

2021-01-05, Exam, Part 2, in

Mechanics of fluids, TME226

- **Time:** 14.00-18.00 **Location:** Zoom
- **Teacher:** Lars Davidson, phone 031-772 1404
- **Aids**
 - All.
- **Checking the evaluation and results of your written exam at Canvas. If you have questions on the correction of the exam, add a comment at Canvas and send me an Email.**
- **Grading:** 0-10: 3, 11-20: 4, 21-30: 5.

Q1

- Consider developing incompressible, laminar channel flow obtained from a CFD simulation. The density is equal to one. Use the Matlab or Python file `chan` and the data file `chan_data.dat`, `xp.dat` and `yp.dat`. The data includes the flow in the upper half of the channel. They can be downloaded at Canvas and at <http://www.tfd.chalmers.se/~lada/MoF/exam-21>
 1. Plot the peak velocity at each x_1 location vs. x_1 .
 2. Plot the skinfriction vs. x_1 .
 3. When can the flow be consider to be fully developed?.
 4. Where is the vorticity, ω_3 , largest?
 5. Is there any region where the flow is irrotational?

Upload your Matlab/Python scripts and plots to Canvas.

(15p)

Q2

- Consider fully-developed incompressible, turbulent channel flow obtained from a CFD simulation using a low-Reynolds number $k - \varepsilon$ model. The density is equal to one. The height of the channel is 2.0. Use the Matlab or Python file `turb` and the data file `y_u_k_eps_8000.dat`. They can be downloaded at Canvas and at <http://www.tfd.chalmers.se/~lada/MoF/exam-21>

1. Compute the friction velocity, u_τ .
2. Where is the velocity gradient smallest and largest, respectively?
3. The boundary condition for ε is given by Eq. 11.170 in the eBook. Verify that the ε values at the walls agree with this b.c. (check both walls)
4. The AKN model was used to produce the data. Compute the damping function, f_μ . Plot it vs. x_2 for $x_2 < 0.05$.
5. Compute the viscous diffusion term in the k equation. Plot it vs. x_2^+ and zoom in to $0 < x_2^+ < 100$.

Upload your Matlab/Python scripts and plots to Canvas.

(15p)

TME225 Mechanics of fluids: Formula sheet to be used at written examinations

► The $\epsilon - \delta$ identity reads

$$\epsilon_{inm}\epsilon_{mjk} = \epsilon_{min}\epsilon_{mjk} = \epsilon_{nmi}\epsilon_{mjk} = \delta_{ij}\delta_{nk} - \delta_{ik}\delta_{nj}$$

► Strain rate tensor, vorticity tensor

$$\begin{aligned} \frac{\partial v_i}{\partial x_j} &= \frac{1}{2} \left(\underbrace{\frac{\partial v_i}{\partial x_j} + \frac{\partial v_i}{\partial x_j}}_{2\partial v_i/\partial x_j} + \underbrace{\frac{\partial v_j}{\partial x_i} - \frac{\partial v_j}{\partial x_i}}_{=0} \right) \\ &= \frac{1}{2} \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) + \frac{1}{2} \left(\frac{\partial v_i}{\partial x_j} - \frac{\partial v_j}{\partial x_i} \right) = S_{ij} + \Omega_{ij} \end{aligned}$$

► The vorticity vector is computed as

$$\begin{aligned} \boldsymbol{\omega} &= \nabla \times \mathbf{v} \\ \omega_i &= \epsilon_{ijk} \frac{\partial v_k}{\partial x_j} \end{aligned}$$

► The material derivative

$$\rho \frac{d\Psi}{dt} = \rho \frac{\partial \Psi}{\partial t} + \rho v_j \frac{\partial \Psi}{\partial x_j}$$

where $\Psi = v_i, u, T, k, \overline{v'_i v'_j} \dots$

► The balance equation for mass

$$\frac{d\rho}{dt} + \rho \frac{\partial v_i}{\partial x_i} = 0$$

► The balance equation for linear momentum

$$\rho \frac{dv_i}{dt} = \frac{\partial \sigma_{ji}}{\partial x_j} + \rho f_i$$

► The balance equation for internal energy

$$\rho \frac{du}{dt} = \sigma_{ji} \frac{\partial v_i}{\partial x_j} - \frac{\partial q_i}{\partial x_i}$$

► The equation for kinetic energy reads

$$\rho \frac{dk}{dt} = \frac{\partial v_i \sigma_{ji}}{\partial x_j} - \sigma_{ji} \frac{\partial v_i}{\partial x_j} + \rho v_i f_i$$

► The constitutive law for Newtonian viscous fluids

$$\sigma_{ij} = -p\delta_{ij} + 2\mu S_{ij} - \frac{2}{3}\mu S_{kk}\delta_{ij}, \quad \sigma_{ij} = -p\delta_{ij} + \tau_{ij}$$

$$q_i = -k \frac{\partial T}{\partial x_i}$$

► Viscosity

μ : dynamic viscosity

ν : kinematic viscosity ($\nu = \mu/\rho$)

► The continuity equation and the Navier-Stokes equation for incompressible flow with constant viscosity read (*conservative* form, p denotes the hydrostatic pressure, i.e. $p = 0$ if $v_i = 0$)

$$\frac{\partial v_i}{\partial x_i} = 0$$

$$\rho \frac{\partial v_i}{\partial t} + \rho \frac{\partial v_i v_j}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \mu \frac{\partial^2 v_i}{\partial x_j \partial x_j}$$

► The Navier-Stokes equation for incompressible flow with constant viscosity read (*non-conservative* form)

$$\rho \frac{\partial v_i}{\partial t} + \rho v_j \frac{\partial v_i}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \mu \frac{\partial^2 v_i}{\partial x_j \partial x_j}$$

The viscous stress tensor then reads

$$\tau_{ij} = 2\mu S_{ij} = \mu \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$$

► The equation for internal energy reads

$$\rho \frac{du}{dt} = -p \frac{\partial v_i}{\partial x_i} + \underbrace{2\mu S_{ij} S_{ij} - \frac{2}{3}\mu S_{kk} S_{ii}}_{\Phi} + \frac{\partial}{\partial x_i} \left(k \frac{\partial T}{\partial x_i} \right)$$

► Streamfunction, Ψ ; potential, Φ

$$v_1 = \frac{\partial \Psi}{\partial x_2}, \quad v_2 = -\frac{\partial \Psi}{\partial x_1}$$

$$v_k = \frac{\partial \Phi}{\partial x_k}$$

► The Rayleigh problem

$$\eta = \frac{x_2}{2\sqrt{\nu t}}, \quad f = \frac{v_1}{V_0}$$

$$\frac{d^2 f}{d\eta^2} + 2\eta \frac{df}{d\eta} = 0$$

► Blasius solution

$$\xi = \left(\frac{V_{1,\infty}}{\nu x_1} \right)^{1/2} x_2, \quad \Psi = (\nu V_{1,\infty} x_1)^{1/2} g$$

$$\frac{1}{2} g g'' + g''' = 0$$

► The Navier-Stokes (different form of the convective term)

$$\frac{\partial v_i}{\partial t} + \frac{\partial k}{\partial x_i} - \varepsilon_{ijk} v_j \omega_k = -\frac{1}{\rho} \frac{\partial P}{\partial x_i} + \nu \frac{\partial^2 v_i}{\partial x_j \partial x_j} + f_i$$

► Complex functions

$$f = u + iv, \quad z = x + iy, \quad z = re^{i\theta} = r(\cos\theta + i\sin\theta)$$

In fluid mechanics, $f = \Phi + i\Psi$, i.e. the streamfunction is the imaginary part and the velocity potential is the real part.

► The Laplace operator in polar coordinates reads

$$\nabla^2 f = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2}$$

► Velocities from Ψ in polar coordinates

$$v_r = \frac{1}{r} \frac{\partial \Psi}{\partial \theta}, \quad v_\theta = -\frac{\partial \Psi}{\partial r}$$

► The Bernoulli equation

$$p_1 + \frac{\rho V_1^2}{2} + \rho g h_1 = \text{const}$$

► The transport equation for the vorticity reads

$$\frac{d\omega_p}{dt} \equiv \frac{\partial \omega_p}{\partial t} + v_k \frac{\partial \omega_p}{\partial x_k} = \omega_k \frac{\partial v_p}{\partial x_k} + \nu \frac{\partial^2 \omega_p}{\partial x_j \partial x_j}$$

► The Kolmogorov scales $v_\eta = (\nu\varepsilon)^{1/4}$, $\ell_\eta = \left(\frac{\nu^3}{\varepsilon}\right)^{1/4}$, $\tau_\eta = \left(\frac{\nu}{\varepsilon}\right)^{1/2}$

► The $-5/3$ law

$$E(\kappa) = \text{const.} \varepsilon^{2/3} \kappa^{-5/3}$$

► The *time averaged* continuity equation and Navier-Stokes equation for incompressible flow with constant viscosity read

$$\begin{aligned} \frac{\partial \bar{v}_i}{\partial x_i} &= 0 \\ \rho \frac{\partial \bar{v}_i \bar{v}_j}{\partial x_j} &= -\frac{\partial \bar{p}}{\partial x_i} + \frac{\partial}{\partial x_j} \left(\mu \frac{\partial \bar{v}_i}{\partial x_j} - \rho \overline{v'_i v'_j} \right) \end{aligned} \quad (1)$$

► Units

$$\begin{aligned}\nu &= \frac{\mu}{\rho} & m^2/s \\ \varepsilon & & m^2/s^3 \\ k & & m^2/s^2\end{aligned}$$

► The wall region

Friction velocity: $\tau_w = \rho u_\tau^2$, $x_2^+ = \frac{x_2 u_\tau}{\nu}$

The linear law: $\frac{\bar{v}_1}{u_\tau} = \frac{u_\tau x_2}{\nu}$ or $\bar{v}_1^+ = x_2^+$

The log-law: $\frac{\bar{v}_1}{u_\tau} = \frac{1}{\kappa} \ln\left(\frac{x_2 u_\tau}{\nu}\right) + B$ or $\bar{v}_1^+ = \frac{1}{\kappa} \ln(x_2^+) + B$

► The exact k equation reads

$$\frac{\partial \bar{v}_j k}{\partial x_j} = -\overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j} - \frac{\partial}{\partial x_j} \left[\frac{1}{\rho} \overline{v'_j p'} + \frac{1}{2} \overline{v'_j v'_i v'_i} - \nu \frac{\partial k}{\partial x_j} \right] - \nu \frac{\partial v'_i}{\partial x_j} \frac{\partial v'_i}{\partial x_j}$$

► The exact K equation reads

$$\begin{aligned}\frac{\partial \bar{v}_j K}{\partial x_j} &= \nu \frac{\partial^2 K}{\partial x_j \partial x_j} - \frac{1}{\rho} \frac{\partial \bar{v}_i \bar{p}}{\partial x_i} - \nu \frac{\partial \bar{v}_i}{\partial x_j} \frac{\partial \bar{v}_i}{\partial x_j} \\ &\quad - \frac{\partial \bar{v}_i \overline{v'_i v'_j}}{\partial x_j} + \overline{v'_i v'_j} \frac{\partial \bar{v}_i}{\partial x_j}.\end{aligned}$$

► The modelled k and ε equations

$$\begin{aligned}\frac{\partial k}{\partial t} + \bar{v}_j \frac{\partial k}{\partial x_j} &= \nu_t \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) \frac{\partial \bar{v}_i}{\partial x_j} + g_i \beta \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} \\ &\quad - \varepsilon + \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right] \\ \frac{\partial \varepsilon}{\partial t} + \bar{v}_j \frac{\partial \varepsilon}{\partial x_j} &= \frac{\varepsilon}{k} c_{\varepsilon 1} \nu_t \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) \frac{\partial \bar{v}_i}{\partial x_j} \\ &\quad + c_{\varepsilon 1} g_i \frac{\varepsilon}{k} \frac{\nu_t}{\sigma_\theta} \frac{\partial \bar{\theta}}{\partial x_i} - c_{\varepsilon 2} \frac{\varepsilon^2}{k} + \frac{\partial}{\partial x_j} \left[\left(\nu + \frac{\nu_t}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_j} \right] \\ \nu_t &= C_\mu \frac{k^2}{\varepsilon}\end{aligned}$$

► Wall functions

$$u_\tau = \frac{\kappa \bar{v}_{1,P}}{\ln(E u_\tau \delta x_2 / \nu)}$$

$$k_P = C_\mu^{-1/2} u_\tau^2, \quad C_\mu = 0.09$$

$$\varepsilon_P = P^k = \frac{u_\tau^3}{\kappa \delta x_2}$$

► Low-Reynolds number model: different wall boundary conditions for ε :

$$\varepsilon_{wall} = \nu \frac{\partial^2 k}{\partial x_2^2}$$

$$\varepsilon_{wall} = 2\nu \left(\frac{\partial \sqrt{k}}{\partial x_2} \right)^2$$

$$\varepsilon_{wall} = \frac{2\nu k}{x_2^2}$$

► In the Boussinesq assumption an eddy (i.e. a *turbulent*) viscosity is introduced to model the unknown Reynolds stresses in Eq. 1. The stresses are modelled as

$$\overline{v'_i v'_j} = -\nu_t \left(\frac{\partial \bar{v}_i}{\partial x_j} + \frac{\partial \bar{v}_j}{\partial x_i} \right) + \frac{2}{3} \delta_{ij} k = -2\nu_t \bar{s}_{ij} + \frac{2}{3} \delta_{ij} k$$

Trick 1:

$$A_i \frac{\partial B_j}{\partial x_k} = \frac{\partial A_i B_j}{\partial x_k} - B_j \frac{\partial A_i}{\partial x_k}$$

Trick 2:

$$A_i \frac{\partial A_i}{\partial x_j} = \frac{1}{2} \frac{\partial A_i A_i}{\partial x_j}$$