

Multiphysics simulations of nuclear reactors and more

Gothenburg Region OpenFOAM®User Group
Meeting

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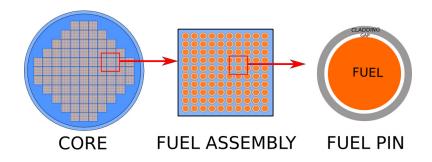
Outline

- Multiphysics and multiscale in Light Water Reactors (LWRs)
- Neutronics and thermal-hydraulics in OpenFOAM®:
- Multiple mesh methodology; mapping and parallelization
- Handling large sets of input parameters
- Example of a simplified Pressurized Water Reactor assembly

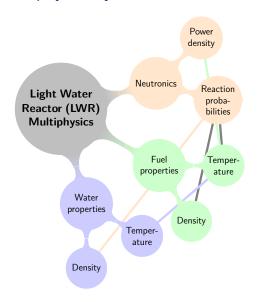
and more ...

Coupled pressure and velocity solver in foam-extend-3.1

Multiscale systems



Multiphysics systems



Fuel reaction probabilities:

Temperature and density coupling

Power density:

Energy source in fuel temperature

Temperatures:

Dependence between water and fuel properties

Water cross-sections:

Water density coupling

FIRE - Fine mesh deterministic REactor modelling

Development of a fine mesh computational tool for nuclear fuel bundles:

- integrated approach for solving neutronics and thermal-hydraulics
- single and two-phase flow models based on first principles
- high-resolution coupling on fine meshes using HPC
- fuel bundle size calculations, ultimately coupled to coarse mesh solvers

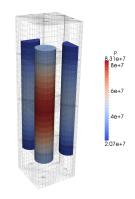


Figure: Power density distribution at fuel pins.

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Supervisors:

Christophe Demazière, Paolo Vinai, Srdjan Sasic

Neutronics solver

Steady-state eigenvalue problem

- Eigenvalue problem solved by power iteration method
- Diffusion solver based on multiple groups:

$$\nabla \cdot (D_g \nabla \Phi_g) + \Sigma_{T,g} \Phi_g = S_g + \frac{1}{k} F_g \tag{1}$$

- Fast but limited accuracy for fine-mesh with heterogeneous parameters
- Implemented using a block matrix formulation
- Discrete ordinates method, multiple groups and multiple directions:

$$\Omega_m \cdot \nabla \Psi_{m,g} + \Sigma_{T,g} \Psi_{m,g} = S_{m,g} + \frac{\chi_g}{k} F_g \tag{2}$$

- More accurate, but computationally heavy
- Transport method required for fine mesh problems

More information:

Block matrix systems in OFW9 training, Zagreb, 2014: "Block coupled matrix solvers in foam-extend-3", Klas Jareteg and Ivor Clifford

Neutronics solver - Discrete ordinates method

Implementation of discrete ordinates:

- Standard matrix solvers potentially inefficient
- Following ordinate Ω_m , a direct sweep through the domain allows $\Psi_{m,g}$ to be computed in one sweep
- Sweeping order of the cells calculated at initialization
- Parallelization handled as in GaussSeidel solvers (corresponding to full boundary exchange after finisihed sweep)

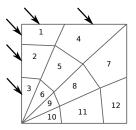


Figure: Example of a sweep ordering for an unstructured mesh

```
Code: steadyDOMSweeNeutronics.C

for (register label cellI=0; cellI<nCells; cellI++)

{

// Modification for ordered sweep

register label cellJ = sweepOrder[cellI];

363

364

365
```

Thermal-hydraulics single-phase solver

Steady state single phase solver:

- Approach equivalent to simpleFoam
- Buoyancy taken into account for density variation from heating
- Generally slow convergence for pressure and velocity

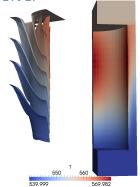


Figure: Temperature distribution in coolant around a single fuel pin.

More information:

Presentation on coupled pressure and velocity solver from OFW9, Zagreb, 2014: "puCoupledFoam - an open source coupled incompressible pressure-velocity solver based on foam-extend" Klas Jareteg, Vuko Vukcevic, Hrvoje Jasak

Thermal-hydraulics: conjugate heat transfer

- Multiregion approach, separate meshes for all solid and liquid regions
- Implicit heat transfer by using regionCouple
 - Explicit iteration over all regions not an alternative, too many regions
- Temperature dependent thermophysical properties
 - Based on table interpolation, inheriting basicThermo

Thermal-hydraulics two-phase solver

- Two-phase flow model under development to extend solver to Boiling Water Reactors (BWRs)
- Large variety of complex behavior to be covered
- Solver based on a population balance methods

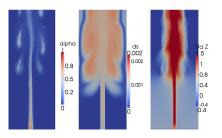


Figure: Void fraction, bubble mean diameter and axial velocity

Steady state coupling algorithm

- Explicit scheme, coupled convergence iteration
- Neutronics and thermal-hydraulic modules implemented as classes.
 Easy testing of different implementations using inheritance and run-time choosable mechanism

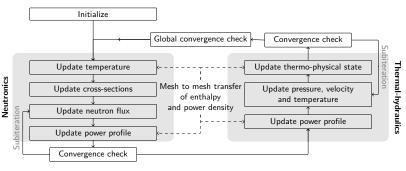


Figure: Iterative coupled scheme. [1]

Class structure

- Solvers for each field written as objects
- Direct inheritance allows for different models to be tested in the coupled scheme

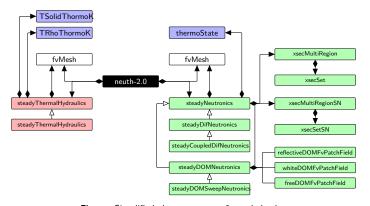
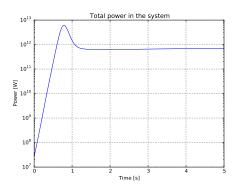


Figure: Simplified class structure of coupled solver

Transient multiphysics calculations

Master thesis project by Rasmus Andersson

- Currently developing a transient multiphysics solver
- Thermal-hydraulic solvers based on PISO algorithm, with variable density
- Neutronics solver based on diffusion solver



Multiple meshes - Generation and setup

- Repeating structure of fuel pins allows for repeated mesh
- Automatic setup of region coupled interfaces for the thermal-hydraulics

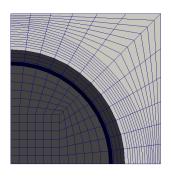


Figure: Mesh example for a quarter of a fuel pin

Multiple meshes - Mapping I

Different meshes in different regions:

- Finer mesh in the liquid coolant than in neutronics in general
- Mapping algorithm needed for data exchange:

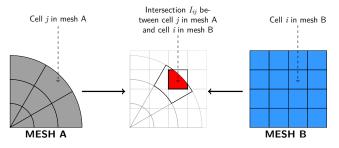


Figure: Example of mapping of two overlapping meshes. [1]

- Fully conservative transfer of extensive quantities
- Geometric overlaps computed equivalent to GGI face overlaps, extended to 3D

Multiple meshes - Mapping II

Mapping handled locally on each CPU

```
Code: neuthFoam-2.0.C

// Compute cell intersection between all fuel meshes and neutronics 164

PtrList<intersectionChecker> iSolid(I); 165

forAll(iSolid,i) 167

{ 168
    iSolid.set(i, new intersectionChecker(solidMeshes[i], neutronicsMesh)); 169
}
```

```
Code: neuthFoam-2.0.C
  Transper power distribution from neutronics to fuel meshes
                                                                               297
const volScalarField& Pnk = neutronics->P();
                                                                                298
PtrList<volScalarField>& PS = thermalhydraulics->P():
                                                                                299
                                                                                300
                                                                               301
forAll(solidMeshes.i)
                                                                               302
    // Transfer the power field and immediately normalize
                                                                               303
    solidMeshes[i].backwardFieldVolumetric(PS[i],Pnk);
                                                                               304
                                                                               305
```

Multiple meshes - Mapping III

- Parallelization: all meshes are split in same planes
- meshPartitionerRegion (not yet released) used to generate cell sets.

```
      Code: meshPartitionerDict

      Directions (1 1 4);
      1

      Mode "manual";
      2

      X (0.0 1.0);
      3

      Y (0.0 1.0);
      4

      Z (-100.0 0.4 0.7 1.1 100.0);
      5
```

Neutronics mesh - cross-section handling

- Different cross-sections in different materials
- Handled using cell sets

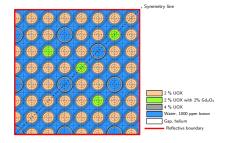


Figure: Horizontal view of test system. [1]

Example case

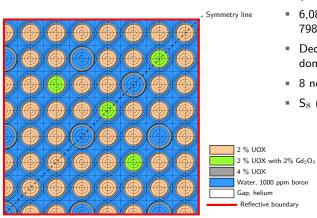


Figure: Horizontal view of test system. [1]

• Quarter of 15×15 system

PWR conditions

 System height 100 cm (+2 × 20 cm reflector)

• 6,088,000 cells in coolant, 798,000 in neutronics

Decomposed in 64 domains

8 neutron energy groups

S₈ (80 directions)

Example case - Results I I

- Problem converged in 14 hours using 64 CPUs (Nehalem Intel® Xeon® E5520, 2.27GHz)
- Multiphysics coupling converged in 8 iterations

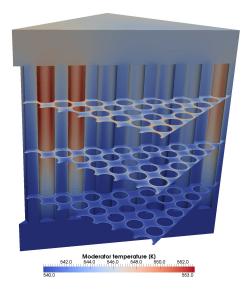


Figure: Moderator temperature. [1]

Example case - Results I I

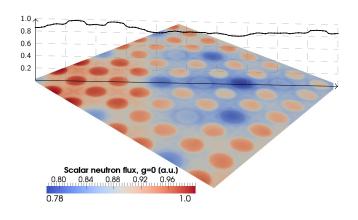


Figure: Scalar flux at mid-elevation for the fast group. [1]

Slow convergence in incompressible flow solvers

Background

- Generally slow convergence of segregated steady-state incompressible solvers
- A large number of iterations needed to resolve coupling between pressure and velocity
- Coupled solvers potentially give an increased convergence rate

Applications

- Single-phase flow around PWR between fuel pins
- Low mach simulations around external surfaces
-

Implicit formulation

Navier-Stokes, incompressible, steady-state equations:

$$\nabla \cdot (\mathbf{U}) = 0 \tag{3}$$

$$\nabla \cdot (\mathbf{U}\mathbf{U}) - \nabla(\nu \nabla \mathbf{U}) = -\frac{1}{\rho} \nabla p \tag{4}$$

with the semi-discretized form:

$$\sum_{\text{faces}} \mathbf{U}_{\text{f}} \cdot \mathbf{S}_{\text{f}} = 0 \tag{5}$$

$$\sum_{\text{faces}} \left[\mathbf{U}\mathbf{U} - \nu \nabla \mathbf{U} \right]_{\text{f}} \cdot \mathbf{S}_{\text{f}} = -\sum_{\text{faces}} P_{\text{f}} \mathbf{S}_{\text{f}}$$
 (6)

Rhie-Chow interpolation in the continuity equation:

$$\sum_{\text{faces}} \left[\overline{\mathbf{U}_{f}} - \overline{\mathbf{D}_{f}} \left(\nabla P_{f} - \overline{\nabla P_{f}} \right) \right] \cdot \mathbf{S}_{f} = 0 \tag{7}$$

a coupled system of four equations is formulated.

pUCoupledFoam - Coupled incompressible solver I

Coupled solver

Coupled solver implemented in foam-extend-3

Example case

- Structured mesh, 4800 cells, laminar case
- Comparison of SIMPLE algorithm and coupled algorithm

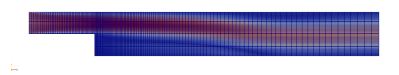


Figure: Geometry and velocity solution for back facing step case

pUCoupledFoam - Coupled incompressible solver II

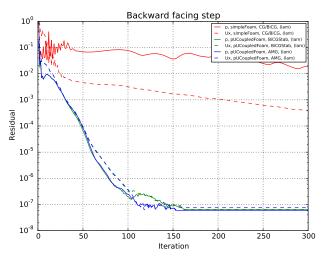


Figure: Performance of simpleFoam compared to pUCoupledFoam.

Questions?

More information:

[1] K. Jareteg et al. "Coupled fine-mesh neutronics and thermal-hydraulics - modeling and implementation for PWR fuel assemblies". In: Submitted to Annals of Nuclear Energy, Special Issue: "Multi-Physics Modeling of LWR Static and Transient Behavior" (2014).