frac{\partial v_i v_j}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \mu \frac{\partial^2 v_i}{\partial x_j \partial x_j}$$

► Decompose the variables and time average

$$\bar{v} = \frac{1}{2T} \int_{-T}^T v dt, \quad v_i = \bar{v}_i + v'_i, \quad \overline{v'} = 0, \quad p = \bar{p} + p'$$

$$\begin{aligned} \frac{\overline{\partial v_i + v'_i}}{\partial x_i} &= \frac{\partial \bar{v}_i}{\partial x_i} + \frac{\overline{\partial v'_i}}{\partial x_i} \stackrel{0}{=} \frac{\partial \bar{v}_i}{\partial x_i} \\ \frac{\overline{\partial v_i v_j}}{\partial x_j} &= \frac{\partial}{\partial x_j} \left\{ \overline{(\bar{v}_i + v'_i)(\bar{v}_j + v'_j)} \right\} = \frac{\partial}{\partial x_j} \left( \overline{\bar{v}_i \bar{v}_j + \bar{v}_i v'_j + \bar{v}_j v'_i + v'_i v'_j} \right) \\ &= \frac{\partial}{\partial x_j} \left( \overline{\bar{v}_i \bar{v}_j} + \overline{\bar{v}_i v'_j} \stackrel{0}{=} + \overline{\bar{v}_j v'_i} \stackrel{0}{=} + \overline{v'_i v'_j} \right) = \frac{\partial \bar{v}_i \bar{v}_j}{\partial x_j} + \frac{\overline{\partial v'_i v'_j}}{\partial x_j} \end{aligned}$$

► The steady RANS (Reynolds-Averaged Navier-Stokes) equations

$$\frac{\partial \bar{v}_i}{\partial x_i} = 0, \quad \rho \frac{\partial \bar{v}_i \bar{v}_j}{\partial x_j} = -\frac{\partial \bar{p}}{\partial x_i} + \frac{\partial}{\partial x_j} \left( \underbrace{\mu \frac{\partial \bar{v}_i}{\partial x_j} - \rho \overline{v'_i v'_j}}_{\tau_{ij,tot}} \right) \quad (36.1)$$

¶ See Section 6.1.1, [Boundary-layer approximation](#)

▶ RANS in developing boundary layer flow

$$\bar{v}_2 \ll \bar{v}_1, \quad \frac{\partial \bar{v}_1}{\partial x_1} \ll \frac{\partial \bar{v}_1}{\partial x_2}$$

$$\rho \bar{v}_1 \frac{\partial \bar{v}_1}{\partial x_1} + \rho \bar{v}_2 \frac{\partial \bar{v}_1}{\partial x_2} = -\frac{\partial \bar{p}}{\partial x_1} + \frac{\partial}{\partial x_2} \underbrace{\left[ \mu \frac{\partial \bar{v}_1}{\partial x_2} - \overline{\rho v'_1 v'_2} \right]}_{\tau_{tot}}$$

▶ Left side: each term include one large ( $\bar{v}_1$  and  $\partial/\partial x_2$ ) and one small ( $\bar{v}_2$  and  $\partial/\partial x_1$ ) part

¶ See Section 6.2, [Wall region in fully developed channel flow](#)

▶ RANS in fully developed channel flow

$$0 = \underbrace{-\frac{\partial \bar{p}}{\partial x_1}}_{f(x_1)} + \underbrace{\frac{\partial}{\partial x_2} \left( \mu \frac{\partial \bar{v}_1}{\partial x_2} - \overline{\rho v'_1 v'_2} \right)}_{g(x_2)} = -\frac{\partial \bar{p}}{\partial x_1} + \frac{\partial \tau_{tot}}{\partial x_2}$$

▶ Integration from  $x_2 = 0$  to  $x_2$  gives

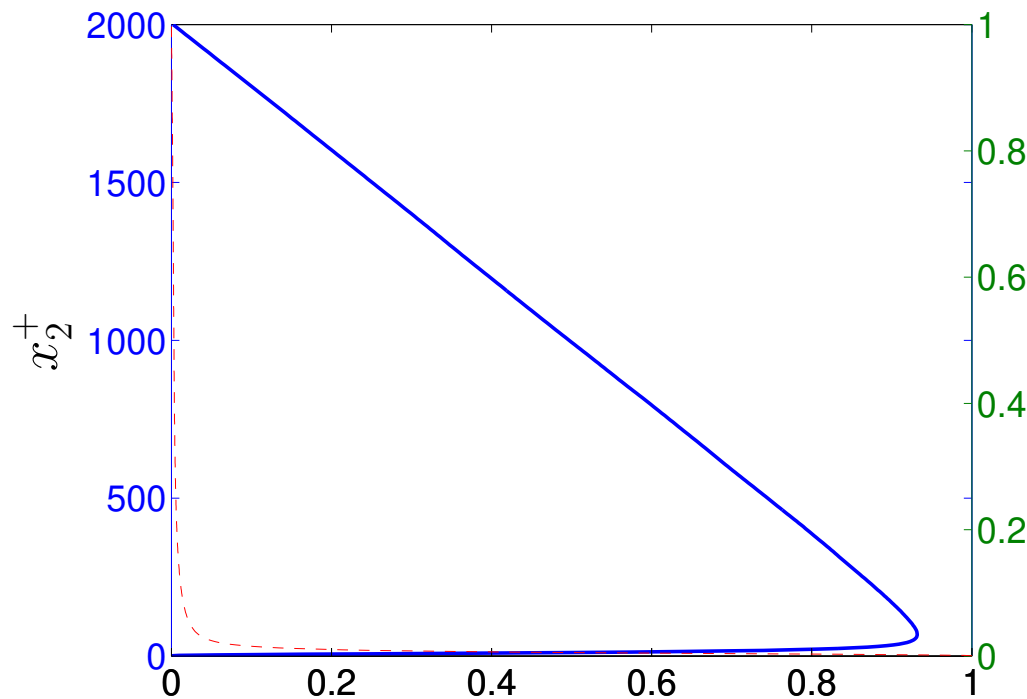
$$\tau_{tot}(x_2) - \tau_w = \frac{\partial \bar{p}}{\partial x_1} x_2 \quad \Rightarrow \quad \tau_{tot} = \tau_w + \frac{\partial \bar{p}}{\partial x_1} x_2 = \tau_w \left( 1 - \frac{x_2}{\delta} \right)$$

▶ Last equality:  $-\frac{\partial \bar{p}}{\partial x_1} = \frac{\tau_w}{\delta}$  (force balance)

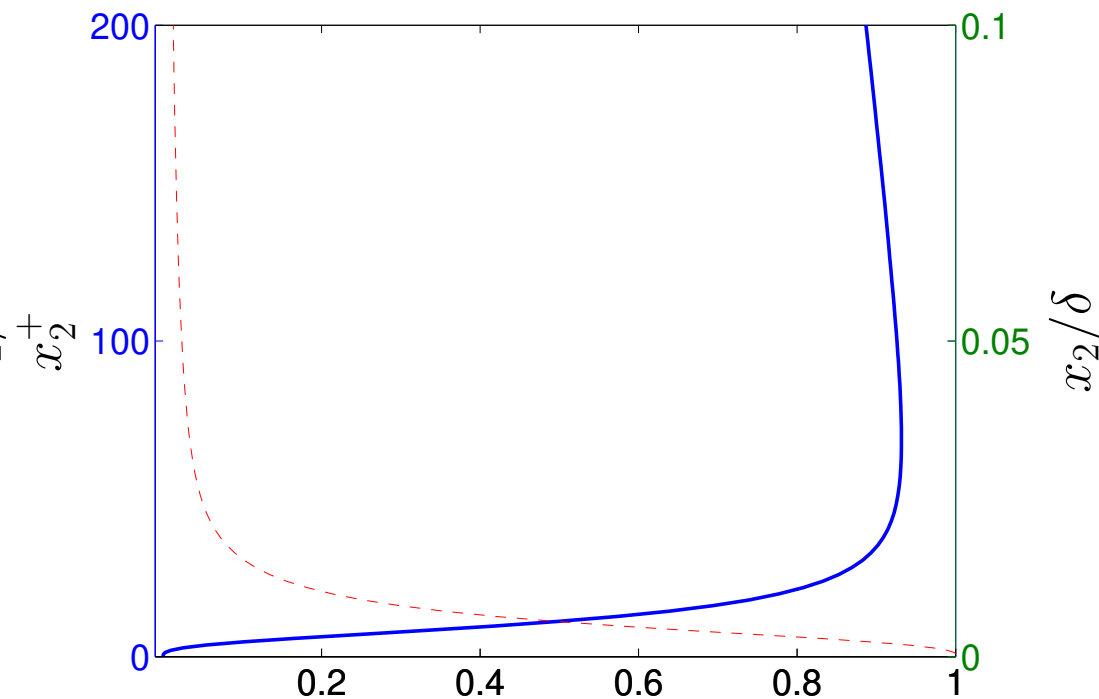


$$0 = -\frac{\partial \bar{p}}{\partial x_1} + \frac{\partial}{\partial x_2} \left( \mu \frac{\partial \bar{v}_1}{\partial x_2} - \overline{\rho v'_1 v'_2} \right)$$

► lower half of channel



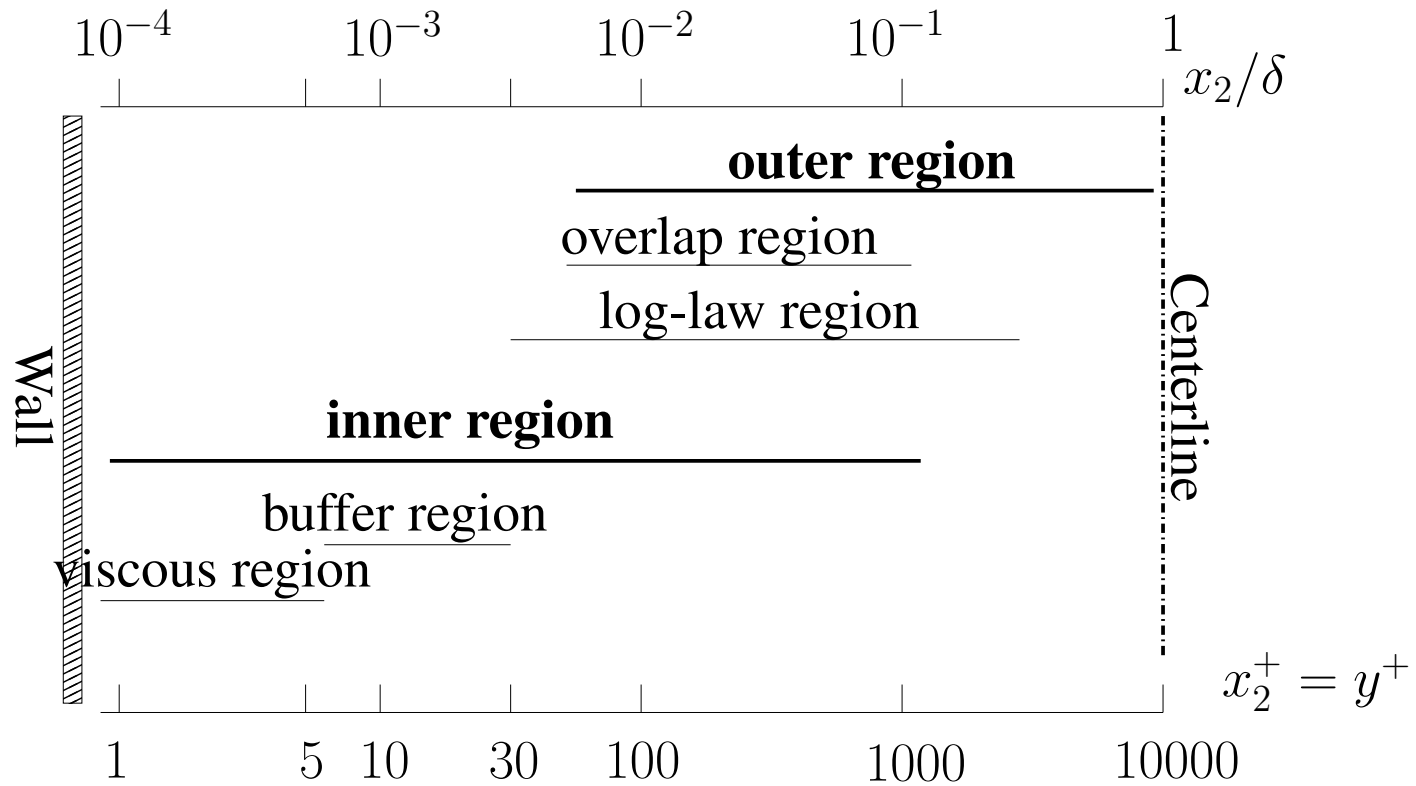
Full view



Zoom

—:  $-\overline{\rho v'_1 v'_2}/\tau_w$ ; - -:  $\mu(\partial \bar{v}_1/\partial x_2)/\tau_w$ .

► The different wall regions



► Wall shear stress

$$\tau_w = \mu \left. \frac{\partial \bar{v}_1}{\partial x_2} \right|_w \equiv \rho u_\tau^2 \Rightarrow u_\tau = \left( \frac{\tau_w}{\rho} \right)^{1/2}, \quad x_2^+ = \frac{x_2 u_\tau}{\nu}$$

► The linear velocity law

$$\left. \frac{\partial \bar{v}_1}{\partial x_2} \right|_w = \frac{\tau_w}{\mu} = \frac{\rho u_\tau^2}{\mu} = \frac{u_\tau^2}{\nu}$$

► Integration gives (recall that both  $\nu$  and  $u_\tau^2$  are constant)

$$\bar{v}_1 = \frac{1}{\nu} u_\tau^2 x_2 + C_1 = \frac{1}{\nu} u_\tau^2 x_2$$

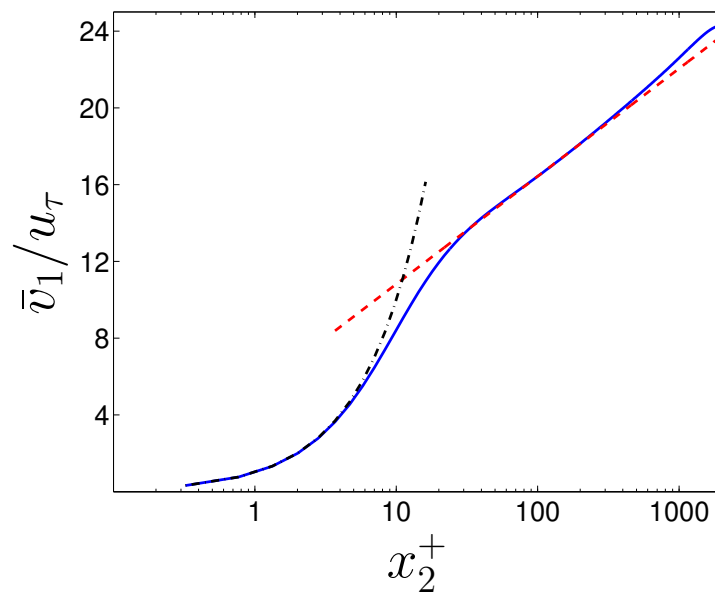
Divide by  $u_\tau$ :

$$\frac{\bar{v}_1}{u_\tau} = \frac{u_\tau x_2}{\nu} \quad \text{or} \quad \bar{v}_1^+ = x_2^+$$

► The log-law (turbulent region)

Velocity scale:  $u_\tau$ ; ► length scale:  $\ell \propto x_2 \Rightarrow \ell = \kappa x_2$

$$\begin{aligned} \frac{\partial \bar{v}_1}{\partial x_2} &= \frac{u_\tau}{\kappa x_2} \Rightarrow \frac{\partial \bar{v}_1 / u_\tau}{\partial x_2} = \frac{1}{\kappa x_2} \Rightarrow \frac{\partial \bar{v}_1 / u_\tau}{\partial (x_2 u_\tau / \nu)} = \frac{1}{\kappa (x_2 u_\tau / \nu)} \\ \Rightarrow \frac{\partial \bar{v}_1^+}{\partial x_2^+} &= \frac{1}{\kappa x_2^+} \quad \text{integrate:} \Rightarrow \bar{v}_1^+ = \frac{1}{\kappa} \ln x_2^+ + B \end{aligned}$$

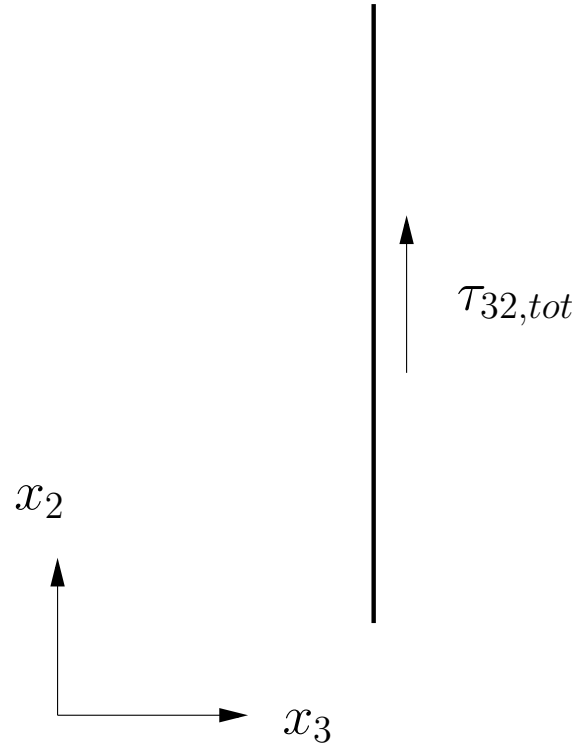


Velocity profile in fully developed channel flow.  $\bar{v}_1^+ = x_2^+$ ,  $\bar{v}_1^+ = \frac{1}{\kappa} \ln x_2^+ + B$ ,  $\kappa = 0.41$ ,  $B = 5.2$ .

- ▶ In CFD, you may want to put the first cell at  $x_2^+ \equiv \frac{x_2 u_\tau}{\nu} \simeq 1$ : how to find  $u_\tau$ ?
- ▶ N.B.  $\bar{v}_{1,centerline}/u_\tau = 24 \Rightarrow$  good estimate for  $u_\tau$  ( $\bar{v}_{1,centerline}/u_\tau$  increases weakly with Reynolds number)
- ▶ Example: channel flow (or boundary layer),  $x_2^+ \equiv \frac{x_2 u_\tau}{\nu} = 1$  gives
  - water:  $x_2 = \nu x_2^+ / u_\tau = 1 \cdot 10^{-6} \cdot 1/(1/24) = 2.4 \cdot 10^{-5} m = 2.4 \cdot 10^{-2} mm$
  - air:  $x_2 = \nu x_2^+ / u_\tau = 15 \cdot 10^{-6} \cdot 1/(1/24) = 3.6 \cdot 10^{-4} m = 3.6 \cdot 10^{-1} mm$
- ▶  $0.2\delta/x_2$  (at  $x_2^+ = 1$ ): estimate of ratio of largest to smallest turbulent length scales
- ▶ estimate of  $\varepsilon$ ?  $u_\tau^3/(0.2\delta)$

¶ See Section 6.3, Reynolds stresses in fully developed channel flow

► Symmetry plane or 2D: what value does  $\tau_{32,tot} = \tau_{32} - \overline{\rho v'_3 v'_2}$  take?

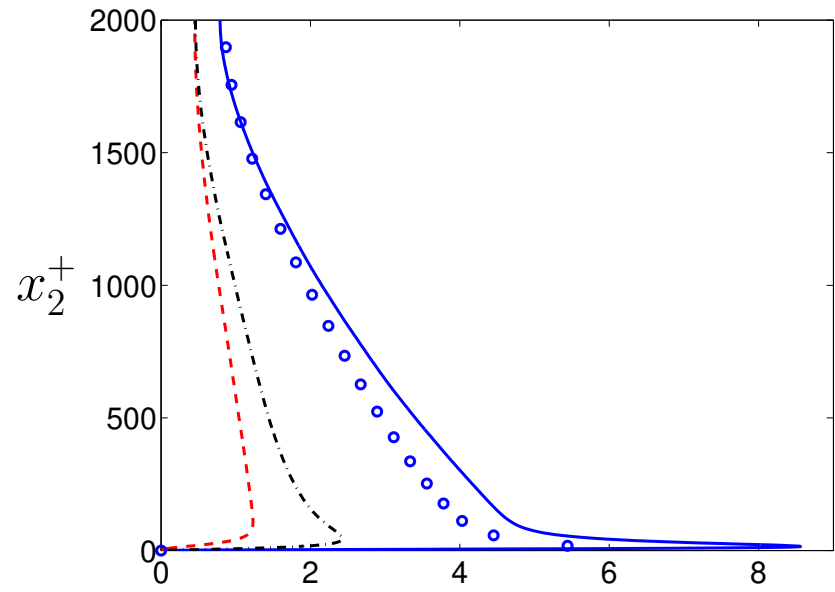


►  $\bar{v}_3 = \partial/\partial x_3 = 0$

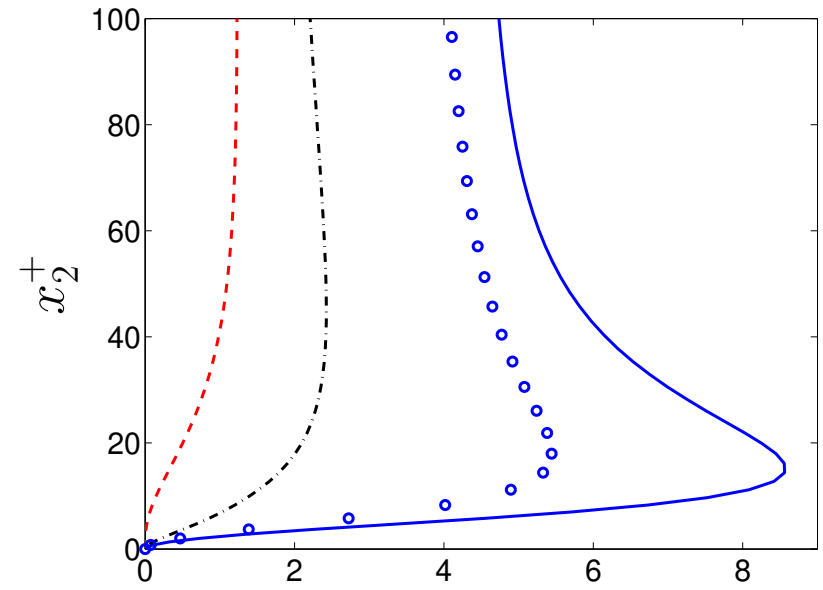
$$\tau_{32} = \mu \left( \frac{\partial \bar{v}_3}{\partial x_2} + \frac{\partial \bar{v}_2}{\partial x_3} \right) = 0, \quad \overline{\rho v'_3 v'_2} = -\mu_t \left( \frac{\partial \bar{v}_3}{\partial x_2} + \frac{\partial \bar{v}_2}{\partial x_3} \right) = 0$$

► note that  $\overline{v'_3 v'_3} \neq 0$

► Normal Reynolds stresses



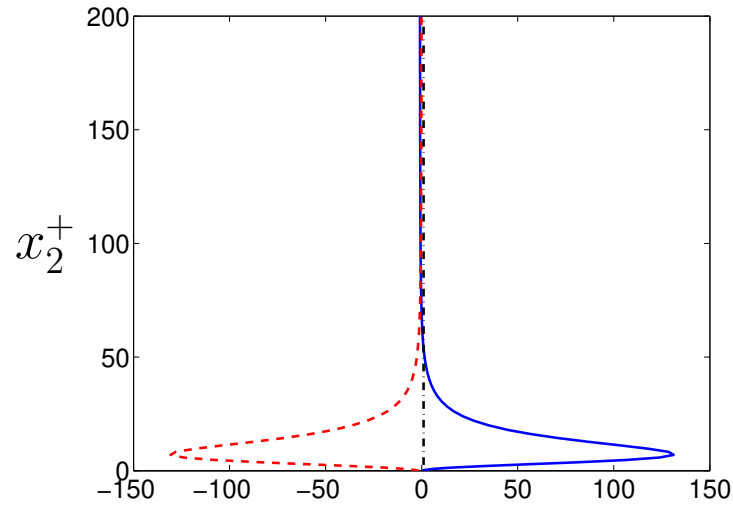
—:  $\overline{\rho v_1'^2}/\tau_w$ ; - -:  $\overline{\rho v_2'^2}/\tau_w$ ; - · -:  $\overline{\rho v_3'^2}/\tau_w$



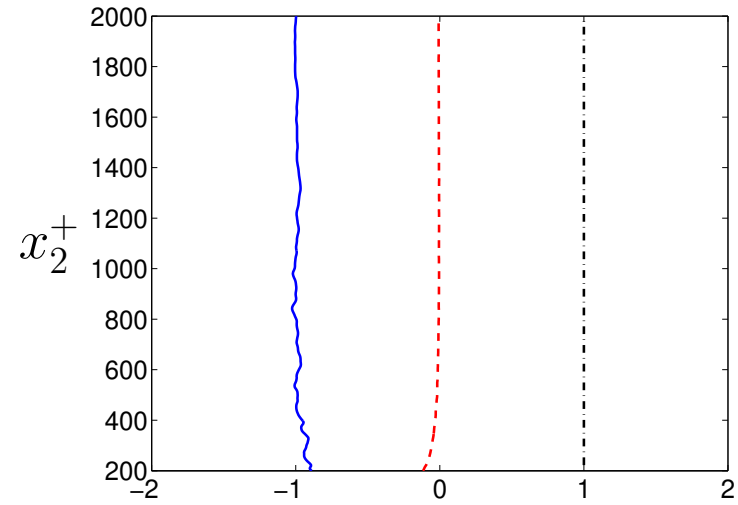
—:  $-\overline{\rho v_1' v_2'}/\tau_w$ ; - -:  $\mu(\partial \bar{v}_1/\partial x_2)/\tau_w$ .

► Forces on a fluid element

$$0 = -\frac{\partial \bar{p}}{\partial x_1} + \frac{\partial}{\partial x_2} \left( \mu \frac{\partial \bar{v}_1}{\partial x_2} - \overline{\rho v'_1 v'_2} \right)$$



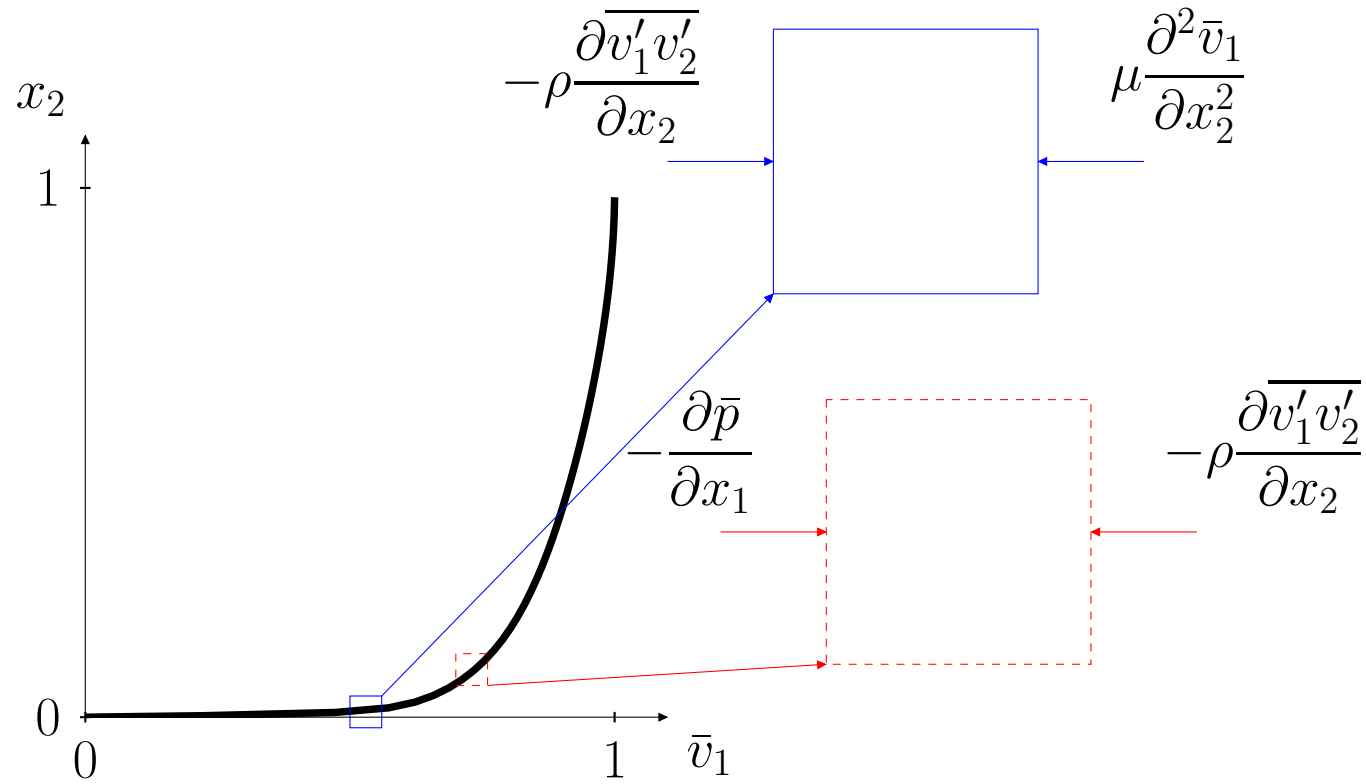
Near the wall



Far from the wall

Gradient of shear stresses. —:  $-\rho(\overline{\partial v'_1 v'_2} / \partial x_2) / \tau_w$ ; - - -:  $\mu(\partial^2 \bar{v}_1 / \partial x_2^2) / \tau_w$ ; - · - · -:  $-(\partial \bar{p} / \partial x_1) / \tau_w$ .

► Forces in a boundary layer. The dashed line and the solid line:  $x_2^+ \simeq 400$  and  $x_2^+ \simeq 20$ , respectively





## Lecture 8

¶ See Section 8.1, Rules for time averaging

▶ Time averaging

$$\bar{v} = \frac{1}{2T} \int_{-T}^T v dt, \quad \overline{v'} = 0 \quad (37.1)$$

▶ What is the difference between  $\overline{v'_1 v'_2}$  and  $\overline{v'_1} \overline{v'_2}$ ?

▶ Using 37.1 we get

$$\overline{v'_1 v'_2} = \frac{1}{2T} \int_{-T}^T v'_1 v'_2 dt$$

whereas

$$\overline{v'_1} \overline{v'_2} = \left( \frac{1}{2T} \int_{-T}^T v'_1 dt \right) \left( \frac{1}{2T} \int_{-T}^T v'_2 dt \right)$$

which is zero

► What is the difference between  $\overline{v_1'^2}$  and  $\overline{v_1'}^2$ ? Using 37.1 we get

$$\overline{v_1'^2} = \frac{1}{2T} \int_{-T}^T v_1'^2 dt$$

whereas

$$\overline{v_1'}^2 = \left( \frac{1}{2T} \int_{-T}^T v_1' dt \right)^2$$

which is zero

► Show that  $\overline{\bar{v}_1 v_1'^2} = \bar{v}_1 \overline{v_1'^2}$ . Using 37.1 we get

$$\overline{\bar{v}_1 v_1'^2} = \frac{1}{2T} \int_{-T}^T \bar{v}_1 v_1'^2 dt$$

and since  $\bar{v}$  does not depend on  $t$  we can take it out of the integral as

$$\bar{v}_1 \frac{1}{2T} \int_{-T}^T v_1'^2 dt = \bar{v}_1 \overline{v_1'^2}$$

► Show that  $\overline{\bar{v}_1} = \bar{v}_1$ . Using 37.1 we get

$$\overline{\bar{v}_1} = \frac{1}{2T} \int_{-T}^T \bar{v}_1 dt$$

and since  $\bar{v}$  does not depend on  $t$  we can take it out of the integral as

$$\bar{v}_1 \frac{1}{2T} \int_{-T}^T dt = \bar{v}_1 \frac{1}{2T} 2T = \bar{v}_1$$

► Show that  $\overline{\bar{v}_1 v'_1} = 0$ . Using 37.1 we get

$$\overline{\bar{v}_1 v'_1} = \frac{1}{2T} \int_{-T}^T \bar{v}_1 v'_1 dt = \bar{v}_1 \frac{1}{2T} \int_{-T}^T v'_1 dt = \bar{v}_1 \overline{v'_1} = 0$$

¶ See Section 11.6, The Boussinesq assumption

► The RANS equations read (see Eq. 36.1)

$$\frac{\partial \bar{v}_i \bar{v}_j}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \frac{\partial}{\partial x_j} \left( \nu \frac{\partial \bar{v}_i}{\partial x_j} - \overline{v'_i v'_j} \right)$$

► The last term, the Reynolds stress, is unknown. ► It must be modeled

► This is called the **closure problem** ► We need a **turbulence model**

► Write the diffusion term above without assuming constant viscosity

$$\frac{\partial}{\partial x_j} \left\{ \nu \left( \frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) - \overline{v'_i v'_j} \right\} \quad (37.2)$$

► We replace  $\overline{v'_i v'_j}$  by a turbulent viscosity,  $\nu_t$ :

$$\frac{\partial}{\partial x_j} \left\{ (\nu + \nu_t) \left( \frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) \right\} \quad (37.3)$$

► Identification of Eqs. 37.2 and 37.3 gives

$$-\overline{v'_i v'_j} = \nu_t \left( \frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) \quad (37.4)$$

$$-\overline{v'_i v'_j} = \nu_t \left( \frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) \quad (37.4)$$

This equation is not valid upon contraction.

$$\overline{v'_i v'_i} = -\nu_t \left( \frac{\partial \bar{v}_i}{\partial x_i} + \frac{\partial \bar{v}_i}{\partial x_i} \right)$$

▶ Left-side ( $= \overline{v'_i v'_i}$ ) and right side ( $= 0$ ) are different!

We modify Eq. 37.4 as

$$\overline{v'_i v'_j} = -\nu_t \left( \frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) + \frac{1}{3} \delta_{ij} \overline{v'_k v'_k} = -2\nu_t \bar{s}_{ij} + \frac{2}{3} \delta_{ij} k \quad (37.5)$$

▶ Contracted left side:  $\overline{v'_i v'_i} = 2k$     ▶ contracted right side:  $2\nu_t \bar{s}_{ii} + \frac{2}{3} \delta_{ii} k = 0 + \frac{2}{3} \cdot 3k = 2k$

▶  $\nu$ : different for different fluids (air, water, ...)

▶  $\nu_t$ : depends on the flow, i.e.  $\nu_t = \nu_t(x_i)$

▶ Now we need to model the turbulent viscosity in the Boussinesq assumption (Eq. 37.5).

▶ Recall the dimension of  $\nu$ : ▶  $m^2/s$

▶  $\nu_t$  estimated as a turbulent velocity fluctuation times a turbulent length scale

$$\nu_t \propto \mathcal{U}\mathcal{L}$$

▶ The velocity scale:  $k^{1/2}$  ▶ Dissipation (energy transfer eddy-to-eddy):  $\varepsilon \propto \mathcal{U}^3/\mathcal{L}$

⇒  $\mathcal{L} \propto k^{3/2}/\varepsilon$  ▶ We get

$$\nu_t = C_\mu \frac{k^2}{\varepsilon}, \quad C_\mu = 0.09. \quad (37.6)$$

¶ See Section 8.2, The Exact  $k$  Equation

▶  $k = \overline{v'_i v'_i} / 2$  appears in the expression for the turbulence viscosity.

▶ The first step is to derive the  $k$  equation. ▶ Take N-S for  $v'_i$ , multiply by  $v'_i$  and time average

$$\overline{v'_i \frac{\partial}{\partial x_j} [v_i v_j - \bar{v}_i \bar{v}_j]} = \underbrace{-\frac{1}{\rho} \overline{v'_i \frac{\partial}{\partial x_i} [p - \bar{p}]}}_{\text{IV}} + \underbrace{\nu \overline{v'_i \frac{\partial^2}{\partial x_j \partial x_j} [v_i - \bar{v}_i]}}_{\text{V}} + \underbrace{\overline{\frac{\partial v'_i v'_j}{\partial x_j} v'_i}}_{\text{VI}}$$

Using  $v_j = \bar{v}_j + v'_j$ , the left side can be rewritten as

$$\overline{v'_i \frac{\partial}{\partial x_j} [(\bar{v}_i + v'_i)(\bar{v}_j + v'_j) - \bar{v}_i \bar{v}_j]} = \overline{v'_i \frac{\partial}{\partial x_j} \left[ \underbrace{\bar{v}_i v'_j}_{\text{I}} + \underbrace{v'_i \bar{v}_j}_{\text{II}} + \underbrace{v'_i v'_j}_{\text{III}} \right]}$$

▶ Term I is rewritten as

$$\overline{v'_i \frac{\partial}{\partial x_j} (\bar{v}_i v'_j)} = \overline{v'_i v'_j \frac{\partial \bar{v}_i}{\partial x_j}} + \underbrace{\overline{\bar{v}_i v'_i \frac{\partial v'_j}{\partial x_j}}}_{\text{cont.eq.}} = \overline{v'_i v'_j \frac{\partial \bar{v}_i}{\partial x_j}}$$

▶ Term II

$$\overline{v'_i \frac{\partial}{\partial x_j} (v'_i \bar{v}_j)} = \overline{v'_i v'_i \frac{\partial \bar{v}_j}{\partial x_j}} + \overline{v'_i \bar{v}_j \frac{\partial v'_i}{\partial x_j}} \stackrel{\text{Trick 2}}{=} \bar{v}_j \frac{\partial}{\partial x_j} \left( \frac{\overline{v'_i v'_i}}{2} \right) = \bar{v}_j \frac{\partial k}{\partial x_j}$$

▶ Term III

$$\overline{v'_i \frac{\partial}{\partial x_j} (v'_i v'_j)} = \overline{v'_i v'_i \frac{\partial v'_j}{\partial x_j}} + \overline{v'_j v'_i \frac{\partial v'_i}{\partial x_j}} \stackrel{\text{Trick 2}}{=} \overline{v'_j \frac{\partial}{\partial x_j} \left( \frac{v'_i v'_i}{2} \right)} \stackrel{\text{Trick 1}}{=} \frac{\partial}{\partial x_j} \left( \frac{\overline{v'_j v'_i v'_i}}{2} \right) - \overline{v'_i v'_i \frac{\partial v'_j}{\partial x_j}}$$

$$\underbrace{\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j} + \bar{v}_j \frac{\partial k}{\partial x_j} + \frac{\partial}{\partial x_j} \left( \frac{\overline{v'_j v'_i v'_i}}{2} \right)}_{\text{I+II+III}} = \underbrace{-\frac{1}{\rho} \overline{v'_i} \frac{\partial}{\partial x_i} [p - \bar{p}]}_{\text{IV}} + \underbrace{\overline{\nu v'_i} \frac{\partial^2}{\partial x_j \partial x_j} [v_i - \bar{v}_i]}_{\text{V}} + \underbrace{\overline{\frac{\partial v'_i v'_j}{\partial x_j} v'_i}}_{\text{VI}} \quad (37.7)$$

► First term on the right side (Term IV)

$$-\frac{1}{\rho} \overline{v'_i} \frac{\partial p'}{\partial x_i} \stackrel{\text{Trick 1}}{=} -\frac{1}{\rho} \overline{\frac{\partial p' v'_i}{\partial x_i}} + \frac{1}{\rho} \overline{p' \frac{\partial v'_i}{\partial x_i}} \overset{0}{\cancel{}}$$

► Second term on the right side (Term V), omit  $\nu$

$$\overline{v'_i} \frac{\partial^2 v'_i}{\partial x_j \partial x_j} \stackrel{\text{Trick 1}}{=} \frac{\partial}{\partial x_j} \left( \overline{\frac{\partial v'_i}{\partial x_j} v'_i} \right) - \overline{\frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}} \stackrel{\text{Trick 2}}{=} \frac{\partial}{\partial x_j} \left( \frac{1}{2} \overline{\left( \frac{\partial v'_i v'_i}{\partial x_j} \right)} \right) - \overline{\frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}} = \frac{\partial^2 k}{\partial x_j \partial x_j} - \overline{\frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}}$$

► Third term on the right side (Term VI)

$$\overline{\frac{\partial v'_i v'_j}{\partial x_j} v'_i} = \overline{\frac{\partial v'_i v'_j}{\partial x_j} \bar{v}_i} = 0$$

► Insert Terms IV, V and VI in Eq. 37.7

$$\underbrace{\frac{\partial \bar{v}_j k}{\partial x_j}}_{\text{I}} = \underbrace{-\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j}}_{\text{II}} - \underbrace{\frac{\partial}{\partial x_j} \left[ \frac{1}{\rho} \overline{v'_j p'} + \frac{1}{2} \overline{v'_j v'_i v'_i} - \nu \frac{\partial k}{\partial x_j} \right]}_{\text{III}} - \underbrace{\nu \overline{\frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}}}_{\text{IV}} \quad (37.8)$$



$$\underbrace{\frac{\partial \bar{v}_j k}{\partial x_j}}_{\text{I}} = \underbrace{-\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j}}_{\text{II}} - \underbrace{\frac{\partial}{\partial x_j} \left[ \frac{1}{\rho} \overline{v'_j p'} + \frac{1}{2} \overline{v'_j v'_i v'_i} - \nu \frac{\partial k}{\partial x_j} \right]}_{\text{III}} - \underbrace{\nu \frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}}_{\text{IV}}$$

The terms have the following meaning.

**I. Convection.**

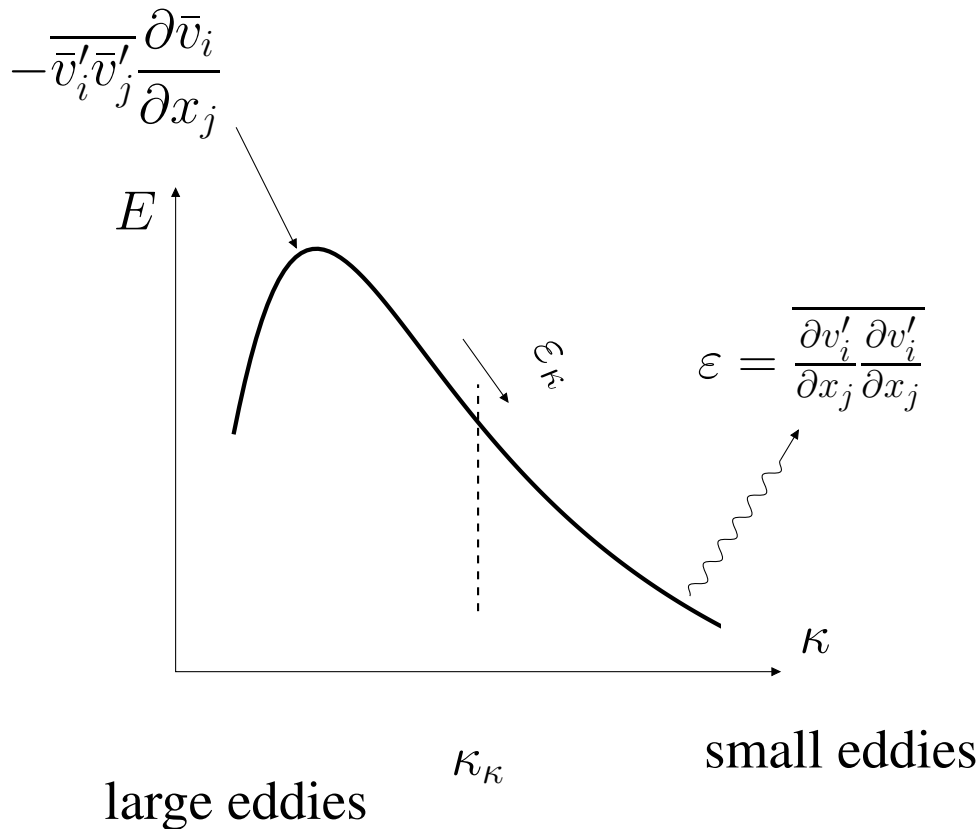
**II. Production,  $P^k$ .** The large turbulent scales extract energy from the mean flow. It is largest for small wavenumbers. It can be written as  $P^k = -\overline{v'_i v'_j} \bar{S}_{ij}$ . Hence only  $\bar{S}_{ij}$  creates turbulence, not  $\bar{\Omega}_{ij}$

**III.** The two first terms represent **turbulent diffusion** by pressure-velocity fluctuations, and velocity fluctuations, respectively. The last term is viscous diffusion.

**IV. Dissipation,  $\varepsilon$ .** It is largest for high wavenumbers

- The  $k$  equation in symbolic form:

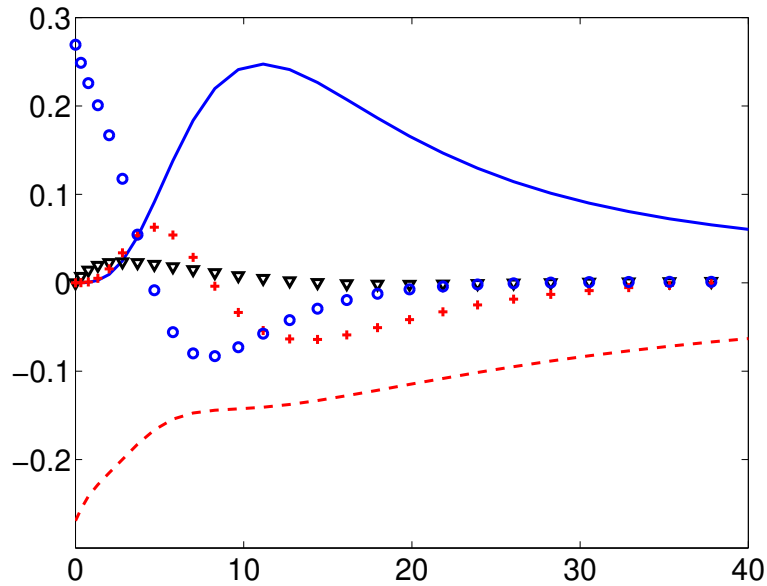
$$C^k = P^k + D^k - \varepsilon$$



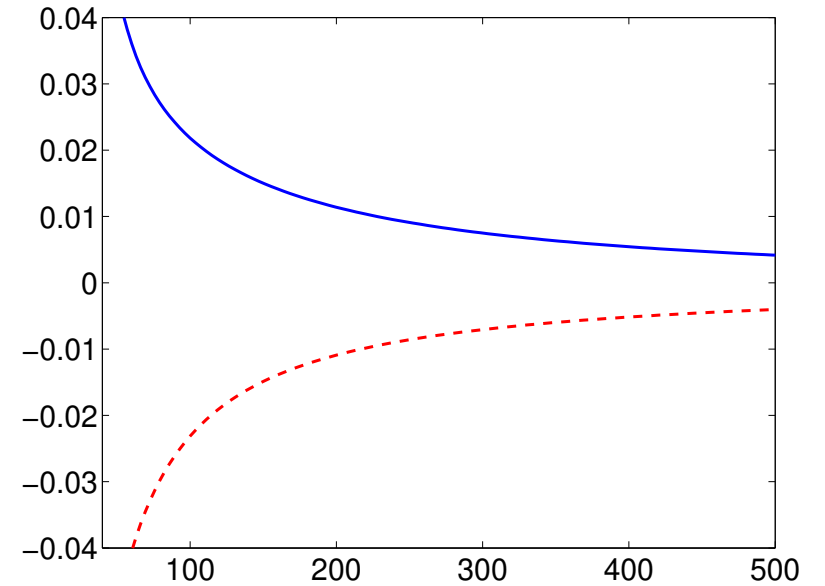
¶ See Section 8.3, The Exact  $k$  Equation: 2D Boundary Layers

► In 2D boundary-layer flow,  $\partial/\partial x_2 \gg \partial/\partial x_1$ ,  $\bar{v}_2 \ll \bar{v}_1$ , we get

$$\frac{\partial \bar{v}_1 k}{\partial x_1} + \frac{\partial \bar{v}_2 k}{\partial x_2} = -\overline{v'_1 v'_2} \frac{\partial \bar{v}_1}{\partial x_2} - \frac{\partial}{\partial x_2} \left[ \frac{1}{\rho} \overline{p' v'_2} + \frac{1}{2} \overline{v'_2 v'_i v'_i} - \nu \frac{\partial k}{\partial x_2} \right] - \nu \overline{\frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}}$$



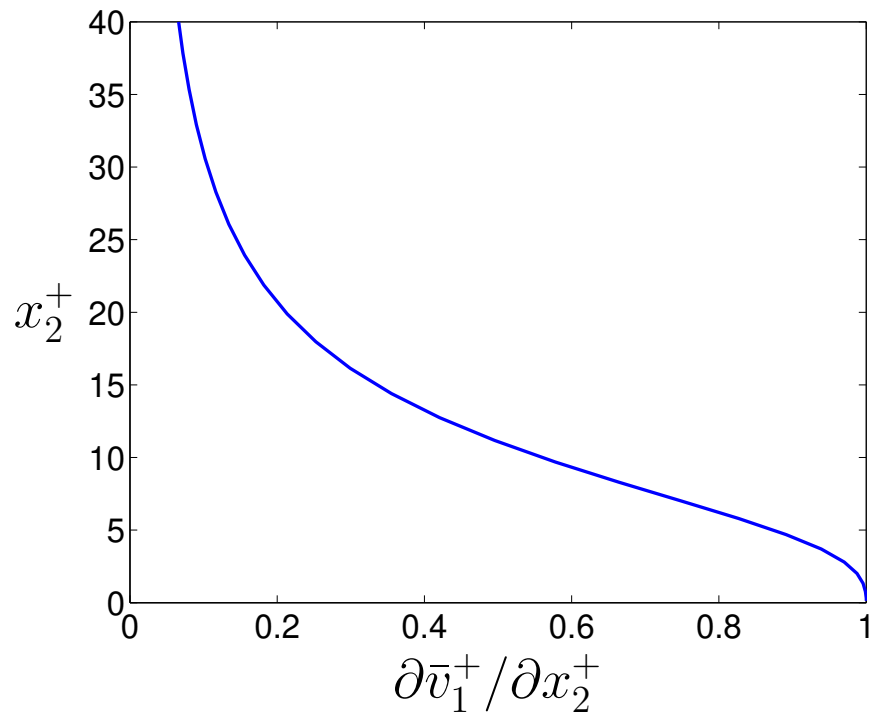
Zoom near the wall  $x_2^+$



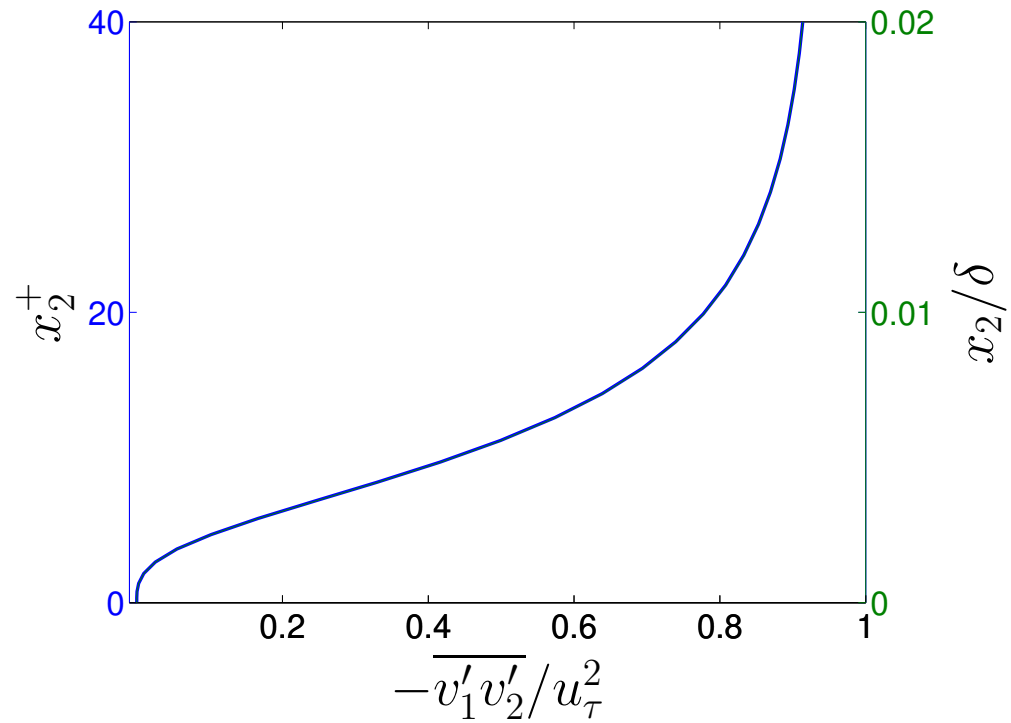
Outer region  $x_2^+$

—:  $P^k$ ; - -:  $-\varepsilon$ ;  $\nabla$ :  $-\overline{\partial v' p'}/\partial x_2$ ; +:  $-\overline{\partial v'_2 v'_i v'_i}/2/\partial x_2$ ; o:  $\nu \partial^2 k/\partial x_2^2$ .

Velocity gradient



Reynolds shear stress



The production term  $-\overline{v'_1 v'_2} \frac{\partial \bar{v}_1}{\partial x_2}$

## Lecture 9

¶ See Section 8.6, The transport equation for  $\bar{v}_i \bar{v}_i / 2$

► The main source term in  $k$  eq is  $P^k$ . ► Hence,  $k$  gets energy via  $P^k$ . ► From where?

► Answer: from  $K = \bar{v}_i \bar{v}_i / 2$ . ► Let's derive the transport eq. for  $K$ .

Multiply the RANS equations by  $\bar{v}_i$  so that

$$\underbrace{\bar{v}_i \left( \frac{\partial \bar{v}_i \bar{v}_j}{\partial x_j} \right)}_{\text{I}} = \bar{v}_i \left( \underbrace{-\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i}}_{\text{II}} + \nu \underbrace{\frac{\partial^2 \bar{v}_i}{\partial x_j \partial x_j}}_{\text{III}} - \underbrace{\frac{\partial \overline{v'_i v'_j}}{\partial x_j}}_{\text{IV}} \right)$$

Term I:

$$\bar{v}_i \frac{\partial \bar{v}_i \bar{v}_j}{\partial x_j} = \bar{v}_i \bar{v}_j \frac{\partial \bar{v}_i}{\partial x_j} + \cancel{\bar{v}_i \bar{v}_i \frac{\partial \bar{v}_j}{\partial x_j}}^0 \stackrel{\text{Trick 2}}{=} \frac{1}{2} \bar{v}_j \frac{\partial \bar{v}_i \bar{v}_i}{\partial x_j} = \frac{\partial \bar{v}_j K}{\partial x_j}$$

Term II:

$$-\bar{v}_i \frac{\partial \bar{p}}{\partial x_i} \quad \text{main source term in, for example, channel flow} \quad \left( -\bar{v}_1 \frac{\partial \bar{p}}{\partial x_1} > 0 \right)$$

Term III:

$$\nu \bar{v}_i \frac{\partial}{\partial x_j} \left( \frac{\partial \bar{v}_i}{\partial x_j} \right) \stackrel{\text{Trick 1}}{=} \nu \frac{\partial}{\partial x_j} \left( \underbrace{\bar{v}_i \frac{\partial \bar{v}_i}{\partial x_j}}_{\partial / \partial_j (\bar{v}_i \bar{v}_i / 2)} \right) - \nu \frac{\partial \bar{v}_i}{\partial x_j} \frac{\partial \bar{v}_i}{\partial x_j} \stackrel{\text{Trick 2}}{=} \nu \frac{\partial^2 K}{\partial x_j \partial x_j} - \nu \frac{\partial \bar{v}_i}{\partial x_j} \frac{\partial \bar{v}_i}{\partial x_j}$$

Term IV:

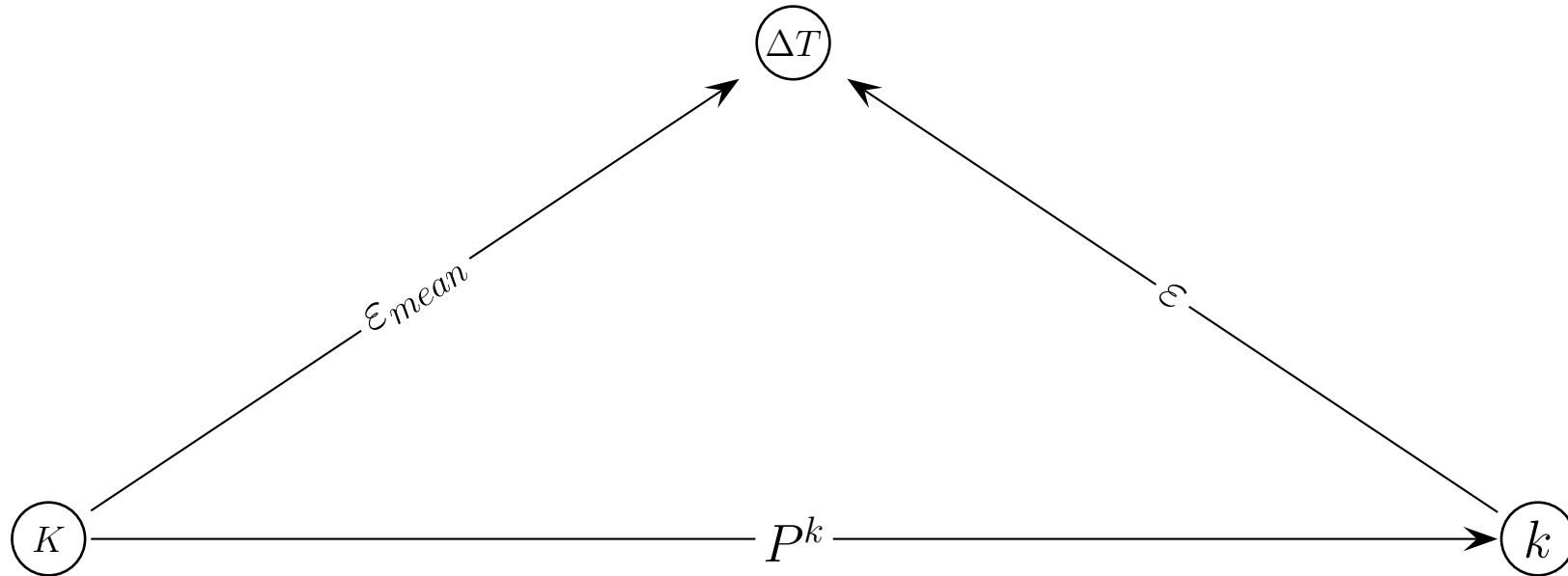
$$-\bar{v}_i \frac{\partial \overline{v'_i v'_j}}{\partial x_j} \stackrel{\text{Trick 1}}{=} -\frac{\partial \overline{\bar{v}_i v'_i v'_j}}{\partial x_j} + \overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j}.$$

►  $K = \frac{1}{2}\overline{v_i v_i}$  equation

$$\frac{\partial \bar{v}_j K}{\partial x_j} = \underbrace{\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j}}_{-P^k, \text{ sink}} \underbrace{- \frac{\bar{v}_i}{\rho} \frac{\partial \bar{p}}{\partial x_i}}_{\text{source}} - \frac{\partial}{\partial x_j} \left( \overline{v_i v'_i v'_j} - \nu \frac{\partial K}{\partial x_j} \right) \underbrace{- \nu \frac{\partial \bar{v}_i}{\partial x_j} \frac{\partial \bar{v}_i}{\partial x_j}}_{\varepsilon_{mean}, \text{ sink}}$$

►  $k = \frac{1}{2}\overline{v'_i v'_i}$  equation (see Eq. 37.8)

$$\frac{\partial \bar{v}_j k}{\partial x_j} = \underbrace{-\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j}}_{P^k, \text{ source}} - \frac{\partial}{\partial x_j} \left[ \frac{1}{\rho} \overline{v'_j p'} + \frac{1}{2} \overline{v'_j v'_i v'_i} - \nu \frac{\partial k}{\partial x_j} \right] \underbrace{- \nu \frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}}_{\varepsilon, \text{ sink}}$$



Transfer of energy between mean kinetic energy ( $K$ ), turbulent kinetic energy ( $k$ ) and internal energy (denoted as an increase in temperature,  $\Delta T$ ).  $K = \frac{1}{2}\overline{v_i v_i}$  and  $k = \frac{1}{2}\overline{v'_i v'_i}$ .

¶ See Section 11.7.1, Production terms

► The exact  $k$  eq. reads (see Eq. 37.8)

$$\frac{\partial \bar{v}_j k}{\partial x_j} = -\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j} - \frac{\partial}{\partial x_j} \left[ \frac{1}{\rho} \overline{v'_j p'} + \frac{1}{2} \overline{v'_j v'_i v'_i} - \nu \frac{\partial k}{\partial x_j} \right] - \nu \overline{\frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}} \quad (38.1)$$

► Production term needs to be modelled.

$$\begin{aligned} P^k &= -\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j} = \left[ \nu_t \left( \frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) - \frac{2}{3} \delta_{ij} k \right] \frac{\partial \bar{v}_i}{\partial x_j} = 2\nu_t \bar{s}_{ij} \frac{\partial \bar{v}_i}{\partial x_j} - \frac{2}{3} \delta_{ij} k \frac{\partial \bar{v}_i}{\partial x_j} \\ &= 2\nu_t \bar{s}_{ij} (\bar{s}_{ij} + \bar{\Omega}_{ij}) - k \frac{\partial \bar{v}_i}{\partial x_i} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} \end{aligned}$$

► Also the diffusion term needs to be modeled. Example: heat flux is modelled as

$$\overline{v'_i \theta'} = -\frac{\nu_t}{\sigma_t} \frac{\partial \bar{\theta}}{\partial x_i} \quad \blacktriangleright q_i = k \frac{\partial \bar{\theta}}{\partial x_i}$$

► The diffusion term in  $k$  eq, Eq. 38.1, is modelled as

$$\frac{1}{2} \overline{v'_j v'_i v'_i} = \overline{v'_j k'} = -\frac{\nu_t}{\sigma_k} \frac{\partial k}{\partial x_j} \Rightarrow -\frac{1}{2} \overline{\frac{\partial v'_j v'_i v'_i}{\partial x_j}} = \frac{\partial}{\partial x_j} \left( \frac{\nu_t}{\sigma_k} \frac{\partial k}{\partial x_j} \right)$$

¶ See Section 11.8, The  $k - \varepsilon$  model

► Modelled  $k$  equation

$$\frac{\partial k}{\partial t} + \bar{v}_j \frac{\partial k}{\partial x_j} = 2\nu_t \bar{s}_{ij} \bar{s}_{ij} + \frac{\partial}{\partial x_j} \left\{ \left( \nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right\} - \varepsilon \quad (38.2)$$

See Section 11.5, The  $\varepsilon$  equation

►  $\nu_t = C_\mu \frac{k^2}{\varepsilon} \Rightarrow$  We need an equation for  $\varepsilon$ : ► Look at  $k$  equation in symbolic form:

$$C^k = P^k + D^k - \varepsilon$$

►  $\varepsilon$  equation in symbolic form:

$$C^\varepsilon = P^\varepsilon + D^\varepsilon - \Psi^\varepsilon$$

► Use the source terms as in  $k$  eq, and add turbulent time-scale  $\varepsilon/k$  to get correct dimensions:

$$P^\varepsilon - \Psi^\varepsilon = \frac{\varepsilon}{k} (c_{\varepsilon 1} P^k - c_{\varepsilon 2} \varepsilon)$$

► The final form of the modelled  $\varepsilon$  equation

$$\frac{\partial \varepsilon}{\partial t} + \bar{v}_j \frac{\partial \varepsilon}{\partial x_j} = \frac{\varepsilon}{k} (c_{\varepsilon 1} P^k - c_{\varepsilon 2} \varepsilon) + \frac{\partial}{\partial x_j} \left[ \left( \nu + \frac{\nu_t}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_j} \right] \quad (38.3)$$





► Summary of the  $k - \varepsilon$  model.

- The Reynolds stress tensor,  $\overline{v'_i v'_j}$ , needs to be modeled, see Eq. 36.1
- We use the Boussinsq assumption, see Eq. 37.5, to replace the unknown  $\overline{v'_i v'_j}$  with the turbulent viscosity,  $\nu_t$  (a new unknown).
- We make a model for  $\nu_t = C_\mu \frac{k^2}{\varepsilon}$ , see Eq. 37.6, which includes  $k$  and  $\varepsilon$
- We formulate modeled equations for  $k$  (Eq. 38.2) and  $\varepsilon$  (Eq. 38.3)
- Now we have closed Eq. 36.1. The equations we need to solve are
  - The time-averaged continuity equation (Eq. 36.1)
  - Three time-averaged Navier-Stokes equations (Eq. 36.1)
  - Two equations for  $k$  (Eq. 38.2) and  $\varepsilon$  (Eq. 38.3)
  - The equation for turbulent viscosity,  $\nu_t = C_\mu k^2 / \varepsilon$  (Eq. 37.6)

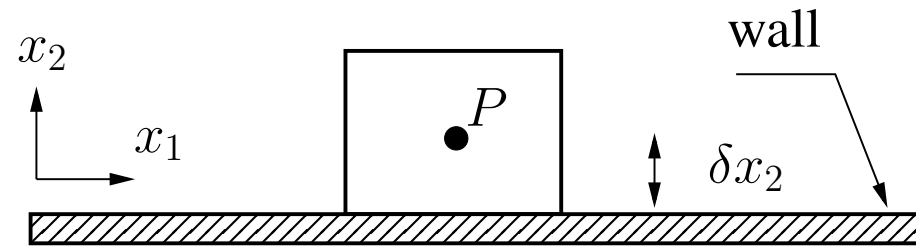
## Lecture 10

¶ See Section 11.14, Wall boundary conditions

► Two options for treating the wall boundary conditions.

- Coarse mesh near the walls. Assume that the logarithmic law applies. This is called **wall functions**
- Fine mesh. Modify the turbulence models to account for the viscous effects. This is called **Low-Reynolds number models**

See Section 11.14.1, Wall Functions



Wall-adjacent cell.

► We don't resolve the boundary layer. We **assume** that the velocity obeys the log-law at this location

► The log-law reads  $\frac{\bar{v}_1}{u_\tau} = \frac{1}{\kappa} \ln \left( \frac{u_\tau x_2}{\nu} \right) + B$

It is re-written as

$$\frac{\bar{v}_1}{u_\tau} = \frac{1}{\kappa} \ln \left( \frac{E u_\tau x_2}{\nu} \right), \quad E = 9.0, \quad B = \frac{1}{\kappa} \ln E$$

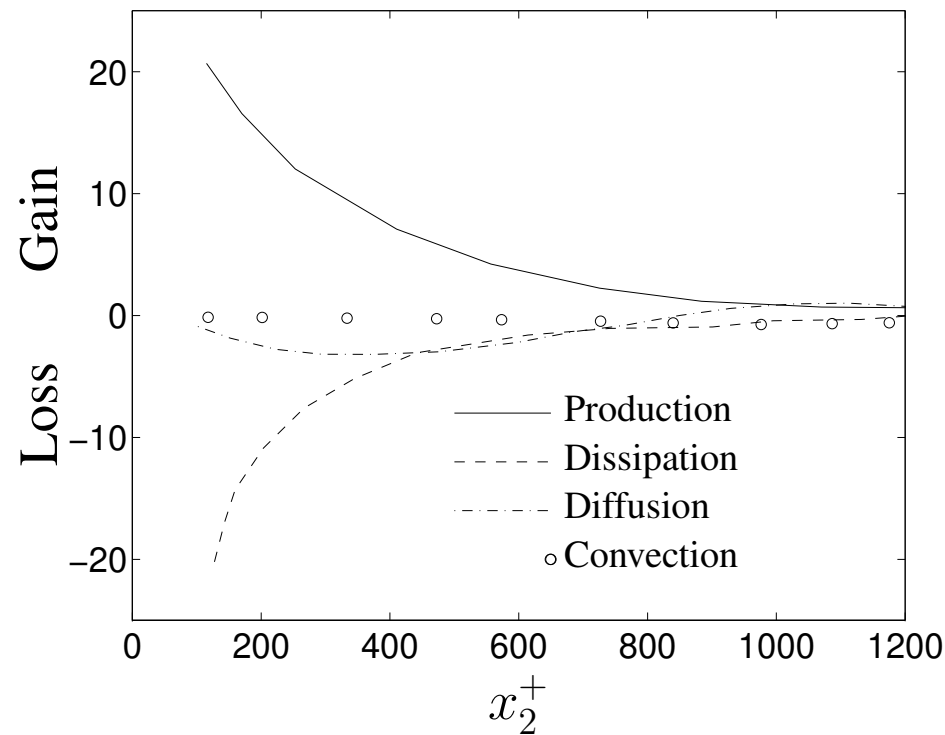
Friction velocity is computed as

$$u_\tau = \frac{\kappa \bar{v}_{1,P}}{\ln(E u_\tau \delta x_2 / \nu)}$$

► subscript  $P$  denotes the wall-adjacent cell    ► It is obtained by iteration.    ► Finally

$$\tau_w = \rho u_\tau^2 \quad \text{is used a force wall boundary condition.} \quad (39.1)$$

► B.c. for  $k$ .



Boundary along a flat plate. Energy balance in  $k$  equation.

► In the log-region, production and dissipation in the  $k$  eq. are large. The  $k$  eq. reads

$$0 = P^k - \rho\varepsilon = -\overline{\rho v_1' v_2'} \frac{\partial \bar{v}_1}{\partial x_2} - \rho\varepsilon \quad \Rightarrow \quad 0 = -\overline{v_1' v_2'} \frac{\partial \bar{v}_1}{\partial x_2} - \varepsilon \quad (39.2)$$

In the log-region

$$\frac{\tau_w}{\rho} = -\overline{v_1' v_2'} = \nu_t \frac{\partial \bar{v}_1}{\partial x_2} \quad \Rightarrow \quad \frac{\partial \bar{v}_1}{\partial x_2} = \frac{-\overline{v_1' v_2'}}{\nu_t} \quad (39.3)$$

Inserting Eq. 39.3 into Eq. 39.2 gives

$$0 = \frac{\overline{v_1' v_2'}^2}{\nu_t} - \varepsilon = \frac{u_\tau^4}{\nu_t} - \varepsilon \quad \text{with} \quad \nu_t = C_\mu k^2 / \varepsilon \quad \Rightarrow \quad k_P = C_\mu^{-1/2} u_\tau^2 \quad (39.4)$$

▶ B.c. for  $\varepsilon$ .

▶ Velocity gradient in the log-region: when deriving the log-law we assumed

$$\partial \bar{v}_1 / \partial x_2 \simeq u_\tau / (\kappa x_2)$$

▶ Shear stress in log-region  $-\overline{v'_1 v'_2} \simeq u_\tau^2$

▶ The production term reads  $P^k = -\overline{v'_1 v'_2} \frac{\partial \bar{v}_1}{\partial x_2} = \frac{u_\tau^3}{\kappa \delta x_2}$

Eq. 39.2 gives

$$\varepsilon_P = P^k = \frac{u_\tau^3}{\kappa \delta x_2}$$

▶ Note that both the  $k$  and  $\varepsilon$  b.c. are applied at the wall-adjacent cells in the **interior** domain.

▶ Hence, formally they are not b.c.

▶ The b.c. for the wall-parallel velocity is expressed as a wall shear stress

¶ See Section 11.14.2, [Low-Re Number Turbulence Models](#)

▶ In Low-Re number models we **resolve** the boundary layer, i.e. we use a refined grid near the wall.

▶ First (wall-adjacent) at  $x_2^+ < 1$  ▶ B.c.  $v_i = 0$ .

▶ The turbulence near the wall is not fully turbulent: ▶ the viscous effect is large.

⇒ We must modify the turbulence model.

▶ Analyze the turbulence near the wall. ▶ Taylor expansion of  $v'_i$  near the wall (also valid for  $\bar{v}_i$ ) gives

$$\begin{aligned}v'_1 &= a_0 + a_1 x_2 + a_2 x_2^2 + \dots \\v'_2 &= b_0 + b_1 x_2 + b_2 x_2^2 + \dots \\v'_3 &= c_0 + c_1 x_2 + c_2 x_2^2 + \dots\end{aligned}\tag{39.5}$$

▶ At the wall:  $v'_1 = v'_2 = v'_3 = 0$  which gives  $a_0 = b_0 = c_0$ .

▶ Furthermore  $\partial v'_1 / \partial x_1 = \partial v'_3 / \partial x_3 = 0$ : ▶ continuity eq. gives  $\partial v'_2 / \partial x_2 = 0 \Rightarrow b_1 = 0$ .

Equation 39.5 now reads

$$\begin{aligned}v'_1 &= a_1 x_2 + a_2 x_2^2 + \dots \\v'_2 &= \quad \quad \quad b_2 x_2^2 + \dots \\v'_3 &= c_1 x_2 + c_2 x_2^2 + \dots\end{aligned}\tag{39.6}$$

$$\begin{aligned}
v'_1 &= a_1 x_2 + a_2 x_2^2 + \dots \\
v'_2 &= \phantom{a_1 x_2} + b_2 x_2^2 + \dots \\
v'_3 &= c_1 x_2 + c_2 x_2^2 + \dots
\end{aligned} \tag{39.6}$$

► Using Eq. 39.6 we can write

$$\begin{aligned}
\overline{v_1'^2} &= \overline{a_1^2 x_2^2} + \dots &= \mathcal{O}(x_2^2) \\
\overline{v_2'^2} &= \overline{b_2^2 x_2^4} + \dots &= \mathcal{O}(x_2^4) \\
\overline{v_3'^2} &= \overline{c_1^2 x_2^2} + \dots &= \mathcal{O}(x_2^2) \\
\overline{v_1' v_2'} &= \overline{a_1 b_2 x_2^3} + \dots &= \mathcal{O}(x_2^3) \\
k &= \frac{1}{2} \overline{(a_1^2 + c_1^2) x_2^2} + \dots &= \mathcal{O}(x_2^2) \\
\partial \bar{v}_1 / \partial x_2 &= \overline{a_1} + \dots &= \mathcal{O}(x_2^0) \\
\partial v_1' / \partial x_2 &= a_1 + \dots &= \mathcal{O}(x_2^0) \\
\partial v_2' / \partial x_2 &= 2b_2 x_2 + \dots &= \mathcal{O}(x_2^1) \\
\partial v_3' / \partial x_2 &= c_1 + \dots &= \mathcal{O}(x_2^0) \\
\varepsilon &\propto \overline{\frac{\partial v_1'}{\partial x_2} \frac{\partial v_1'}{\partial x_2}} + \overline{\frac{\partial v_2'}{\partial x_2} \frac{\partial v_2'}{\partial x_2}} + \overline{\frac{\partial v_3'}{\partial x_2} \frac{\partial v_3'}{\partial x_2}} = \mathcal{O}(x_2^0) + \mathcal{O}(x_2^2) + \mathcal{O}(x_2^0) &= \mathcal{O}(x_2^0) \\
\nu_t &= C_\mu \frac{k^2}{\varepsilon} \propto \frac{\mathcal{O}(x_2^4)}{\mathcal{O}(x_2^0)} &= \mathcal{O}(x_2^4)
\end{aligned} \tag{39.7}$$



¶ See Section 11.14.3, Low-Re  $k - \varepsilon$  Models

► Now let's compare the exact and the modeled  $k$  equation near the wall

► The exact  $k$  equation (see Eq. 37.8)

$$\rho \bar{v}_1 \frac{\partial k}{\partial x_1} + \rho \bar{v}_2 \frac{\partial k}{\partial x_2} = \underbrace{-\overline{\rho v'_1 v'_2} \frac{\partial \bar{v}_1}{\partial x_2}}_{\mathcal{O}(x_2^3)} - \underbrace{\frac{\partial \overline{p' v'_2}}{\partial x_2}}_{\mathcal{O}(x_2^3)} - \underbrace{\frac{\partial}{\partial x_2} \left( \frac{1}{2} \overline{\rho v'_2 v'_i v'_i} \right)}_{\mathcal{O}(x_2^3)} + \underbrace{\mu \frac{\partial^2 k}{\partial x_2^2}}_{\mathcal{O}(x_2^0)} - \underbrace{\mu \frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}}_{\mathcal{O}(x_2^0)}$$

The modeled  $k$  equation (see Eq. 38.2)

$$\rho \bar{v}_1 \frac{\partial k}{\partial x_1} + \rho \bar{v}_2 \frac{\partial k}{\partial x_2} = \underbrace{\mu_t \left( \frac{\partial \bar{v}_1}{\partial x_2} \right)^2}_{\mathcal{O}(x_2^4)} + \underbrace{\frac{\partial}{\partial x_2} \left( \frac{\mu_t}{\sigma_k} \frac{\partial k}{\partial x_2} \right)}_{\mathcal{O}(x_2^4)} + \underbrace{\mu \frac{\partial^2 k}{\partial x_2^2}}_{\mathcal{O}(x_2^0)} - \underbrace{\rho \varepsilon}_{\mathcal{O}(x_2^0)}$$

► the exact and the modeled dissipation term behave in the same way

► this is not true for the production term and the turbulent diffusion term

► To make the modeled production term behave as  $\mathcal{O}(x_2^3)$ :

replace  $C_\mu$  with  $C_\mu f_\mu$  (damping function) where  $f_\mu \propto \mathcal{O}(x_2^{-1})$  e.g.  $f_\mu = 1/x_2^+$  or as in Assignment 2

►  $C_\mu \rightarrow C_\mu f_\mu$  also fixes the modeled turb. diffusion term

► Now we look at the modeled  $\varepsilon$  eq. (see Eq. 38.3)    ►  $C_\mu \rightarrow C_\mu f_\mu \Rightarrow \mu_t \propto \mathcal{O}(x_2^3)$

$$\underbrace{\rho \bar{v}_1 \frac{\partial \varepsilon}{\partial x_1}}_{\mathcal{O}(x_2^1)} + \underbrace{\rho \bar{v}_2 \frac{\partial \varepsilon}{\partial x_2}}_{\mathcal{O}(x_2^2)} = \underbrace{C_{\varepsilon 1} \frac{\varepsilon}{k} P^k}_{\mathcal{O}(x_2^1)} + \underbrace{\frac{\partial}{\partial x_2} \left( \frac{\mu_t}{\sigma_\varepsilon} \frac{\partial \varepsilon}{\partial x_2} \right)}_{\mathcal{O}(x_2^2)} + \underbrace{\mu \frac{\partial^2 \varepsilon}{\partial x_2^2}}_{\mathcal{O}(x_2^0)} - \underbrace{C_{\varepsilon 2} \rho \frac{\varepsilon^2}{k}}_{\mathcal{O}(x_2^{-2})}$$

► Modification of turbulent viscosity modifies both production and turbulent diffusion

► Terms that are non-zero when  $x_2 \rightarrow 0$ :    ► the viscous diffusion term and the destruction term.

► But they can't balance each other:    ► the first is  $\propto \mathcal{O}(x_2^0)$  and the second  $\propto \mathcal{O}(x_2^{-2})$ .

► We fix this by multiplying the destruction term by  $f_2 \propto \mathcal{O}(x_2^2)$

► Suitable form of  $f_2$ ?    ►  $f_2 = \min(x_2^{+2}, 1)$     ► better:  $f_2 = (1 - \exp(-x_2^+))^2$

Taylor expansion gives  $f_2 = \left( 1 - \underbrace{(1 - x_2^+ + x_2^{+2} \dots)}_{\exp(-x_2^+)} \right)^2 = (x_2^+ - x_2^{+2} \dots)^2$

$$= x_2^{+2} - 2x_2^{+3} + x_2^{+4} \dots = \mathcal{O}(x_2^2)$$

¶ See Section 11.14.5, Different ways of prescribing  $\varepsilon$  at or near the wall

► Boundary condition for  $k$  (since  $v'_i \rightarrow 0$  near the wall)

$$k = 0$$

The exact form of  $k$  equation for boundary layer flow

$$\bar{v}_1 \frac{\partial k}{\partial x_1} + \bar{v}_2 \frac{\partial k}{\partial x_2} = -\overline{v'_1 v'_2} \frac{\partial \bar{v}_1}{\partial x_2} - \frac{\partial}{\partial x_2} \left[ \frac{1}{\rho} \overline{p' v'_2} + \frac{1}{2} \overline{v'_2 v'_i v'_i} - \nu \frac{\partial k}{\partial x_2} \right] - \nu \overline{\frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}}$$

► Boundary condition for No I for  $\varepsilon$ : ► look at the  $k$  eq. near the wall.

► The only non-vanishing terms are

$$0 = \mu \frac{\partial^2 k}{\partial x_2^2} - \rho \varepsilon \quad \Rightarrow \quad \varepsilon_{wall} = \nu \frac{\partial^2 k}{\partial x_2^2} \quad (39.8)$$

► Eq. 39.8 can be used as boundary conditions of  $\varepsilon$ . Not good. It includes a 2nd derivative of  $k$

► Let's try something else. ► Exact form of the  $\varepsilon$  term near wall (see Eq. 39.7):

$$\varepsilon = \nu \left\{ \overline{\left( \frac{\partial v'_1}{\partial x_2} \right)^2 + \left( \frac{\partial v'_2}{\partial x_2} \right)^2 + \left( \frac{\partial v'_3}{\partial x_2} \right)^2} \right\} = \nu \left\{ \overline{\left( \frac{\partial v'_1}{\partial x_2} \right)^2 + \left( \frac{\partial v'_3}{\partial x_2} \right)^2} \right\}$$

where we have assumed:  $\partial/\partial x_2 \gg \partial/\partial x_1 \simeq \partial/\partial x_3$  and  $\partial v'_1/\partial x_2 \simeq \partial v'_3/\partial x_2 \gg \partial v'_2/\partial x_2$ .

$$\varepsilon = \nu \left\{ \left( \frac{\partial v'_1}{\partial x_2} \right)^2 + \left( \frac{\partial v'_3}{\partial x_2} \right)^2 \right\}$$

► Taylor expansion gives (see Eq. 39.7)

$$\varepsilon = \nu \left( \overline{a_1^2} + \overline{c_1^2} \right) + \dots \quad (39.9)$$

The turbulent kinetic energy (see Eq. 39.7)

$$k = \frac{1}{2} \left( \overline{a_1^2} + \overline{c_1^2} \right) x_2^2 + \dots \quad (39.10)$$

so that

$$\left( \frac{\partial \sqrt{k}}{\partial x_2} \right)^2 = \frac{1}{2} \left( \overline{a_1^2} + \overline{c_1^2} \right) + \dots \quad (39.11)$$

Eqs. 39.9 and 39.11 gives

$$\varepsilon_{wall} = 2\nu \left( \frac{\partial \sqrt{k}}{\partial x_2} \right)^2 .$$

► This is b.c. No II for  $\varepsilon$  It also includes a derivative of  $k$ . Not so good ...

$$\varepsilon = \nu \left( \overline{a_1^2} + \overline{c_1^2} \right) + \dots \quad (39.9)$$

$$k = \frac{1}{2} \left( \overline{a_1^2} + \overline{c_1^2} \right) x_2^2 + \dots \quad (39.10)$$

► Often the following boundary condition is used

$$\varepsilon_{wall} = \left( \frac{2\nu k}{x_2^2} \right) \quad (39.12)$$

Comparing Eqs. 39.10 and 39.12 we see that Eq. 39.12 is satisfied.

► This is b.c. No III for  $\varepsilon$

- **Summary of the low-Re number model.**

- Fine mesh near the wall. The first cell center is located at  $x_2^+ \lesssim 1$ .
- This means that standard wall b.c. can be used, i.e.  $\bar{v}_1 = \bar{v}_2 = \bar{v}_3 = k = 0$ .
- There are three different (I-III) options for the wall b.c. for  $\varepsilon$ :  
usually  $\varepsilon_P = 2\nu k_P / (x_2^2)$  is used for the wall-adjacent cells

- **Summary of wall-functions.**

- Coarse mesh near the wall. The first cell center is located at  $30 \lesssim x_2^+ \lesssim 400$ .  
It is located in the log region.
- Friction velocity,  $u_\tau$ , computed from the log-law.
- A shear stress b.c. is used for the wall-parallel velocity component:  $\tau_w = \rho u_\tau^2$
- In the log-region we know that the  $k$  equation can be simplified as  $0 = P^k - \varepsilon$   
 $\Rightarrow k_P = C_\mu^{-1/2} u_\tau^2$  ( $k_P$  is prescribed for the wall-adjacent cells)
- We use the simplified  $k$  equation also for  $\varepsilon$ :  $0 = P^k - \varepsilon$  gives

$$0 = -\overline{v'_1 v'_2} \frac{\partial \bar{v}_1}{\partial x_2} - \varepsilon \quad \Rightarrow \quad 0 = -u_\tau^2 \frac{u_\tau}{\kappa x_2} - \varepsilon \quad \Rightarrow \quad \varepsilon_P = \frac{u_\tau^3}{\kappa x_2}$$

$\varepsilon_P$  is prescribed for the wall-adjacent cells