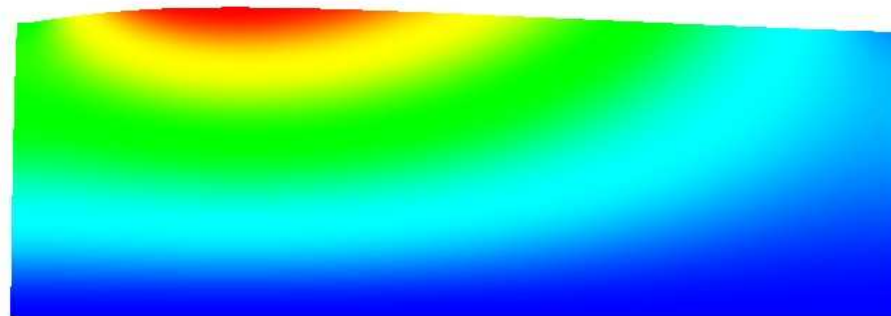


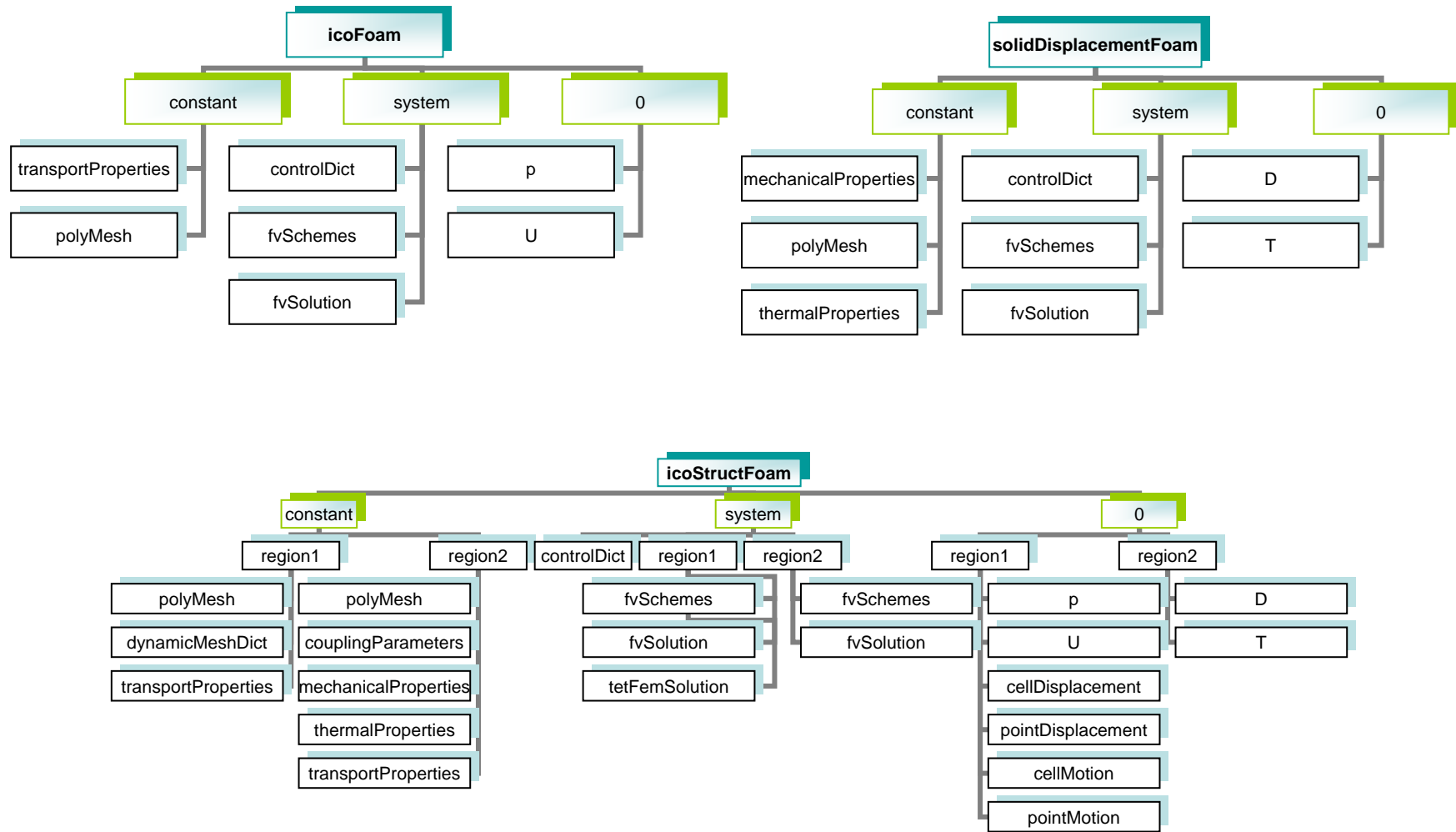
# icoStructFoam

*a fluid-structure interaction solver*

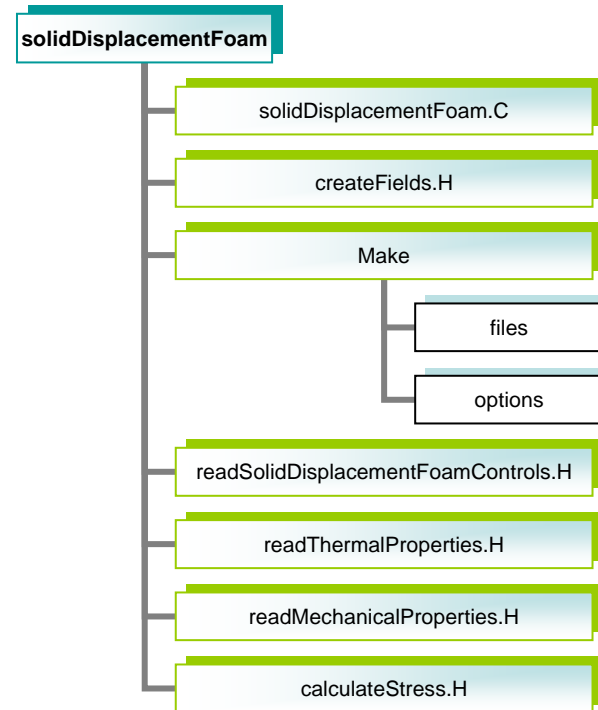
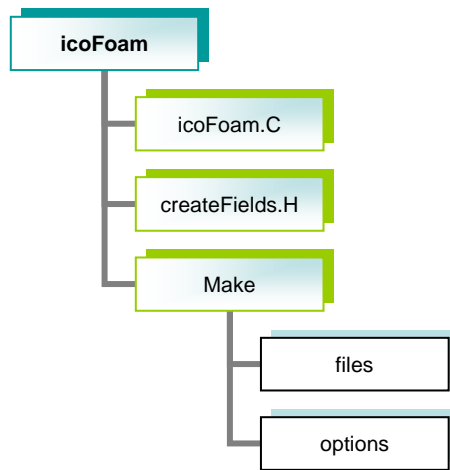
*Philip Evegren*



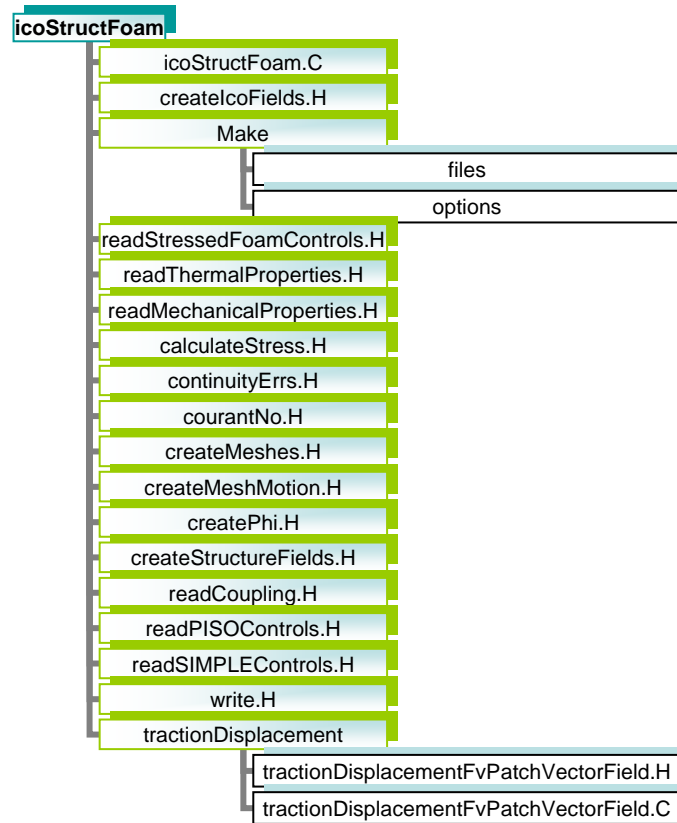
# Cases



# Solvers



# Solvers



# Source code

```
/*-----*\
## #### ##### |
## ## ## | Copyright: ICE Stroemungsfoschungs GmbH
## ## #### |
## ## ## | http://www.ice-sf.at
## #### ##### |
-----*/
```

```
=====  
\\ / F ield | OpenFOAM: The Open Source CFD Toolbox  
\\ / O peration |  
\\ / A nd | Copyright (C) 1991-2005 OpenCFD Ltd.  
\\ M anipulation |  
-----*/
```

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## Application

icoStructFoam

## Description

Transient solver for incompressible, laminar flow of Newtonian fluids coupled with structural mechanics

Based on icoFoam and solidDisplacementFoam  
Coupling after an idea by conjugateFoam

ICE Revision: \$Id:

/local/openfoam/branches/WikiVersions/FluidStructCoupling/icoStructFoam/icoStructFoam.C 1906 2007-08-28T16:16:19.392553Z bgschaid \$

```
/*-----*/
```

```
#include "fvCFD.H"  
#include "Switch.H"  
#include "fixedValueFvPatchFields.H"  
#include "tractionDisplacement/tractionDisplacementFvPatchVectorField.H"  
#include "fvMesh.H"  
#include "PrimitivePatchInterpolation.H"  
#include "motionSolver.H"
```

```
// ***** //
```

```
int main(int argc, char *argv[])  
{
```

```
# include "setRootCase.H"
```

```
# include "createTime.H"
```

- **fixedValueFvPatchFields.H** type defining the fixedValue patches to scalar, tensor etc (included in fvCFD.H).
- **tractionDisplacement/tractionDisplacementFvPatchVectorField.H** declaration of the tractionDisplacement boundary condition.
- **fvMesh.H** Mesh data declarations (included in fvCFD.H).
- **primitivePatchInterpolation.H** declaration of interpolation functions from points to faces and vice versa.
- **motionSolver.H** declaration of mesh-motion solver.

# Source code

```
# include "createMeshes.H"

# include "readMechanicalProperties.H"
# include "readStressedFoamControls.H"
# include "readThermalProperties.H"

# include "createIcoFields.H"
# include "createStructureFields.H"

# include "readCoupling.H"

# include "createMeshMotion.H"

# include "initContinuityErrs.H"

// *****

Info<< "\nStarting time loop\n" << endl;

for (runTime++; !runTime.end(); runTime++)
{
    Info<< "Time = " << runTime.timeName() << nl << endl;

    if(runTime.value()>=startMeshMotion.value()) {
        Info << "\nMoving mesh\n" << endl;

        // Make the fluxes absolute
        // fvc::makeAbsolute(phi, U);

        // dispVals=inter.faceToPointInterpolate(displace);
        dispVals=displace;

        scalar maxDist=-1e10;
        scalar maxAway=-1e10;

        if(displacementMotionSolver) {
            volVectorField::GeometricBoundaryField &meshDisplacement=
const_cast<volVectorField&>(mesh1.objectRegistry::lookupObject<volVectorField>("cellDisplacement")).boundaryField();

            if(typeid(meshDisplacement[fluidSide])!=typeid(fixedValueFvPatchField<vector>)) {
                FatalErrorIn("Coupled Solver ") << "Fluid side not movable" << exit(FatalError);
            }

            vectorField &mDisp=refCast<vectorField>(meshDisplacement[fluidSide]);

            scalar factor=1/motionRelaxation.value();

            forAll(fluidMesh,fluidI) {
                label solidI=exchange[fluidI];

                // vector here=mesh1.points()[fluidPoints[fluidI]];
                vector here=fluidMesh.faceCentres()[fluidI];
                vector old =oldPoints[fluidI];
                vector disp=dispVals[solidI];
                vector neu=disp*factor+(here-old)*(1-factor);
                vector move=neu;

                mDisp[fluidI]=move;
            }
        }
    }
}
```

## displacement based mesh motion

- **createMeshes.H** creates meshes for fluid region and solid region respectively (same thing as createMesh.H).
- **readMechanicalProperties.H** reading the mechanicalProperties dictionary and computing some parameters (same as for sDF).
- **readStressedFoamControls.H** reading "stressAnalysis" subdictionary of fvSolution in region 2 (solid region).
- **readThermalProperties.H** reading thermal properties and computing parameters (same as for sDF).
- **createIcoFields.H** create fields for fluid domain (same as createFields.H in iF).
- **createStructureFields.H** create fields for solid domain (same as createFields.H in sDF).
- **readCoupling.H** read "couplingParameters" file in constant/region2/. Identifying the coupled patches and checking that the meshes are next to each other. Set original face coordinates, *oldPoints*, for common fluid patch.
- **createMeshMotion.H** initializes mesh motion solver and if it is displacement based or not. Initial displacement is set.
- **initContinuityErrs.H** found in iF.

# Source code

displacement based  
mesh motion

```
        if(mag(here-old)>maxDist) {
            maxDist=mag(here-old);
        }
        if(mag(neu-here)>maxAway) {
            maxAway=mag(here-neu);
        }
    }

} else {
    volVectorField::GeometricBoundaryField &motionU=
const_cast<volVectorField&>(mesh1.objectRegistry::lookupObject<volVectorField>("cellMotionU")).boundary
Field());

    if(typeid(motionU[fluidSide])!=typeid(fixedValueFvPatchField<vector>)) {
        FatalErrorIn("Coupled Solver ") << "Fluid side not movable" << exit(FatalError);
    }

    vectorField &patchU=refCast<vectorField>(motionU[fluidSide]);

    // tetPointVectorField neu=inter.faceToPointInterpolate(patchU);
    scalar factor=1/(runTime.deltaT().value()*motionRelaxation.value());
    // const labelList& fluidPoints=fluidPatch.meshPoints();

    // forAll(fluidPoints,fluidI) {
    forAll(fluidMesh,fluidI) {
        label solidI=exchange[fluidI];

        // vector here=mesh1.points()[fluidPoints[fluidI]];
        vector here=fluidMesh.faceCentres()[fluidI];
        vector old =oldPoints[fluidI];
        vector disp=dispVals[solidI];
        vector neu=disp+old;
        vector move=factor*(neu-here);

        patchU[fluidI]=move;

        if(mag(here-old)>maxDist) {
            maxDist=mag(here-old);
        }
        if(mag(neu-here)>maxAway) {
            maxAway=mag(here-neu);
        }
    }
}
mesh1.movePoints(motionPtr->newPoints());
// U.correctBoundaryConditions();

Info << "\nBiggest movement: " << maxDist << " Bigges divergence " << maxAway << endl;

// Make the fluxes relative
// fvc::makeRelative(phi, U);
}

Info << "Solving flow in mesh1\n" << endl;
{
# include "readPISOControls.H"
# include "CourantNo.H"

fvVectorMatrix UEqn
```

motion based  
mesh motion

$$D_{tot} = Df + (P - P_{old})(1 - f)$$

icoFoam

# Source code

```
(
    fvm::ddt(U)
    + fvm::div(phi, U)
    - fvm::laplacian(nu, U)
);

solve(UEqn == -fvc::grad(p));

// --- PISO loop
for (int corr=0; corr<nCorr; corr++)
{
    volScalarField rUA = 1.0/UEqn.A();

    U = rUA*UEqn.H();
    phi = (fvc::interpolate(U) & mesh1.Sf())
    + fvc::ddtPhiCorr(rUA, U, phi);

    adjustPhi(phi, U, p);

    for (int nonOrth=0; nonOrth<=nNonOrthCorr; nonOrth++)
    {
        fvScalarMatrix pEqn
        (
            fvm::laplacian(rUA, p) == fvc::div(phi)
        );

        pEqn.setReference(pRefCell, pRefValue);
        pEqn.solve();

        if (nonOrth == nNonOrthCorr)
        {
            phi -= pEqn.flux();
        }
    }
}

# include "continuityErrs.H"

    U -= rUA*fvc::grad(p);
    U.correctBoundaryConditions();
}

}

Info << "InSolving structure in mesh2In" << endl;

#
{
    include "readStressedFoamControls.H"
    int iCorr = 0;
    scalar initialResidual = 0;

    do
    {
        if (thermalStress)
        {
            volScalarField& T = Tptr();
            solve
            (
                fvm::ddt(T) == fvm::laplacian(DT, T)
            );
        }
    }
}
```

icoFoam

$$\frac{\partial u_i}{\partial t} + \frac{\partial u_i u_j}{\partial x_j} - \nu \frac{\partial^2 u_i}{\partial x_j \partial x_j} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i}$$
$$\frac{\partial u_i}{\partial x_i} = 0$$

solidDisplacementFoam

$$\frac{\partial^2 D_i}{\partial t^2} = \frac{\partial}{\partial x_j} (2\mu + \lambda) \frac{\partial D_i}{\partial x_j} + \frac{\partial \sigma_{ij}}{\partial x_j}$$



# Source code

```
{
    fvVectorMatrix DEqn
    (
        fvm::d2dt2(D)
        ==
        fvm::laplacian(2*mu + lambda, D, "laplacian(DD,D)")
        + divSigmaExp
    );

    if (thermalStress)
    {
        const volScalarField& T = Tptr();
        DEqn += threeKalpha*fvc::grad(T);
    }

    //UEqn.setComponentReference(1, 0, vector::X, 0);
    //UEqn.setComponentReference(1, 0, vector::Z, 0);

    initialResidual = DEqn.solve().initialResidual();

    if (!compactNormalStress)
    {
        divSigmaExp = fvc::div(DEqn.flux());
    }
}

volTensorField gradD = fvc::grad(D);
sigmaD = mu*twoSymm(gradD) + (lambda*1)*tr(gradD);

if (compactNormalStress)
{
    divSigmaExp =
        fvc::div(sigmaD - (2*mu + lambda)*gradD, "div(sigmaD)");
}
else
{
    divSigmaExp += fvc::div(sigmaD);
}

} while (initialResidual > convergenceTolerance && ++iCorr < nCorr);

# include "calculateStress.H"

    Info << "\nMaximum Displacement: " << max(mag(D)).value() << endl;

}

Info << "\nCoupling the solutions\n" << endl;

scalarField & fluidP = p.boundaryField()[fluidSidel];

scalarField &solidP = displace.pressure();

forAll(fluidP,fi) {
    solidP[exchange[fi]]=-fluidP[fi];
}

# include "write.H"
```

solidDisplacementFoam

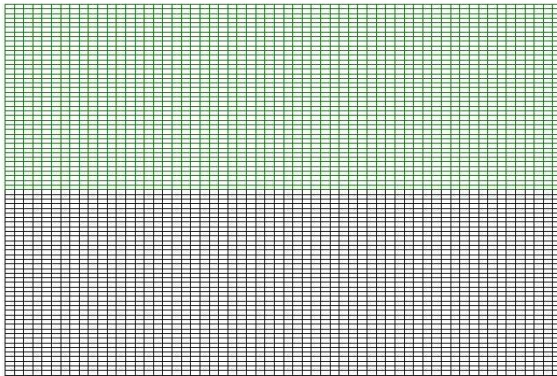
coupling pressure

1. The fluid mesh is deformed according to the displacement of the solid boundary.
2. The flow is solved for in the deformed fluid region.
3. The deformation of the solid region is solved for, based on the pressure distribution at the solid/fluid interface from previous timestep.
4. The pressure is transferred from the fluid to the solid region.

# Running a case

- Download the solver using:

```
svn checkout https://openfoam-extend.svn.sourceforge.net/svnroot/openfoam-extend/trunk/Breeder/solvers/other/IcoStructFoam/
```



- Compile the solver using wmake

- Run the blockMesh utility

```
ln -s region1/polyMesh/ IcoStructFoamTest/constant/polyMesh
blockMesh . IcoStructFoamTest
rm IcoStructFoamTest/constant/polyMesh
ln -s region2/polyMesh/ IcoStructFoamTest/constant/polyMesh
blockMesh . IcoStructFoamTest
rm IcoStructFoamTest/constant/polyMesh
```

# Running a case

- **Boundary & initial conditions**  
**region1**

```
dimensions [0 1 -1 0 0 0];
internalField uniform (0 0 0);
boundaryField
{
    bottom
    {
        type    fixedValue;
        value    uniform (0 0 0);
    }
    top
    {
        type    fixedValue;
        value    uniform (0 0 0);
    }
    frontAndBack
    {
        type    empty;
    }
    inlet
    {
        type    fixedValue;
        value    uniform (0.005 0 0);
    }
    outlet
    {
        type
zeroGradient;
    }
}
```



```
dimensions [0 2 -2 0 0 0];
internalField uniform 0;
boundaryField
{
    bottom
    {
        type    zeroGradient;
    }
    top
    {
        type    zeroGradient;
    }
    frontAndBack
    {
        type    empty;
    }
    inlet
    {
        type    zeroGradient;
    }
    outlet
    {
        type    fixedValue;
        value    uniform 0;
    }
}
```

# Running a case

- **Boundary & initial conditions region1**

```
dimensions [0 1 0 0 0 0];
internalField uniform (0 0 0);
boundaryField
{
    bottom
    {
        type    fixedValue;
        value    uniform (0 0 0);
    }

    top
    {
        // type    zeroGradient;
        type    fixedValue;
        value    uniform (0 0 0);
    }

    frontAndBack
    {
        type    empty;
    }

    inlet
    {
        type    zeroGradient;
    }

    outlet
    {
        type    zeroGradient;
    }
}
```

← **cD**

**pD** →

```
dimensions [0 1 0 0 0 0];
internalField uniform (0 0 0);
boundaryField
{
    bottom
    {
        type    fixedValue;
        value    uniform (0 0 0);
    }

    top
    {
        // type    zeroGradient;
        // type    fixedValue;
        // value    uniform (0 0 0);
    }

    frontAndBack
    {
        type    empty;
    }

    inlet
    {
        type    zeroGradient;
    }

    outlet
    {
        type    zeroGradient;
    }
}
```

# Running a case

- **Boundary & initial conditions region2**

```
dimensions [0 1 0 0 0 0];
internalField uniform (0 0 0);
boundaryField
{
    bottom
    {
        type tractionDisplacement;
        traction uniform (0 0 0);
        pressure uniform 0;
        value uniform (0 0 0);
    }
    top
    {
        type fixedValue;
        value uniform (0 0 0);
    }
    frontAndBack
    {
        type empty;
    }
    inlet
    {
        // type tractionDisplacement;
        // traction uniform (0 0 0);
        // pressure uniform 0;
        type fixedValue;
        value uniform (0 0 0);
    }
    outlet
    {
        type tractionDisplacement;
        traction uniform (0 0 0);
        pressure uniform 0;
        value uniform (0 0 0);
    }
}
```

← **D**

**couplingParameters**

```
// ***** //
fluidSide top;
solidSide bottom;
startMeshMotion time [0 0 1 0 0 0] 0.1;
motionRelaxation iTime [0 0 -1 0 0 0] 5;
// ***** //
```

# Running a case

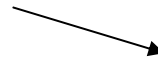
- Other properties

```
// ***** //  
  
twoDMotion yes;  
  
//solver laplaceTetDecomposition;  
  
//diffusion quadratic patchEnhanced;  
  
//frozenDiffusion off;  
  
//distancePatches  
//(  
//);  
dynamicFvMesh dynamicMotionSolverFvMesh;  
  
motionSolverLibs ("libfvMotionSolvers.so");  
// motionSolverLibs ("libfvMotionSolvers.dylib");  
  
solver displacementLaplacian;  
  
diffusivity uniform;  
  
// ***** //
```

**dynamicMeshDict**



**controlDict**



```
// ***** //  
  
applicationClass laplacianFoam;  
  
startFrom startTime;  
  
startTime 0;  
  
stopAt endTime;  
  
endTime 1;  
  
deltaT 0.001;  
  
writeControl runTime;  
  
writeInterval 0.01;  
  
cycleWrite 0;  
  
writeFormat ascii;  
  
writePrecision 6;  
  
writeCompression uncompressed;  
  
timeFormat general;  
  
timePrecision 6;  
  
runTimeModifiable yes;  
  
//  
***** //  
***** //
```

# Running a case

- **Run by typing:**

*< solver > < path > < case >*

- **Post-processing**

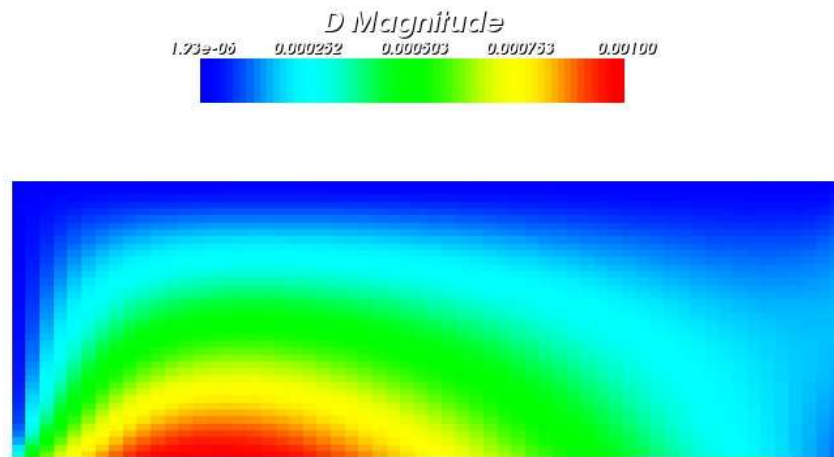
*foamToVTK . icoStructFoamTest -mesh region1*

*foamToVTK . icoStructFoamTest -mesh region2*

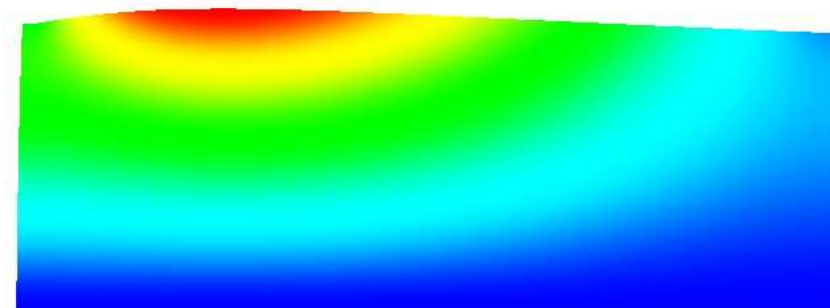
**Launch paraview**

# Running a case

Displacement of solid region



Displacement of fluid region



*cellDisplacement Magnitude*

0.00   0.000233   0.000506   0.000757   0.00101





# Running a case

Stress field of solid region



Pressure field of fluid region



# Running a case

Velocity field of fluid region

