



# Fluid-Structure Interaction Analysis of the Forces Causing Stent Graft Migration



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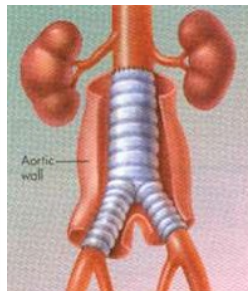
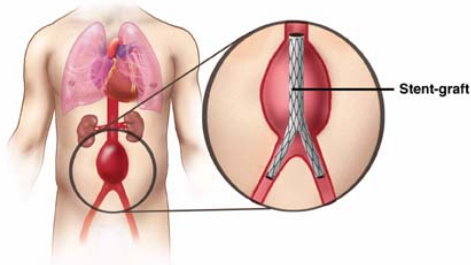
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# Introduction

- Abdominal aortic aneurysm
  - A localized dilation of the abdominal aortic vessel
  - Common for males of 65 years of age and older
- Common treatments
  - Open surgery - Dacron or e-PTFE (gore-tex) tube - Graft
  - Inserted internal reinforcement, relining the vessel - Stent graft
    - Endovascular Aortic Repair (EVAR)



# Introduction

## Problem description

Difficulties regarding attachment of the reinforcing structure

- Anchor hooks only at upper attachment point
- Lower extensions kept in place only by self expansion
- Stent graft migration → pressurized blood flow in the aneurysm → increased risk of rupture



# Introduction

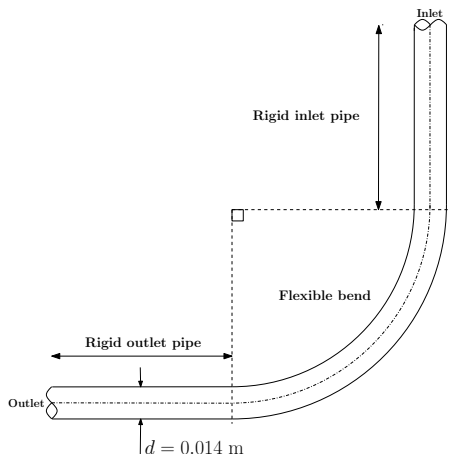
## Purpose

- In 2004, a study by Zarins et al. showed that 18.8% of 1119 patients experienced stent graft migration
- Forces causing stent graft migration of the non-fixated distal attachments are highly interesting.
- An experimental study performed by Malina et al. demonstrates that these forces range between 2 and 3.4 N.
- Previous studies by e.g. Li & Kleinstreuer show forces of these magnitudes from FSI-simulations.
- Comparison of two different numerical approaches when performing FSI simulations

# Introduction

## Method

- Two parallel FSI studies, using two different softwares
  - LS-DYNA (LD), FE-based
  - OpenFOAM (OF), FV-based
- Two different flow scenarios
  - Steady flow
  - Pulsating flow
- Simple momentum balance calculation of deflected inviscid flow.



# Introduction

## Limitations, assumptions and simplifications

- Turbulence not modelled
- No gauge pressure
- Gravity is neglected
- Symmetry
- Fluid medium set to water
- Only one distal extension is simulated
- The flexible bend is in an initial stress free state
- The pulsating flow is assumed to do so sinusoidally with 60 bpm
- Pipe walls modelled as smooth

# Introduction

## Limitations, assumptions and simplifications

### Material properties

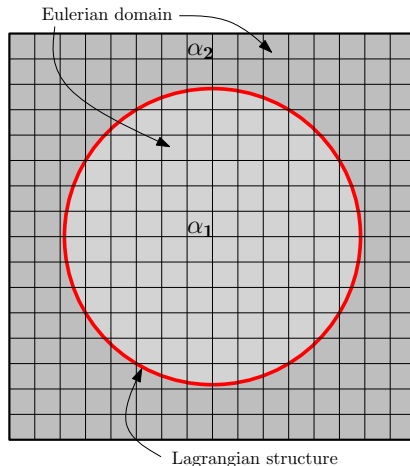
- Fluid
  - Properties of water at 20°C
- Structure (extracted from prior studies)
  - Material is considered isotropic and homogeneous, disregarding the metallic mesh of the stent → Endovascular Graft (EVG)
  - Young's modulus ( $E$ ) = 10 [MPa]
  - Poisson's ratio ( $\eta$ ) = 0.27 [-]
  - Density = 6000 [kg/m<sup>3</sup>]



# Computational methods

## LS-DYNA

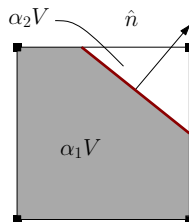
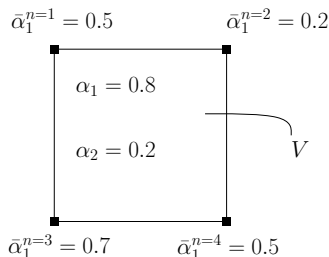
- Lagrangian structure constrained within a fixed, independent Eulerian mesh
- Two Eulerian domains containing the fluid (water) and a dummy material, respectively.
  - Multi-Material ALE (MMALE)
- $\alpha_1$  (water) is the flowing material interacting with the Lagrangian structure



# Computational methods

## LS-DYNA

- Mixed elements are cut with a plane separating the materials
- The orientation of the plane is controlled by the gradient of the volume fraction field (i.e. distribution of  $\alpha_1$  and  $\alpha_2$ ), which is governed by the Lagrangian structure
- When the structure moves, the volume fractions are updated and the interface plane is reconstructed accordingly



$$\hat{n} = \left\| \frac{\partial \bar{\alpha}_1}{\partial x} \right\| \cdot \frac{\partial \alpha_1}{\partial x} = \frac{1}{\sqrt{2}} \begin{Bmatrix} 1 \\ 1 \end{Bmatrix}$$

# Computational methods

## LS-DYNA

### Governing equations

- Fluid
  - Continuity and momentum equation in the Eulerian framework:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\frac{d}{dt}(\rho \mathbf{v}) = -\nabla p + \mu \nabla^2 \mathbf{v}$$

- Structure
  - Conservation of momentum in the Lagrangian framework:

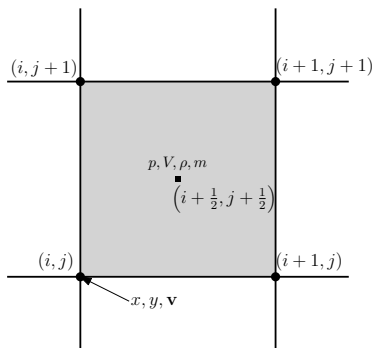
$$\rho_0 \frac{d\mathbf{v}}{dt} = \mathcal{P} \cdot \nabla_{\mathbf{x}} + \rho_0 \mathbf{b}$$

$\mathcal{P}$  is the first Piola-Kirchhoff stress tensor.

# Computational methods

## LS-DYNA

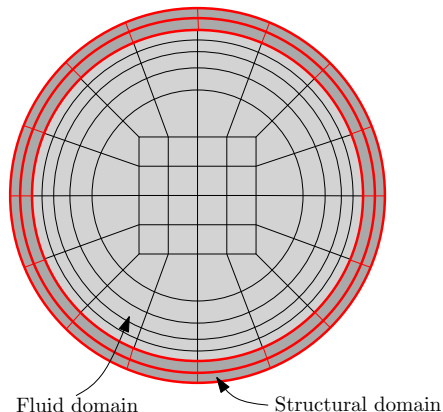
- Constraint based coupling algorithm
  - Conservation of momentum but loss in kinetic energy
- Bulk modulus of water set to  $2.2 \cdot 10^6$  ( $< 2.2 \cdot 10^9$ ) Pa
- van Leer MUSCL advection scheme + Half-Index Shift (HIS) advection algorithm



# Computational methods

## OpenFOAM

- Two separate meshes; one fluid and one structural mesh
- User defined interface  
→ mesh deformation
- Requirement of volume elements  
→ increase of material thickness



# Computational methods

OpenFOAM

## Governing equations

- Fluid
  - Incompressible continuity and momentum equation in the Eulerian framework:

$$\nabla \cdot \mathbf{v} = 0$$

$$\frac{d\mathbf{v}}{dt} = -\frac{1}{\rho}\nabla p + \nu\nabla^2\mathbf{v}$$

- Linear upwind advection scheme
- Structure
  - Conservation of *incremental* momentum in the *updated* Lagrangian framework:

$$\rho_u \frac{d\delta\mathbf{v}}{dt} = (\mathbf{F}_u \cdot \boldsymbol{\Sigma}_u) \cdot \nabla_{\mathbf{X}} + \rho_u \delta\mathbf{b}$$

# Computational methods

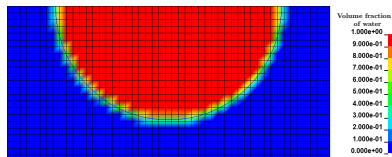
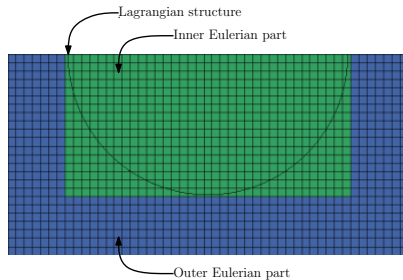
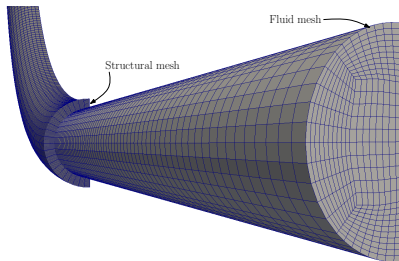
## Boundary conditions

| Software | Boundary       | Type                  | Value                          |
|----------|----------------|-----------------------|--------------------------------|
| OF       | Inlet          | Steady-state velocity | 0.5 [m/s]                      |
|          |                | Periodic velocity     | $0.5 + 0.5\sin(2\pi ft)$ [m/s] |
|          | Outlet         | Mean pressure         | 0 [Pa]                         |
|          | Rigid walls    | No-slip               | -                              |
|          | Flexible walls | Moving wall velocity  | -                              |
|          | Symmetry plane | Symmetry              | -                              |
| LD       | Inlet          | Steady-state velocity | 0.5 [m/s]                      |
|          |                | Periodic velocity     | $0.5 + 0.5\sin(2\pi ft)$ [m/s] |
|          | Outlet         | Zero traction         | 0 [N/m <sup>2</sup> ]          |
|          | Rigid walls    | No-slip               | -                              |
|          | Flexible walls | Moving wall velocity  | -                              |
|          | Symmetry plane | Symmetry              | -                              |

# Computational methods

## Meshes

### Two different meshes

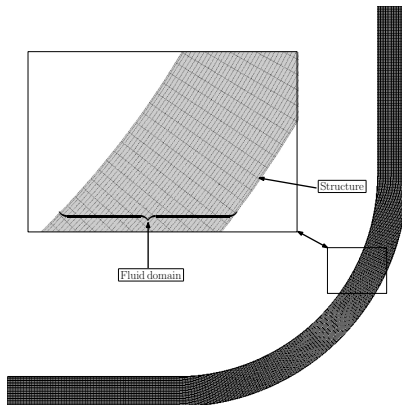
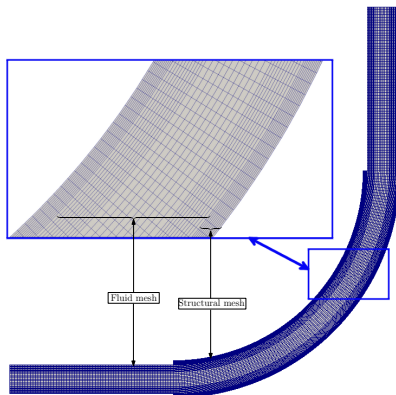




# Computational methods

## Meshes

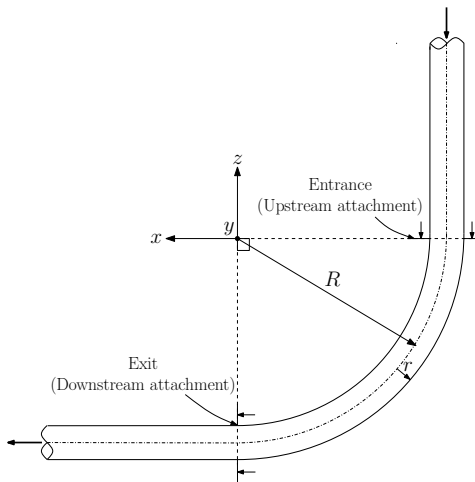
- OF cell count: 108,360
- LD cell count: 285,768 fluid elements, 13,616 structural (shell) elements



# Results

## Overview

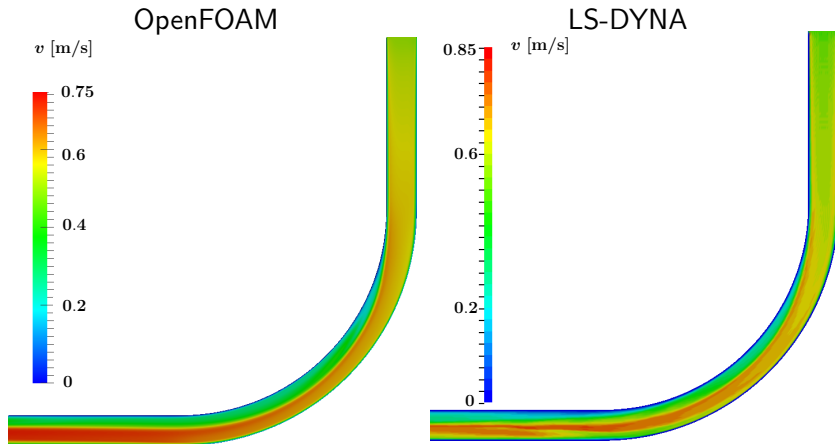
Two coupled analyses on a bent EVG setup using a steady and a sinusoidal inlet velocity boundary condition



# Results

## Steady FSI

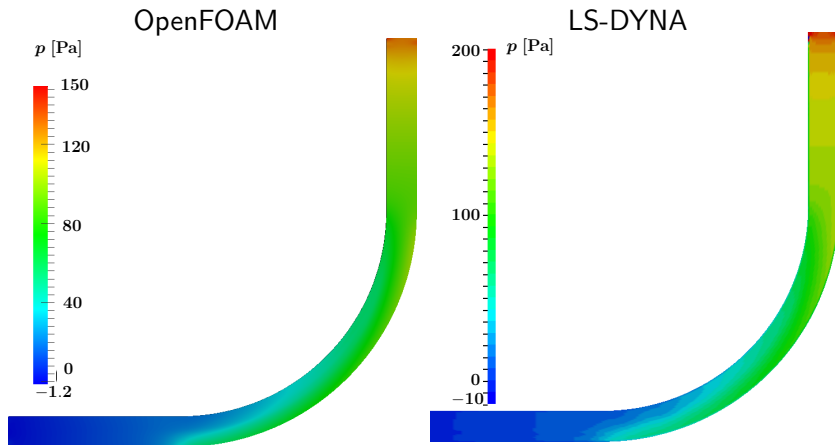
Velocity fields, steady inlet velocity:  $|\mathbf{v}_{inlet}| = 0.5 \text{ m/s}$



# Results

## Steady FSI

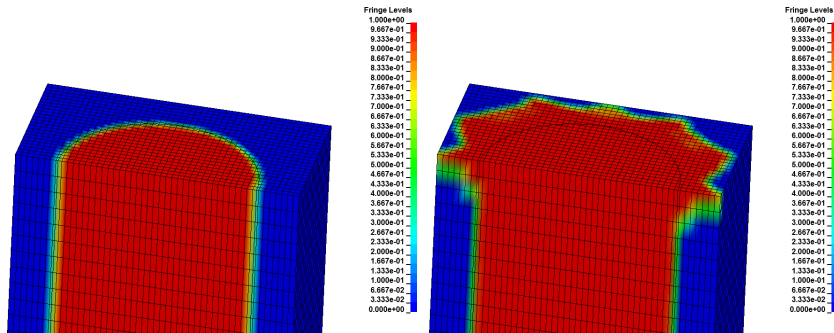
Pressure fields, steady inlet velocity:  $|\mathbf{v}_{inlet}| = 0.5 \text{ m/s}$



# Results

## Steady FSI

- Differences in magnitude may be due to
  - Different meshes
  - Different boundary conditions
  - Numerical leakage at inlet in LD

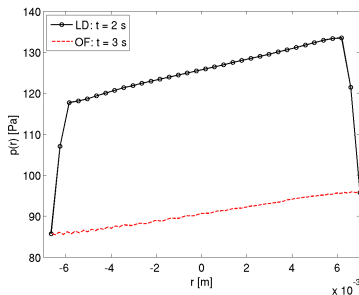
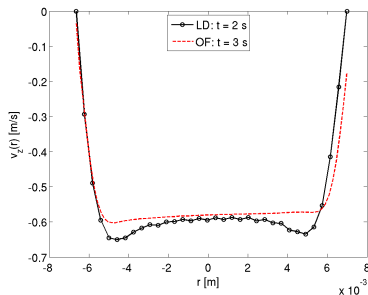


# Results

## Steady FSI

### Cross-sectional velocity and pressure profiles (upstream)

- Boundary layer less developed in LD
  - Lower mesh density in near wall region
  - (Different advection algorithm)
- Volume fraction method used in LD creates uncertainties regarding the near wall solution variables.

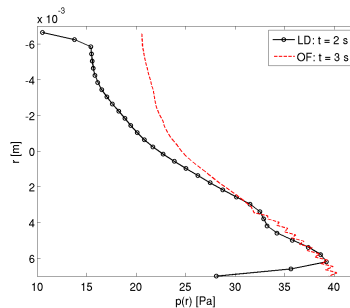
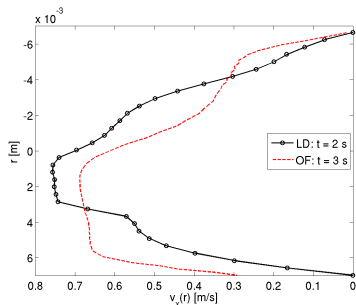


# Results

## Steady FSI

### Cross-sectional velocity and pressure profiles (downstream)

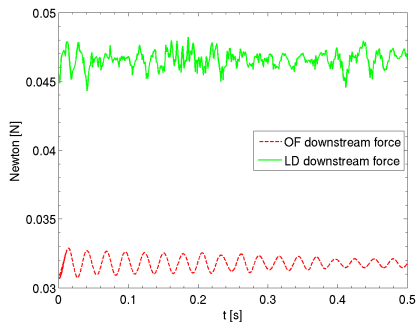
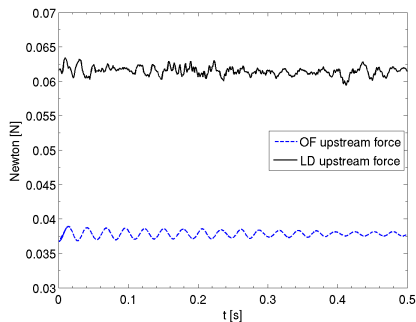
- Laminar flow in OF, occurrence of numerical instabilities in LD
  - Different meshes
  - Different advection algorithms
- The flow separation is validated by the pressure gradients



# Results

## Steady FSI

Upstream and downstream normal forces.



Simple momentum balance calculations show that

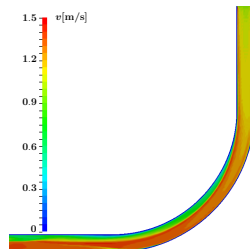
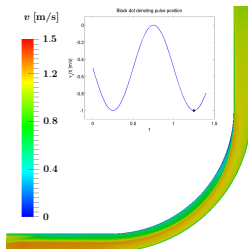
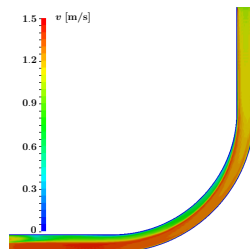
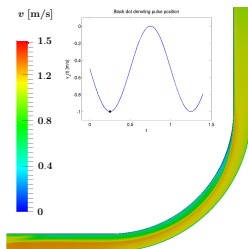
$$F_{upstream} = F_{downstream} \approx 0.03841 \text{ N}$$



# Results

## Pulsating FSI

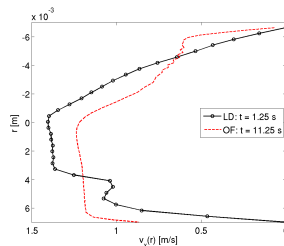
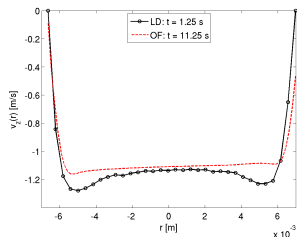
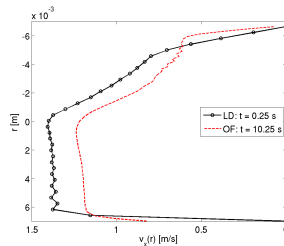
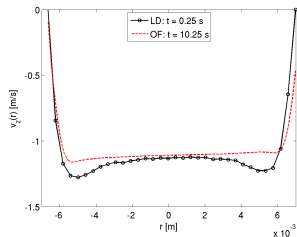
Velocity fields at 0.25 s and 1.25 s,  $|\mathbf{v}_{inlet}| = 1$  m/s



# Results

## Pulsating FSI

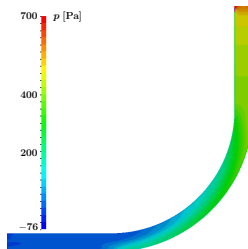
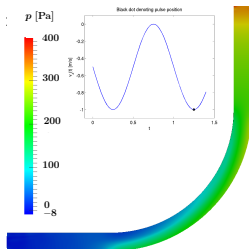
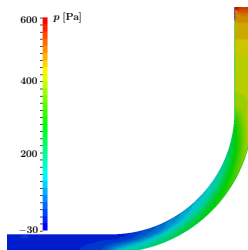
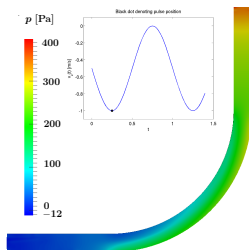
Velocity profiles at 0.25 s and 1.25 s,  $|\mathbf{v}_{inlet}| = 1 \text{ m/s}$



# Results

## Pulsating FSI

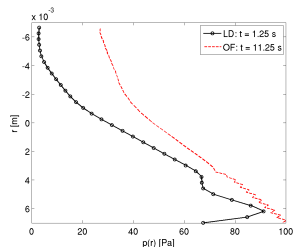
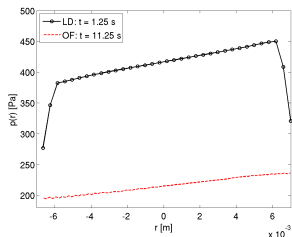
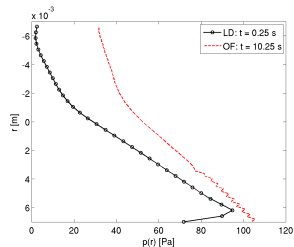
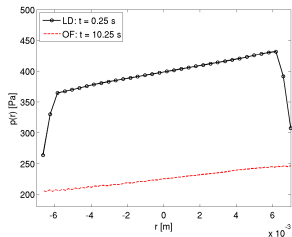
Pressure fields at 0.25 s and 1.25 s,  $|\mathbf{v}_{inlet}| = 1$  m/s



# Results

## Pulsating FSI

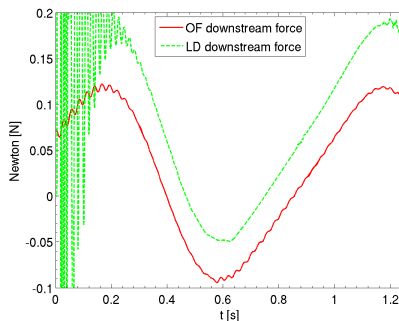
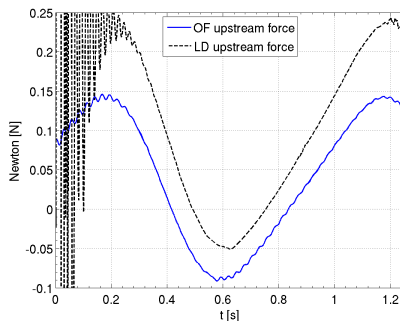
Pressure profiles at 0.25 s and 1.25 s,  $|\mathbf{v}_{inlet}| = 1$  m/s



# Results

## Pulsating FSI

### Normal forces in upstream and downstream attachments



| Software  | Upstream force [N] |        | Downstream force [N] |        |
|-----------|--------------------|--------|----------------------|--------|
|           | 0.25 s             | 1.25 s | 0.25 s               | 1.25 s |
| <b>OF</b> | 0.1298             | 0.1279 | 0.1058               | 0.1039 |
| <b>LD</b> | 0.2286             | 0.2278 | 0.1756               | 0.1751 |

# Conclusions

Judging by prior studies, FSI simulations are realizable and possible to perform in such manner that a fair evaluation of the forces causing stent graft migration is achieved.

However, this project

- only offers simplified simulations of the problem

and

- has been performed using different softwares than in prior studies.

Nonetheless,

- The results show good promise of utilizing both LD and OF for more complex studies.

# Recommendations

There are still several aspects that need to be improved and further tested to reach a more satisfactory level of complexity and accuracy:

- More realistic inlet velocity pulse
- Gauge pressure corresponding to a representative blood pressure
- Parallel experimental and numerical studies
- Parametric studies
- Non-newtonian blood flow
- Longer simulations
- Different setup in LD (e.g. parabolic inlet velocity, different coupling algorithm)

Thank you for listening!